

SA 3. (5 marks)

Match each function $f(t)$ with its Laplace transform $F(s)$ in the table below.
 (The function $u(t)$ denotes the unit step function.)

	$F(s)$		$f(t) (t \geq 0)$
A	$\frac{5(s+1)}{(s^2+2s+2)(s-1)}$	D	$t + e^{2t-4}u(t-2) + (t-1)e^{t-2}u(t-2)$
B	$\frac{2}{(s^2+1)^2}$	E	$e^{-t+1}u(t-1)[\cos(t-1) + \sin(t-1)]$
C	$\frac{1}{s^2} + \frac{2e^{-s}}{s^3} + \frac{e^{-2s}}{s+1}$	F	$1 - 4e^{-t}\sin(t)$
D	$\frac{1}{s^2} + \frac{e^{-2s}}{s-2} + \frac{e^{-2s}s}{(s-1)^2}$	B	$\sin(t) - t \cos(t)$
E	$\frac{e^{-s}(s+2)}{(s^2+2s+2)}$	C	$t + (t-1)^2u(t-1) + e^{-t+2}u(t-2)$
F	$\frac{s^2-2s+2}{s(s^2+2s+2)}$	A	$2e^t - 2e^{-t}\cos(t) + e^{-t}\sin(t)$

SA 4. (5 marks)

Consider a system where an input signal $x(t)$ is related to an output signal $y(t)$ by the differential equation

$$y'' + y' + y = ax' + x$$

Suppose the input is given by $x(t) = \sin(5t)$. Use the transfer function $H(s) = Y(s)/X(s)$ (assuming all initial values for $x(t)$ and $y(t)$ are zero) to find the range of values for the parameter $a > 0$ such that the steady state response satisfies $|y_{ss}(t)| < 1$.

Apply the Laplace Transform:

$$s^2 Y(s) + s Y(s) + Y(s) = a s X(s) + X(s)$$

$$\Rightarrow H(s) = \frac{Y(s)}{X(s)} = \frac{as + 1}{s^2 + s + 1}$$

$$\text{Then } |y_{ss}(t)| \leq |H(5j)|$$

$$|H(5j)| = \left| \frac{a5j + 1}{(5j)^2 + 5j + 1} \right| = \left| \frac{1 + j5a}{-24 + j5} \right| = \frac{\sqrt{1 + 25a^2}}{\sqrt{24^2 + 25}}$$

$$\Rightarrow |y_{ss}(t)| < 1 \quad \text{if} \quad \sqrt{\frac{1 + 25a^2}{24^2 + 25}} < 1$$

$$\Rightarrow \frac{1 + 25a^2}{24^2 + 25} < 1 \quad \Rightarrow \quad 1 + 25a^2 < 24^2 + 25$$

$$a < \sqrt{\frac{24^2 + 24}{25}} = \sqrt{24} \approx 4.9$$

$$\boxed{a < \sqrt{24} \approx 4.9}$$

(c) [5 marks] The spring is placed at the seatback $d_k = l = 0.3\text{m}$. Where should the damper be placed so that the system is critically damped?

$$10.225\ddot{\theta} + 800d_c^2\dot{\theta} + 1000d_k^2\theta = 22.7a$$

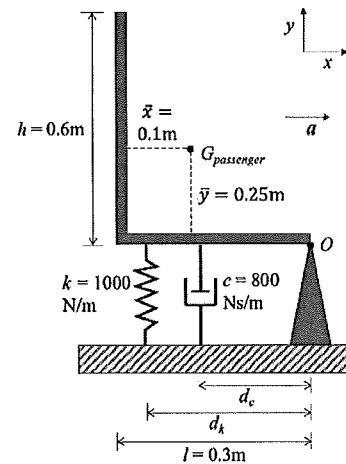
System is critically
damped when

$$(800d_c^2)^2 - 4(10.225)(1000d_k^2) = 0$$

$$\Rightarrow 800d_c^2 = \sqrt{4(10.225)(1000)(0.3)^2}$$

$$d_c = \sqrt{\frac{\sqrt{4(10.225)(1000)(0.3)^2}}{800}}$$

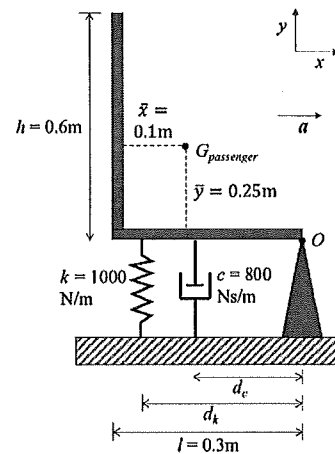
$$d_c \approx 0.275\text{m}$$



(d) [8 marks] The spring is placed at the seatback $d_k = l = 0.3m$, and the damper is placed at $d_c = 0.26m$. The train accelerates at the rate

$$a(t) = 2.6te^{-0.1t}$$

(in m/s^2) so that train nearly reaches 1G ($9.81m/s^2$) after 10 seconds and then the train reaches a steady speed after 60 seconds. Find the general solution of the equation of motion in part (b).



$$10.225\ddot{\theta} + 800d_c^2\dot{\theta} + 1000d_k^2\theta = 22.7a$$

$$\Rightarrow 10.225\ddot{\theta} + 54.08\dot{\theta} + 90\theta = 59.02te^{-0.1t}$$

Complementary solution: $p(s) = 10.225s^2 + 54.08s + 90$

$$s = \frac{-54.08 \pm \sqrt{54.08^2 - 4(10.225)(90)}}{2(10.225)} = -2.644 \pm 1.345i$$

$$\Rightarrow \theta_c(t) = C_1 e^{-2.644t} \cos(1.345t) + C_2 e^{-2.644t} \sin(1.345t)$$

Particular solution: $\theta_p(t) = (At + B)e^{-0.1t}$

$$\begin{aligned} \dot{\theta}_p(t) &= Ae^{-0.1t} - 0.1(At + B)e^{-0.1t} \\ &= (A - 0.1B)e^{-0.1t} - 0.1At e^{-0.1t} \end{aligned}$$

$$\begin{aligned} \ddot{\theta}_p(t) &= -0.1(A - 0.1B)e^{-0.1t} - 0.1Ae^{-0.1t} + 0.1^2 At e^{-0.1t} \\ &= (-0.2A + 0.1^2 B)e^{-0.1t} + 0.1^2 At e^{-0.1t} \end{aligned}$$

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$$\begin{aligned} & 10.225 \ddot{\theta}_p + 54.08 \dot{\theta}_p + 90 \theta_p \\ &= \left((10.225)(0.1^2 A) + 54.08(-0.1 A) + 90 A \right) t e^{-0.1 t} \\ &+ \left((10.225)(-0.2 A + 0.1^2 B) + (54.08)(A - 0.1 B) + 90 B \right) e^{-0.1 t} \\ &= 59.02 t e^{-0.1 t} \end{aligned}$$

$$\Rightarrow 84.694 A = 59.02 \quad \Rightarrow A = 0.697$$

$$\begin{aligned} \Rightarrow (10.225)(-0.2)(0.697) + (54.08)(0.697) + 84.694 B &= 0 \\ \Rightarrow B &= -0.428 \end{aligned}$$

$$\boxed{\Rightarrow \theta_p(t) = (0.697 t - 0.428) e^{-0.1 t}}$$

$$\underline{\theta(t) = \theta_c(t) + \theta_p(t)}$$