

Picard's Method for D.E.'s

The method of successive approximations uses the equivalent integral equation for (1) and an iterative method for constructing approximations to the solution. This is a traditional way to prove (1) and appears in most all differential equations textbooks. It is attributed to the French mathematician Charles Emile Picard (1856-1941).

Theorem 2 (Successive Approximations - Picard Iteration). The solution to the I.V.P in (1) is found by constructing recursively a sequence $\{Y_n(x)\}_{n=0}^{\infty}$ of functions

$$Y_0(x) = Y_0, \text{ and}$$

(2)

$$Y_{n+1}(x) = Y_0 + \int_{x_0}^x f(t, Y_n(t)) dt \text{ for } n \geq 0.$$

Then the solution $y(x)$ to (1) is given by the limit:

$$(3) \quad y(x) = \lim_{n \rightarrow \infty} Y_n(x).$$

Proof.

Begin by reformulating (1) as an equivalent integral equation. Integration of both sides of (1) yields

$$(4) \quad \int_{x_0}^x y'(t) dt = \int_{x_0}^x f(t, y(t)) dt.$$

Applying the Fundamental Theorem of Calculus to the left side of (4) yields

$\int_{x_0}^x y'(t) dt = y(x) - y(x_0) = y(x) - Y_0$ and we have $y(x) - Y_0 = \int_{x_0}^x f(t, y(t)) dt$, which can be rearranged to obtain

$$(5) \quad y(x) = Y_0 + \int_{x_0}^x f(t, y(t)) dt$$

Observe that $y(x)$ occurs on both the left and right hand sides of equation (5). We can use this formula and input $y(t)$ in the integrand $f(t, y(t))$ on the right and then output the next iteration for $y(x)$ on the left side. This is a type of fixed point iteration, the most familiar form of which is Newton's method for root finding.

Start the iteration with the initial function

$$Y_0(t) = Y_0, \quad \checkmark$$

then define the next function $Y_1(x)$ as follows

$$\checkmark Y_1(x) = Y_0 + \int_{x_0}^x f(t, Y_0(t)) dt.$$

Next $Y_1(x)$ is used to construct $Y_2(x)$ as follows

$$Y_1(x) = Y_0 + \int_{x_0}^x f(t, Y_1(t)) dt.$$

The process is repeated, and once $Y_n(t)$ has been obtained, the next function is given recursively by

$$(6) \quad Y_{n+1}(x) = Y_0 + \int_{x_0}^x f(t, Y_n(t)) dt.$$

We must take the limit as $n \rightarrow \infty$ in (6). Assume that the limit (3) exists, then $\lim_{n \rightarrow \infty} Y_{n+1}(x) = Y(x)$ and we write

$$Y(x) = \lim_{n \rightarrow \infty} Y_{n+1}(x) = \lim_{n \rightarrow \infty} \left(Y_0 + \int_{x_0}^x f(t, Y_n(t)) dt \right)$$

If there is "no problem" when taking limits on the right side then we might expect the following

$$Y(x) = \lim_{n \rightarrow \infty} \left(Y_0 + \int_{x_0}^x f(t, Y_n(t)) dt \right)$$

$$Y(x) = Y_0 + \lim_{n \rightarrow \infty} \int_{x_0}^x f(t, Y_n(t)) dt$$

$$Y(x) = Y_0 + \int_{x_0}^x \lim_{n \rightarrow \infty} f(t, Y_n(t)) dt$$

$$Y(x) = Y_0 + \int_{x_0}^x f(t, \lim_{n \rightarrow \infty} Y_n(t)) dt$$

$$Y(x) = Y_0 + \int_{x_0}^x f(t, Y(t)) dt$$

This is the "intuitive proof" of equation (5).

Q.E.D.

For More Proof. More details for the existence and uniqueness of $Y(x)$ can be found in textbooks and the literature.

1. Stephen W. Goode, [Differential Equations and Linear Algebra](#), 3rd edition, Prentice Hall, Upper Saddle River, NJ, 2005, Appendix 4.
2. R. Kent Nagle; Edward B. Saff; and Arthur David Snider, [Fundamentals of Differential Equations and Boundary Value Problems](#), 4th edition, Addison-Wesley, Boston, MA, 2004, Chapter 13, Sections 1 and 2.
3. C. Henry Edwards; and David E. Penney, [Differential Equations and Boundary Value Problems: Computing and Modeling](#), 3rd edition, Prentice Hall, Upper Saddle River, NJ, 2005, Appendix A.1.
4. William E. Boyce; and Richard C. DiPrima, [Elementary Differential Equations and Boundary Value Problems](#), 7th Edition, John Wiley and Sons, New York, NY, 2002, Chapter 2, Section 8.
5. Garrett Birkhoff; and Gian-Carlo Rota, [Ordinary Differential Equations](#), 4rd Ed., John Wiley and Sons, New York, NY, 1989, Chapter 1, p. 23.
6. Einar Hille, [Lectures on Ordinary Differential Equations](#), Addison-Wesley Pub. Co., Reading, MA, 1969, pp. 32-41.
7. Arthur Wouk, [On the Cauchy-Picard Method](#), The American Mathematical Monthly, Vol. 70, No. 2. (Feb., 1963), pp. 158-162, Jstor.



Picard Iterative Process

Indeed, often it is very hard to solve differential equations, but we do have a numerical process that can approximate the solution. This process is known as the **Picard iterative process**.

First, consider the IVP

$$\frac{dy}{dx} = f(x, y), \quad y(x_0) = y_0.$$

It is not hard to see that the solution to this problem is also given as a solution to (called the integral associated equation)

$$y(x) = y_0 + \int_{x_0}^x f(t, y(t)) dt.$$

The Picard iterative process consists of constructing a sequence (y_n) of functions which will get closer and closer to the desired solution.

This is how the process works:

(1) $y_0(x) = y_0$ for every x ;

(2) then the recurrent formula holds

$$y_{n+1}(x) = y_0 + \int_{x_0}^x f(t, y_n(t)) dt,$$

for $n \geq 1$.

Example: Find the approximated sequence (y_n) , for the IVP

$$y' = 2x(1 + y) \quad y(0) = 0.$$

Solution: First let us write the associated integral equation

$$y(x) = \int_0^x 2s(1 + y(s)) ds.$$

Set $y_0(x) = 0$. Then for any $n \geq 1$, we have the recurrent formula

$$y_{n+1}(x) = \int_0^x 2s(1 + y_n(s)) ds.$$

We have $y_1(x) = \int_0^x 2s ds = x^2$, and

$$y_2 = \int_0^x 2s(1 + s^2) ds = x^2 + \frac{x^4}{2}.$$

We leave it to the reader to show that

$$y_n(x) = x^2 + \frac{x^4}{2} + \frac{x^6}{3!} + \dots + \frac{x^{2n}}{n!}.$$

We recognize the Taylor polynomials of (which also get closer and closer to) the function