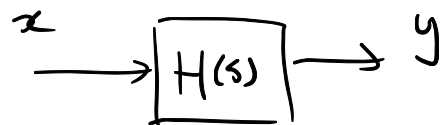


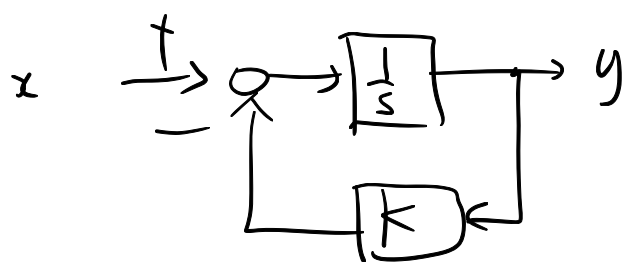
L20 - Nyquist Test

- Stability of LTZ sys



Stable $\iff \operatorname{Re}\{p_i\} < 0$ for all i .

- ① Directly finding CL poles.



$$\frac{Y}{X} = \frac{\frac{1}{s}}{1 + \frac{K}{s}} = \frac{1}{s+K}$$

stable $\iff K > 0$.

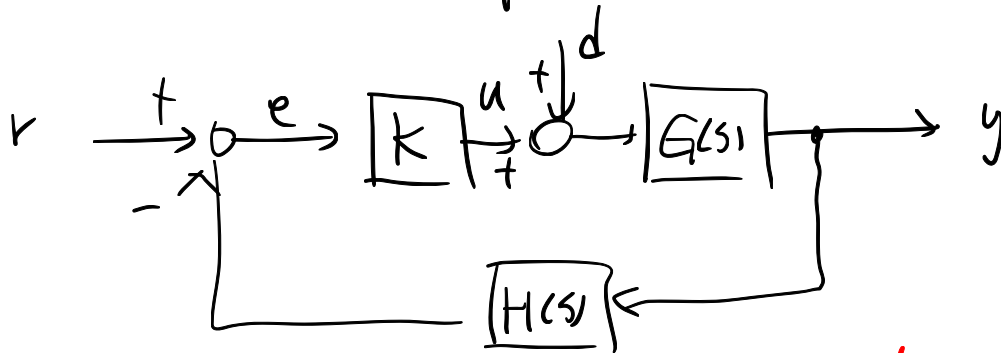
- ② Infer the CL poles. from $L(s)$.

i) Root Locus: the locations of CL poles (explicit).

ii) Nyquist test: the number of CL poles in RHP (implicit)

\Rightarrow "Loop Analysis". $L(s)$

- Characteristic eqn: $f(s) = 0$.



$$\begin{bmatrix} Y \\ U \end{bmatrix} = \underbrace{\begin{bmatrix} \frac{KG}{1+KGH} & \frac{G}{1+KGH} \\ \frac{K}{1+KGH} & -\frac{KGH}{1+KGH} \end{bmatrix}}_{\text{"Matrix"}} \begin{bmatrix} R \\ D \end{bmatrix}.$$

$$= \frac{1}{1+KGH} \begin{bmatrix} KG & G \\ K & -KGH \end{bmatrix} \begin{bmatrix} R \\ D \end{bmatrix}.$$

- CL system is stable $\Leftrightarrow \frac{1}{1+KGH} = S(s)$
No poles in RHP.

Q. What if $G(s)$ has RHP poles? $S = P_0$

$$\left. \frac{G}{1+KGH} \right|_{s=p_0} = \frac{\overset{\infty}{G(p_0)}}{1+K \cancel{G} H} = \left| \frac{1}{KH(p_0)} \right| < \infty$$

A. p_0 is not the pole of $\frac{G}{1+KGH}$ anymore.

• poles of $\frac{1}{1+KGH}$ \iff zeros of $\underline{1+KGH}$.

$$= 1+L(s) \triangleq f(s)$$

• For stability, $\underline{f(s)=0}$ No roots on RHP.
"Char Eqn"

• Root Locus.

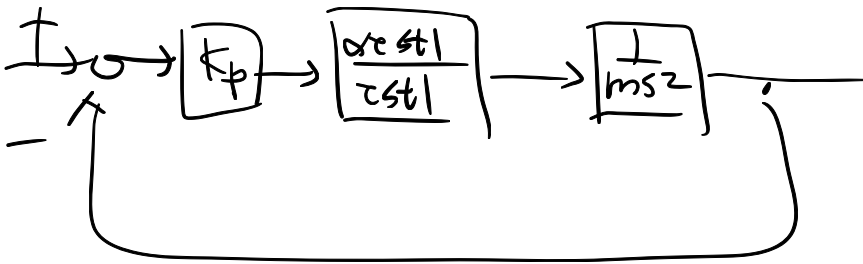
• Infer the locations of CL poles! $\nearrow \frac{1}{1+L(s)}$
 \iff zeros of $1+L(s) \triangleq \underline{f(s)}$

• Shows how the zeros of $f(s)$ move.

