



MECH 420

Sensors and Actuators

Presentation Part 2

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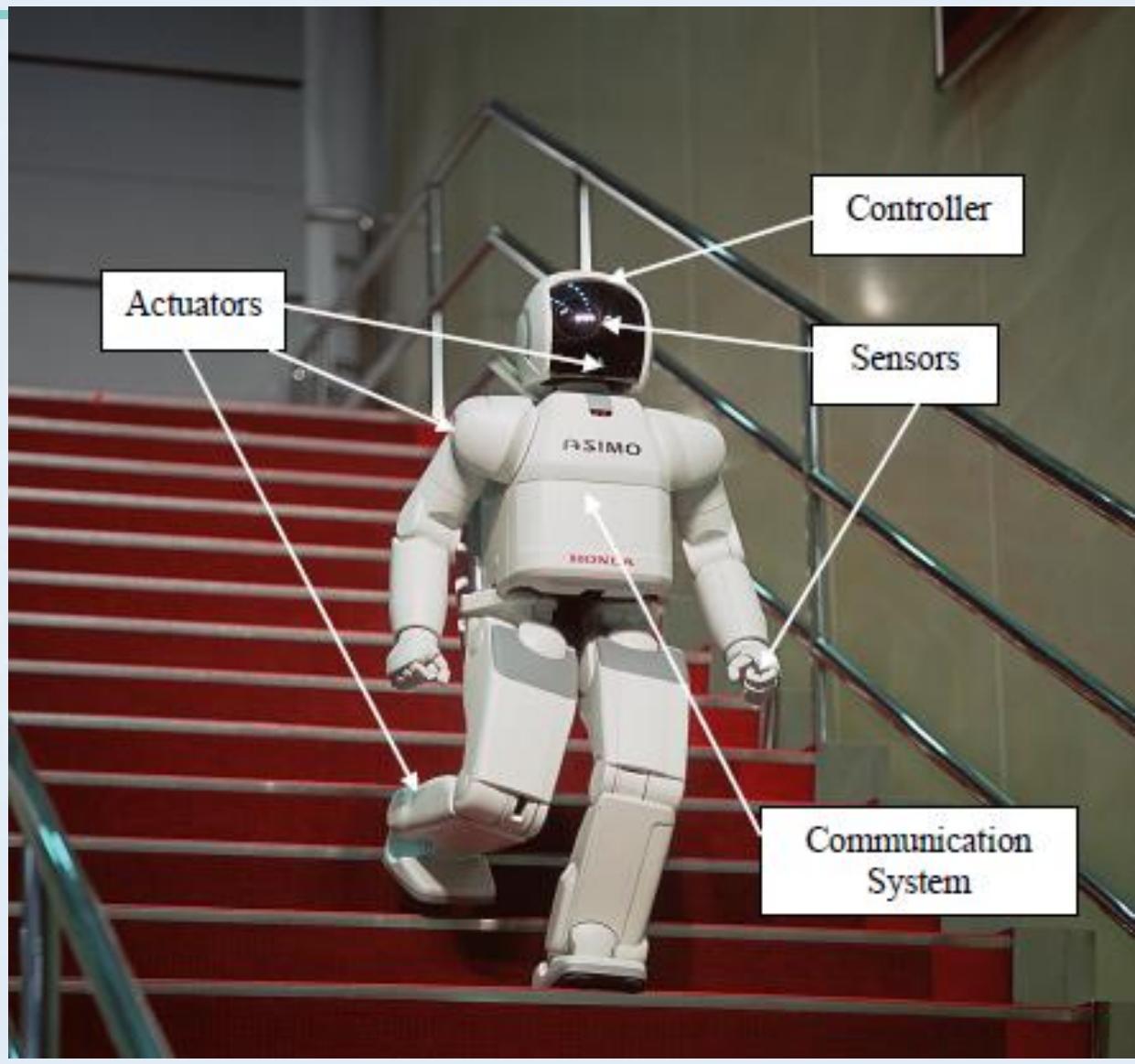
Part 2: Mechatronics & Instrumentation Process

- Mechatronics
- Instrumentation Process
- Examples

Mechatronics

Is this a mechatronic system?

