# Xuan Luo

# Curriculum Vitae

#### Education

2015-now Ph.D., Computer Science and Engineering, University of Washington, Seattle, WA, US.

Advised by Steven M. Seitz and Jason Lawrence in UW Reality Lab.

2011–2015 B.S., Computer Science and Technology, Shanghai Jiao Tong University (SJTU), China.

Program ACM Honored Class (a pilot computer science class in China), Zhiyuan College

9.2014-2.2015 **Visiting Scholar**, *National University of Singapore*, Singapore.

7.2014 Exchange Student, Cornell University, Ithaca, NY, US.

# Work Experience

2017 summer Research Intern, Disney Research, Zurich, Switzerland.

Worked on face performance capture with Thabo Beeler, Derek Bradley, Matthias Niessner and Paulo

Gotardo.

2016 summer Software Engineering Intern, Google Daydream, Seattle, WA, USA.

Worked with Jason Lawrence on utilizing spatial-temporal consistency to denoise 3D models.

#### Skills

Languages C++, Python, Matlab, Java, HTML, LATEX, MySQL, C#,PHP, Verilog, OpenGL, TinyOS

Tools Unity, Photoshop

### Research Interests

Augmented/Virtual Reality

Novel View Synthesis, Computational Display

**Computer Vision** Inpainting, Stereo Matching, Deep Learning, Face Performance Capture

**Graphics** 

#### Honors and Awards

2018 Pepper's Cone highlighted in "Demo Hour" of ACM Interactions Magazine link

2018 Press coverage for Pepper's Cone: Hacker News, iProgrammer, Hack a Day

2015 Distinguished Graduate Scholarship, SJTU

Top 1%

2015 **Shanghai Outstanding Graduate** Top 1%

2013 **National Scholarship, China** Highest scholarship in China, top 1%

2012 Kai Yuan Scholarship, SJTU Top 2%

#### **Publications**

**Xuan Luo**, Jason Lawrence, Steven M. Seitz. "Pepper's Cone: An Inexpensive Do-It-Yourself 3D Display". UIST, 2017.

Min Lin, Shuo Li, **Xuan Luo**. "Purine: A Graph-based Deep Learning Framework". International Conference on Learning Representations (ICLR), 2015.

Xuejiao Bai, **Xuan Luo**, Shuo Li. "Adaptive Stereo Matching via Loop-erased Random Walk". IEEE International Conference on Image Processing (ICIP), 2014.

# Research Experience

#### Novel View Synthesis

Advisor Steven M. Seitz, Jason Lawrence, Ricardo Martin Brualla, University of Washington & Google

2.2017-3.2019 **Visualizing History in 3D**.

Is it possible to see Mark Twain in 3D with full 6 degree-of-freedom? We collected a big dataset of historical stereographs called KeystoneDepth and enabled visualizing tons of historical scenes in 6 DoF.

Computational Display

Advisor Steven M. Seitz, Jason Lawrence, University of Washington, US

10.2015-4.2017 **Pepper's Cone**, UIST 2017, https://roxanneluo.github.io/PeppersCone.html.

Fold a piece of plastic sheet into a cone. Together with your tablet, you can build the Pepper's Cone to observe the "hologram" of your 3D scene in a fun and compelling way.

Stereo Matching

Advisor Hongtao Lu, Center for Brain-like Computing and Machine Intelligence, SJTU, China

8.2013-1.2014 Adaptive Stereo Matching via Loop-erased Random Walk, *ICIP* 2014, http://bcmi.sjtu.edu.cn/~luoxuan/papers/icip2014.pdf.

I proposed to use a random tree generated by Loop-erased Radom Walk (LERW) to replace traditional minimum spanning tree in non-local methods. LERW achieves better results especially over curved & slanted surfaces due to its more adaptive support windows (SW). I also provided a mathematical analysis to explain this strength of randomness, giving deeper understanding of SWs of the tree-based algorithms.

2.2014-8.2014 Fast Non-local Stereo Matching based on Hierarchical Disparity Prediction.

code: https://github.com/roxanneluo/Hierarchical-Disparity-Prediction

I proposed a new framework, DPA. Almost all tree-based algorithms can use DPA to improve speed and accuracy. For example, with DPA, the segment-tree-based algorithm is 6.25 times faster and 3.04% more accurate over Middlebury 2006 dataset.

# Deep Learning

Advisor Shuicheng Yan, Learning and Vision Research Group, National University of Singapore

8.2014-10.2014 **Purine**, ICLR 2015, https://github.com/purine/purine2.

Purine is a flexible graph-based parallel deep learning framework. It outperforms current widely-used deep learning frameworks in that its graph-based design allows any kind of parallelism, both data and model parallelism, arbitrary network structure (e.g., recurrent neural network), and can utilize unlimited number of CPUs and GPUs. And it's fast and easy-to-use. I contributed the multi-GPU & multi-machine data copy part, the key bottleneck for all parallel frameworks, testing codes and part of the network definition protocol. It will be released soon.

#### **Robotics**

Advisor Zhengping Feng, School of Naval Architecture, Ocean and Civil Engineering, SJTU, China

3.2012–3.2013 Development of Low Cost Test-bed for Autonomous Underwater Vehicle (AUV) Onboard Intelligence.

I led four other team members to build a toy submarine equipped with an embedded computer, a gyro, a barometer, etc., to autonomously drive itself. I learned the PID controller, designed and implemented a sliding mode control system, assembled the submarine and carried out a series of underwater experiments.

# Course Projects

Codes of some projects available at https://github.com/roxanneluo

2016.6	Become Brad Pitt, C++, Computer Vis	ion Facial Puppetry
2015.11	Environment Matting, C++&Python, G	raphics Composition of Refractive Objects
2014	Fatworm Database, Java Design	ed and implemented a database management system
2014	Freebase, PHP+MySQL Sma	ll web search engine built over the Freebase database
2014	Wireless Multi-hop Routing, TinyOS	For telecommunication of wireless sensors
2013-2014	Nachos Operating System, Java	Nachos Project from UC Berkeley CS162
2013	Modern Compiler Implementation, Java	Compiler for Simplified C Language
2013	Simulated CPU, Verilog	MIPS CPU design task from UC Berkeley CS152
2013	Galaxy Maze, OpenGL	Self-designed 3D Game.

# Specialty

 $Fine \ Arts \ \ Good \ at \ painting. \ My \ portfolio \ available \ at \ https://photos.app.goo.gl/QtGANBN2gAcajLza9$