

## **FOREWORD**

THE SIMBAD NUMERICAL MODEL CAN BE USED TO SIMULATE THE BEHAVIOR OF A MOORED SHIP, USING THE CUMMINS EQUATION (TIME SIMULATION) AND TAKING INTO ACCOUNT THE FOLLOWING ELEMENTS:

- RANDOM WAVE FORCES (FIRST ORDER AND DRIFT FORCES)
- GUSTY WIND FORCES (GENERATION OF WIND SPEEDS ACCORDING TO THE DAVENPORT SPECTRUM)
- FORCES INDUCED BY A PASSING SHIP
- LINEAR OR NON-LINEAR MOORING CHARACTERISTICS FOR MOORING LINES AND FENDERS,
   AS WELL AS RIGID CONNECTION TYPE MOORING SYSTEM

# **NOTICE**

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#### THE INPUT DATA ARE READ FROM THE FOLLOWING FILES:

- 1. FILES PROVIDED BY THE PRE-PROCESSING PROGRAM (SEE DOCUMENTATION):
- > "HOUL\_IRR.TXT", FOR MAIN CHARACTERISTICS OF SHIP (LENGTH, DRAUGHT, POSITION OF CENTRE OF GRAVITY, MASSES AND INERTIA, HYDROSTATICS, "INFINITY" ADDED MASSES...)
- > "RAD\_IRF.TXT", FOR THE RADIATION DAMPING IMPULSE RESPONSE FUNCTIONS
- > "WAVE\_FOR.TXT" AND "DRIFT\_FOR.TXT" RESPECTIVELY FOR THE WAVE EXCITATION AND DRIFT FORCES TIME SERIES
- 2. FILES SPECIFIC FOR THE SIMBAD NUMERICAL MODEL:
- > "FICH", PROVIDES THE NAMES OF THE INPUT FILES

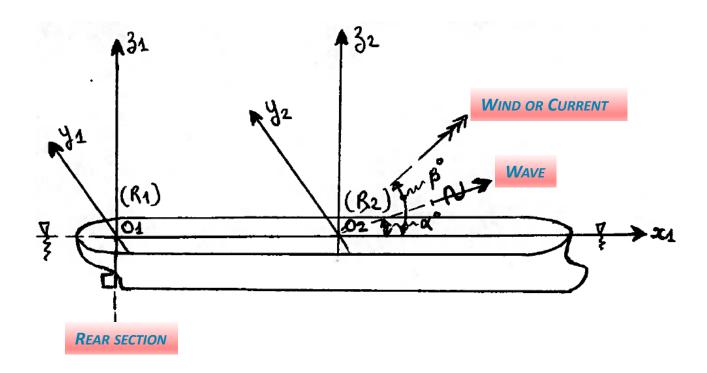
Unlike the previous files, the names of the following files can be changed, by modifying the input file "FICH":

- **▶** "VENT.DAT", FOR THE WIND CHARACTERISTICS
- > "COURANT.DAT", FOR THE CURRENT CHARACTERISTICS
- "AMAR.DAT" FOR THE MOORING SYSTEM
- **▶** "POINT.DAT" FOR A PARTICULAR POINT ABOARD THE SHIP
- "CHEN.DAT" FOR A PASSING SHIP
- ➢ "Houle.res" for the SIMBAD results

THESE FILES ARE DESCRIBED IN DETAILS HEREAFTER.

