



Roujin Mousavifard

Emails: rozhin.mf@gmail.com
rojin.mousavifard@ut.ac.ir
Cell: +989384696208

Personal Website: [My Website](#)
LinkedIn: [Roujin-Mousavifard](#)
Google Scholar: [My Scholar](#)

EDUCATION

University of Tehran (UT)

Tehran, Iran

M.Sc. in Mechatronics Engineering,

2020-2023

Cumulative GPA: 18.43/20 via 29 credits (Thesis included)

- **Thesis:** Control of Robots using a Novel Stochastic Model-Free Trajectory Tracking Controller for Position and a Deep Learning-Based Attitude Controller

Amirkabir University of Technology (Tehran Polytechnic)

Tehran, Iran

B.Sc. in Mechanical Engineering, Control

2015-2020

Cumulative GPA for the last two years: 17.54/20

- **Thesis:** Design and Fabrication of a Portable Vibration Simulator

National Organization of Development for Exceptional Talents (NODET)

Tehran, Iran

Farzanegan High School, High School Diploma in Mathematics and Physics,

2011-2015

High School Diploma Cumulative GPA: 19.60/20

RESEARCH INTERESTS

- Advanced Control Systems
- Autonomous Systems and Robotics
- Machine Learning and AI
- Optimal Control Theory
- Embedded Systems for Automation
- Industry 4.0 and IoT

PUBLICATIONS

- | | |
|---|------|
| Robot Trajectory Tracking using Combined Stochastic Model-Free Position and DDPG-based Attitude Control, ISA Transactions . | 2025 |
| Control of Robots Using Convex QP LMPC and Learning-Based Explicit-MPC, in IEEE Transactions on Industrial Informatics . | 2024 |
| Formation Control of Multi-robots Based on Deep Q-learning, 10th RSI International Conference on Robotics and Mechatronics (ICRoM) | 2022 |
| Formation Control of Multiple Robots Using LSTM-based Model Predictive Control, 10th RSI International Conference on Robotics and Mechatronics (ICRoM) | 2022 |
| Optimal control of self-balancing robot in the presence of uncertainties based on interval analysis, The 27th Annual International Conference of Iranian Society of Mechanical Engineers (ISME) | 2019 |

ACADEMIC EXPERIENCE

Research Assistant at Advanced Service Robots (ASR) Laboratory, Supervisor: Prof. Khalil Alipour, Prof. Bahram Tarvirdizadeh	2022 – Present (Part-time)
Teaching Assistant , Advanced Automatic Control (Graduate Course),	2022 (Spring, Fall)
Instructor , Mechatronics and Automation Laboratory	Spring 2020
Teaching Assistant , Mechatronics (Undergraduate Course)	Spring 2020
Teaching Assistant , Stress-Strain Laboratory, (Undergraduate Course)	2019

INDUSTRIAL EXPERIENCE

Elcarad Industry Company <i>Research and Development</i> Responsibilities: <ul style="list-style-type: none">Contributed to the design of automation and Industry 4.0 condition monitoring systems to meet customer needs.	Tehran, Iran 2022-present
Future Green Systems Company <i>Research and Development</i> Responsibilities: <ul style="list-style-type: none">Developed prototypes by integrating electronics, mechanics, and software technologies.	Tehran, Iran 2021-2022
HDL Company <i>Internship</i> Responsibilities: <ul style="list-style-type: none">Configured smart home modules to automate functionality.	Tehran, Iran Summer 2019
Parskhodro Company <i>Internship</i> Responsibilities: <ul style="list-style-type: none">Control the sealer used in Renault-L90 car industrial line.	Tehran, Iran Summer 2018

NOTABLE PROJECTS

Industrial Projects

Predictive Maintenance System Designed and fabricated a predictive maintenance system, integrating hardware and software, to monitor rotor vibrations, diagnose malfunctions, and predict failures for effective condition monitoring.	Elcarad Industry Company
Modular Tracker Device Designed and prototyped a modular tracker device with an accompanying app that integrates into various gadgets, enhancing capabilities like blood pressure and temperature monitoring for elderly care.	Elcarad Industry Company

RFID Reader and Tracking Module

Elcarad Industry Company

Developed and fabricated an RFID reader with tracking modules to improve the management of livestock, optimizing tracking and resource allocation.

Academic Projects**Robotic Arm for Multi-Tasking**

Advanced Robotics Course

Designed, built, and controlled a robotic arm for trajectory tracking, object following, and color detection, with applications in automation and industrial processes.

Quality Control System Using Deep Learning

Artificial Intelligence Course

Developed a quality control system utilizing deep learning and neural networks for image processing, specifically applied to detect defects in water bottles during production.

SOFTWARE AND PROGRAMMING SKILLS

Programming Languages: MATLAB & Simulink, Python, PyTorch, C, C++, Java

Robotics and Simulation: ROS, Pinocchio, Gazebo, MuJoCo, Simscape Multibody

Embedded Systems: PLC, Arduino, Raspberry Pi, ESP32

Mechanical Software: SOLIDWORKS, MSC ADAMS

Electronic Software: Altium Designer, Proteus Design Suite

Software Development: Android and Web Application Development, SQLite

HONORS & AWARDS

Ranked Top 3 among master of mechatronics engineering students at University of Tehran	2023
--	------

Full Tuition Waiver Scholarship awarded by Amirkabir University of Technology	2015-2020
---	-----------

Recipient of Exceptionally talented student Scholarship awarded as an Exceptionally Talented Student	2015
--	------

Ranked 508 th among more than 250,000 participants in the Nation-Wide University Entrance Exam	2015
---	------

LANGUAGE PROFICIENCY

- English: Level C1 (IELTS: 7.5/9)
- Deutch: Level A2