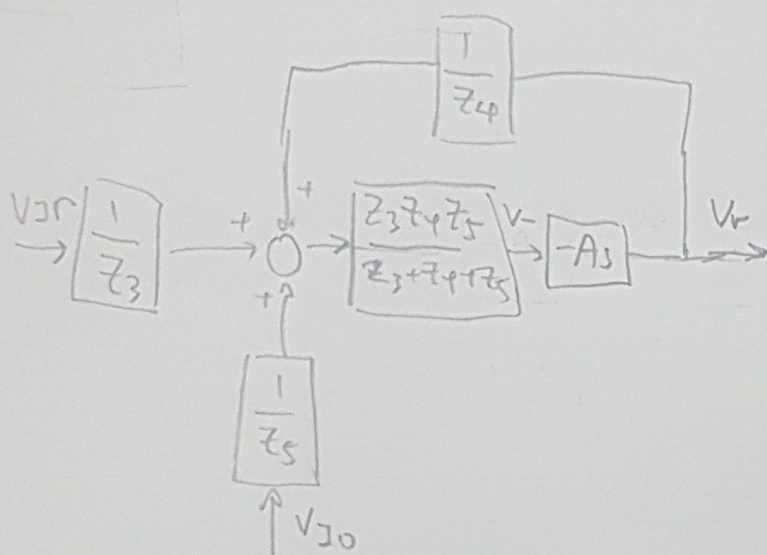


1a.

Ratnaman Pathology #63205165

$$V_r = A_s(s) (0 - V_-)$$

$$0 = \frac{V_- - V_{Ir}}{z_3} + \frac{V_- - V_r}{z_4} + \frac{V_- - V_{Io}}{z_5} \rightarrow V_- = \underbrace{\left(\frac{z_3 z_4 z_5}{z_3 + z_4 + z_5} \right)}_B \left(\frac{V_{Ir}}{z_3} + \frac{V_r}{z_4} + \frac{V_{Io}}{z_5} \right)$$



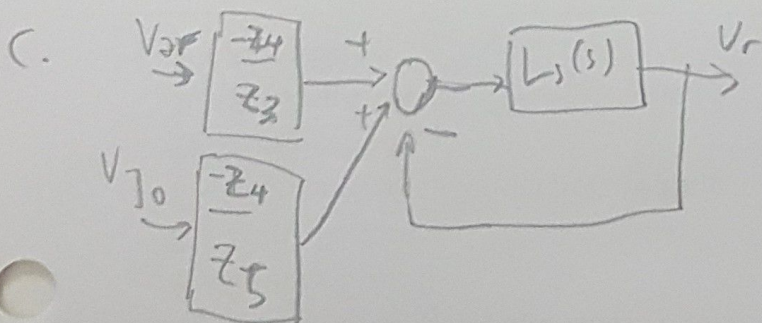
6. $L(s) = \left(\frac{z_3 z_5}{z_3 + z_4 + z_5} \right) (A_s(s)) = \frac{B}{z_4} A_s(s)$ make it positive so part C make sense

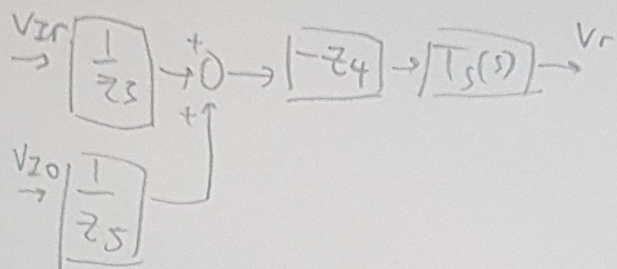
$$V_r = -A_s V_-$$

$$V_r = -A_s \left(B \right) \left(\frac{V_{Ir}}{z_3} + \frac{V_r}{z_4} + \frac{V_{Io}}{z_5} \right)$$

$$V_r = \frac{-A_s B}{z_3} V_{Ir} - \frac{A_s B}{z_4} V_r - \frac{A_s B}{z_5} V_{Io}$$

