Learning Heuristic Selection with Dynamic Algorithm Configuration

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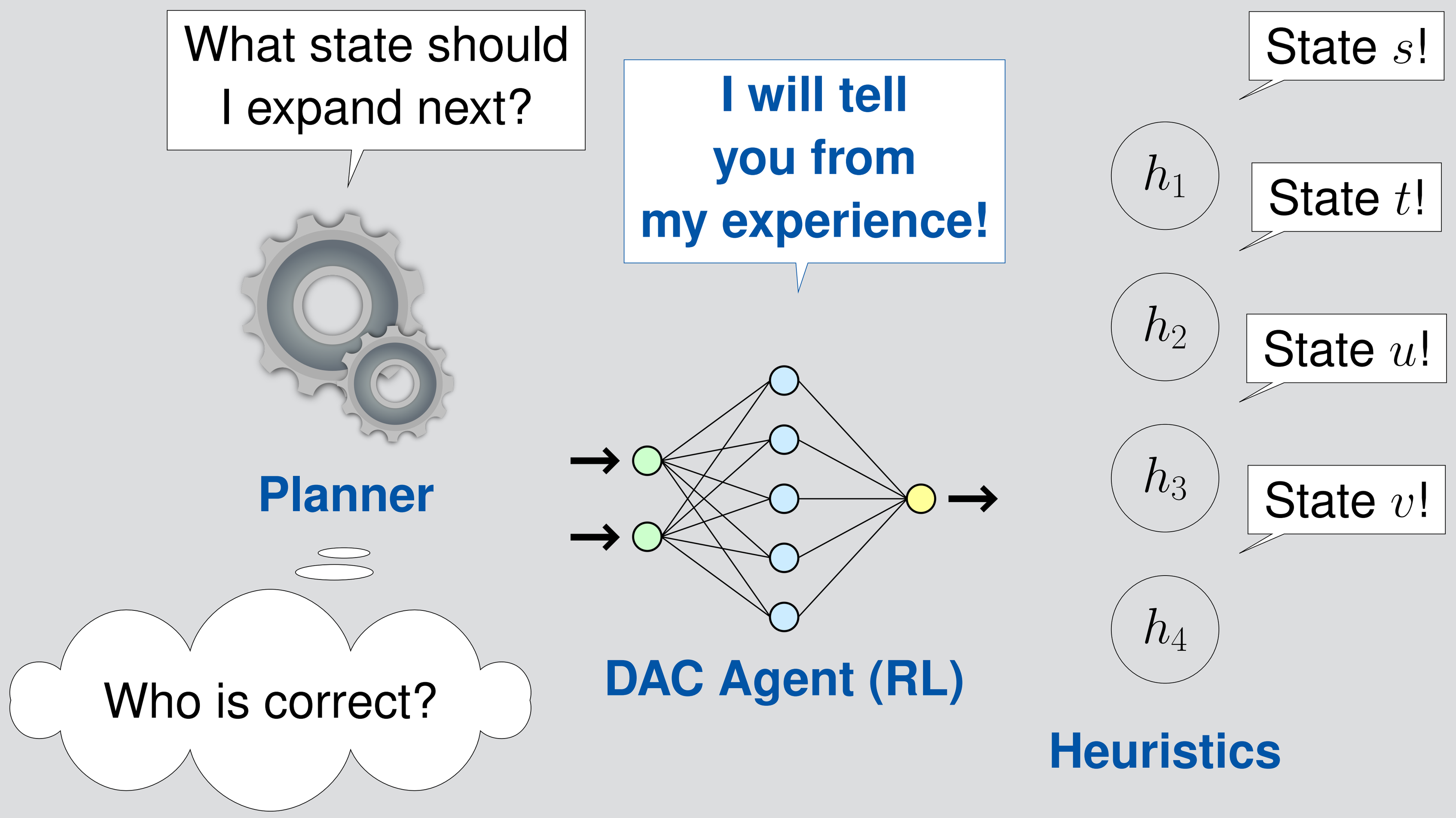
Motivation



