

Tasks

- 1) Project road mapping
- 2) Obstacle Collision Detection Implementation
- 3) Robot Path finding implementation
- 4) Graphical Representation Implementation
- 5) Cell Decomposition Implementation
- 6) Project integration
- 7) Debugging / Testing
- 8) Validation
- 9) Meeting Notes
- 10) Create Report

Task Allocations

Ryan Beltran

Task 1 , 2 , 3 , 6 , 7

James Aubin

Task 1 , 4 , 6 , 7

James Moore

Task 1 , 3 , 6 , 7 , 9

You Ren Chen

Task 1 , 5 , 6 , 7

Nicholas Hemstreet

Task 1 , 3 , 6 , 7 , 10