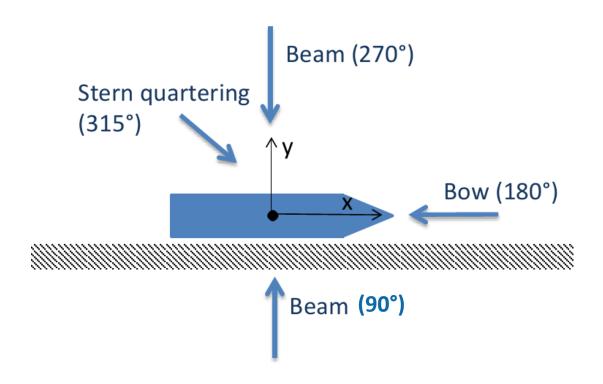
### **COORDINATE SYSTEMS:**

TWO COORDINATE SYSTEMS ARE USED IN THE SIMBAD PROGRAM. THESE COORDINATE SYSTEMS HAVE THE X AXIS POINTING FORWARD, Y TO PORT AND Z UPWARD. THE FIRST FIXED COORDINATE SYSTEM (R1) HAS ITS ORIGIN LOCATED AT THE INTERSECTION OF REAR SECTION, MIDSHIP PLANE AND WATERLINE PLANE. THE SECOND COORDINATE SYSTEM (R2) HAS ITS ORIGIN LOCATED AT THE POSITION OF THE CENTRE OF GRAVITY (WITH ITS X, Y AND Z VALUES SPECIFIED AS PER THE FIRST COORDINATE SYSTEM IN FILE "HOUL\_IRR.TXT").



#### **RELATIVE DIRECTIONS OF ENVIRONMENTAL CONDITIONS:**

The relative direction has been defined in the ship axis system in which waves propagating, wind blowing or current flowing in the direction of the positive X2-axis is defined as  $0^\circ$  and waves propagating, wind blowing or current flowing in the positive Y2-axis as  $90^\circ$ 



## RUNNING THE SIMBAD PROGRAM: INPUT FILE "FICH" PROVIDES THE NAMES OF THE INPUT FILES

Houl\_irr.txt NAME OF FILE NOT TO BE CHANGED VENT.DAT COURANT.DAT AMAR.DAT POINT.DAT CHEN DAT HOULE.RES

INPUT FILE NAMES THAT CAN BE CHANGED (FILE NAME: 12 CHARACTERS MAX. WITH EXTENSION)

# RUNNING THE SIMBAD PROGRAM: INPUT FILE "VENT.DAT" PROVIDES THE WIND CHARACTERISTICS

210.0000 | RELATIVE WIND DIRECTION 0.00 10.22 13.02 2.00 4.00 16.32 18.22 6.00 8.00 20.16 19.90 10.00 12.00 19.19 14.00 23,30 16.00 18.96 18.00 19.95 20.00 22,05 22.00 16.86 24.00 18.02 26.00 13.48 28.00 15.77 30.00 20.65 32.00 18.27 WIND SPEED TIME SERIES (TIME IN S VS. WIND SPEED IN M/S). IT IS MANDATORY TO END WITH A NEGATIVE TIME VALUE. THE 34.00 18.07 NUMBER OF TIME STEPS IS LIMITED TO 1000. If the simulation time is greater than the duration of the time series, 36.00 19.52 38.00 16.74 THE SERIES IS REPEATED CYCLICALLY. 40.00 18.35 42.00 16.90 44.00 15.13 46.00 20.91 48.00 17.20 50.00 20.08 52.00 20.88 54.00 17.19 56.00 17.49 16.30 58.00 60.00 19.09 62.00 22.00 64.00 17.98 66.00 13.65