Humanoid robot:

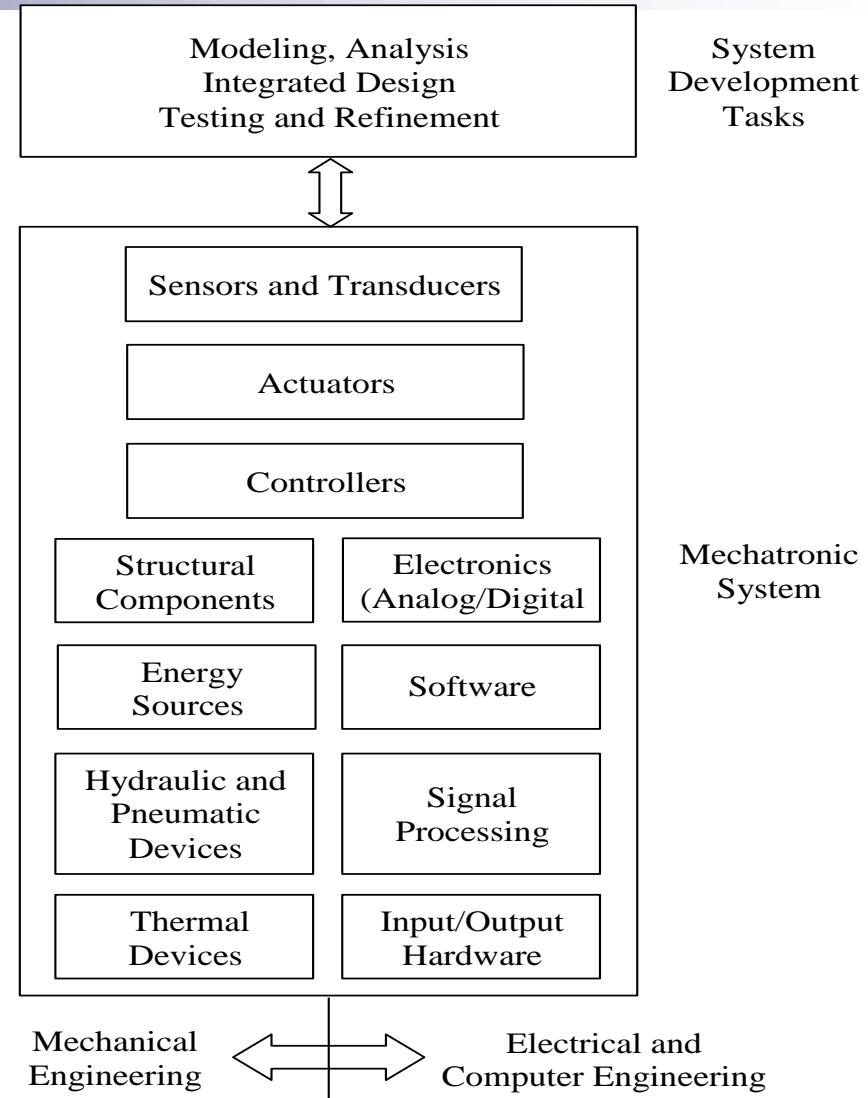


What is a Mechatronic System?

- An electromechanical system?
- A system with sensors, actuators, and controllers?
- A multi-physics system?
- A multi-domain system?
- A system designed by considering all domains/components simultaneously?
- A system designed by using similar (analogous) methods for the different domains?
- An optimized system?
- A system designed through a mechatronics approach?
Then, what is the mechatronic approach?

