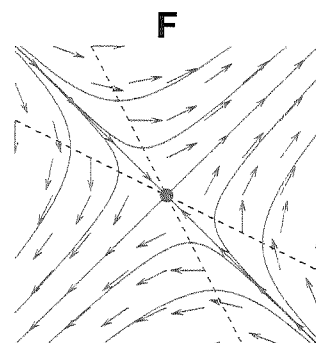
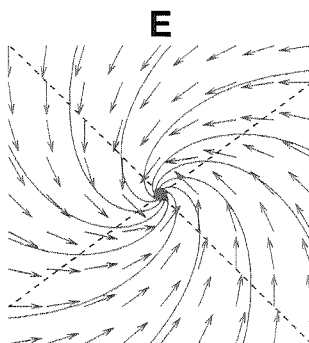
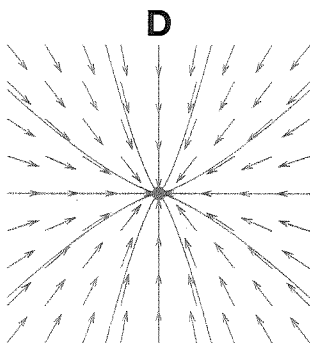
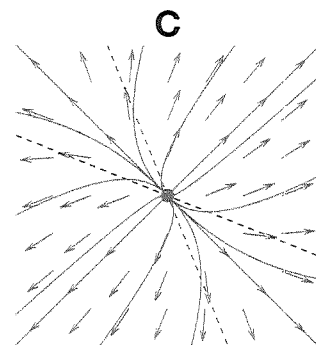
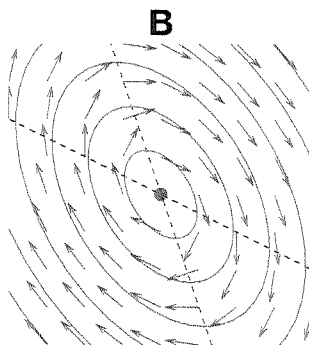
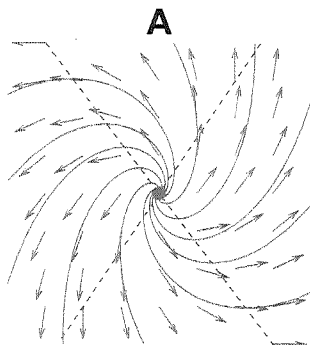


**SA 1. [5 marks]**

Each figure is the phase portrait of a linear system  $\dot{x} = Ax$  for some matrix  $A$ . Match each figure with the corresponding matrix in the table below.



C	$\begin{bmatrix} 5 & 2 \\ 2 & 5 \end{bmatrix}$		F	$\begin{bmatrix} 2 & 4 \\ 4 & 2 \end{bmatrix}$
D	$\begin{bmatrix} -3 & 0 \\ 0 & -4 \end{bmatrix}$		A	$\begin{bmatrix} 3 & -2 \\ 4 & 3 \end{bmatrix}$
B	$\begin{bmatrix} 1 & 2 \\ -3 & -1 \end{bmatrix}$		E	$\begin{bmatrix} -3 & -3 \\ 3 & -4 \end{bmatrix}$

**SA 2. [5 marks]**

Find values  $a$ ,  $b$ ,  $c$  and  $d$  such that  $x_1(t)$  is a solution of the linear system of equations  $\dot{x} = Ax$  where

$$x_1(t) = \begin{bmatrix} 1 \\ 0 \\ 2 \\ -1 \end{bmatrix} e^{-3t} \quad A = \begin{bmatrix} a & 1 & b & 2 \\ -1 & 1 & c & -1 \\ b & 2 & 1 & a \\ c & -1 & d & 1 \end{bmatrix}$$

