

Problems 1 through 6 are worth 10 points each. Problem 7 is worth 15 points for a total of 75. *All work must be shown for full credit.* Please begin each problem on a new page and label what problem you are working on. No outside resources are permitted.

1

Consider the following MATLAB code. You may assume that **a** and **b** are positive integers.

```
%beginning of function
function out = mystery(a,b)
    if a < b %want a to be greater than or equal to b
        temp = b; b = a; a = temp;
    end
    while mod(a,b) != 0 %run until a is divisible by b
        temp = b;
        b = mod(a,temp);
        a = temp;
    end
    out = b;
end
%end of function
```

a) One of the lines above has a syntax error that will not allow the function to be run. Identify the error and briefly explain how to correct it.

b) If $c = \text{mystery}(32,12)$, what is the value of c ? Explain how you came to your answer.

2

a) Using the composite trapezoid rule, numerically estimate the integral

$$\int_0^4 (x-1)^2 dx$$

using uniformly spaced nodes at each integer in the domain of integration.

b) Compute the error from using the scheme in part a. Then, give two *different* ways to more accurately estimate this integral numerically.

3

a) Define what is meant by *cubic spline* and, for these, *natural* and *not-a-knot* conditions.

b) Determine the parameters a , b , c , d , and e so that the following function $s(x)$ is a *natural* cubic spline on the interval $[0, 2]$ with knots at $x = 0, 1$, and 2 .

$$s(x) = \begin{cases} a + b(x-1) + c(x-1)^2 + d(x-1)^3 & 0 \leq x \leq 1 \\ (x-1)^3 + ex^2 - 1 & 1 \leq x \leq 2 \end{cases}$$

—Exam continued on back—

4

Suppose $c > 0$ and we want to numerically approximate the square root of c using Newton's method. In other words, we wish to numerically find the (positive) root of $f(x) = x^2 - c$ using the scheme:

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

a) Prove that the error $e_n = x_n - \sqrt{c}$ satisfies the recurrence relation

$$e_{n+1} = \frac{1}{2} \frac{e_n^2}{e_n + \sqrt{c}}$$

b) Using the relation from part a, determine the order of convergence assuming the initial guess is sufficiently close to the root.

5

a) Write a MATLAB function `lagbasis(nodes,j,x)` that has inputs

- a nonempty vector of x -coordinates `nodes` (representing interpolation nodes)
- a positive integer `j` less than or equal to `length(nodes)` (representing an index for the above vector)
- a real number `x` that is not necessarily an element of `node`

and returns the value of the j th *Lagrange basis function* evaluated at x , i.e. calculates $\ell_j(x)$.

b) Write MATLAB code that would make a plot that contains a curve representing the Lagrange polynomial interpolating the points $(-1,1)$, $(0,0)$, and $(2,4)$. You may call your function from the previous part. **Bonus:** add code to label the axes of the plot (any name you want) and make the Lagrange polynomial curve red.

6

a) Derive the fourth order accurate centered difference approximation for the first derivative of a function $f(x)$, assuming uniform grid spacing h .

b) The third order accurate expression for the first derivative of $f(x)$ given by forward differences is

$$f'(x_0) = \frac{-\frac{11}{6}f(x_0) + 3f(x_1) - \frac{3}{2}f(x_2) + \frac{1}{3}f(x_3)}{h}$$

Here, $x_j = x_0 + jh$, where j is the spacing between adjacent nodes. What is the third order accurate expression for the first derivative of $f(x)$ at $x = x_0$ given by *backward* differences?

7

Clearly indicate if each statement is true or false. No work needs to be shown for this section.

- The best rootfinding algorithm is always the one of highest order.
- Two shortcomings of polynomial interpolation include Gibbs's phenomenon and aliasing error.
- In the Gaussian quadrature approximation of $\int_a^b f(x)dx$, the sum of the weights w_i always equals $b-a$.
- The error due to polynomial interpolation can be minimized by using Chebyshev nodes.
- The midpoint rule and the trapezoid rule are the same order of accuracy.

—End of exam—