Mechatronics

- Origin of Term:
“MECHANics and elecTRONICS,”
Yasakawa Electric Co.,
1969
- Accepted Definition:
Synergistic application of mechanics, electronics, control engineering, and computer science in the development of **electromechanical** products and systems, through **integrated design**



Traditional Definition of Mechatronics

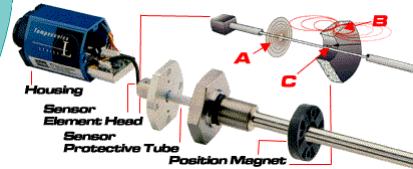
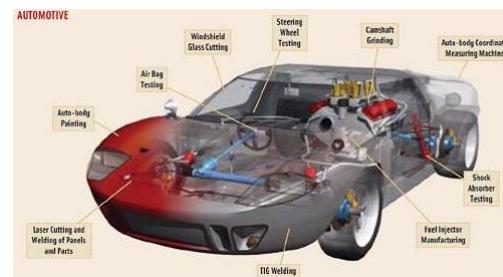
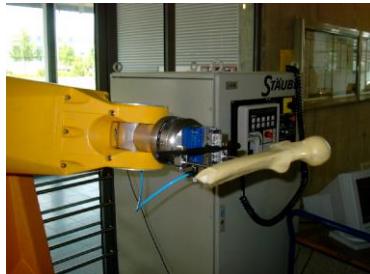
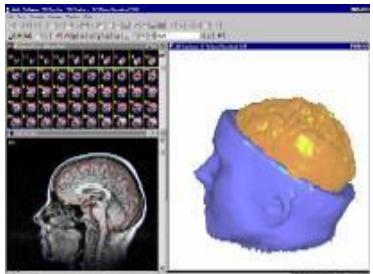


Information Technology
(Control & Computer
Engineering)

Mechanical
Engineering

Electrical
Engineering

Mechatronics



Exploring the Definition of a Mechatronic System

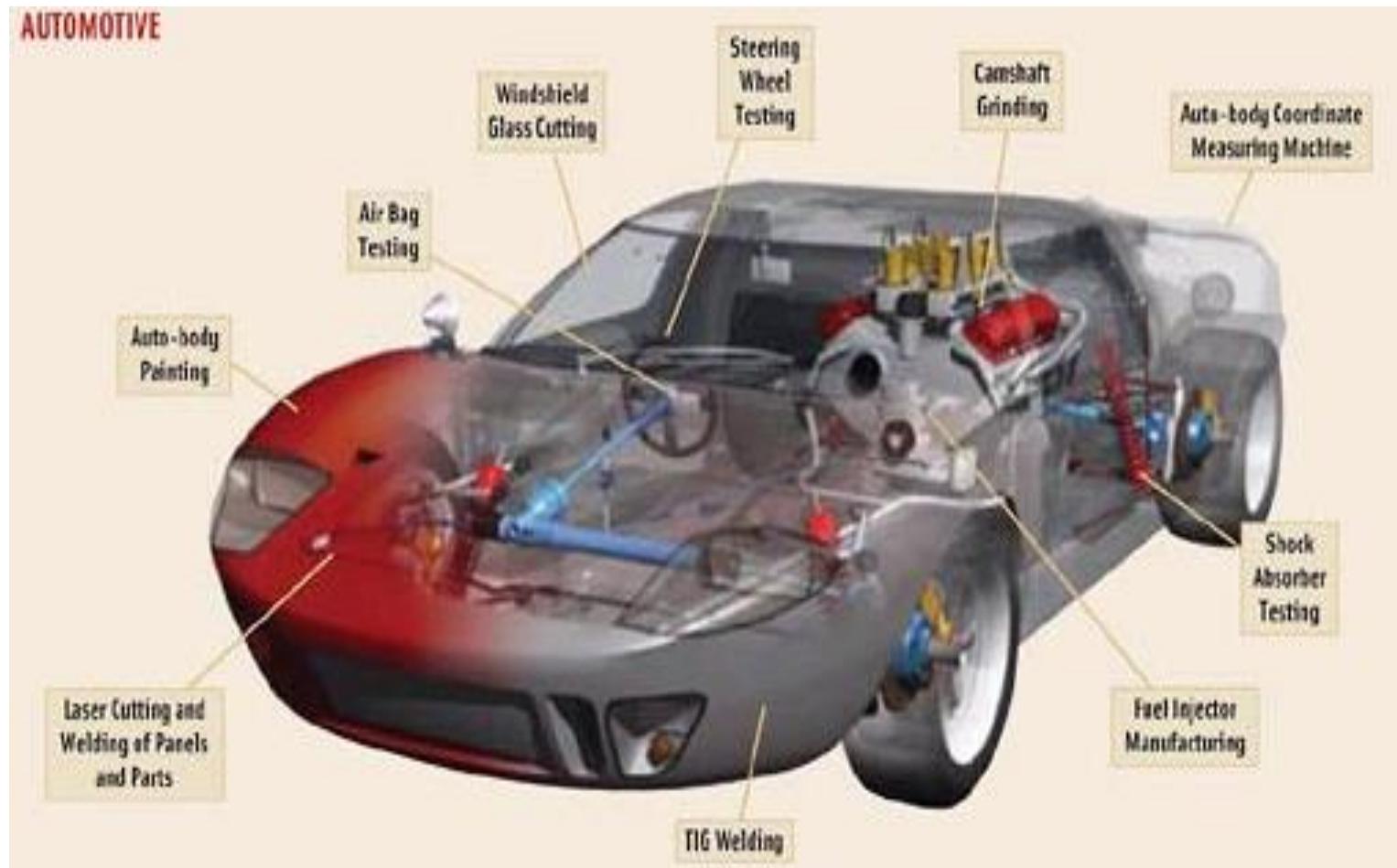
- There is some validity of everything that was listed before
- The key aspects of the popular definition: **Synergistic application; multi-domain (mechanics, electronics, control engineering, computer science); electromechanical products and systems; integrated design**