We must have  $A\vec{x}_1 = \dot{\vec{x}}_1$

$$A\vec{x}_1 = \begin{bmatrix} a & 1 & b & 2 \\ -1 & 1 & c & -1 \\ b & 2 & 1 & a \\ c & -1 & d & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 2 \\ -1 \end{bmatrix} e^{-3t} = \begin{bmatrix} a+2b-2 \\ -1+2c+1 \\ b+2-a \\ c+2d-1 \end{bmatrix} e^{-3t}$$

$$\dot{\vec{x}}_1 = \begin{bmatrix} -3 \\ 0 \\ -6 \\ 3 \end{bmatrix} e^{-3t} \Rightarrow \begin{aligned} a+2b-2 &= -3 & (1) \\ 2c &= 0 & (2) \\ -a+b+2 &= -6 & (3) \\ c+2d-1 &= 3 & (4) \end{aligned}$$

$$(1) \text{ and } (3) \Rightarrow \begin{aligned} a+2b &= -1 \\ -a+b &= -8 \\ \hline 3b &= -9 \end{aligned} \quad \begin{aligned} \boxed{b} &= \boxed{-3} \\ \boxed{a} &= \boxed{5} \end{aligned}$$

$$(2) \text{ and } (4) \Rightarrow \boxed{c} = \boxed{0} \quad \boxed{d} = \boxed{2}$$

Equivalently, we must have  $\begin{bmatrix} 1 \\ 0 \\ 2 \\ -1 \end{bmatrix}$  is an eigenvector of  $A$  with eigenvalue  $\lambda = -3$

$$\Rightarrow A \begin{bmatrix} 1 \\ 0 \\ 2 \\ -1 \end{bmatrix} = \begin{bmatrix} -3 \\ 0 \\ -6 \\ 3 \end{bmatrix}$$

(c) [2 marks] Write equations (1) and (2) in matrix form  $\dot{\mathbf{v}} = A\mathbf{v}$  as a two-dimensional, first-order, linear, homogeneous system of equations.

$$\frac{dv_a(t)}{dt} + \frac{1}{C} \left( \frac{1}{R_1} + \frac{1}{R_2} \right) v_a(t) - \frac{1}{R_2 C} v_b(t) = 0 \quad (1)$$

$$-\frac{dv_a(t)}{dt} + 2\frac{dv_b(t)}{dt} + \frac{R_2}{L} v_b(t) = 0 \quad (2)$$

$$(1) \Rightarrow \boxed{\dot{v}_a = -\frac{1}{C} \left( \frac{1}{R_1} + \frac{1}{R_2} \right) v_a + \frac{1}{R_2 C} v_b}$$

$$(2) \Rightarrow \dot{v}_b = \frac{1}{2} \dot{v}_a - \frac{R_2}{2L} v_b$$

Plug (1) into (2)

$$\dot{v}_b = \frac{1}{2} \left( -\frac{1}{C} \left( \frac{1}{R_1} + \frac{1}{R_2} \right) v_a + \frac{1}{R_2 C} v_b \right) - \frac{R_2}{2L} v_b$$

$$\boxed{\dot{v}_b = -\frac{1}{2C} \left( \frac{1}{R_1} + \frac{1}{R_2} \right) v_a + \left( \frac{1}{2R_2 C} - \frac{R_2}{2L} \right) v_b}$$

$$\Rightarrow \boxed{\begin{bmatrix} \dot{v}_a \\ \dot{v}_b \end{bmatrix} = \begin{bmatrix} -\frac{1}{C} \left( \frac{1}{R_1} + \frac{1}{R_2} \right) & \frac{1}{R_2 C} \\ -\frac{1}{2C} \left( \frac{1}{R_1} + \frac{1}{R_2} \right) & \frac{1}{2R_2 C} - \frac{R_2}{2L} \end{bmatrix} \begin{bmatrix} v_a \\ v_b \end{bmatrix}}$$

(d) [8 marks] When  $R_2 = 100 \Omega$ ,  $C = 0.01 F$  and  $L = 1 H$ , the system of equations is

$$\begin{bmatrix} \dot{v}_a \\ \dot{v}_b \end{bmatrix} = \begin{bmatrix} -\frac{100}{R_1} - 1 & 1 \\ -\frac{50}{R_1} - \frac{1}{2} & -49.5 \end{bmatrix} \begin{bmatrix} v_a \\ v_b \end{bmatrix}.$$

In this case, find a range of values for  $R_1$  such that  $v_a(t)$  and  $v_b(t)$  oscillate as they decay to their steady-state values (i.e., they exhibit an underdamped response).

