

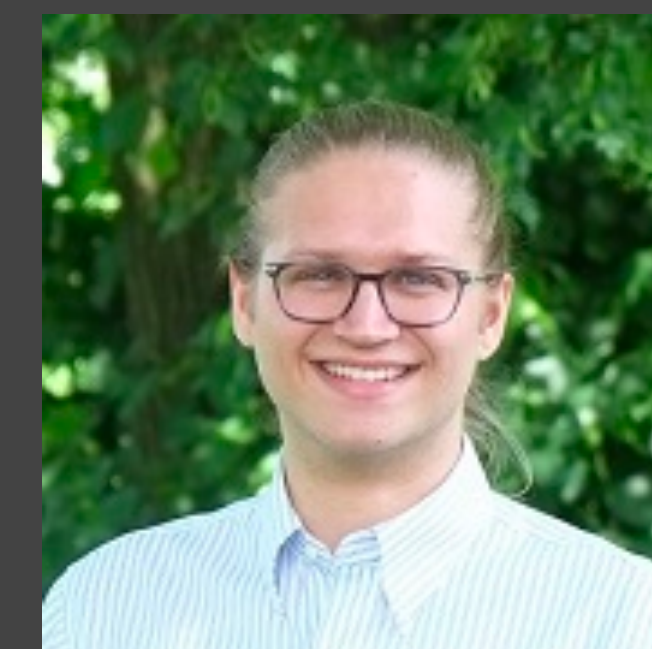
Online Covering

Secretaries, Prophets, and Universal Maps

FOCS 2021 + Forthcoming Work
Roie Levin



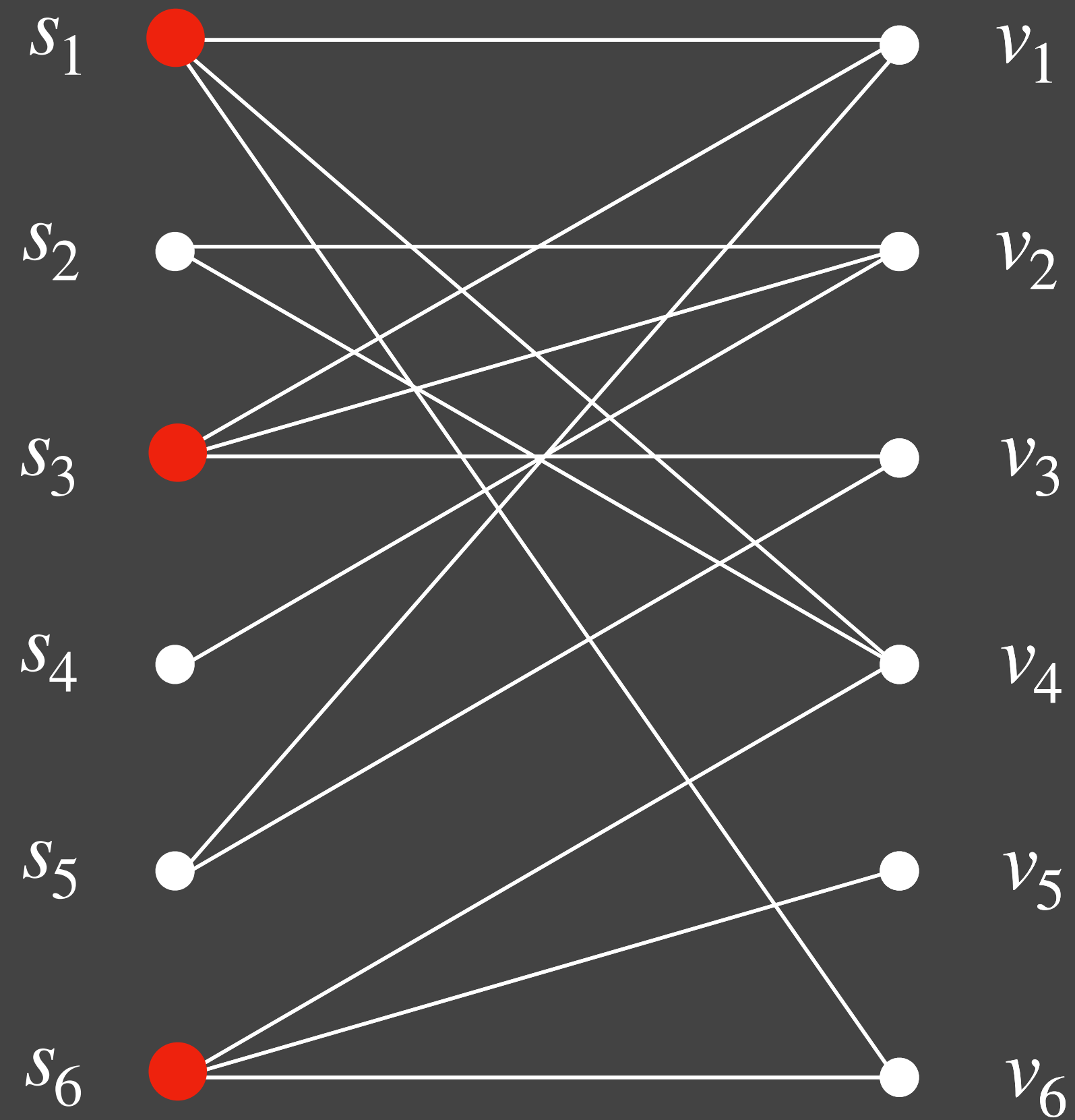
Anupam Gupta (CMU)



Gregory Kehne (Harvard)

Set Cover

\mathcal{S}
 m sets



Apx: $\log n + 1$
[Johnson 74],[Lovasz 75],
[Chvatal 79]