Our “Extended” Definition for a Mechatronic System

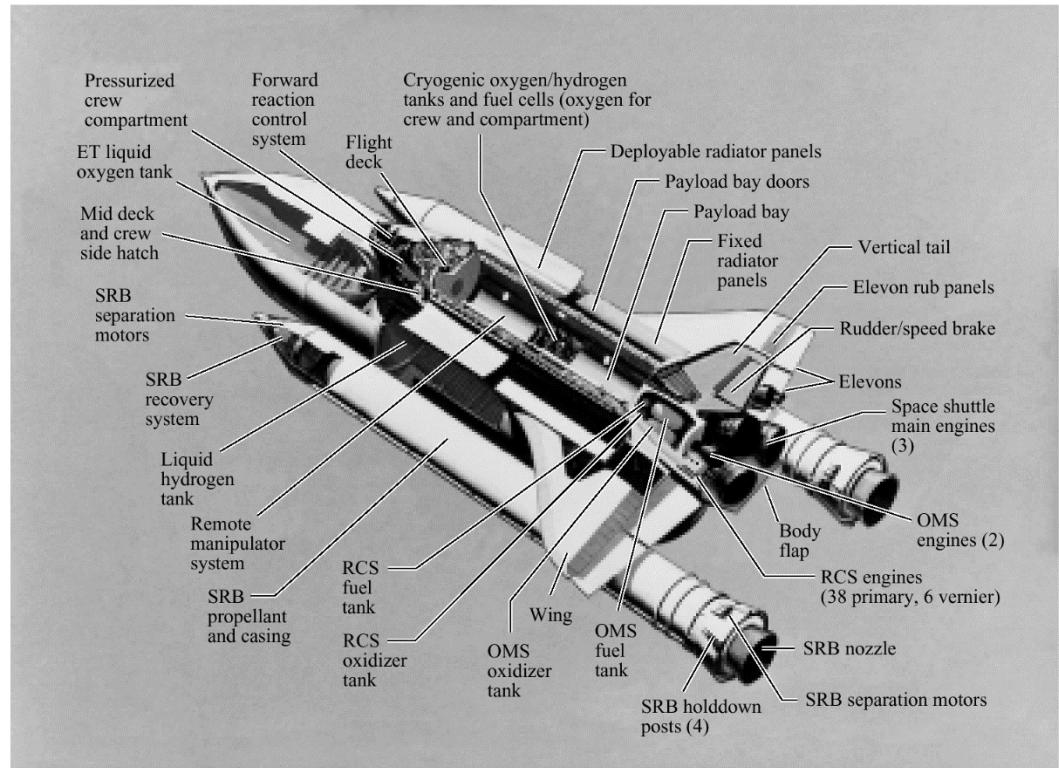
- A multi-physics system (not limited to electro-mechanical)
- Approach used in the development:
 - Integrated (concurrent, synergistic, etc.) approach
→ All domains are considered together
 - Unified (analogous, etc.) approach → similar approaches are used for the different domain
 - Unique result → typically, optimal result (only one best solution)
 - Systematic approach → Clearly articulated set of steps are used in the development

Note: These considerations are applicable to modeling, design, instrumentation, control, operation, etc.

