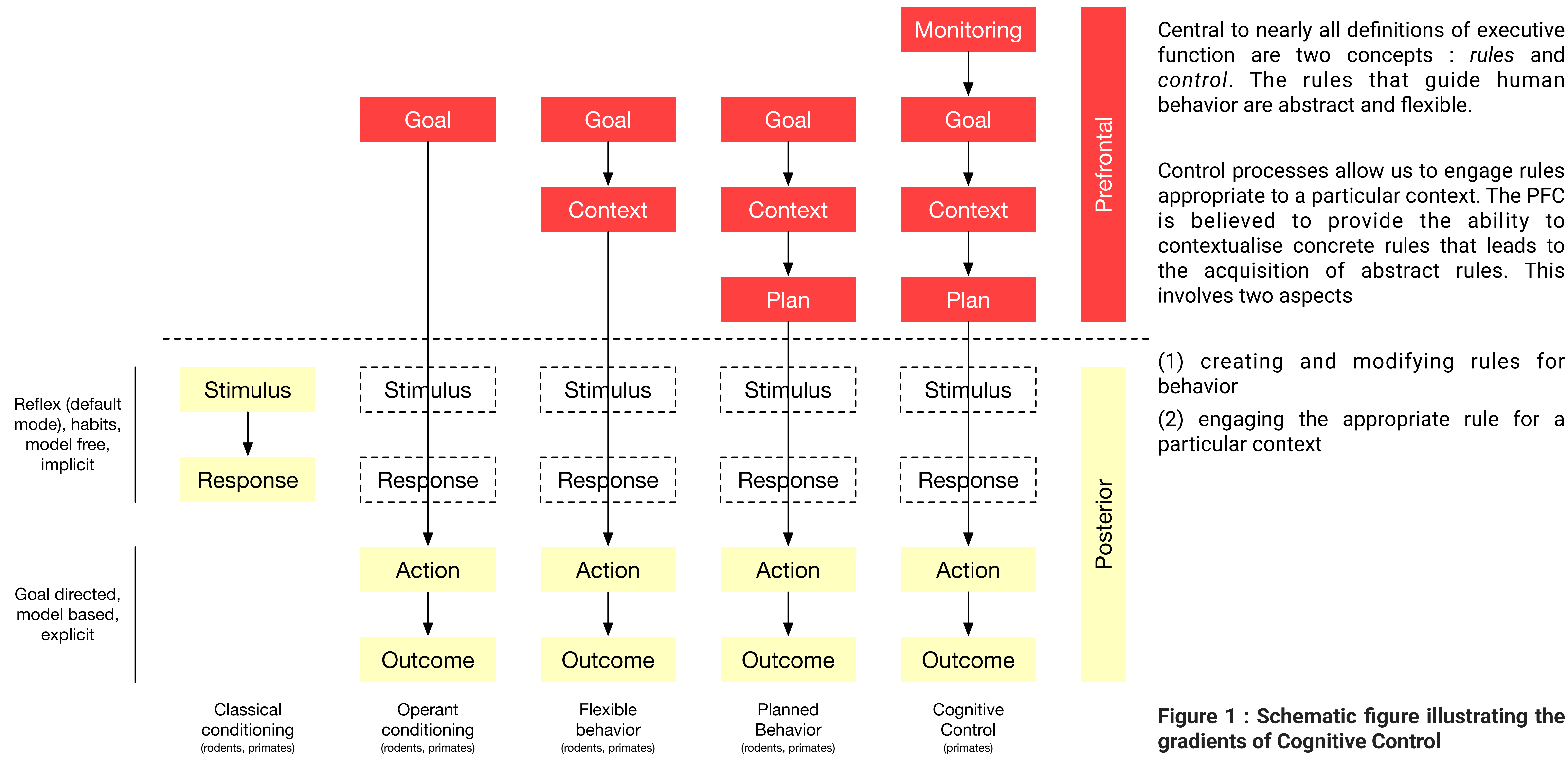


Computational models to explore constituents of Cognitive Control

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Introduction



Hierarchical model with Selective Attention

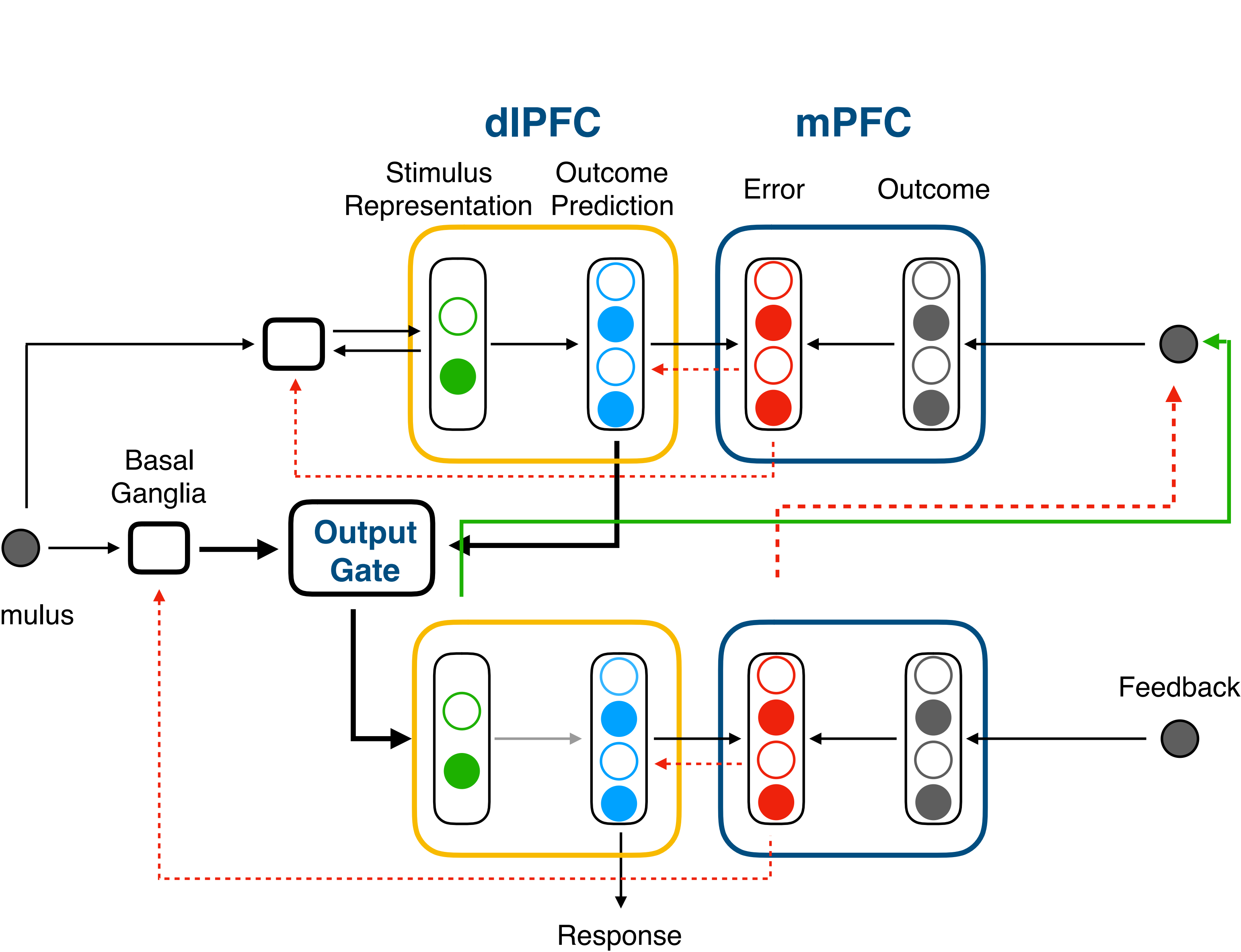


Figure 2 : A hierarchical model of the medial-lateral PFC interactions, with top-down control exerted through an output gate [1] [2]

The **mPFC** is responsible for the prediction and monitoring of errors. The error representations are used to refine predictions about likely outcomes

The **dIPFC** is responsible for the elaboration of contextual rules by learning to maintain representations of stimuli that reliably co-occur with outcome prediction errors.

Bottom up : Errors are broadcasted through the network, using proxy outcomes

Top-down : The output gate is used to select when and which representations should influence downstream processing

References

[1] Dagar, S., Alexandre, F., Rougier, N. (2022). "From Concrete to Abstract Rules: A Computational Sketch". *Brain Informatics. BI 2022*

[2] Alexander W. H. and Brown J. W. "Hierarchical error representation : a computational model of anterior cingulate and dorsolateral prefrontal cortex". *Neural Computation 2015*

[3] Chatham C. H., Frank M. J., Badre D. "Corticostriatal output gating during selection from working memory". *Neuron 2014*

Concrete to Abstract Rules

