

# Raj P Patel

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## Objective

Third year computer engineering student with experience in C hardware programming, MATLAB data analysis, and controls. Proficient at project planning, timeline management, and documentation. Seeking a Summer internship starting in May 2019.

## Education

### Georgia Institute of Technology | Atlanta, GA

August 2016 – Present

Bachelor of Science in Computer Engineering, GPA 3.68

Expected Graduation, May 2020

Robotics Minor (applied)

## Skills

**Programming:** C, MATLAB, C++, VHDL, MIPS Assembly, Bash Scripting, VPython, HTML, CSS, ReStructuredText, Java (enrolled)

**Hardware:** Microcontroller (ARM mbed, TI LaunchPad), GPIO, Sensors, Altera DE2 FPGA, Oscilloscope, Soldering, Multimeter

**Software:** Mbed Online Compiler, TI Code Composer Studio, Altera Quartus II, Coolterm, Git Version Control, Simulink, Trello

**Communication:** Data Analysis, Documentation, Instruction Guide, Gantt Chart, Teamwork, Presentation, Technical Papers

**Languages:** English (fluent), Gujarati (conversational)

## Experience

### Intelligent Vision and Automation Lab (IVALab) | Atlanta, GA | Advisor: Patricio Vela

Jan 2019 – Present

#### Undergraduate Researcher

Team-based effort to improve position tracking accuracy for quadrupedal locomotion.

- Characterize motor by estimating plant transfer function with bode plot analysis
- Design adaptive integral controller based on motor torque response

### Ghost Robotics | Philadelphia, PA

May 2018 – Jul 2018

#### Mechatronics Intern

Devise scalable quadrupedal UGV with SDK control for security and inspection.

- Developed robotic gaits in C++ to showcase and document different SDK functionalities
- Performed QA tests on motor systems, assembled robots, and evaluated UI design
- Soldered connections for motor systems, power routing, and battery management systems (BMS)
- Scripted automatic SDK installation in Bash, decreasing computer setup time by 85%
- Edited Makefile for automatic port detection, decreasing firmware flash setup time by 50%
- Wrote beginner-friendly documentation in ReStructuredText to highlight essential SDK features
- Mapped relationship to approximately convert between robotic leg extension in meters and radians
- Generated interactive animation in VPython that prints C++ robotic leg extension and angle code

### Vertically Integrated Projects (VIP): Smart City Infrastructure | Atlanta, GA

Jan 2018 – Apr 2018

#### Undergraduate Researcher

Team-based effort to determine feasibility of UGV tracking rural road degradation.

- Collected asphalt sample data to assess reliability and accuracy of the texture-recording instrument
- Prepared three MATLAB functions to visualize, analyze, and validate wornness of asphalt texture
- Presented data collection and testing progress to other subteams monthly

### Kumon North America | Cherry Hill, NJ

Sep 2014 – Dec 2015

#### Mathematics and Reading Tutor

Mathematics, reading, and writing tutoring for K-12 students using Kumon method.

- Allocated time for synthesizing different explanations to suitably teach 10+ students individually
- Improved scoring and data logging efficiency by 57% after combining both into a collated process

## Projects

### Servo Control

Jan 2019

#### Embedded Systems Design Course

- Controlled servo motion with ARM mbed in C++ PWM signal, H Bridge, and AC power supply

<b>I2C Sensor Interfacing</b> <b>Control Systems Design Course</b> <ul style="list-style-type: none"> <li>Enabled I2C bus on TI Launchpad in C to retrieve data from TI BoosterPack accelerometer on a timer interrupt</li> </ul>	Nov 2018
<b>SCI LED State Machine</b> <b>Control Systems Design Course</b> <ul style="list-style-type: none"> <li>Used SCI module on TI Launchpad in C to transmit commands to LEDs and receive confirmations with Coolterm</li> </ul>	Oct 2018
<b>DC Motor Instantaneous Position Control</b> <b>Control Systems Design Course</b> <ul style="list-style-type: none"> <li>Setup PWM actuation and QEP sensing on TI Launchpad in C to rotate motor with state-space integral controller</li> </ul>	Oct 2018
<b>Galaga Game Controller</b> <b>Engineering Software Design Course</b> <ul style="list-style-type: none"> <li>Coded multiple game element classes with polymorphism and virtual functions</li> <li>Utilized ARM mbed in C++ with LCD, accelerometer, speaker, and pushbutton interrupts</li> </ul>	Apr 2018
<b>Number Sense Data Collection</b> <b>Engineering Software Design Course</b> <ul style="list-style-type: none"> <li>Constructed object counting test based on random number generator</li> <li>Utilized ARM mbed in C++ with LCD, speaker, microSD data logging, and pushbutton interrupts</li> </ul>	Feb 2018
<b>Labyrinth Game Controller</b> <b>Programming Hardware / Software Systems Course</b> <ul style="list-style-type: none"> <li>Managed heap to store doubly-linked list of different levels with game elements</li> <li>Utilized ARM mbed in C++ with LCD, accelerometer, speaker, LED, and pushbutton interrupts</li> </ul>	Nov 2017
<b>AmigoBot Object Detection (Team-Based)</b> <b>Digital Design Lab Course</b> <ul style="list-style-type: none"> <li>Theorized algorithm for robot movement and object detection using odometry and ultrasonic sensors</li> <li>Programmed and debugged Altera DE2 SCOMP robot moving and scanning algorithm in VHDL</li> <li>Produced extensive documentation, including proposal, presentation, animation, and design report</li> </ul>	Nov 2017
<b>Image Object Recognition</b> <b>Programming Hardware / Software Systems Course</b> <ul style="list-style-type: none"> <li>Composed algorithm in MIPS Assembly to scan images for potentially scaled versions of object</li> <li>Required 3% less static instructions, 35% less dynamic instructions, and 59% less storage than benchmark</li> </ul>	Oct 2017
<b>Relevant Coursework</b>	
<b>Engineering Software Design:</b> C++, Class, Polymorphism, Inheritance, Virtual Function, Heap Management, Doubly-Linked List, Random Number Generator	
<b>Feedback Control Systems:</b> Laplace Transform, Transfer Function, State Space, Stability, Routh Table, Root Locus, Bode Plots	
<b>Leadership</b>	
<b>Georgia Tech Department of Housing   Atlanta, GA</b> <b>Resident Assistant (RA) of Towers-Hanson Residence Halls</b> <ul style="list-style-type: none"> <li>Build inclusive home for 30+ Freshmen residents and act as first-responder to emergency situations</li> <li>Coordinate 30+ semesterly events by reserving resources, making marketing, and budgeting expenses</li> <li>Advise Towers-Hanson Hall Council about planning events and handling reimbursements</li> <li>Single-handedly created staff website in HTML and CSS to centralize access to common resources</li> <li>Awarded 2017-2018 Towers-Hanson Resident Advisor of the Year</li> </ul>	Aug 2017 – Present
<b>Georgia Tech Residence Hall Association (RHA)   Atlanta, GA</b> <b>Vice President of Matheson-Perry-Gray-Hayes Hall Council</b> <ul style="list-style-type: none"> <li>Communicated between RHA Executive Board, RAs, and residents for policy and event awareness</li> <li>Voted on 100+ sponsorship and resolution bills at Legislative Council for responsible budget usage</li> <li>Awarded 2016-2017 RHA Vice President of the Year</li> <li>Awarded 2016-2017 RHA Hall Council of the Year</li> </ul>	Sep 2016 – May 2017