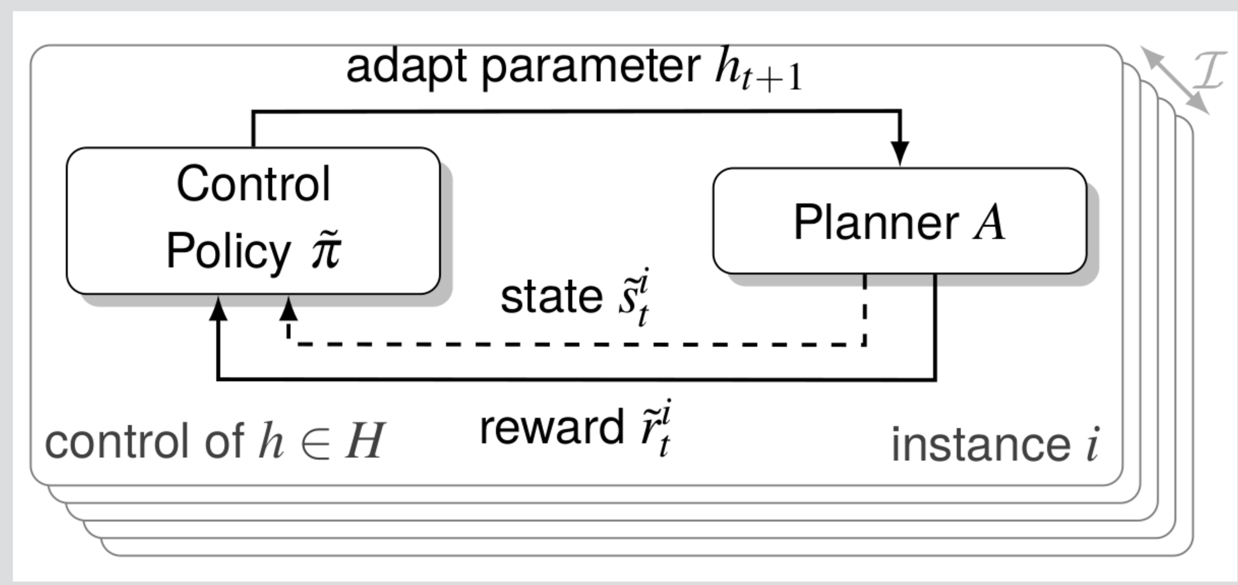
Satisficing Planning

- Search for a **good plan**
- **Inadmissible heuristics** are difficult to combine
- Greedy search with **multiple heuristics**
  - States evaluated with **each** heuristic
  - One **separate** open list for each heuristic

Automated Algorithm Configuration

- Algorithm Selection (AS) $\tilde{\pi} : \mathcal{I} \to H$
  - Considers **instance** (e.g. portfolio planner)
- Adaptive Algorithm Configuration (AAC) $\tilde{\pi} : \mathbb{N}_0 \to H$
  - Considers **time step** (e.g. alternation of heuristics)
- **Dyn. Algorithm Configuration** $\tilde{\pi} : \mathcal{I} \times \mathbb{N}_0 \times \tilde{\mathcal{S}} \to H$
  - Considers **instance**, **time step** and **planner state**
  - Problem can be considered as **MDP**
  - **Our approach** based on **Reinforcement Learning**

Dynamic Algorithm Configuration (DAC) – Theoretical Results



- An **optimal DAC policy** is **at least as good** as an **optimal AS policy** and an **optimal AAC policy**. □
- There is a **family of planning tasks** so that a **DAC policy** expands **exponentially fewer states** until a plan is found. □

Features and Rewards

- Features for **each heuristic** $h \in H$ (open list)
  - $\max_h$, $\min_h$, μ_h, σ_h^2, $\#_h$ and $t \in \mathbb{N}_0$
- Difference of each feature between $t-1$ and t

Reward in Training

Each expansion **step** until solution is found: **-1**

Experimental Results

- $H = \{h_{\text{ff}}, h_{\text{cg}}, h_{\text{cea}}, h_{\text{add}}\}$
- **6 domains** with **100 instances**
  - Per train and test set
- ε-greedy **deep Q-learning**
  - 2-layer network with 75 hidden units
  - 5 different DAC polices **per domain**
- **DAC** performs **overall best**
- **Best** AS is worse than **DAC policies**

Unseen Test Set

Algorithm	CONTROL POLICY			SINGLE HEURISTIC				BEST AS
Domain (#Inst.)	**DAC**	RND	ALT	h_{ff}	h_{cg}	h_{cea}	h_{add}	SGL. h
BARMAN (100)	**84.4**	83.8	83.3	66.0	17.0	18.0	18.0	67.0
BLOCKS (100)	**92.9**	83.6	83.7	75.0	60.0	92.0	92.0	93.0
CHILDS (100)	**88.0**	86.2	86.7	75.0	86.0	86.0	86.0	86.0
ROVERS (100)	95.2	**96.0**	**96.0**	84.0	72.0	68.0	68.0	91.0
SOKOBAN (100)	87.7	87.1	87.0	88.0	**90.0**	60.0	89.0	92.0
VISITALL (100)	56.9	51.0	51.5	37.0	**60.0**	**60.0**	**60.0**	60.0
SUM (600)	**505.1**	487.7	488.2	425.0	385.0	384.0	413.0	489.0

DAC can improve **heuristic selection** by condering **instance**, **time step** and **planner state**.