

## Vectorisation example : Atomic decay via Spontaneous Emission

### Worked example : JC Hamiltonian

Recall :

$$H = \frac{\hbar\omega_1}{2} \hat{\sigma}_z + \hbar\omega_2 \left( a^\dagger a + \frac{1}{2} \right) + \hbar G (a \sigma_{eg} + a^\dagger \sigma_{ge})$$

$$|\psi(0)\rangle = |e, 0\rangle \rightarrow \rho(0) = |e, 0\rangle \langle e, 0|$$

At the beginning of the project, we worked out :

$$\hat{H} = \begin{matrix} & \begin{matrix} \langle g, n+1 | \\ \hbar \end{matrix} & \begin{matrix} \langle e, n | \\ G\sqrt{n+1} \end{matrix} \\ \begin{matrix} |g, n+1\rangle \\ |e, n\rangle \end{matrix} & \begin{bmatrix} \omega_2(n+\frac{3}{2}) - \frac{\omega_1}{2} & \\ \hbar G\sqrt{n+1} & \hbar\omega_2(n+\frac{1}{2}) + \frac{\omega_1}{2} \end{bmatrix} \end{matrix}$$

Simplifications :  $\omega_1 = \omega_2 = \omega$ ,  $n=0$  and  $\hbar=1$  :

$$\hat{H} = \begin{bmatrix} \omega & G \\ G & \omega \end{bmatrix}$$

For our jump superoperator,  $\hat{L}$ , we choose the spontaneous emission :

$$\hat{L} = \gamma |g\rangle \langle e| = \gamma |g\rangle \langle e| \otimes \mathbb{1}^\top$$

lastly, we say that :

$$|\dot{\rho}(t)\rangle\rangle = \hat{L} |\rho(t)\rangle\rangle \rightarrow \begin{bmatrix} \dot{\rho}_{g,g}(t) \\ \dot{\rho}_{g,e}(t) \\ \dot{\rho}_{e,g}(t) \\ \dot{\rho}_{e,e}(t) \end{bmatrix} = \begin{bmatrix} \hat{L} \end{bmatrix} \begin{bmatrix} \rho_{g,g}(t) \\ \rho_{g,e}(t) \\ \rho_{e,g}(t) \\ \rho_{e,e}(t) \end{bmatrix}$$

where :

$$\hat{L} = -i(\mathbb{1} \otimes H - H^\top \otimes \mathbb{1}) + \left[ (L^* \otimes L - \frac{1}{2}(\mathbb{1} \otimes L^\dagger L) - \frac{1}{2}(L^\dagger L)^\top \otimes \mathbb{1}) \right]$$

- So, we need to calculate the components of  $\tilde{L}$  in order to get a full matrix representation.

Calculation.

$$\cdot \mathbb{1} \otimes H = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \otimes \begin{pmatrix} \omega & \alpha \\ \alpha & \omega \end{pmatrix} = \begin{bmatrix} \omega & \alpha & 0 & 0 \\ \alpha & \omega & 0 & 0 \\ 0 & 0 & \omega & \alpha \\ 0 & 0 & \alpha & \omega \end{bmatrix}$$

$$\cdot H^T \otimes \mathbb{1} = \begin{pmatrix} \omega & \alpha \\ \alpha & \omega \end{pmatrix} \otimes \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{bmatrix} \omega & 0 & \alpha & 0 \\ 0 & \omega & 0 & \alpha \\ \alpha & 0 & \omega & 0 \\ 0 & \alpha & 0 & \omega \end{bmatrix}$$

$$\therefore -i(\mathbb{1} \otimes H - H^T \otimes \mathbb{1}) = -i \begin{bmatrix} 0 & \alpha & -\alpha & 0 \\ \alpha & 0 & 0 & -\alpha \\ -\alpha & 0 & 0 & \alpha \\ 0 & -\alpha & \alpha & 0 \end{bmatrix}$$

- For  $L$ , let's use matrix representation, being careful of basis.

$$L = \gamma \begin{bmatrix} \langle g| & \langle e| \\ 0 & 1 \end{bmatrix} \begin{matrix} |g\rangle \\ |e\rangle \end{matrix} \Rightarrow \text{note that, as shown previously, } L \text{ action on QTL subsystems is } \mathbb{1}.$$

$$L = \gamma \cdot \begin{bmatrix} \langle g, 1| & \langle e, 0| \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{matrix} |g, 1\rangle \\ |e, 0\rangle \end{matrix}$$

- Term by term calculation:

$$L^\dagger \otimes L = |\gamma|^2 \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\cdot \mathbb{1} \otimes L^\dagger L : L^\dagger L = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} |y|^2$$

$$\Rightarrow \mathbb{1} \otimes \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} |y|^2 = |y|^2 \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\cdot (L^\dagger L)^T \otimes \mathbb{1} = |y|^2 \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \otimes \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = |y|^2 \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

• Now, sum the jump-operator terms:

$$\hat{\mathcal{L}}_L = L^* \otimes L - \frac{1}{2} \mathbb{1} \otimes L^\dagger L - \frac{1}{2} (L^\dagger L)^T \otimes \mathbb{1}$$

$$= |y|^2 \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} - |y|^2 \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & \frac{1}{2} & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{2} \end{bmatrix} - |y|^2 \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{1}{2} & 0 \\ 0 & 0 & 0 & \frac{1}{2} \end{bmatrix}$$

$$= |y|^2 \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & -\frac{1}{2} & 0 & 0 \\ 0 & 0 & -\frac{1}{2} & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

• Finally add  $\hat{\mathcal{L}}_H + \hat{\mathcal{L}}_L = \hat{\mathcal{L}}$

$$\hat{\mathcal{L}} p \gg = \begin{bmatrix} 0 & -i\alpha & i\alpha & |y|^2 \\ -i\alpha & -\frac{1}{2}|y|^2 & 0 & i\alpha \\ i\alpha & 0 & -\frac{1}{2}|y|^2 & -i\alpha \\ 0 & i\alpha & -i\alpha & -|y|^2 \end{bmatrix} \begin{bmatrix} p_{g_1, g_1}(t) \\ p_{g_1, e_0}(t) \\ p_{e_0, g_1}(t) \\ p_{e_0, e_0}(t) \end{bmatrix} = \begin{bmatrix} \dot{p}_{g_1, g_1}(t) \\ \dot{p}_{g_1, e_0}(t) \\ \dot{p}_{e_0, g_1}(t) \\ \dot{p}_{e_0, e_0}(t) \end{bmatrix}$$

• We now have four differential equations to solve, with initial condition  $p(0) = |e, 0\rangle \langle e, 0|$ .