\mathcal{U}
 n elements

Online Set Cover

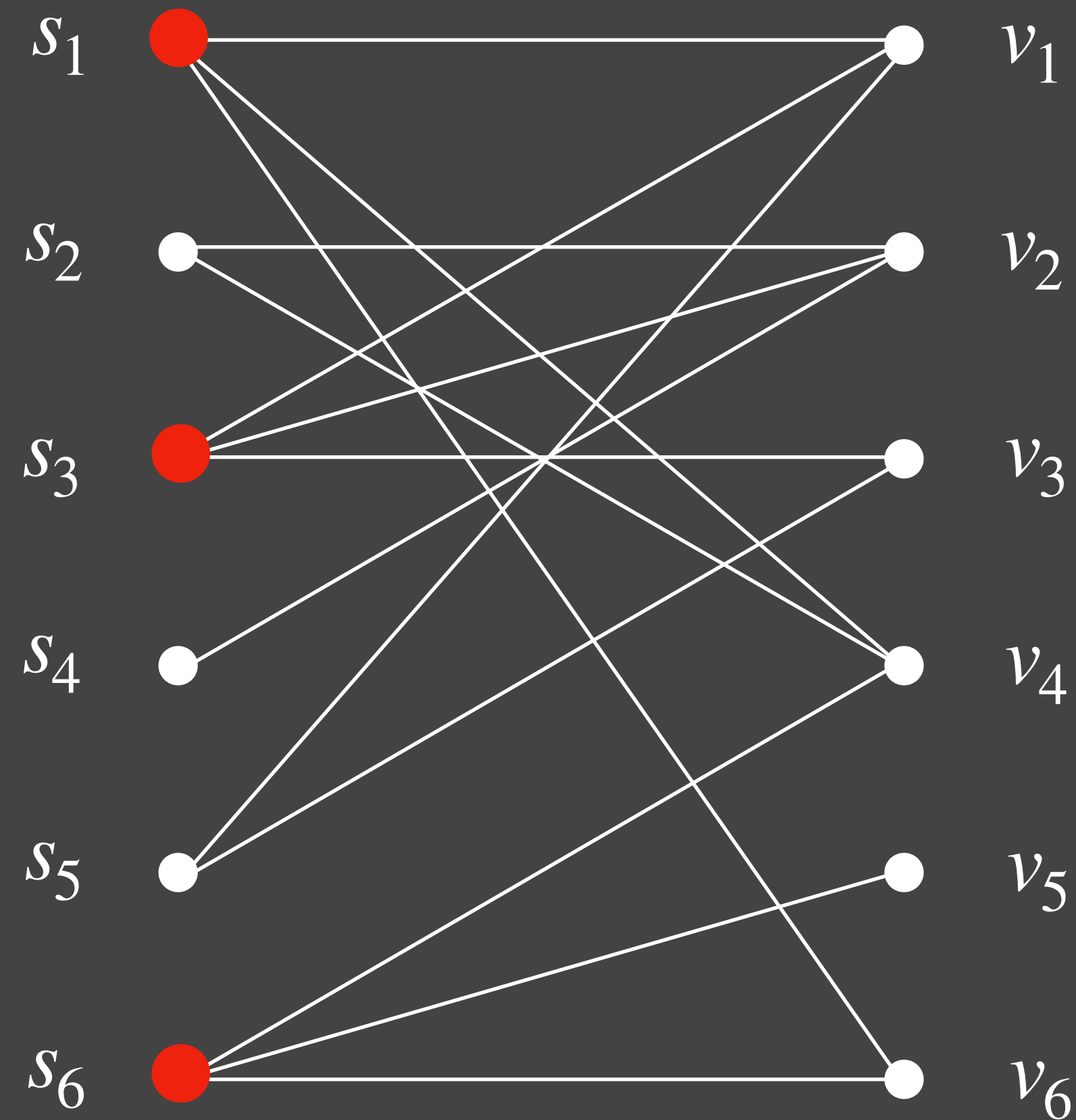
[Alon Awerbuch Azar Buchbinder Naor 03]

CR: $O(\log n \log m)$

[Alon+ 03]

[Buchbinder Naor 09]

