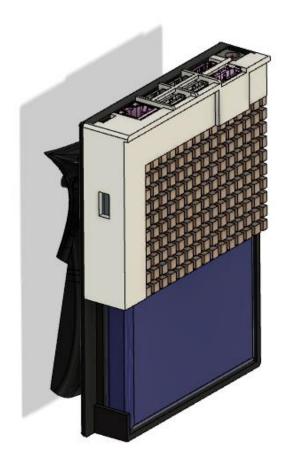
Robotics Practical

Nano-backpack designed for humanoid NAO robot



Slide 1 11.12.2020 Barth, Wagner

Mechanical design



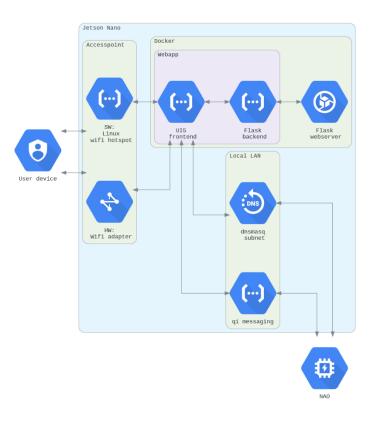
- Battery cover integrated in printed backpack
- Access to all Nano connectors
- Improved heat sink

Nano



- Modern Linux environment
- Overcome NAO hardware limitations
- Onboard power supply in the backpack
- GPU for greater possibilities in computer vision

System architecture



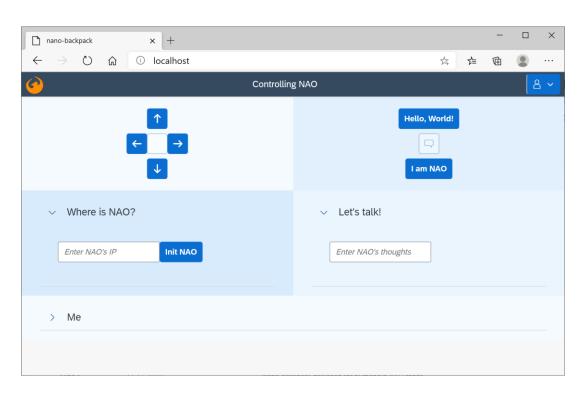
- Access Nano remotely
- Docker container runs web app

Docker

```
PS C:\Users\alexb\Documents\GitHub\nano-backpack\src\app> docker build -t "nano-backpack" .
[+] Building 3.4s (9/9) FINISHED
PS C:\Users\alexb\Documents\GitHub\nano-backpack\src\app> docker run --rm -it -p 80:80 nano-backpack
* Serving Flask app "app" (lazy loading)
* Environment: production
  Use a production WSGI server instead.
* Debug mode: on
* Running on http://0.0.0.0:80/ (Press CTRL+C to quit)
* Restarting with stat
* Debugger is active!
* Debugger PIN: 306-270-198
```

• Caching \rightarrow build in few seconds, no internet access required

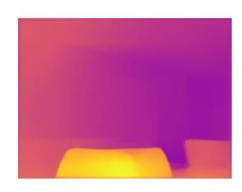
Webapp



- UI5 front-end (JS)
- Flask back-end (Python)
- See video

Depth estimation in video stream





- Custom dataclass to handle video input
- Can later be combined with ALVideoDevice of the NAOqi-API

Benefits

- 1. Overcome previous hardware limitations
- 2. Easy start with step-by-step instructions
- 3. Reuse, modify, extend webapp and Docker image
- 4. State-of-the-art development environment
- 5. Ready-to-use depth estimation in video stream