

Subject: CSE-413, Computer Graphics

Total: 2.00 hours
Section B : 1.00 hour

Full Marks: 180
Section B : 90

INSTRUCTIONS:

- a. Use **SEPARATE** answer scripts for each section.
- b. **Question – 5 and Question – 8 (Viva Voce)** in **Section B** are compulsory.
- c. Answer any **OTHER ONE** question from this section (**From Q - 6 & Q - 7**).
- d. Figures in the margin indicate full **marks**.
- e. Assume reasonable data if necessary.
- f. **Symbols** used have their usual meanings.

SECTION-B

Question – 5 (Compulsory)

- a. Imagine a scenario: 16
 - camera is at $(2, 7, 3)$
 - The projection plane equation: $2x + 3y + 4z = 10$

Now generate the projection matrix for the projected point $P'(x', y', z')$ for any point $P(x, y, z)$.
- b. For a camera, the definition is: 10
 - i) Position of the camera at $(1, 1, 1)$
 - ii) Looking direction $(l) = -Y$ axis
up direction $(u) = -Z$ axis
right direction $(r) = X$ axis

Now, to align the camera as $l=Y$ axis, $u=Z$ axis and $r=X$ axis at $(0, 0, 0)$ point, calculate the transformation matrix.
- c. Using the projection of a polygon, is it possible to derive the equation of the plane in which the polygon lies? If yes, explain the procedure with proper example. 10

Question – 6

- a. To draw a set of overlapping polygons, it is required to prioritize the objects according to their depth from the view point. Using an appropriate depth sort algorithm: 6+10
 - i) How can you calculate the x-extent, y-extent and z-extent of a polygon?
 - ii) Briefly discuss how can you find the sequence of the overlapping polygons.
- b. Generate a Binary Space Partitioning Tree from the given set of polygons. 12

Note: You need to provide a short description for each step.
Use the polygon 3 as the starting point.
The arrows indicate the front side of the object.

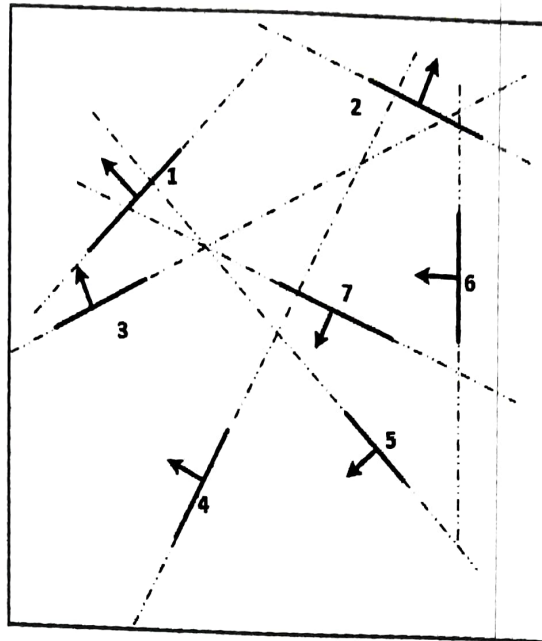


Figure for Question 6(b)

- c. An algorithm examines all n objects for each pixel and finds the closest one to draw. Now, explain the advantages and disadvantages of this kind of algorithms.

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Question – 7

- a. When ray tracing is performed, it is necessary to compute only whether a ray intersects an extent or not, not what actual points of intersection are. Consider each point (x, y, z) along the ray from $(3, 8, 10)$ to $(1, 1, 1)$ and a sphere with center at $(4, 5, 7)$ and radius 10. Derive the ray-sphere intersection equation using the quadratic formula and show how it can be simplified to determine only the ray and the sphere just intersect or not.
- b. i) Shortly describe the importance of geometric continuity and parametric continuity in case of joining two curves.
- ii) "First degree continuity in the parameter of t implies first degree of geometric continuity and vice versa"- what do you think about the statement? Justify your answer with appropriate examples.
- c. How can you differentiate between optimizing and avoiding intersection calculations (for a ray and an object) as efficiency considerations for ray tracing?

12

6+12

6

Question – 8 Viva Voce (Compulsory)

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