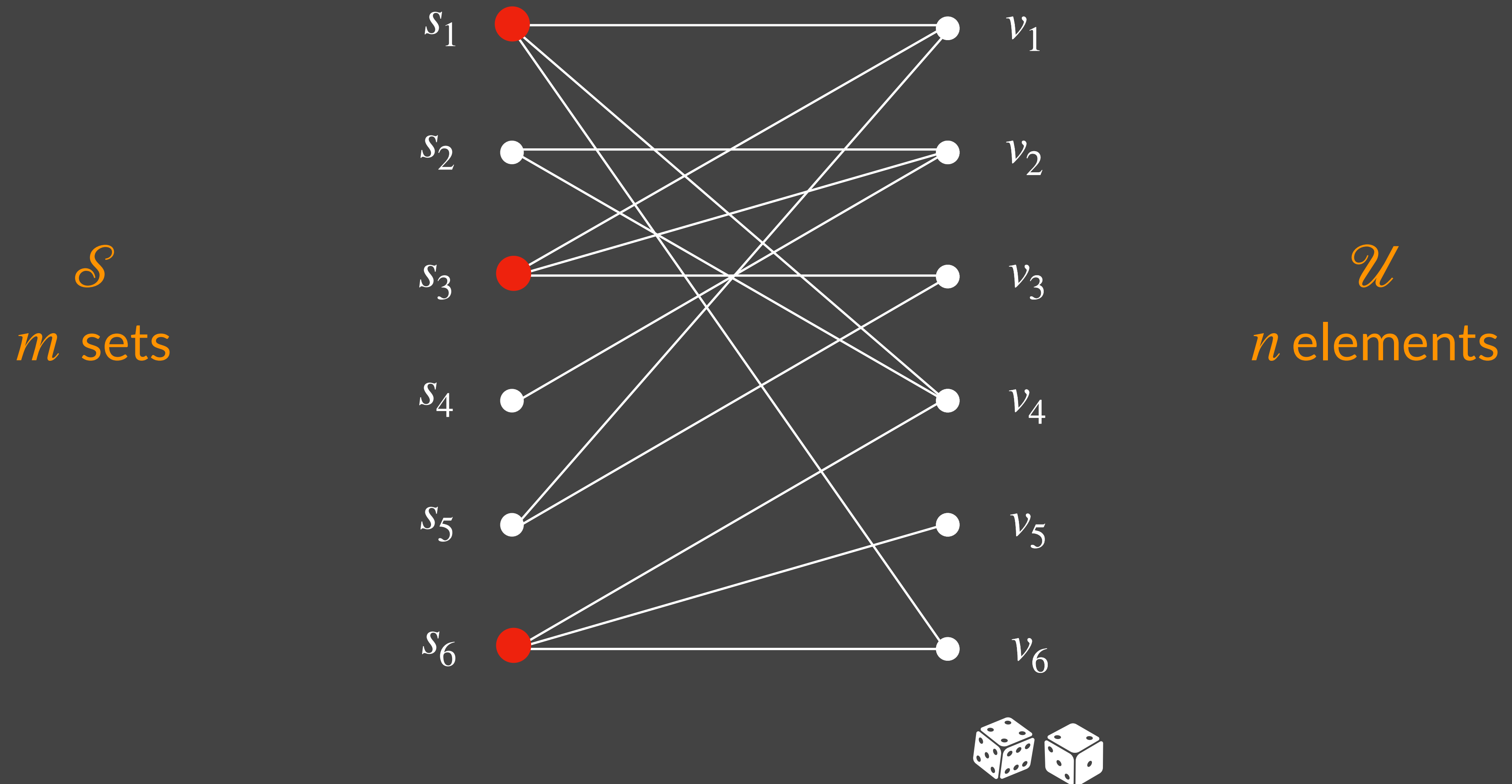
\mathcal{S}
 m sets



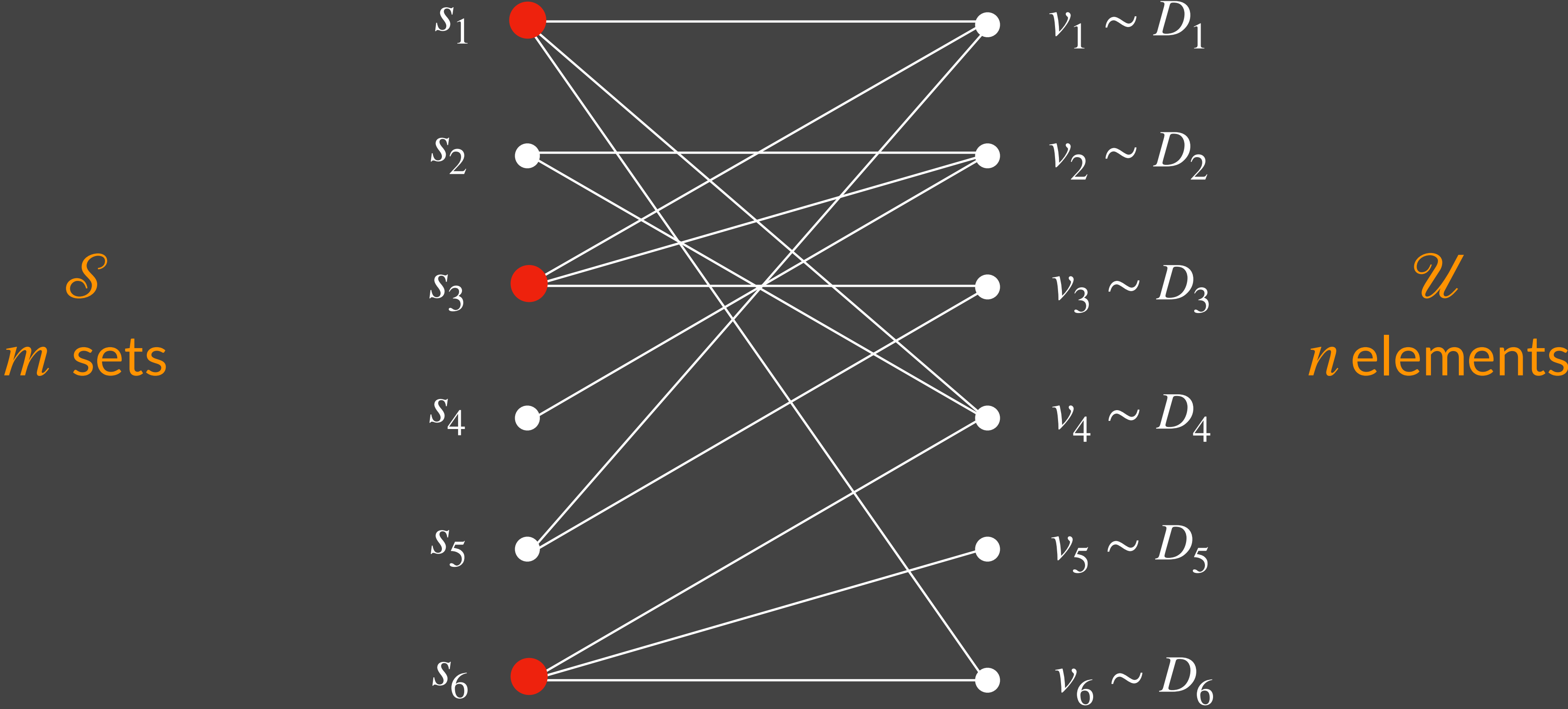
\mathcal{U}
 n elements

Q: What happens beyond the worst case?

Relaxation 1: Random Order (RO)



Relaxation 2: Random Instance



The Landscape

Instance

$m = \# \text{ sets}$

$n = \# \text{ elements}$

		Instance	
		Random	Adversarial
Arrival Order	Random	$O(\log(m [\text{support size}]))$ [Gupta Grandoni Leonardi Miettinen Sankowski Singh 08]	$O(\log mn)$ Our work <i>Secretary</i>
	Adversarial	$O(\log mn)$ Our work <i>Prophet</i>	$O(\log n \log m)$ [Alon+ 03] [Buchbinder Naor 09]

New!

Bonus Properties!

1. Only need single sample from each D_i !
2. Universal! Gives sample complexity bound $O(n)$.

Theorem [Gupta Kehne L. FOCS 21]:

There is a poly time algorithm for secretary Covering IPs with competitive ratio $O(\log mn)$.

Theorem [Gupta Kehne L. 22]:

There is a poly time algorithm for prophet Covering IPs with competitive ratio $O(\log mn)$.

Talk Outline

➔ Intro

➔ Secretary

LearnOrCover in Exponential Time

LearnOrCover in Poly Time

(Single Sample) Prophet

Conclusion & Extensions

Set Cover via Random Rounding

2 Stage algorithm!

(I) Solve LP.

$$\begin{aligned} \min \quad & \sum_S x_S \\ \forall v \in \mathcal{U} : \quad & \sum_{S \ni v} x_S \geq 1 \\ \forall S \in \mathcal{S} : \quad & x_S \geq 0 \end{aligned}$$

This is relaxation, so $c(x) \leq c(\text{OPT})$.

(II) Round.

Buy S with probability x_S .

Expected cost is $c(x)$!

Can show $\forall v \in \mathcal{U}$, covered with constant prob.

Repeat $O(\log n)$ times, union bound.

Expected Cost: $O(\log n) \cdot \text{OPT}$

How [Alon+ 03] works

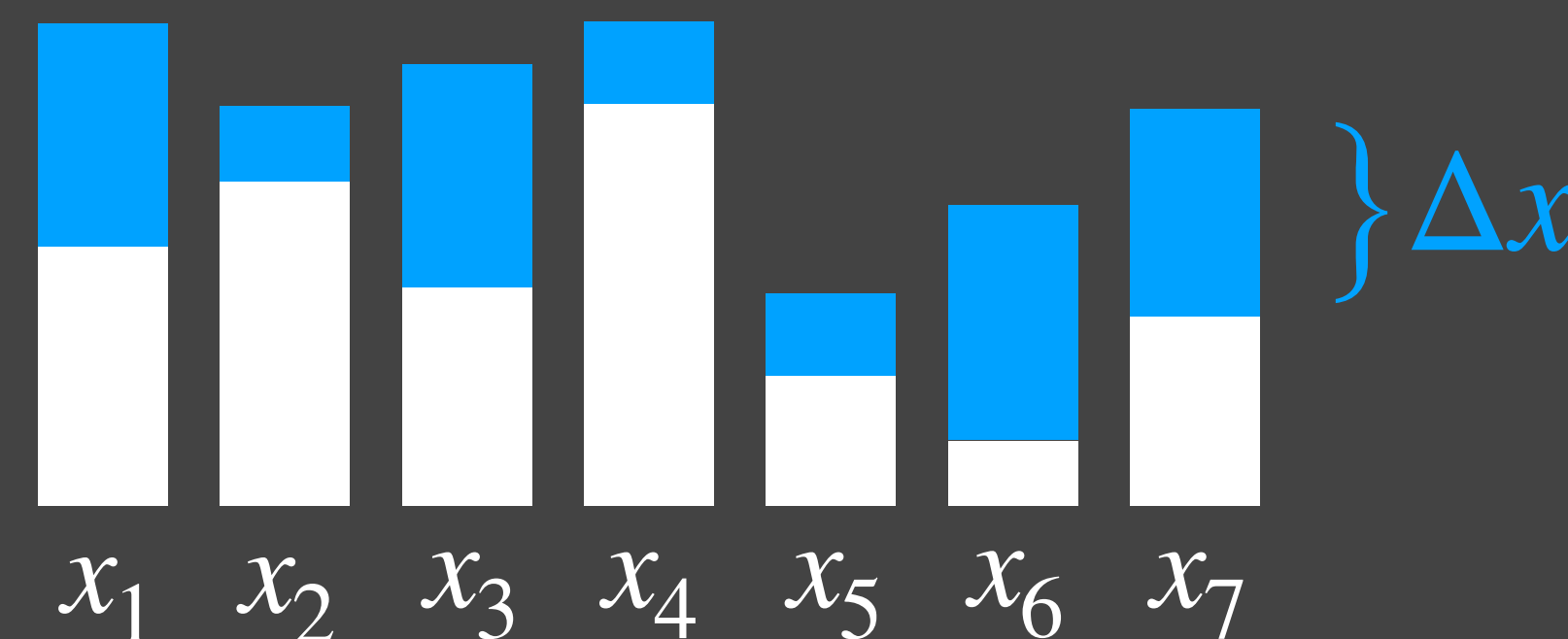
Same 2 Stages!

(I) Solve LP **Online**.

$$\begin{aligned} \min \quad & \sum_S x_S \\ \forall v \in \mathcal{U} : \quad & \sum_{S \ni v} x_S \geq 1 \\ \forall S \in \mathcal{S} : \quad & x_S \geq 0 \end{aligned}$$

Can guarantee x is $O(\log m)$ -apx, and only increases *monotonically*.