An Example of Mechatronic System



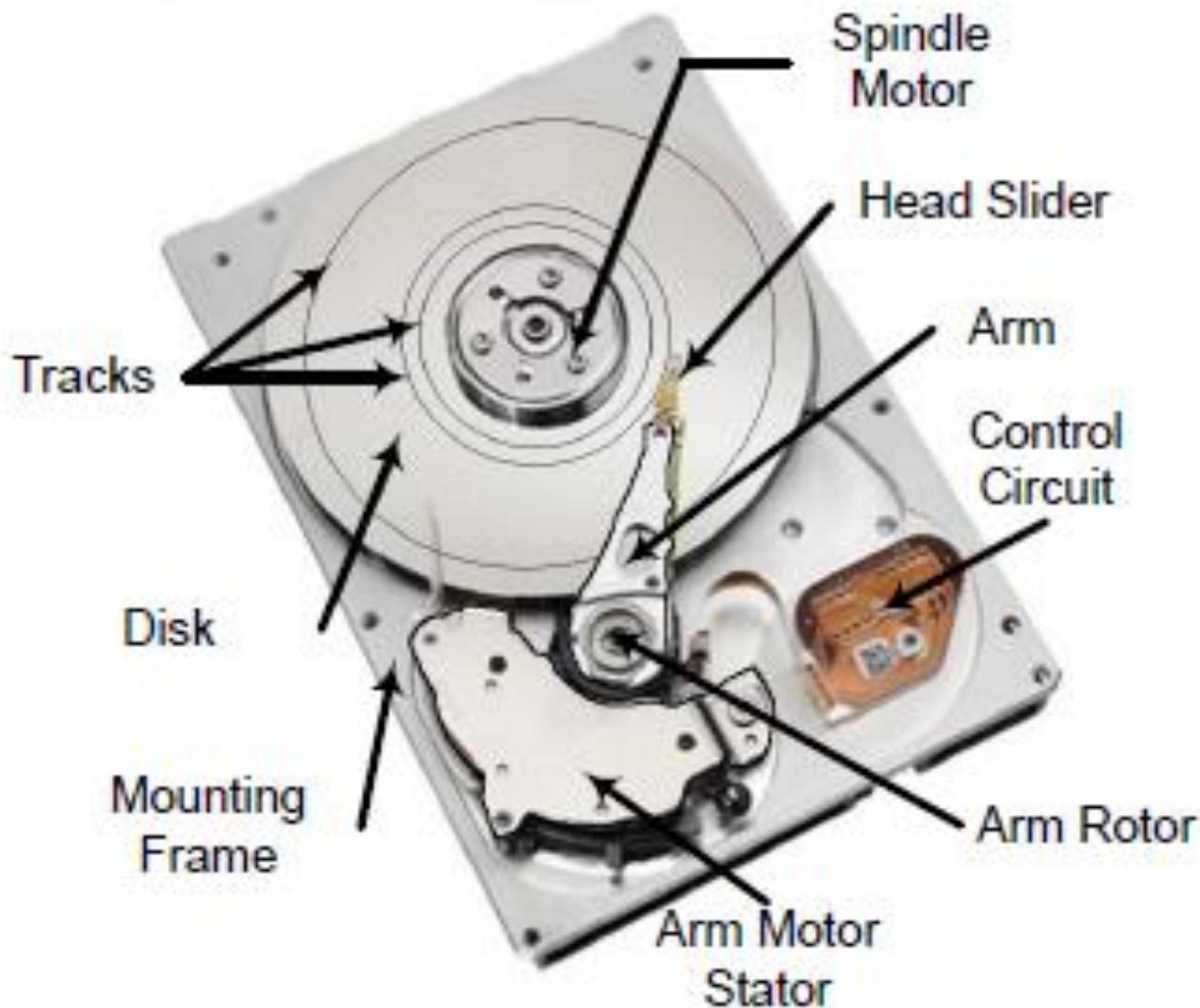
A spacecraft is a multi-domain system consisting of multiple subsystems



© NASA-Houston.