# RUNNING THE SIMBAD PROGRAM: INPUT FILE "VENT.DAT" PROVIDES THE WIND CHARACTERISTICS

1968.00 17.69 1970.00 17.34 1972.00 21.37 1974.00 16.50 1976.00 19.60 1978.00 18.94 WIND SPEED TIME SERIES (TIME IN S VS. WIND SPEED IN M/S). IT IS MANDATORY TO END WITH A NEGATIVE TIME VALUE. THE 1980.00 15.30 1982.00 13.70 NUMBER OF TIME STEPS IS LIMITED TO 1000. IF THE SIMULATION TIME IS GREATER THAN THE DURATION OF THE TIME SERIES, 1984.00 10.65 THE SERIES IS REPEATED CYCLICALLY. 1986.00 11.59 1988.00 16.70 1990.00 11.93 1992.00 10.10 1994.00 11.96 1996.00 10.55 -1 SIDE WIND AREA/FRONT WIND AREA/VESSEL LENGTH/HEIGHT OF SIDE WIND AREA 1405,000 11.00000 6200.000 281,0000 CENTRE OF GRAVITY ABOVE THE WATERLINE PLANE 0.02 0.00 -0.01 0.90 0.91 0.18 -0.10 10.0 -0.06 20.0 0.87 0.34 -0.12 -0.18 30.0 -0.29 0.79 0.53 -0.17 40.0 0.68 0.71 -0.20 -0.39 50.0 0.55 0.85 -0.20 -0.46 60.0 0.39 0.94 -0.51 -0.17 70.0 0.22 1.00 -0.14 -0.54 80.0 0.10 1.04 -0.10 -0.56 90.0 0.02 1.05 -0.06 -0.57 RELATIVE WIND DIRECTION (FROM 0° TO 180°) / WIND COEFFICIENTS CX, CY, CN, CK (SEE NOTE HEREAFTER) 100.0 -0.05 1.05 -0.02 -0.56 110.0 -0.15 1.02 0.01 -0.55 120.0 -0.30 0.96 -0.52 0.03 130.0 -0.48 -0.46 0.86 0.04 -0.37 140.0 -0.67 0.69 0.05 150.0 -0.81 0.47 0.04 -0.25 160.0 -0.91 0.26 0.03 -0.14 170.0 -0.99 0.10 0.02 -0.06 180.0 -1.02 0.00 0.00 0.00

# RUNNING THE SIMBAD PROGRAM: INPUT FILE "VENT.DAT" PROVIDES THE WIND CHARACTERISTICS

```
123.0000
0.000000E+00
               0.0000000E+00
               0.000000E+00
 10000.00
        -1
                1320.000
 5300,000
                               274,0000
                                              8.500000
0.000000E+00
               0.3500000
                              0.0000000E+00
                                             0.0000000E+00
                                                            0.0000000E+00
 10.00000
               0.3500000
                              0.1300000
                                            -2.5000000E-02 -0.3300000
 20.00000
               0.2500000
                              0.2900000
                                            -2.999999E-02 -0.5400000
 30.00000
               0.2000000
                              0.4300000
                                            -7.5000003E-02 -0.8200000
 40.00000
               0.2100000
                              0.5500000
                                            -9.0000004E-02 -1.080000
 50.00000
               0.2600000
                              0.6300000
                                            -0.1150000
                                                            -1.240000
 60.00000
               0.3000000
                                            -9.0000004E-02 -1.350000
                              0.6800000
 70.00000
               0.2200000
                              0.7100000
                                            -2.9999999E-02 -1.410000
 80.00000
               0.1300000
                              0.7200000
                                            -2.5000000E-02 -1.480000
 90.00000
               0.0000000E+00
                              0.7200000
                                             0.0000000E+00 -1.530000
                                             1.5000000E-02 -1.490000
 100.0000
              -5.0000001E-02
                              0.7100000
 110,0000
              -7.9999998E-02
                                             2.999999E-02 -1.400000
                              0.6800000
 120.0000
              -0.1000000
                              0.6400000
                                             5.0000001E-02 -1.270000
 130.0000
              -0.1500000
                              0.5500000
                                             7.5000003E-02 -1.100000
 140.0000
              -0.2000000
                              0.4300000
                                             5.0000001E-02 -0.9100000
 150.0000
              -0.2500000
                              0.3000000
                                             3.999999E-02 -0.6200000
 160,0000
             -0.3000000
                              0.1900000
                                             2.999999E-02 -0.3800000
 170.0000
              -0.3500000
                              9.0000004E-02 1.5000000E-02 -0.2200000
 180.0000
              -0.4000000
                              0.0000000E+00 0.0000000E+00 0.0000000E+00
```

WHEN THERE IS NO WIND, SUCH AN INPUT FILE WITH A NIL SPEED IS REQUIRED

#### **N**OTE ON THE WIND FORCES CALCULATION:

THE FOLLOWING FORMULAS ARE USED. RELATIVE TO COORDINATE SYSTEM R2:

SURGE WIND FORCE:  $F_{xv} = \frac{1}{2} \rho_a \cdot C_x \cdot A_i \cdot V^2$ 

SWAY WIND FORCE:  $F_{yy} = \frac{1}{2} \rho_a \cdot C_y \cdot A_T \cdot V^2$ 

YAW WIND MOMENT:  $M_{nv} = \frac{1}{2} \rho_a \cdot C_n \cdot A_T \cdot V^2 \cdot L_{pp}$ 

ROLL WIND MOMENT:  $M_{kv} = \frac{1}{2} \rho_a \cdot C_k \cdot A_T \cdot V^2 \cdot H$ 

WITH:

CX, CY, CN, CK: WIND COEFFICIENTS VS. RELATIVE DIRECTION

V, WIND SPEED (M/S)

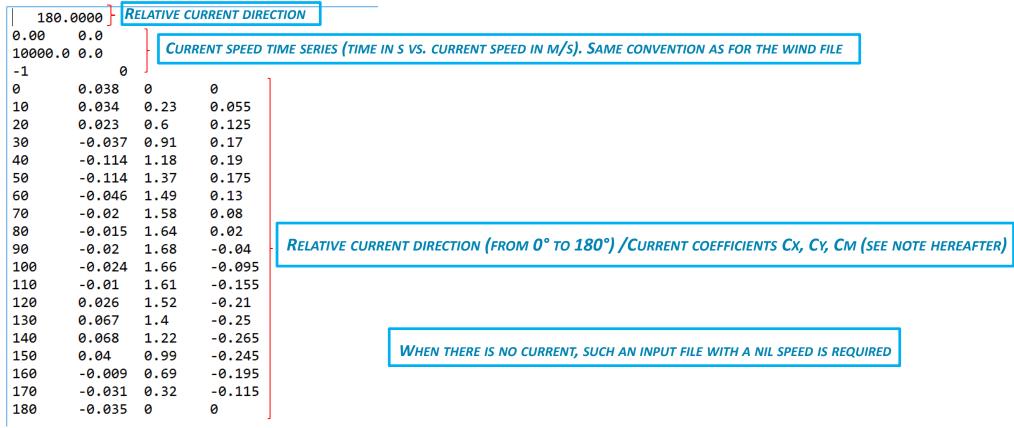
AL, AT: SIDE WIND AND FRONT WIND AREAS (M2)

LPP: SHIP LENGTH (M)

H: HEIGHT OF SIDE WIND AREA CENTRE OF GRAVITY ABOVE THE WATERLINE PLAN

 $P_a$ : AIR DENSITY (KG/M3)

#### INPUT FILE "COURANT.DAT" PROVIDES THE CURRENT CHARACTERISTICS



#### **NOTE ON THE CURRENT FORCES CALCULATION:**

THE FOLLOWING FORMULAS ARE USED, RELATIVE TO COORDINATE SYSTEM R2:

**SURGE WIND FORCE:**  $F = \frac{1}{2} \rho C_F U^2 A_C$ 

SWAY WIND FORCE:  $F = \frac{1}{2} \rho C_F U^2 A_C$ 

**YAW WIND MOMENT:**  $M = \frac{1}{2} \rho C_M U^2 A_c L_{pp}$ 

WITH:

CF = CX , CY: CURRENT COEFFICIENTS IN SURGE OR SWAY VS. RELATIVE DIRECTION

CM = CURRENT COEFFICIENTS IN YAW VS. RELATIVE DIRECTION

**U**, CURRENT SPEED (M/S)

Ac: Current area  $(M2) = LPP \times T$ 

LPP: SHIP LENGTH (M)

T: SHIP DRAFT (M)

P: WATER DENSITY (KG/M3)