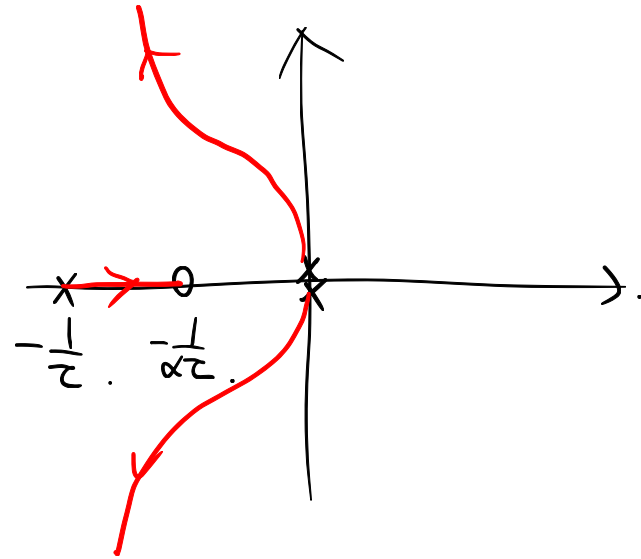
$$1+KG(s)H(s)=0 \Rightarrow \underline{G(s)H(s) = -\cancel{\frac{1}{K}}}$$

- ① when $k \rightarrow \infty$. roots of $f(s) = 0 \rightarrow$ zeros of $L(s)$.
- ② when $k \rightarrow 0$. root of $f(s) = 0 \rightarrow$ poles of $L(s)$.
- ③ when $0 < k < \infty$, " \rightarrow $\star \nabla G(s_0) H(s_0) = 1 \neq 0$

Example.



$$L(s) = K_p \cdot \frac{s+1}{s^2+1} \cdot \frac{1}{ms^2}$$



Remark.

- $L(s) = \frac{a(s)}{b(s)}$ "Rational function"
- Can't handle e^{-sT} , \sqrt{s} .
- Different when many poles & zero.

Motivations

- No need for exact CL pole locations
- Just need to check "existence" of CL poles on PMP.

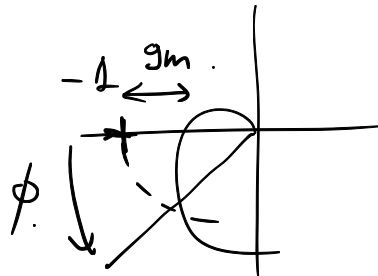
• Nyquist test.

- Infer the # of unstable CL poles from $L(s)$.

$$\left(\frac{1}{1+L}, \quad \begin{array}{l} \#L \triangleq \textcircled{P(s)} \\ \underline{P(s)=0} \end{array} \right)$$

- Requires less info on $L(s)$.
 - ① $L(j\omega)$
 - ② No of unstable poles of $L(s)$.

- Gm, ϕ_m \leftarrow Nyquist plot.