$$V_r = \underbrace{\frac{A_s B}{z_4}}_{L_s} \left(\left(\frac{-z_4}{z_3} V_{Ir} \right) - (V_r) + \left(\frac{-z_4}{z_5} V_{Io} \right) \right)$$





$$T_s = \frac{BA_1/z_4}{1 + BA_1/z_4} = \frac{L_s}{1 + L_s}$$

$$V_r (1 + L_s) = L_s (-z_4) \left(\frac{V_{zr}}{z_s} + \frac{V_{zo}}{z_s} \right)$$

$$V_r = \frac{L_s}{1 + L_s} (-z_4) \left(\frac{V_{zr}}{z_s} + \frac{V_{zo}}{z_s} \right)$$

2a. $L(j\omega) \Big|_{\omega \rightarrow 0} \rightarrow \infty \Rightarrow \frac{I_o}{V_{zr}} \Big|_{\omega \rightarrow 0} = \frac{-1}{R_3} \left(\frac{R_5}{R_1} \right)$

from lecture notes

$$\frac{2A}{10V} = \frac{1}{R_3} \left(\frac{1k}{.2} \right)$$

$$R_3 = \frac{1000}{.2} \left(\frac{10}{2} \right) \Omega = 25k\Omega$$

2b. $L(s) = \left(\frac{1}{R_4 s} + R_4 \right) T_s(s) \left(\frac{R_1 + R_2}{R_1} \right) T_d(s) \left(\frac{1}{1ms + R_{in} + R_s} \right) \left(\frac{R_1}{R_5} \right)$

$C_4 = \infty$ 1 94.4 Hz 300 kHz

$$= R_4 \left(\frac{10k}{1k} \right) \left(\frac{1}{1ms + 6} \right) \left(\frac{.2}{1k} \right)$$

$$= \frac{2R_4}{5 + 6000}$$

Using MATLAB $\rightarrow \phi_m = 90.2 \text{ deg} \gg 90^\circ$

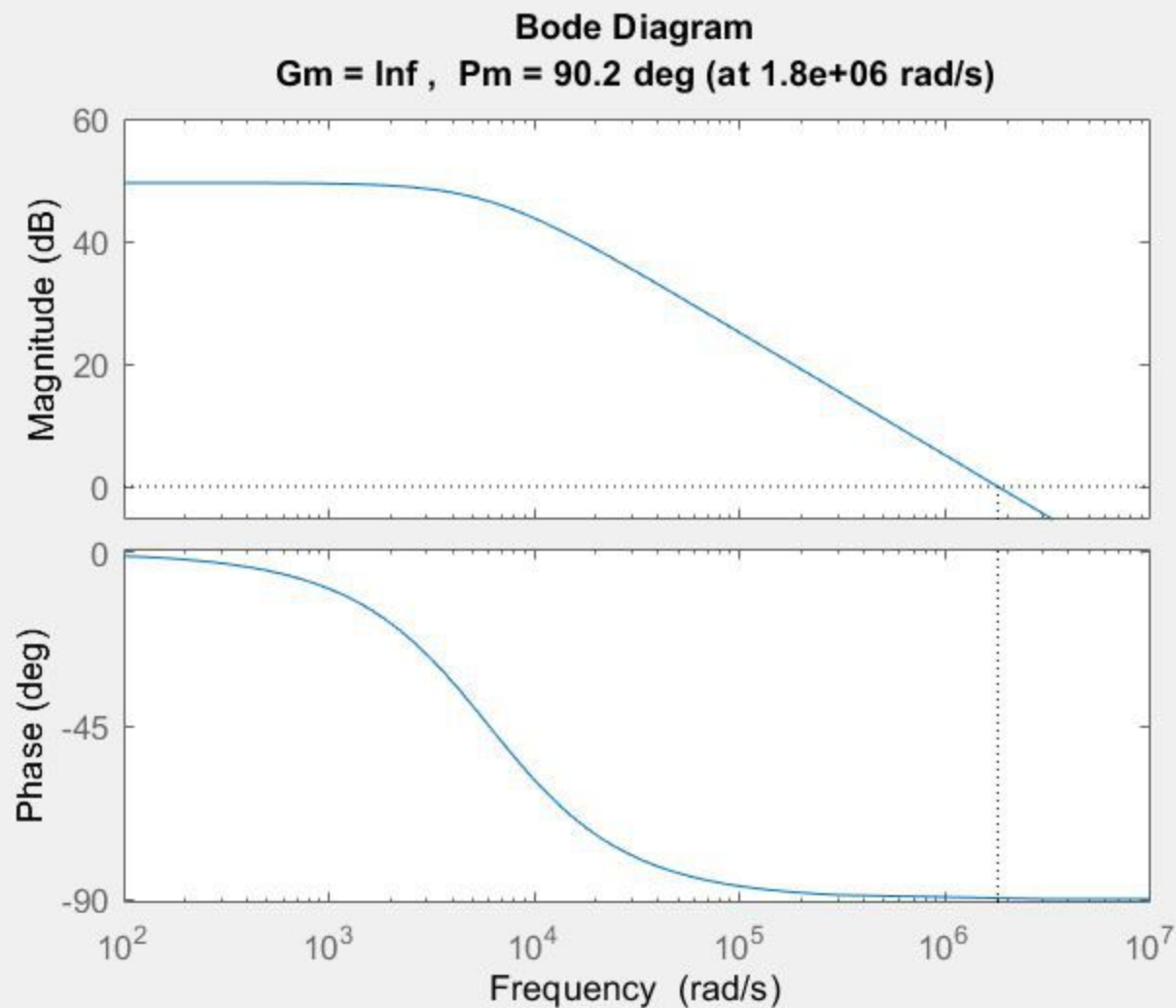
$$\omega_c = 1.8 \times 10^4 \text{ rad/s} = 286 \text{ kHz} \leq 300 \text{ kHz}$$

