

16 bit - int

0 0000 0000 1111 0111 1111
255 1111 1111

int x

* Always declared unsigned explicitly

unsigned int x = 0;

Global Variables

```
int global_var;
```

```
int main (void)
```

```
{  
}
```

```
int myISR ( )
```

```
{  
}
```

- Variables can fail to update across subroutines because of compiler optimization.

- Define as "volatile"

- turn off compiler optimization

volatile unsigned int global_var = 0;

MCU Programming Structures

1. Polling — constantly checking

```
int main ( )
```

```
{ while (1)
```

```
{ if (PIN & BIT3)
```

```
// do something
```

```
}
```

- Can still miss events.

2. Interrupt - driven Programming

```
int main ( )
```

```
// Enable local interrupts
```



```
// Set up registers { Enable global interrupts  
while (1);
```

```
#pragma ...  
// ISR ← most of your code.
```

Problem: While ISR is executing, no other interrupts can be serviced.

For example, UART at 9600 baud
1 bit = 833 clock cycles (clock = 8 MHz)
1 byte \approx 8400 clock cycles

Event-driven Programming

```
#pragma ...  
// ISR ← keep minimal  
e.g. for UART Rx — get byte from Rx buffer  
// Set a software flag
```

```
int main()
```

```
    // Set up registers
```

```
    // Enable interrupts
```

```
    while (1)
```

```
    { If (flag == True)
```

```
        { // Event handler
```

```
            // Flag = 0;
```

```
        If (flag2 == True)
```

```
            ...
```

```
    }
```

} can be interrupted.

Lab #2 Exam

5 Exercises ——— Yes/No outcome

Total time : 2.5 hours Open Computer.

	<u>Completion</u>	<u>Grade</u>	<u>Time</u>	<u>Grade</u>
1	20%		20%	
2	40%		20%	
3	60%		20%	
4	80%		10%	
5	90%		10%	

① Be organized

② Don't panic