Computer Hardware

E.g., Hard-disk drive (HDD) unit of a computer



Questions on Mechatronics

Think about answers to the following questions (not necessarily now):

- **Meaning of Mechatronics?**
- **Key steps of development of a mechatronic product?**
- **Advantages of Mechatronics?**

White Board Discussion on Mechatronics

**The mechatronic approach is said to be:
Integrated, Unified, Systematic, and Unique.
Why? What are its advantages?**

Motivation for Mechatronic Products

- Sequentially designed and instrumented components of existing “multi-domain” systems are not optimally matched; **coupling/interactions are not considered**
- High potential for improvement through **concurrent, unified, and optimal design and instrumentation**

Benefits of Mechatronic Design and Instrumentation:

- **Optimality and better component matching**
- **Increased efficiency**
- **Cost effectiveness**
- **Ease of system integration and expansion/enhancement**
- **Compatibility & ease of cooperation with other systems**
- **Improved controllability**
- **Increased reliability**
- **Increased product life**

“Why” (for each benefit)?

“Mechatronic” Instrumentation

Mechatronic Approach to Instrumentation—Concurrent & Unified Instrumentation

- Treat instrumentation as an integral part of design
- Design/incorporate the instrumentation concurrently

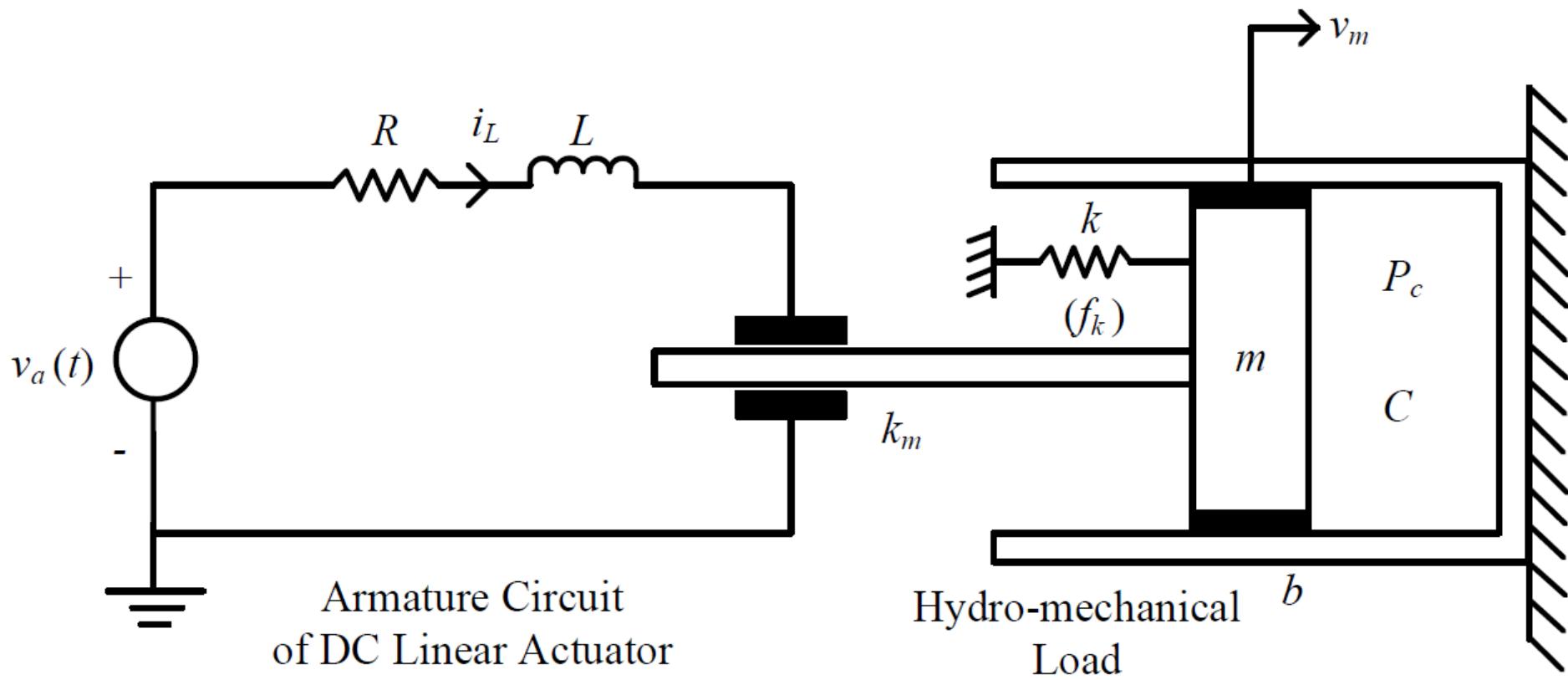
(consider all aspects and components of instrumentation simultaneously)