$$R_4 = 950k\Omega$$

```
1 - r4 = 900000;  
2 - sys = tf([2*r4], [1 6000]);  
3 - margin(sys);
```

Figure 1

File Edit View Insert Tools Desktop Window Help



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$$L(s) = \left(\frac{1}{Cs} + 900k \right) \left(\frac{2}{s+6000} \right) = \frac{2(1 + C4900ks)}{Cs(s+6000)}$$

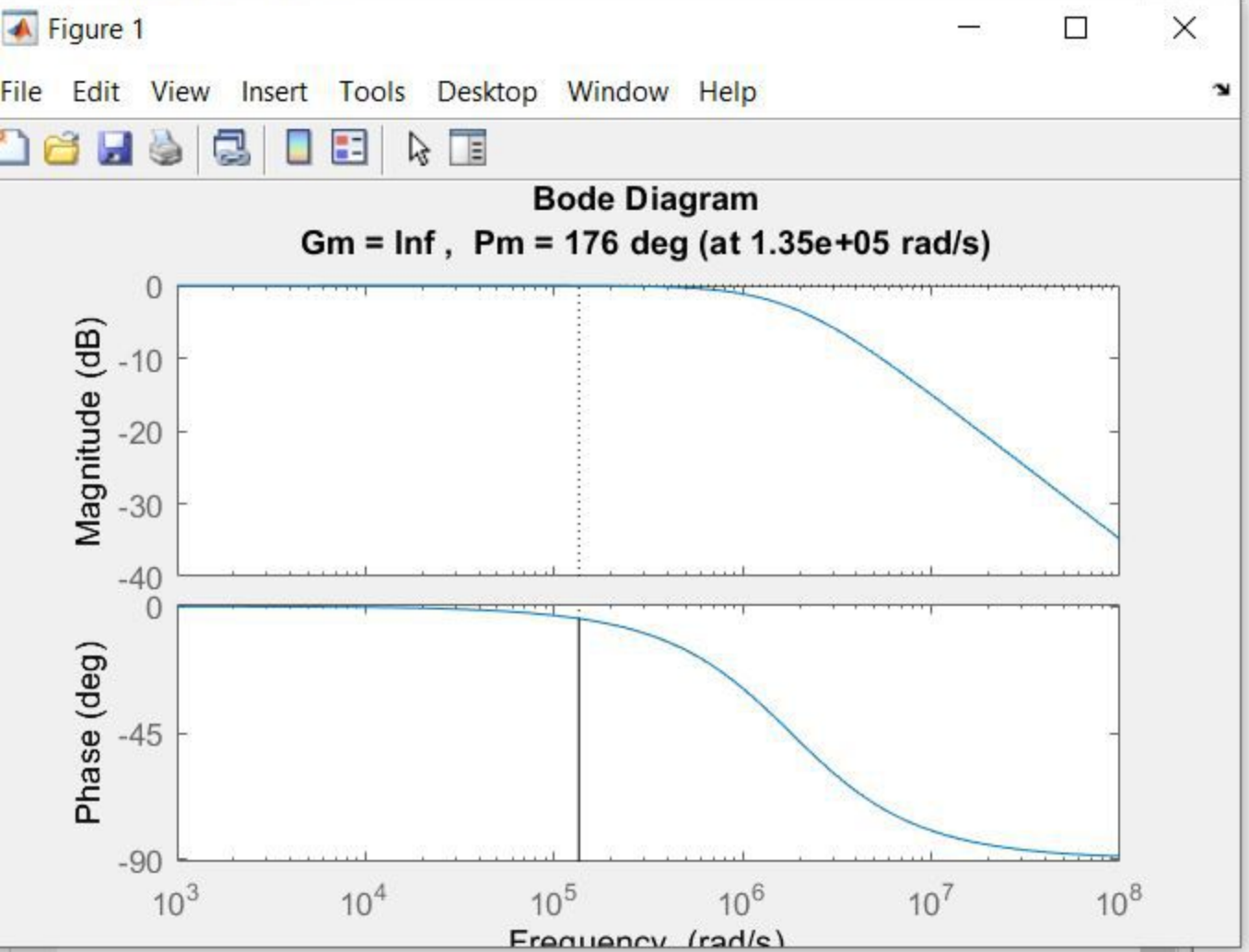
$$G(s) = \frac{L(s)}{1+L(s)}$$

Using MATLAB $\rightarrow \omega_c = 1.25 \times 10^5 \leq 300kHz$

$$\phi_m = 176^\circ$$

$$C_p = 0.1nF$$

```
1 - r4 = 900000;  
2 - %sys = tf([2*r4], [1 6000]);  
3 - %margin(sys);  
4 - c4 = .00000000001;  
5 - sys = tf([r4*c4*2 2], [c4 6000*c4 0]);  
6 - sys = sys/(1+sys);  
7 - margin(sys);
```



2d.

$$L(s) = T_s(s) \left(\frac{1}{.1n s} + 900k \right) \frac{z}{s+6000}$$

from Q1: $T_s = \frac{BA_s/z_4}{1 + BA_s/z_4}$

$$= \frac{z_3 z_5}{z_3 + z_4 + z_5 + z_3 z_5}$$

$$= \frac{(25k) 1k}{25k + \frac{1}{.1n s} + 900k + 1k + 25k(1k)}$$

$$= \frac{(25k) 1k}{25k + \frac{1}{.1n s} + 900k + 1k + 25k(1k)}$$

$$G(s) = \frac{L(s)}{1 + L(s)}$$

```

r4 = 900000;
%sys = tf([2*r4], [1 6000]);
%margin(sys);
c4 = .1*10^(-9);
sys = tf([r4*c4*2 2], [c4 6000*c4 0]);
z4 = tf([r4*c4 1], [c4 0]);
Ts = 25000*1000/(25000+z4+1000+25000*1000);
sys = Ts*sys;
sys = sys/(1+sys);
margin(sys);

```

and Window

o MATLAB? See resources for [Getting Started](#).

hw4
hw4
hw4
hw4
hw4
hw4
hw4
hw4
hw4