INPUT FILE "AMAR.DAT" DEFINES THE MOORING SYSTEM

```
12}
                                                           TOTAL NUMBER OF MOORING LINES AND FENDERS. MAX.: 22
                   4 336500.0 -188320.0 82873.0
       1
       1 0.0000000E+00
 -66,000
              65.50000
                             7.50000
 -15.0000
                5.00000
                              22,0000
 98100.0
             0.0000000E+00
                   4 596520.0 -415490.0 186330.0 -18592.0
       1 0.0000000E+00
 -21,0000
              65.50000
                              7,50000
 -6.0000
           16.50000
                            22.00000
147200.0
             0.0000000E+00
                   4 394520.0 -272190.0 121920.0 -12132.0
       1 0.0000000E+00
              65.50000
                             7.50000
25,00000
1.50000
            18.50000
                            22.00000
123600.0
             0.0000000E+00
                   4 358580.0 -219240.0 97027.0 -9332.8
       1 0.0000000E+00
 93,0000
              29.00000
                             7.50000
 25.0000
              23,00000
                            22,00000
129500.0
             0.0000000E+00
                   4 354470.0 -213390.0 94326.0 -9034.9
       1 0.0000000E+00
151,0000
              29.00000
                             7.50000
221,0000
             23,00000
                            22,00000
 68700.0
             0.0000000E+00
                   4 375670.0 -244040.0 108590.0 -10621.0
       1 0.0000000E+00
221,0000
              65.50000
                             7.50000
252,0000
              13,50000
                            22,00000
 88300.0
             0.0000000E+00
                   4 580970.0 -391990.0 175120.0 -17314.0
       1 0.0000000E+00
263.0000
              65.50000
                             7.50000
262.0000
             10,00000
                            22,00000
132400.0
             0.0000000E+00
                   4 352330.0 -210370.0 92935.0 -8882.0
```

**EACH MOORING LINE OR FENDER DEFINED AS FOLLOWS:** FIRST LINE:

PARAMETER FOR THE TYPE OF CONNECTION: 1 FOR A CLASSIC MOORING LINE. **2** FOR A SPECIFIC CONNECTION, -1 FOR A FENDER

FOR CLASSIC MOORING LINE AND FENDER (PARAMETERS 1 AND -1), THE STIFFNESS MAY BE DEFINED WITH A POLYNOMIAL CURVE UP TO DEGREE 5. DEFINING THE MOORING LOAD AS A FUNCTION OF ELONGATION OR THE **REACTION FORCE AS A FUNCTION OF DEFLECTION, SUCH AS:** 

 $A * x + B * x^2 + C * x^3 + D * x^4$  (x being the elongation or DEFLECTION), THEN FOR A STRONG NON-LINEAR STIFFNESS: INDICATE (DEGREE) 4 (AND COEFFICIENTS:) A (N/M), B(N/M2), C(N/M3), D(N/M4) AND FOR A LINEAR STIFFNESS: (DEGREE) 1 (AND) A(N/M)

A SPECIFIC CONNECTION (PARAMETER 2) IS A UNIT THAT RESPONDS TO THE ERROR IN DISPLACEMENT (X AND Y DIRECTIONS) WITH A REACTION FORCE WITH THE AIM OF GETTING THE UNIT, AND THUS THE SHIP, BACK IN THE NEUTRAL POSITION. THE MODEL OF THE UNITS IS WRITTEN TO CALCULATE THE ANGLE AND MAGNITUDE OF THIS REACTION FORCE. THE ERROR IN DISPLACEMENT IS RUN THROUGH A PID CONTROLLER. THE CONTROL VALUE AND THE ANGLE, DEFINING THE MAXIMUM FORCE, ARE USED TO DETERMINE THE MAXIMUM FORCE. IN ANY CASE, TO PREVENT THE FORCES LARGER THAN THE MAXIMUM FORCE, THE CONTROL VARIABLE HAS A MAXIMUM OF 1. EACH UNIT IS ALLOCATED TO EXERT A SWAY FORCE OF 230 KN AND A SURGE FORCE OF 100 KN. FOR THIS SPECIFIC CONNECTION, THE NUMBER INDICATING THE DEGREE OF THE POLYNOMIAL IS NOW THE NUMBER OF COUPLED UNITS. IT MUST BE FOLLOWED BY AS MANY NIL VALUES AS THERE ARE NUMBER OF UNITS (EXAMPLE: 2 / 0. / 0.)