(II) Round **Online**.

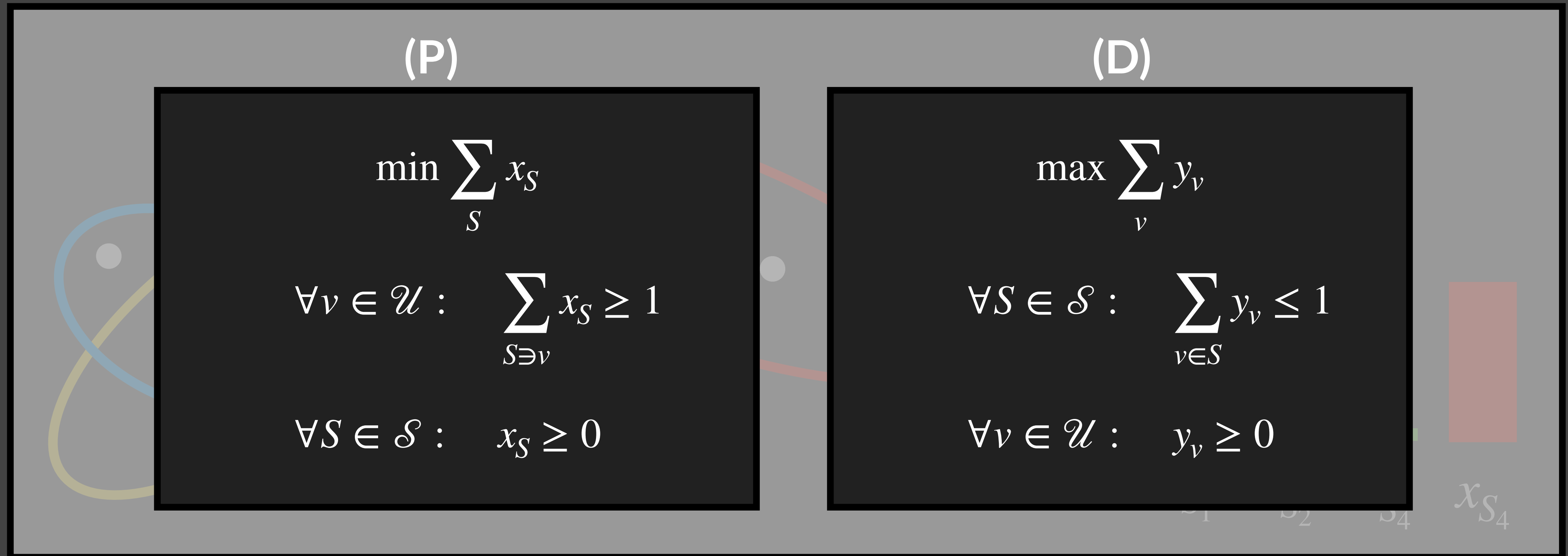


Take S
with prob.
 $\propto \Delta x_S$.

Suffices to analyze *offline* rounding.
Repeat $\log n$ times, union bound.

Expected Cost: $O(\log n \log m) \cdot \text{OPT}$

Online LP Solver of [Alon+ 03]



Init $x \leftarrow 1/m$.

While v (fractionally) uncovered:

- $\times 2$ to x_S for all $S \ni v$.
- $+1$ to y_v .

Claim 1: x feasible for (P).

Claim 2: $c(x) \leq c(y)$

Claim 3: $y/\log m$ feasible for (D).

Neither stage of [Alon+ 03] can be improved!

Independent rounding loses $\Omega(\log n)$.

Theorem [Gupta Kehne L.]: $\Omega(\log m)$ for fractional algos in RO.

Theorem [Gupta Kehne L.]: algo of [Alon+ 03] gets $\Omega(\log m \log n)$ in RO.

New algorithm needed!

We maintain coarse solution x , neither feasible nor monotone,
but round x anyway...

Talk Outline

Intro

➔ Secretary

➔ LearnOrCover in Exponential Time

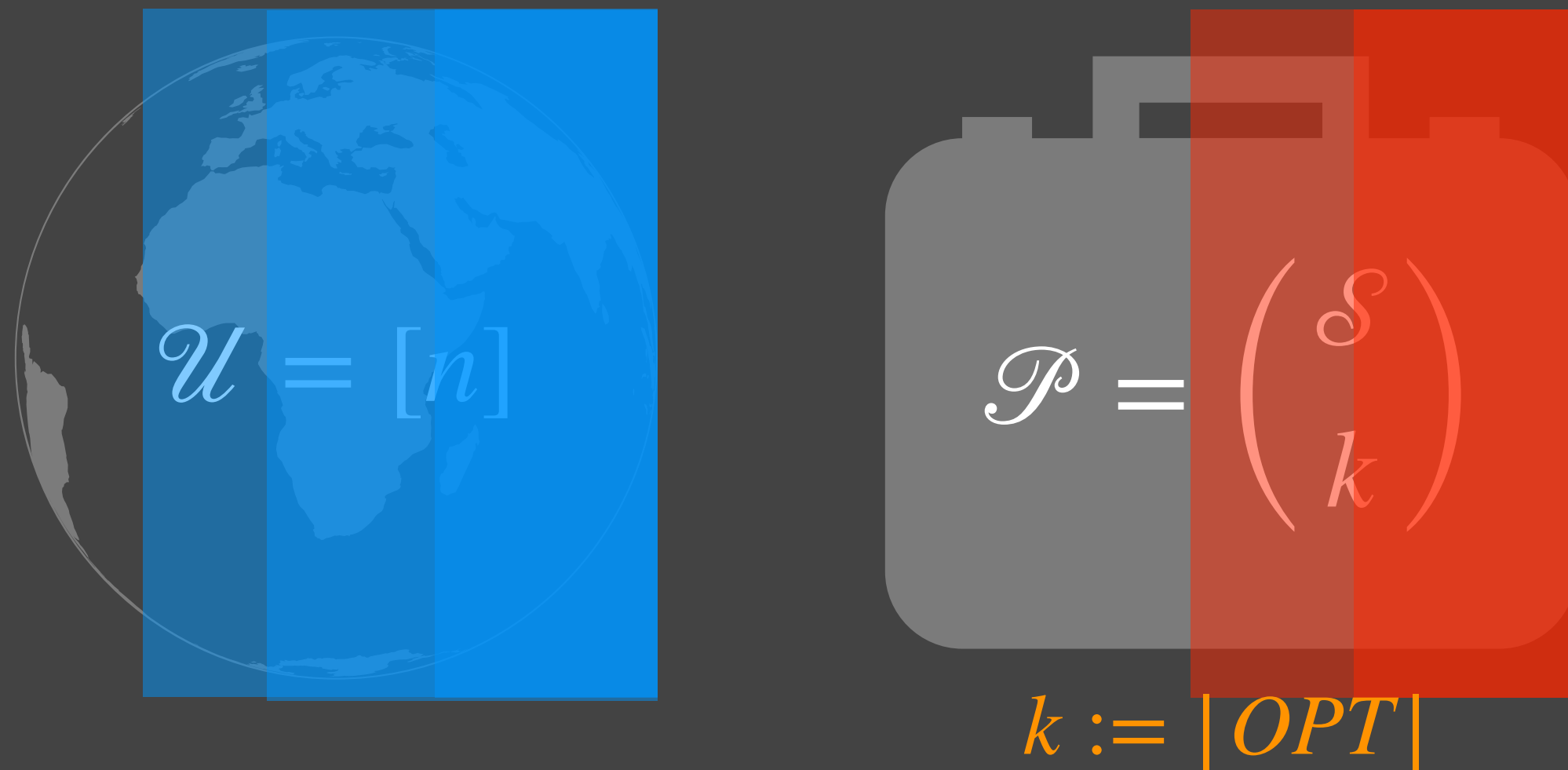
LearnOrCover in Poly Time

(Single Sample) Prophet

Conclusion & Extensions

LearnOrCover

(Unit cost, exp time warmup)



@ time t , element v arrives:

If v covered, do nothing.

