

Lecture 15

Energy Relationships

$$V = \frac{1}{2} \vec{q}^T [K] \vec{q} > 0 \text{ for } \vec{q} \neq 0$$

$$T = \frac{1}{2} \dot{\vec{q}}^T [M] \dot{\vec{q}} > 0 \text{ for } \dot{\vec{q}} \neq 0$$

$$R = \frac{1}{2} \dot{\vec{q}}^T [C] \dot{\vec{q}} \geq 0 \text{ for } \dot{\vec{q}} \neq 0$$

$V=0$ @ equilibrium

"Positive definite"

$$\frac{1}{2} \vec{q}^T [K] \vec{q} > 0 \text{ for stable system}$$

$$\geq 0 \text{ for neutral system}$$

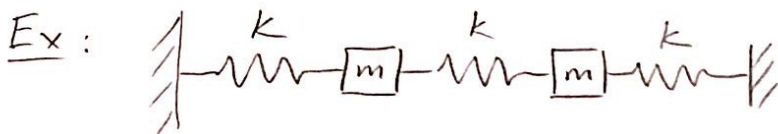
$[K]$ is positive semi-definite

$$\frac{1}{2} \vec{q}^T [K] \vec{q} \text{ can be anything}$$

Test for positive definite

$$\begin{bmatrix} * & * & * & * \\ * & * & * & * \\ * & * & * & * \\ * & * & * & * \end{bmatrix}$$

Require at diagonal determinants > 0



$$[K] = \begin{bmatrix} 2k & -k \\ -k & 2k \end{bmatrix}$$

$$\text{minors} = 2k, 3k^2$$

Both $> 0 \rightarrow$ positive definite



$$[k] = \begin{bmatrix} k & -k \\ -k & k \end{bmatrix}$$

$$\text{minors} = k, 0$$

\rightarrow Positive semi-definite

Orthogonality of Mode shapes

Recall $([K] - \omega^2[M])\vec{u} = \vec{0}$ where \vec{u} is mode shape

$\Rightarrow \omega^2[M]\vec{u} = [K]\vec{u}$ generalized Eigenvalue problem

$\hookrightarrow \vec{u} = \text{mode shape} = \text{eigenvector}$

$\hookrightarrow \omega^2 = (\text{natural frequency})^2 = \text{eigenvalue}$

Note:  Dot product $\vec{q}_1 \cdot \vec{q}_2 \leftrightarrow \vec{q}_1^T \vec{q}_2$

For eigenvector "r": $\omega_r^2 [M]\vec{u}_r = [K]\vec{u}_r$

eigenvector "s": $\omega_s^2 [M]\vec{u}_s = [K]\vec{u}_s$

Premultiply \vec{u}_s^T : $\omega_r^2 \vec{u}_s^T [M]\vec{u}_r = \vec{u}_s^T [K]\vec{u}_r$

\vec{u}_r^T : $\omega_s^2 \vec{u}_r^T [M]\vec{u}_s = \vec{u}_r^T [K]\vec{u}_s$

Consider $\vec{u}_s^T [M]\vec{u}_r = \sum_i \sum_j u_{si} M_{ij} u_{rj}$

$= \sum_i \sum_j u_{rj} M_{ij} u_{si} \leftarrow \text{Rearrange}$

$= \sum_j \sum_i u_{rj} M_{ij} u_{si} \leftarrow \text{Reverse sum order}$

$= \sum_i \sum_j u_{ri} M_{ji} u_{sj} \leftarrow \text{Rename } i \leftrightarrow j$

$= \sum_i \sum_j u_{ri} M_{ij} u_{sj} \leftarrow \text{Note } [M] \text{ is symmetric}$

$= \vec{u}_r^T [M]\vec{u}_s$

$\Rightarrow \vec{u}_s^T [M]\vec{u}_r = \vec{u}_r^T [M]\vec{u}_s$ Similarly for $[K]$

Sub into $\omega_r^2 \vec{u}_s^T [M] \vec{u}_r = \vec{u}_s^T [K] \vec{u}_r$

$$\omega_r^2 \vec{u}_r^T [M] \vec{u}_s = \vec{u}_r^T [K] \vec{u}_s$$

Also $\omega_s^2 \vec{u}_s^T [M] \vec{u}_s = \vec{u}_s^T [K] \vec{u}_s$

Subtract: $(\omega_r^2 - \omega_s^2) \vec{u}_r^T [M] \vec{u}_s = 0$

$$\Rightarrow \vec{u}_r^T [M] \vec{u}_s = 0 \text{ for } \omega_r \neq \omega_s$$