### INPUT FILE "AMAR.DAT" DEFINES THE MOORING SYSTEM (FOLLOWING)

```
1
                 4 336500.0 -188320.0 82873.0 -7786.7
       1 0.0000000E+00
 -66,000
           65.50000
                           7.50000
 -15.0000
            5.00000
                          22.0000
 98100.0 0.0000000E+00
                 4 596520.0 -415490.0 186330.0 -18592.0
       1 0.0000000E+00
 -21.0000
           65,50000
                          7,50000
 -6.0000 16.50000
                          22.00000
147200.0
           0.0000000E+00
                 4 394520.0 -272190.0 121920.0 -12132.0
       1 0.0000000E+00
          65.50000
                         7.50000
25.00000
1.50000 18.50000
                          22.00000
123600.0 0.0000000E+00
                 4 358580.0 -219240.0 97027.0 -9332.8
       1 0.0000000E+00
93,0000
             29,00000
                         7.50000
25.0000
           23.00000
                          22,00000
129500.0 0.0000000E+00
                 4 354470.0 -213390.0 94326.0 -9034.9
       1 0.0000000E+00
151.0000
           29.00000
                         7.50000
221,0000
           23,00000
                          22,00000
 68700.0 0.0000000E+00
                 4 375670.0 -244040.0 108590.0 -10621.0
       1 0.0000000E+00
221.0000
             65.50000
                          7.50000
252,0000
                          22,00000
           13,50000
 88300.0
            0.0000000E+00
                 4 580970.0 -391990.0 175120.0 -17314.0
       1 0.0000000E+00
263.0000
             65.50000
                         7.50000
262,0000
           10.00000
                          22.00000
132400.0 0.0000000E+00
                 4 352330.0 -210370.0 92935.0 -8882.0
```

**EACH MOORING LINE OR FENDER DEFINED AS FOLLOWS:** 

#### **SECOND LINE:**

A DAMPING MAY BE DEFINED WITH A POLYNOMIAL CURVE UP TO DEGREE 5, AS A FUNCTION OF ELONGATION OR DEFLECTION SPEED. CONVENTIONS ARE THE SAME AS FOR THE INTRODUCTION OF STIFFNESS. IF THERE IS NO DAMPING: PUT 1/0.

#### THIRD LINE:

POSITION OF THE BOLLARD AT QUAY (PARAMETER 1) OR OF FENDER SUPPORT (GENERALLY THE QUAY OR WHARF)(PARAMETER -1), IN THE FIRST FIXED COORDINATE SYSTEM (R1). FOR A SPECIFIC CONNECTION (PARAMETER 2), IT IS THE POINT ON THE SHIP'S HULL WHERE THE CONNECTION IS FIXED.

#### **FOURTH LINE:**

POSITION OF THE MOORING POINT ON-BOARD THE SHIP (PARAMETER 1). IF THERE IS A LONG MOORING LENGTH ON-BOARD THE SHIP, IT IS PREFERABLE TO POSITION THE POINT AT THE FAIRLEAD AND TO TAKE THIS LENGTH INTO ACCOUNT IN THE CALCULATION OF THE STIFFNESS.

FOR A FENDER (PARAMETER -1), IT IS THE POINT ON THE SHIP'S HULL WHERE THE FENDER IS IN TOUCH. ONLY THE Y COORDINATES ARE DIFFERENT BETWEEN THE TWO POSITIONS.

FOR A SPECIFIC CONNECTION (PARAMETER 2), ONLY THE Y COORDINATE DIFFERS FROM THE PREVIOUS POINT AND IT SHOULD BE PLACED 1 M IN FRONT OF THIS POINT.