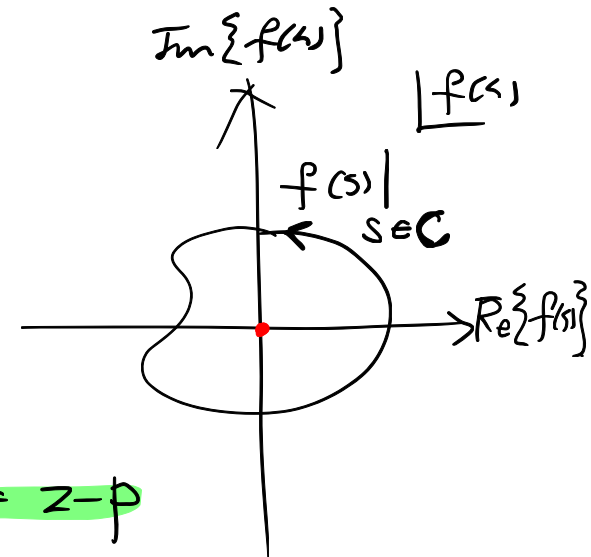
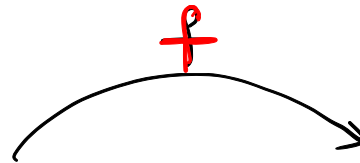
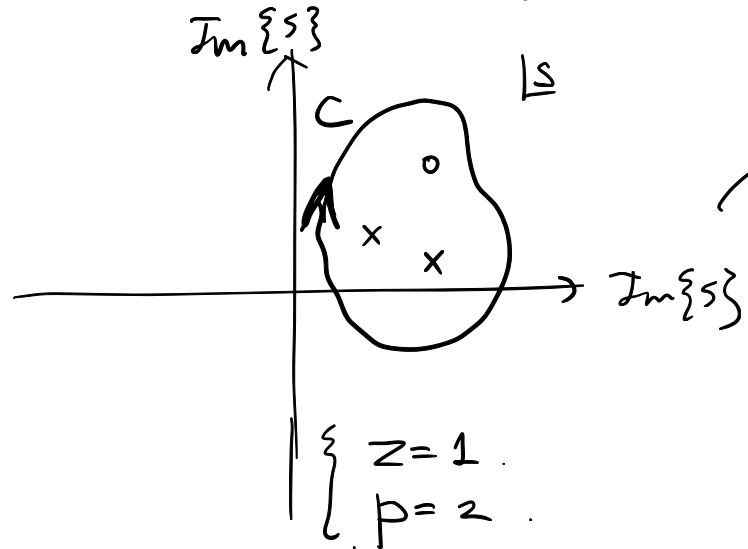


• Key Ideas

• CL poles \iff zeros of $f(s) \triangleq 1 + L(s)$.
 "Z"

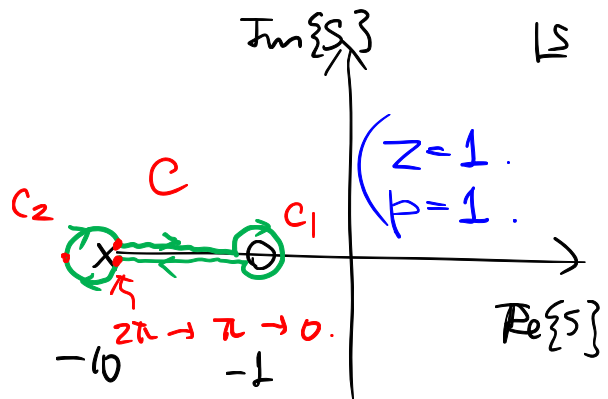
• Cauchy's Argument principle. : $f(s)$.

- Consider a complex fn $f: \mathbb{C} \rightarrow \mathbb{C}$.

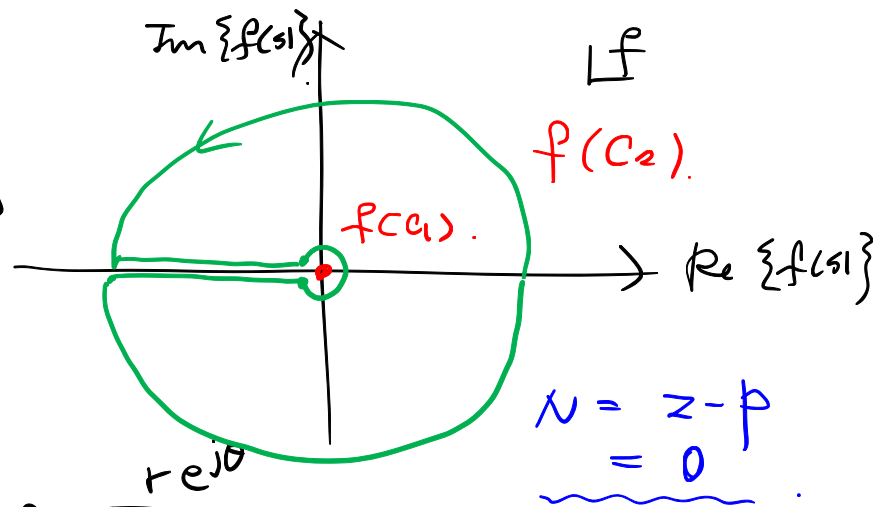


$$\begin{aligned} N &= Z - P \\ &= 1 - 2 \\ &= \underline{\underline{-1}} \end{aligned}$$

Example $f(s) = \frac{s+1}{s+10}$.



