Calibration results
====================
Camera-system parameters:
cam0 (/camera/image_raw):
type: <class 'aslam_cv.libaslam_cv_python.EquidistantDistortedPinholeCameraGeometry'>
distortion: [0.3605195   2.76623466 -17.57839982 36.54081515] +- [0.04406732   0.86039973   6.63898741
17.12946854]
projection: [659.63388457 878.81537926 321.54589753 247.25875486] +- [7.81154973 10.25277145   0.97024598
1.58383432]
reprojection error: [0.000000, 0.000001] +- [0.181252, 0.184588]
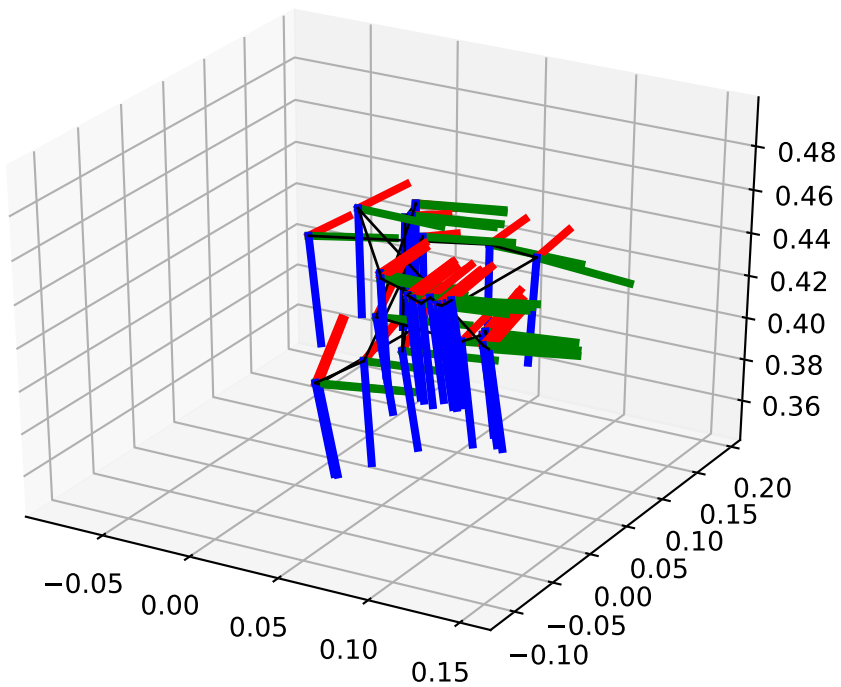

Target configuration
====================

Type: aprilgrid
Tags:
Rows: 6
Cols: 6
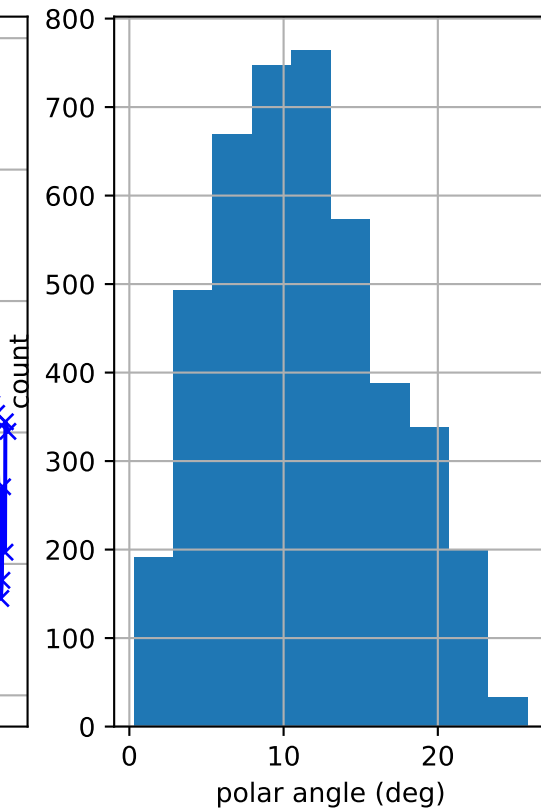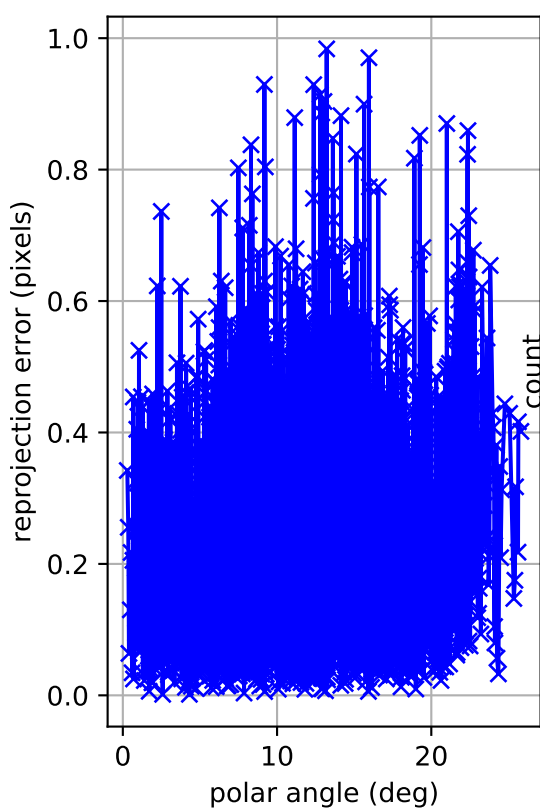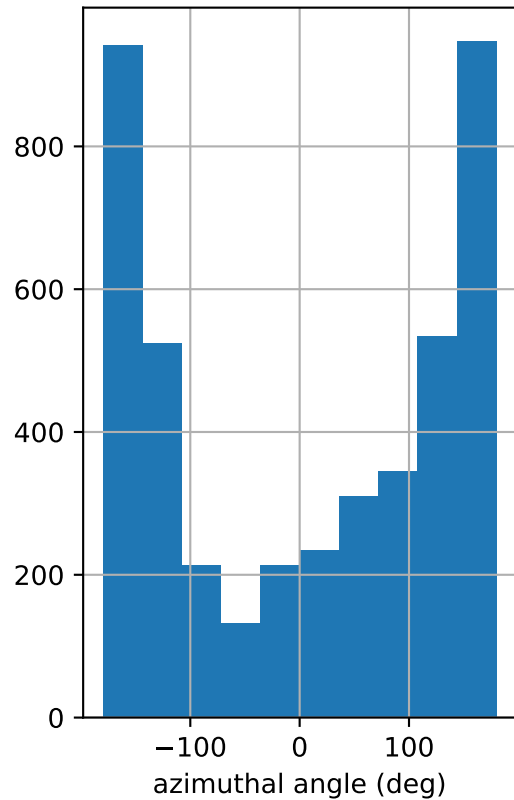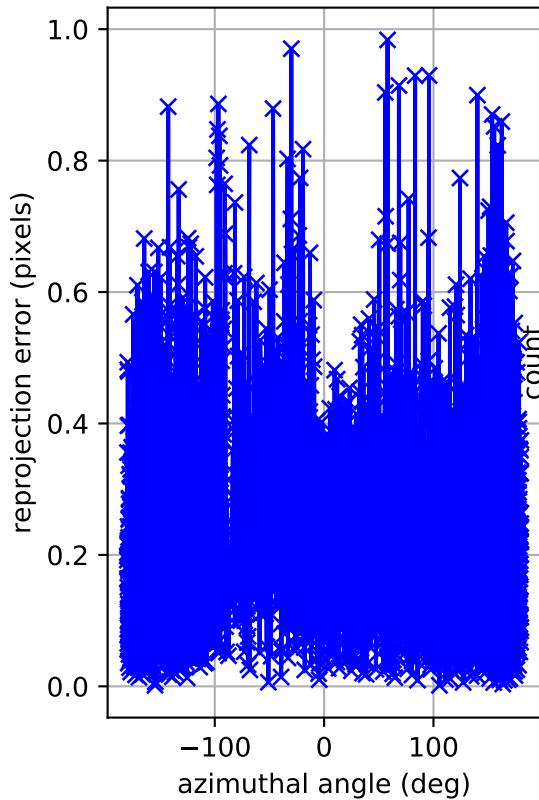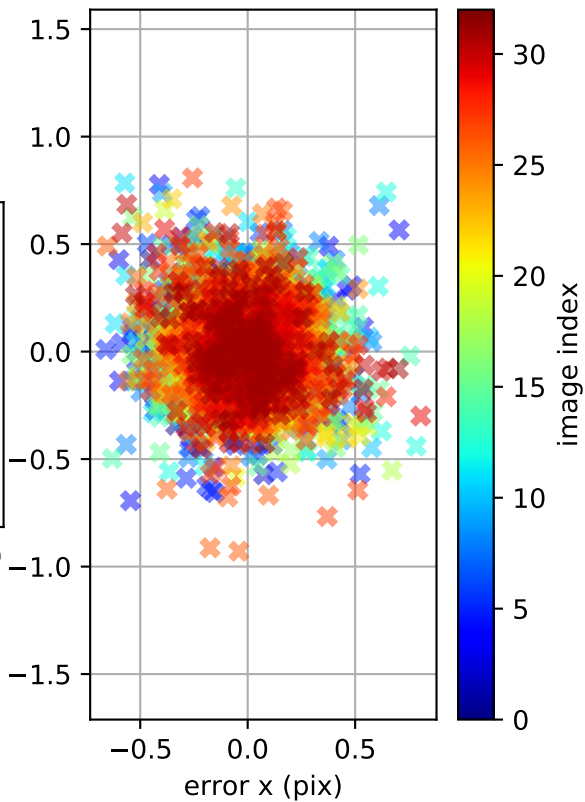Size: 0.02 [m]
Spacing 0.006 [m]
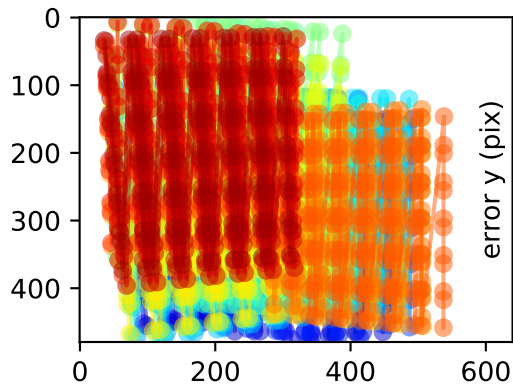
cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners
cam0