Else:

(I) choose $T \sim \mathcal{P}$, buy random $R \sim T$.

(II) “Prune” $T \not\ni v$ from \mathcal{P} .

Buy arbitrary set to cover v .

Case 1: $\geq 1/2$ of $T \in \mathcal{P}$ cover $\geq 1/2$ of \mathcal{U} .

R covers $\frac{|\mathcal{U}|}{4k}$ in expectation.

\mathcal{U} shrinks by $\left(1 - \frac{1}{4k}\right)$ in expectation.

Case 2: $> 1/2$ of $T \in \mathcal{P}$ cover $< 1/2$ of \mathcal{U} .

$\geq 1/2$ of $T \in \mathcal{P}$ pruned w.p. $1/2$.

\mathcal{P} shrinks by $3/4$ in expectation.

RO Set Cover

(Exponential Time Warmup)

Case 1: (COVER)

\mathcal{U} shrinks by $\left(1 - \frac{1}{4k}\right)$ in expectation.

Case 2: (LEARN)

\mathcal{P} shrinks by 3/4 in expectation.

$|\mathcal{U}|$ initially n , $\Rightarrow O(k \log n)$ COVER steps suffice.

$|\mathcal{P}|$ initially $\binom{m}{k} \approx m^k$, $\Rightarrow O(k \log m)$ LEARN steps suffice.

$\Rightarrow O(k \log mn)$ steps suffice.

But how to make
polytime?

Can we reuse LEARN/
COVER intuition?

Talk Outline

Intro

Secretary

- ➔ LearnOrCover in Exponential Time
- ➔ LearnOrCover in Poly Time

(Single Sample) Prophet

Conclusion & Extensions

LearnOrCover

(Unit cost)

Init. $x \leftarrow 1/m$.

@ time t , element v arrives:

If v covered, do nothing.

Else:

(I) Buy random $R \sim x$.

(II) $\forall S \ni v$, set $x_S \leftarrow e \cdot x_S$.
Renormalize $x \leftarrow x/\|x\|_1$.

Buy arbitrary set to cover v .

Idea! Measure convergence with potential function:

$$\Phi(t) = c_1 \text{KL}(x^* || x^t) + c_2 \log |\mathcal{U}^t|$$

$\mathcal{U}^t :=$ uncovered elements @ time t

$x^* :=$ uniform distribution on OPT

Claim 1: $\Phi(0) = O(\log mn)$, and $\Phi(t) \geq 0$.

Claim 2: If v uncovered, then $E[\Delta\Phi] \leq -\frac{1}{k}$.

(Recall $k = |OPT|$)

Bound $E_R[\Delta \log |\mathcal{U}^t|]$ over randomness of R .

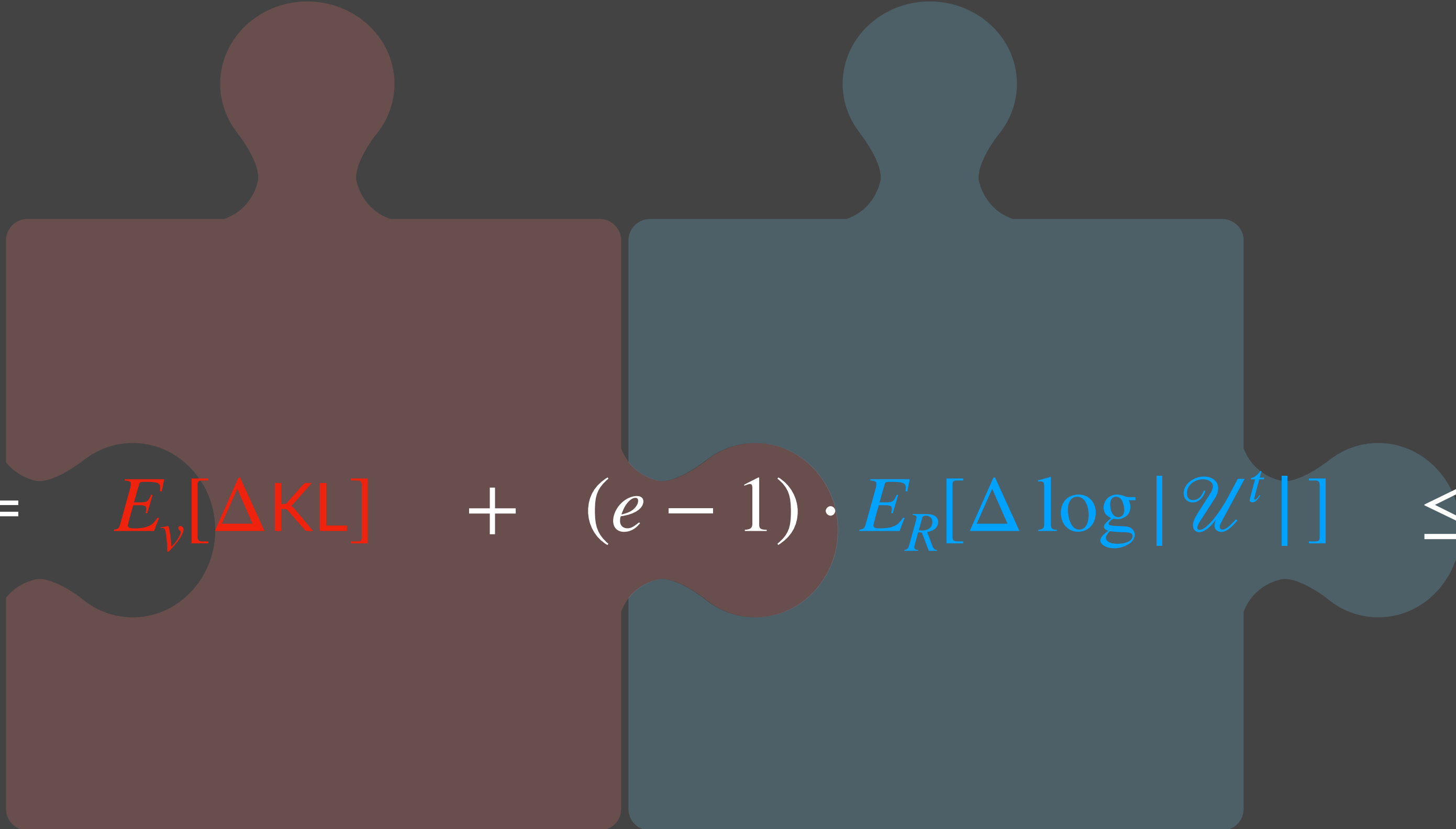
Bound $E_v[\Delta KL]$ over randomness of v . \longleftarrow This is where we use RO!

Claim 2a: If v^t uncovered,

$$E_v[\Delta \text{KL}] \leq (e - 1) \cdot E_v \left[\sum_{S \ni v} x_S \right] - \frac{1}{k}.$$

Claim 2b: If v^t uncovered,

$$E_R[\Delta \log |\mathcal{U}^t|] \leq - E_v \left[\sum_{S \ni v} x_S \right].$$


$$E[\Delta \Phi] = E_v[\Delta \text{KL}] + (e - 1) \cdot E_R[\Delta \log |\mathcal{U}^t|] \leq -\frac{1}{k}$$

Since $\Phi(0) = O(\log(mn))$, expected total cost is $k \log(mn)$.

