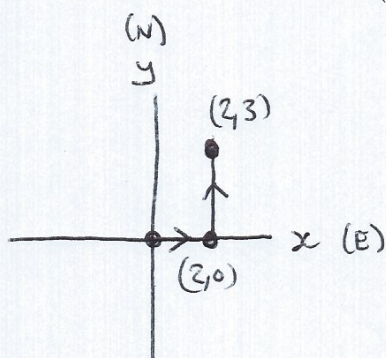


1. (10 marks) You are standing at the origin $(0,0)$ of a coordinate system (x,y) in which (as usual) the x direction is east and the y direction is north (all distances in m.). The elevation of the surrounding land is given by a function $f(x,y)$.

- (a) (5 marks) Walking 2 m. east, you gain 0.5 m. of elevation. Then walking a further 3 m. north, you gain a further 2.8 m. elevation. Using linear approximation, estimate $\nabla f(0,0)$.

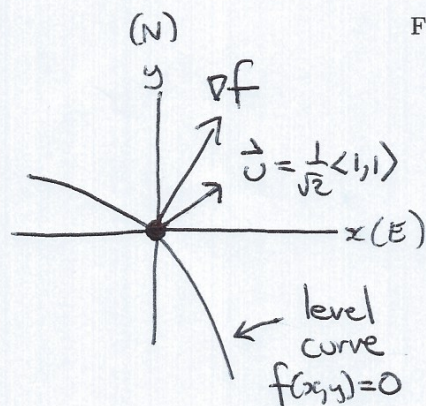


$$\begin{aligned} \bullet 0.5 &= f(2,0) - f(0,0) \approx f_x(0,0) \cdot 2 \Rightarrow f_x(0,0) \approx 0.25 \\ \bullet 2.8 + 0.5 &= f(2,3) - f(0,0) \approx f_x(0,0) \cdot 2 + f_y(0,0) \cdot 3 \\ &\approx 0.5 + f_y(0,0) \cdot 3 \Rightarrow f_y(0,0) \approx \frac{2.8}{3} \approx 0.93 \\ \Rightarrow \nabla f(0,0) &\approx \langle 0.25, 0.93 \rangle \end{aligned}$$

- (b) (5 marks) Suppose you happen to know the following two things:

- the curve $\frac{x^2}{40} + x + \frac{y^2}{10} + 2\sqrt{3}y = 0$ is a level curve (contour line) of constant elevation $f(x,y)$;
- if you walk directly north-east from $(0,0)$, your rate of ascent is 0.7 (vertical m. per horizontal m.).

Find $\nabla f(0,0)$



$$\Rightarrow \alpha = \frac{\sqrt{2}(0.7)}{1+2\sqrt{3}}$$

$$\begin{aligned} \bullet \nabla f(0,0) &\text{ is normal to the level curve at } (0,0) \\ \bullet \nabla \left[\frac{x^2}{40} + x + \frac{y^2}{10} + 2\sqrt{3}y \right] &= \left\langle \frac{x}{20} + 1, \frac{y}{5} + 2\sqrt{3} \right\rangle \\ &= \langle 1, 2\sqrt{3} \rangle \text{ (at } (0,0) \text{) is also normal} \\ &\text{to the level curve} \\ \Rightarrow \nabla f(0,0) &= \alpha \langle 1, 2\sqrt{3} \rangle \text{ for some } \alpha \end{aligned}$$

$$\begin{aligned} \bullet 0.7 &= D_{\vec{u}} f(0,0) = \nabla f(0,0) \cdot \frac{1}{\sqrt{2}} \langle 1, 1 \rangle = \frac{\alpha}{\sqrt{2}} (1 + 2\sqrt{3}) \\ \Rightarrow \nabla f(0,0) &= \left\langle \frac{\sqrt{2}(0.7)}{1+2\sqrt{3}}, \frac{2\sqrt{2}\sqrt{3}(0.7)}{1+2\sqrt{3}} \right\rangle \approx \langle 0.22, 0.77 \rangle \end{aligned}$$