f



$$C_1: -1 + re^{j\theta}$$

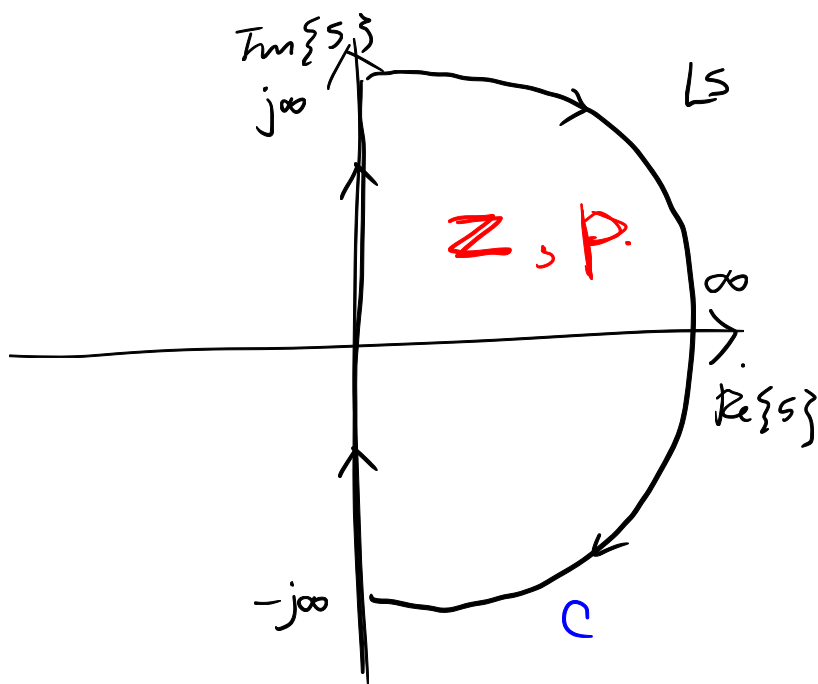
$$\rightarrow f(s)|_{s \in C_1} \approx \frac{re^{j\theta}}{9 + re^{j\theta}}$$

$$C_2: -10 + re^{j\theta}$$

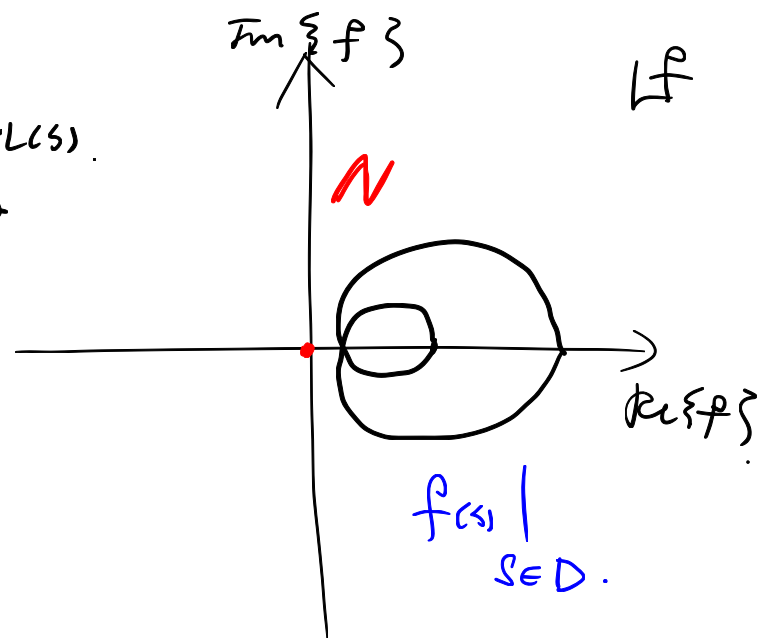
$$\rightarrow f(s)|_{s \in C_2} \approx \frac{-9 + re^{j\theta}}{re^{j\theta}} = \frac{9}{r} e^{j(\pi - \theta)}$$

$2\pi \rightarrow \pi \rightarrow 0$
 $-\pi \rightarrow 0 \rightarrow \pi$

° Apply it to $f(s) = 1 + L(s)$.
? zeros in RHP.



$$f(s) = 1 + L(s)$$



Z : # of zeros of $f(s) = 1 + L(s)$ inside D .

P : # of poles of $f(s) = 1 + L(s)$ inside D . \Leftrightarrow # of poles of $L(s)$ inside D .

N : # of cw encirclements of $f(s)|_{s \in D}$ about the origin.

$$\Rightarrow N = Z - P \Leftrightarrow \boxed{Z = N + P}$$

\downarrow
 $f(s)$

$Z = 0 \Rightarrow \text{Stability!}$

$$\vee f(s_0) \rightarrow \infty. \iff 1 + L(s_0) \rightarrow \infty$$

\Rightarrow poles of $f(s)$ = poles of $L(s)$.