Let  $A = \begin{bmatrix} -\frac{100}{R_1} - 1 & 1 \\ -\frac{50}{R_1} - \frac{1}{2} & -49.5 \end{bmatrix}$  we need eigenvalues of  $A$  to be complex

Characteristic polynomial:  $\det(A - \lambda I)$

$$= \lambda^2 - \left(-\frac{100}{R_1} - 1 - 49.5\right)\lambda + \left(49.5\left(\frac{100}{R_1} + 1\right) + \left(\frac{50}{R_1} + \frac{1}{2}\right)\right)$$

$$= \lambda^2 + \left(\frac{100}{R_1} + 50.5\right)\lambda + \left(\frac{5000}{R_1} + 50\right)$$

We must have  $\left(\frac{100}{R_1} + 50.5\right)^2 - 4\left(\frac{5000}{R_1} + 50\right) < 0$

$$\Rightarrow (100 + 50.5R_1)^2 - 20000R_1 - 200R_1^2 < 0$$

$$2350.25R_1^2 - 9900R_1 + 10000 < 0$$

find roots.

$$R_1 = \frac{9900 \pm \sqrt{9900^2 - 4(2350.25)(10000)}}{2(2350.25)}$$

$$= \frac{9900 \pm 2000}{4700.5} = 1.681, 2.532$$

$$1.681 < R_1 < 2.532$$

(e) [7 marks] When  $R_1 = R_2 = 1 \Omega$ ,  $C = 1 F$  and  $L = 0.1 H$ , the system of equations is

$$\begin{bmatrix} \dot{v}_a \\ \dot{v}_b \end{bmatrix} = \begin{bmatrix} -2 & 1 \\ -1 & -4.5 \end{bmatrix} \begin{bmatrix} v_a \\ v_b \end{bmatrix}.$$

Find the general solution in this case.

Let  $A = \begin{bmatrix} -2 & 1 \\ -1 & -4.5 \end{bmatrix}$  Characteristic polynomial

$$\begin{aligned} \Rightarrow \det(A - \lambda I) &= \lambda^2 - (-6.5)\lambda + (9 + 1) \\ &= \lambda^2 + 6.5\lambda + 10 \end{aligned}$$

$$\begin{aligned} \Rightarrow \lambda &= \frac{-6.5 \pm \sqrt{6.5^2 - 4(10)}}{2} = \frac{-6.5 \pm 1.5}{2} \\ &= -4, -5/2 \end{aligned}$$

$$\lambda_1 = -4 \quad (A - \lambda_1 I) \vec{v}_1 = \vec{0}$$

$$\begin{bmatrix} 2 & 1 & | & 0 \\ -1 & -0.5 & | & 0 \end{bmatrix} \Rightarrow \vec{v}_1 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

$$\lambda_2 = -5/2 \quad (A - \lambda_2 I) \vec{v}_2 = \vec{0}$$

$$\begin{bmatrix} 0.5 & 1 & | & 0 \\ -1 & -2 & | & 0 \end{bmatrix} \Rightarrow \vec{v}_2 = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

$$\Rightarrow \boxed{\vec{v}(t) = \begin{bmatrix} v_a(t) \\ v_b(t) \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ -2 \end{bmatrix} e^{-4t} + c_2 \begin{bmatrix} 2 \\ -1 \end{bmatrix} e^{-\frac{5}{2}t}} \quad c_1, c_2 \in \mathbb{R}$$