#### **FIFTH LINE:**

**PRETENSION (IN N) FOR THE MOORING LINE AND PRE-DAMPING, IF ANY.** 

# RUNNING THE SIMBAD PROGRAM: INPUT FILE "AMAR.DAT" DEFINES THE MOORING SYSTEM (FOLLOWING)

```
1 8675000.
       -1
       1 0.0000000E+00
 68,0000
             26.00000
                           5.000000
 68,0000
             23,00000
                         5.000000
0.0000000E+00 0.0000000E+00
                1 8675000.
       1 0.0000000E+00
            26.00000
 93.0000
                           5.000000
                       5.000000
 93.0000
            23.00000
0.0000000E+00 0.0000000E+00
                  1 8675000.
       1 0.0000000E+00
             26.00000
151.0000
                           5.000000
151,0000
             23,00000
                           5,000000
0.000000E+00 0.000000E+00
             1 8675000.
       1 0.0000000E+00
185.0000 26.00000
                           5.000000
185.0000
         23.00000
                       5.000000
0.0000000E+00 0.0000000E+00
       2 2 0.0 0.0
       1 0.0000000E+00
 72,9000
         -15.95000
                         3,000000
 72.9000 -14.95000
                         3.000000
  0.0
        0.0000000E+00
                2 0.0 0.0
       1 0.0000000E+00
102,9000
         -15.95000
                         3,000000
102,9000
            -14.95000
                        3,000000
  0.0
        0.0000000E+00
                 2 0.0 0.0
       1 0.0000000E+00
132,9000
         -15.95000
                         3.000000
132,9000
         -14.95000
                         3.000000
  0.0
        0.0000000E+00
       2 0.0 0.0
       1 0.0000000E+00
162.9000 -15.95000
                         3.000000
162.9000
         -14.95000
                         3.000000
  0.0
        0.0000000E+00
```

**EXAMPLES OF FENDER SYSTEM DEFINITION** 

**EXAMPLES OF SPECIFIC CONNECTION DEFINITION** 

# RUNNING THE SIMBAD PROGRAM: INPUT FILE "POINT.DAT" FOR PARTICULAR POINTS ABOARD THE SHIP

1 148.000 23.0000 26.2500

NUMBER OF PARTICULAR POINTS AND COORDINATES OF EACH POINT IN THE FIRST FIXED COORDINATE SYSTEM (R1)

#### INPUT FILE "CHEN.DAT" FOR A PASSING SHIP

```
0.0
200.0 0.0
                       0.0
204.49 4175.07 0.0
208.97 5365.54 0.0
213.46 7155.45 422.6 0.0
217.94 8945.37 1056.5 0.0
222.43 9540.61 1687.7 0.0
226.92 14310.91 2110.3 0.0
231.40 17291.29 2427.3 0.0
235.89 20271.68 2532.9 0.0
240.38 22656.83 2744.2 0.0
244.86 28621.82 5065.9 0.0
249.35 31006.97 6333.7 -81054.8
253.83 36372.51 6967.6 -188933.6
258.32 42928.51 9923.2 -350897.5
262.81 52469.12 13090.1 -701940.7
267.29 59624.57 16888.1 -971929.2
271.78 67375.26 23010.5 -1349796.3
276.27 77515.32 28921.6 -1835833.8
280.75 87651.16 36945.8 -2348695.2
285.24 95401.84 49401.9 -2969581.1
289.72 102557.30 62489.1 -3779546.3
294.21 96592.31 80222.4 -4400432.2
298.70 82880.85 97113.3 -5075403.3
303.18 48298.27 111891.0 -5129342.6
307.67 7155.45 122445.4 -4589365.8
312.15 -54854.27 128567.8 -3320624.3
316.64 -115078.29 127514.0 -1619784.7
321.13 -172912.94 118224.7 944813.7
325.61 -232541.73 103024.4 4049534.7
330.10 -292166.30 86344.8 6992146.1
334.59 -345830.10 61224.1 9286901.9
339.07 -390548.53 27445.2 11338639.0
343.56 -414995.28 -12667.4 12958423.7
348.04 -419170.35 -55313.0 14038231.6
352.53 -413205.36 -97113.3 14389274.9
357.02 -392933.68 -143556.8 13714303.8
```

Time series of forces induced by passing ship relative to coordinate system R2 (surge force X, sway force Y in Newton and yaw moment M in Nm). It is mandatory to end with a negative time value. The number of time steps is limited to 1000. As there is no ramp-up time for this type of simulation, a "blank time" of about 200s is to be introduced at the beginning of the time series.