Claim 2a: If v^t uncovered,

$$E_v[\Delta \text{KL}] \leq (e - 1) \cdot E_v \left[\sum_{S \ni v} x_S \right] - \frac{1}{k}.$$

Proof:

$$\begin{aligned} & \sum_S (x_S^* \log \left(\frac{x_S^*}{x_S^t} \right) - (x_S^* - x_S^t) \log \left(\frac{x_S^*}{x_S^{t-1}} \right)) \\ &= \sum_S x_S^* \log \left(\frac{x_S^{t-1}}{x_S^t} \right) \\ &= \sum_S \cancel{x_S^* \log \|x\|_1} - \sum_{S \ni v} \cancel{x_S^* \log e} \\ &= \log \left(\underbrace{\sum_S x_S^{t-1}}_{=1} + \sum_{S \ni v} (e - 1) \cdot x_S^{t-1} \right) - \underbrace{\sum_{S \ni v} x_S^*}_{\geq 1/k} \\ &\leq \log \left(1 + \sum_{S \ni v} (e - 1) \cdot x_S \right) - \frac{1}{k}. \end{aligned}$$

Use $\log(1 + z) \leq z$, take expectation over v , ■.

Claim 2b: If v^t uncovered,

$$E_R[\Delta \log |\mathcal{U}^t|] \leq - E_v \left[\sum_{S \ni v} x_S \right].$$

Proof:

$$\begin{aligned} & \log |\mathcal{U}^t| - \log |\mathcal{U}^{t-1}| \\ &= \log \left(1 - \frac{|\mathcal{U}^{t-1}| - |\mathcal{U}^t|}{|\mathcal{U}^{t-1}|} \right) \end{aligned}$$

Use $\log(1 - z) \leq -z$.

$$\leq - \frac{1}{|\mathcal{U}^{t-1}|} \sum_{v \in \mathcal{U}^{t-1}} \mathbb{1}\{R \ni v\}.$$

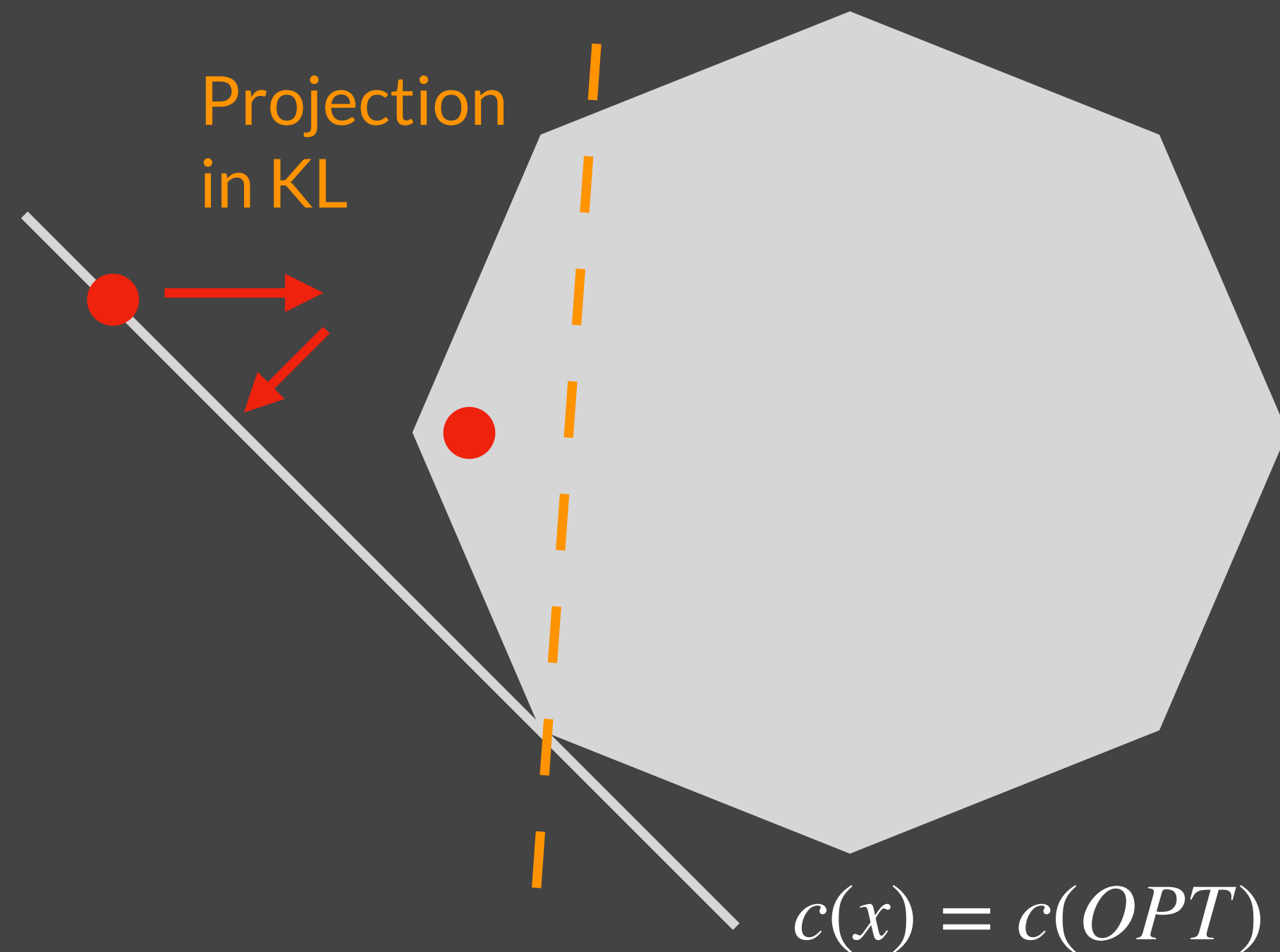
Take expectation over R .

$$\begin{aligned} E_R[\Delta \log |\mathcal{U}^t|] &\leq - \frac{1}{|\mathcal{U}^{t-1}|} \sum_R x_R \sum_{v \in \mathcal{U}^{t-1}} \mathbb{1}\{R \ni v\} \\ &= - \frac{1}{|\mathcal{U}^{t-1}|} \sum_{v \in \mathcal{U}^{t-1}} \sum_{R \ni v} x_R. \quad \blacksquare \end{aligned}$$

LearnOrCover

(Some philosophy)

Perspective 1:



Perspective 2:

Define

$$f(x) := \sum_v \max \left(0, 1 - \sum_{S \ni v} x_S \right)$$

(Goal is to minimize f in smallest # of steps)

$$\begin{aligned} \nabla f|_S(x) &= \# \text{ uncovered elements in } S \\ &\propto E[\mathbb{1}\{v \in S \mid v \text{ uncovered}\}] \end{aligned}$$

RO reveals stochastic gradient...