540.95 -11330.53 0.0 0.0 545.44 -9540.61 0.0 0.0 549.92 -7750.69 0.0 0.0 554.41 -6560.22 0.0 0.0 558.89 -4770.30 0.0 0.0 600.00 0.0 0.0 0.0 -1 0.0 0.0 0.0

# RUNNING THE SIMBAD PROGRAM: OUTPUT FILE "HOULE.RES" FOR ANALYSIS OF SIMBAD RESULTS

	AVERAGE   MIN.	MAX.	MAX-MIN   RMS
WIND (M/S)	0.000E+00   0.000E+00	0.000E+00	0.000E+00   0.000E+00
SURGE (M)	9.676E-03   -4.941E-02	7.246E-02	1.219E-01   1.924E-02
SWAY (M)	-2.753E-01   -2.676E+00	1.120E+00	3.796E+00   5.058E-01
HEAVE (M)	-1.452E-03   -1.281E+00	1.381E+00	2.662E+00   3.387E-01
ROLL (DEG)	-1.201E-01   -3.810E+00	3.443E+00	7.254E+00   9.614E-01
PITCH (DEG)	1.493E-03   -3.463E-02	4.147E-02	7.609E-02   1.025E-02
YAW (DEG)	-4.091E-02   -4.943E-01	3.937E-01	8.880E-01   1.210E-01
POINT 1 :			
SURGE (M)	2.239E-02   -1.376E-01	1.872E-01	3.248E-01   4.344E-02
SWAY (M)	-2.484E-01   -2.801E+00	1.318E+00	4.119E+00   5.355E-01
HEAVE (M)	-3.842E-02   -1.371E+00	1.237E+00	2.608E+00   3.055E-01
TENSION :			
LINE 1 (T)	3.118E+01   0.000E+00	1.121E+02	1.121E+02   1.631E+01
LINE 2 (T)	3.187E+01   0.000E+00	1.184E+02	1.184E+02   1.763E+01
LINE 3 (T)	3.126E+01   0.000E+00	1.138E+02	1.138E+02   1.665E+01
LINE 4 (T)	2.588E+01   1.799E+01	4.229E+01	2.430E+01   2.895E+00
LINE 5 (T)	2.823E+01   1.655E+01	5.038E+01	3.382E+01   3.922E+00

DETERMINATION OF AVERAGE, MINIMUM, MAXIMUM AND STANDARD DEVIATION VALUES FOR MOTIONS, MOORING LINE AND FENDER LOADS. BY CONVENTION, MOORING LINE LOADS ARE POSITIVE AND FENDER LOADS ARE NEGATIVE.

	PERIOD 1 (S)  AMPLITUDE 1 PERIOD 2 (S)  AMPLITUDE 2
WIND (M/S)	0.000E+00   0.000E+00   0.000E+00   0.000E+00
SURGE (M)	8.436E+01   2.660E-02   7.816E+01   2.349E-02
SWAY (M)	2.986E+01   5.954E-01   1.427E+01   5.270E-01
HEAVE (M)	1.518E+01   4.266E-01   1.010E+01   3.629E-01
ROLL (DEG)	1.518E+01   1.639E+00   1.427E+01   1.364E+00
PITCH (DEG)	1.010E+01   1.574E-02   1.034E+01   9.014E-03
YAW (DEG)	2.988E+01   5.421E-01   2.610E+01   2.226E-01
POINT 1	;
SURGE (M)	2.988E+01   1.821E-01   2.611E+01   7.044E-02
SWAY (M)	1.427E+01   6.347E-01   1.518E+01   5.984E-01
HEAVE (M)	1.518E+01   2.883E-01   1.701E+01   2.803E-01
TENSION	;
LINE 1 (T)	1.518E+01   1.858E+01   1.427E+01   1.445E+01
LINE 2 (T)	1.518E+01   2.042E+01   1.427E+01   1.623E+01
	<i>1</i>

**DETERMINATION OF MAIN PERIODS AND AMPLITUDES OF TIME-SERIES FROM A FFT PROCEDURE** 

OTHER RAW OUTPUT FILES ARE ALSO AVAILABLE FOR LATER ANALYSIS (SEE HEREAFTER): MOTIONS, SPEEDS, ACCELERATIONS OF THE CENTER OF GRAVITY OR OF A SPECIFIC POINT; MOORING LINE AND FENDER LOADS.