Talk Outline

Intro

Secretary

LearnOr**Cover** in Exponential Time

➡ **Learn**Or**Cover** in Poly Time

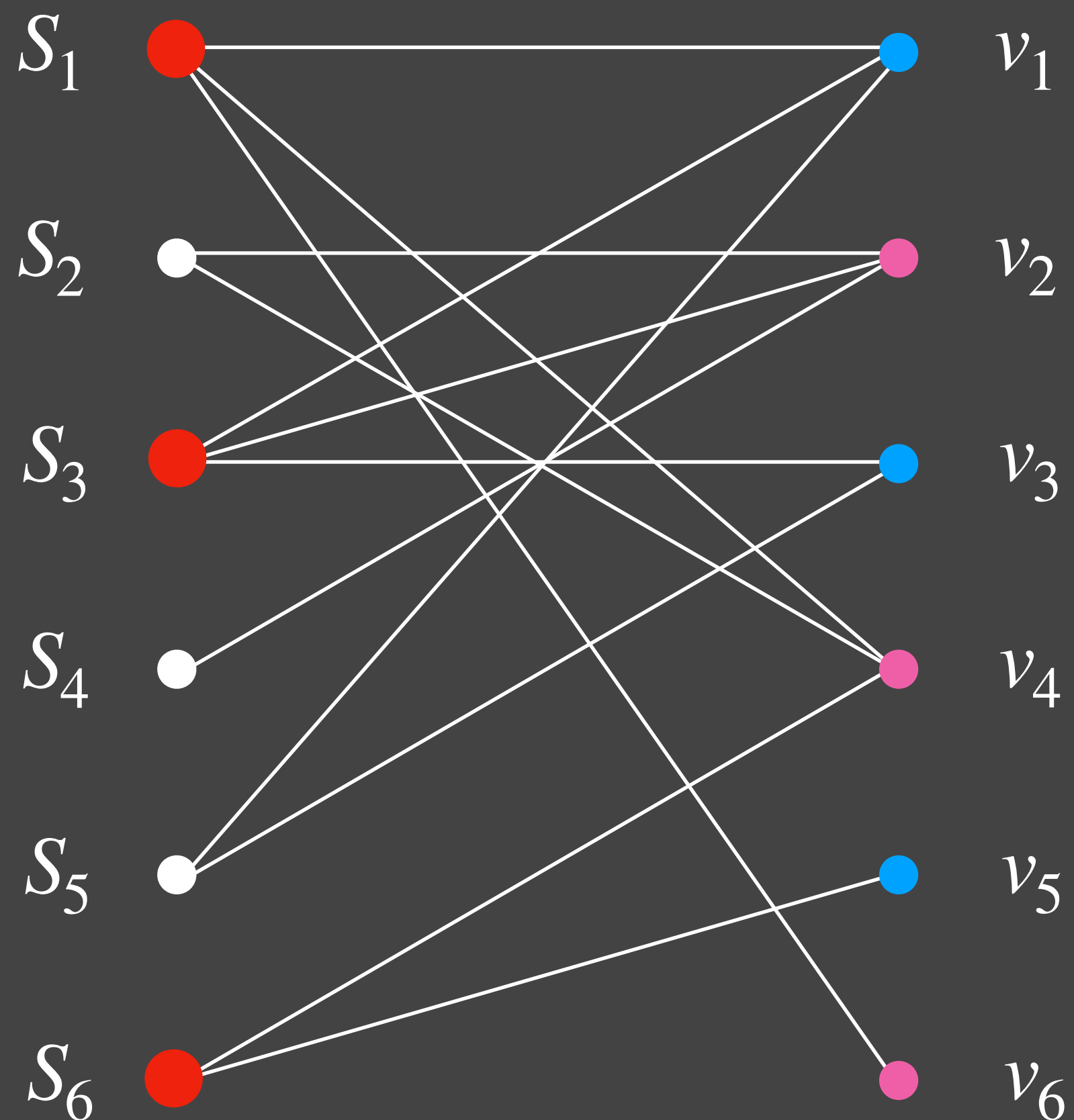
➡ (Single Sample) Prophet

Conclusion & Extensions

Special Case: the With-a-Sample model

Online set cover, but random 1/2 of elements known upfront (see [\[Kaplan Naori Raz 21\]](#)).

Remaining fraction revealed in adversarial order.



Theorem:

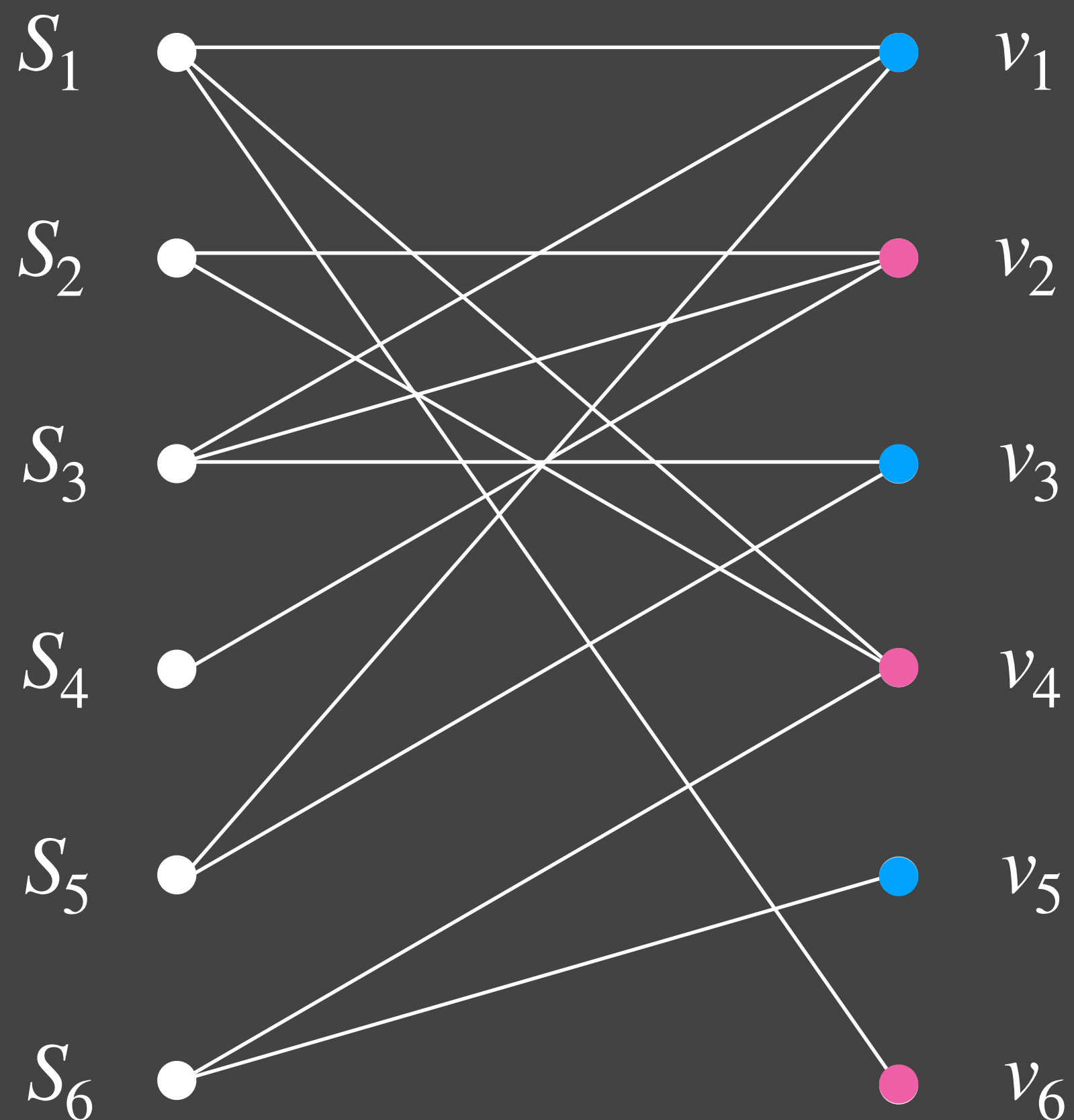
There is a poly time algorithm for Online Set Cover With-a-Sample with competitive ratio $O(\log(mn))$.

Reduction to LearnOrCover!

Idea:

1. Run LearnOrCover on samples.
2. Buy arbitrary sets for remaining elements.

Pretend colored pink (sampled)/blue (adversarial) on arrival.



@ time t :

If v^t pink, feed to LearnOrCover.

If v^t blue, buy arbitrary set to cover.

Recall LearnOrCover proof template:

Claim 1: $\Phi(0) = O(\log mn)$, and $\Phi(t) \geq 0$.

Claim 2: If v^t uncovered, then $E[\Delta\Phi] \leq -\Omega\left(\frac{1}{k}\right)$.

Φ only decreases during pink steps (so with prob. $1/2$),

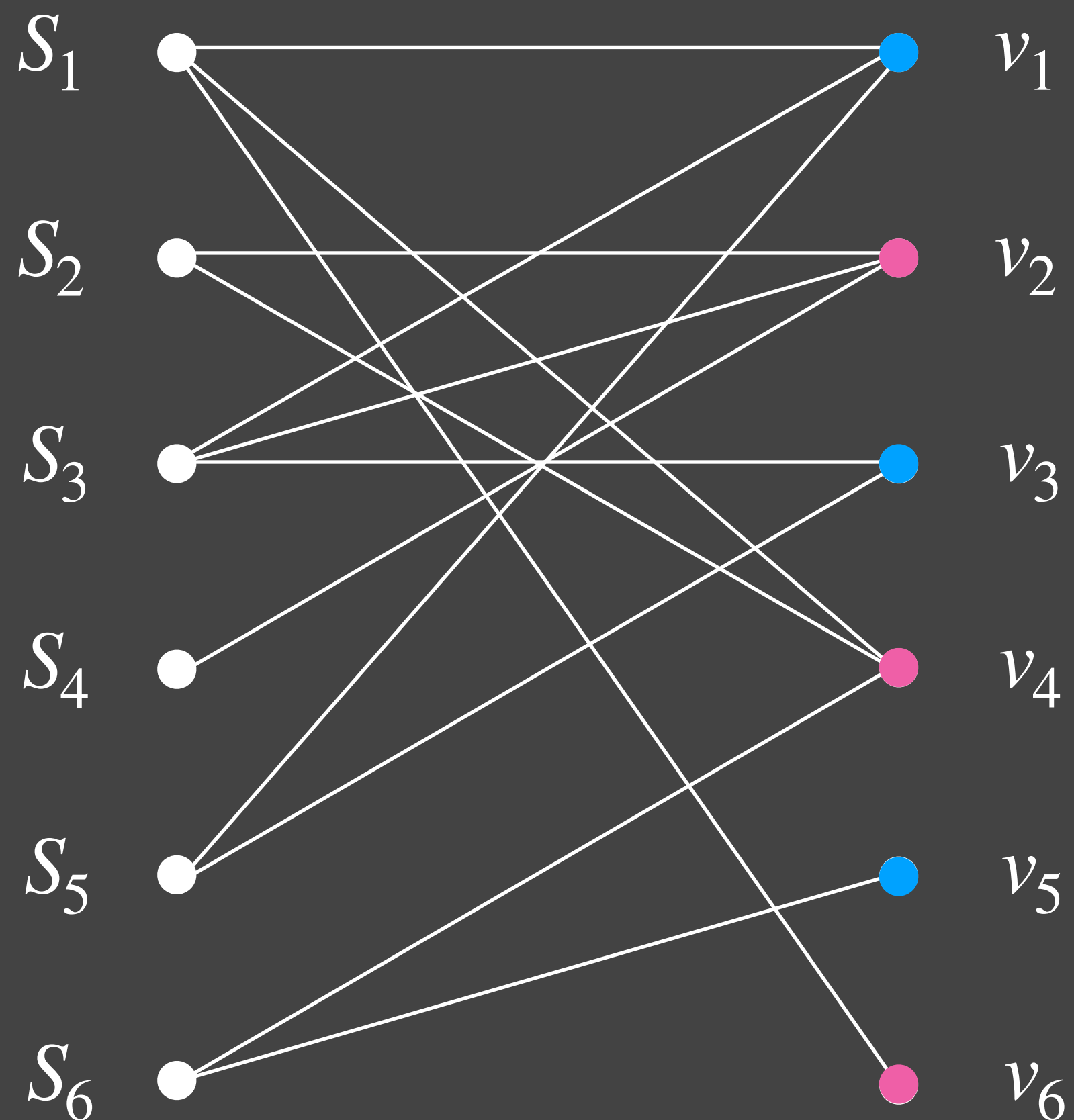
but still $E[\Delta\Phi] \leq -\Omega\left(\frac{1}{k}\right)$.



Universality

Idea: Reduction!

1. Run LearnOrCover on samples.
2. Buy arbitrary sets for remaining elements.



Can build map $f : \mathcal{U} \rightarrow \mathcal{S}$ before we see any actual elements.

When $u \in \mathcal{U}$ arrives, commit to buying $f(u)$!

Our result shows only need $O(n)$ samples to build this map.

Talk Outline

Intro

Secretary

LearnOr**Cover** in Exponential Time

LearnOr**Cover** in Poly Time

➡ (Single Sample) Prophet

➡ Conclusion & Extensions

Conclusion

Theorem: $O(\log mn)$ -comp. algo for RO Covering IPs.

Theorem: $O(\log mn)$ -comp. algo for Prophet Covering IPs.

Theorem: Same results for Non-metric facility location.

Theorem: $\Omega(\log m \log f(\mathcal{N}))$ for RO submodular cover.

+ Single-Sample!
+ Universal!

Open Questions:

Does the LearnOrCover idea lend itself to other problems?
Harder covering problems? Covering IPs w/ box constraints?
Unified theory? Reinterpret old RO results as LearnOrCover?

Thanks!

Backup Slides

Online Covering IPs

$$\min c^\top x$$

$$a_1^\top x \geq 1$$

$$a_2^\top x \geq 1$$

$$a_3^\top x \geq 1$$

$$a_4^\top x \geq 1$$

$$a_5^\top x \geq 1$$

$$x \in \mathbb{Z}_{\geq 0}^m$$

Goal: Maintain feasible solution x that is *monotonically* increasing.

Set Cover is the special case where constraint matrix A is 0/1.

LearnOrCover for non-unit costs

Main issue: # uncovered elements not good proxy for cost.

(Assuming WLOG $c(OPT) = 1$)

$\kappa_v :=$ cost of cheapest set covering v

Main Idea: tune learning & sampling rates as a function of κ_v .

LearnOrCover

Init. $x_S \leftarrow 1/(c_S \cdot m)$.

@ time t , element v arrives:

If v covered, do nothing.

Else:

(I) Buy every set R w.p. $\kappa_v x_R$.

(II) $\forall S \ni v$, set $x_S \leftarrow e^{\kappa_v/c_S} \cdot x_S$.

Renormalize $x \leftarrow x / \langle c, x \rangle$.

Buy **cheapest** set to cover v .

Claim 1: $\Phi(0) = c(OPT) \cdot O(\log mn)$,
and $\Phi(t) \geq 0$.

Claim 2: $E[\Delta\Phi] = -\Omega(\kappa_v)$.

Claim 3: $E[\Delta\text{cost}(\text{ALG})] = O(\kappa_v)$.

$\Rightarrow E[\Delta\Phi + \Delta\text{cost}(\text{ALG})] = 0$.

$E[\text{cost}(\text{ALG})] \leq \Phi(0)$.