- Use similar techniques for different domains in the system

Mechatronic Approach: Integrated, Unified, Unique, Systematic

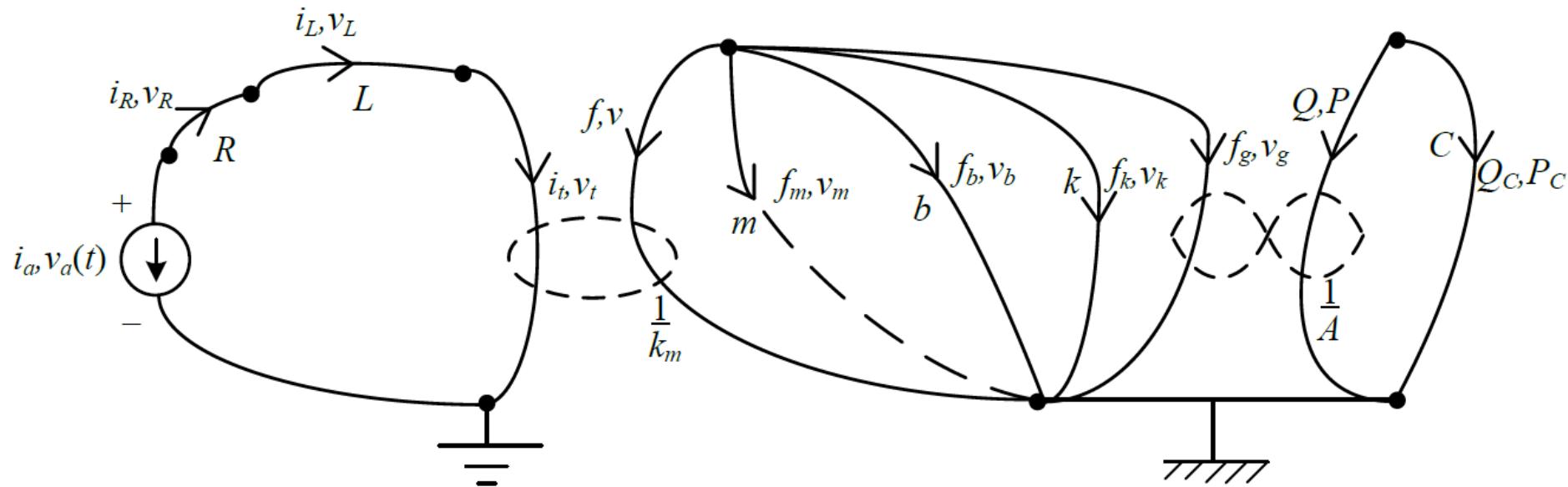
An Example to Justify the "Unified" Approach

Mechatronic Approach: Integrated, Unified, Unique (Optimal), Systematic

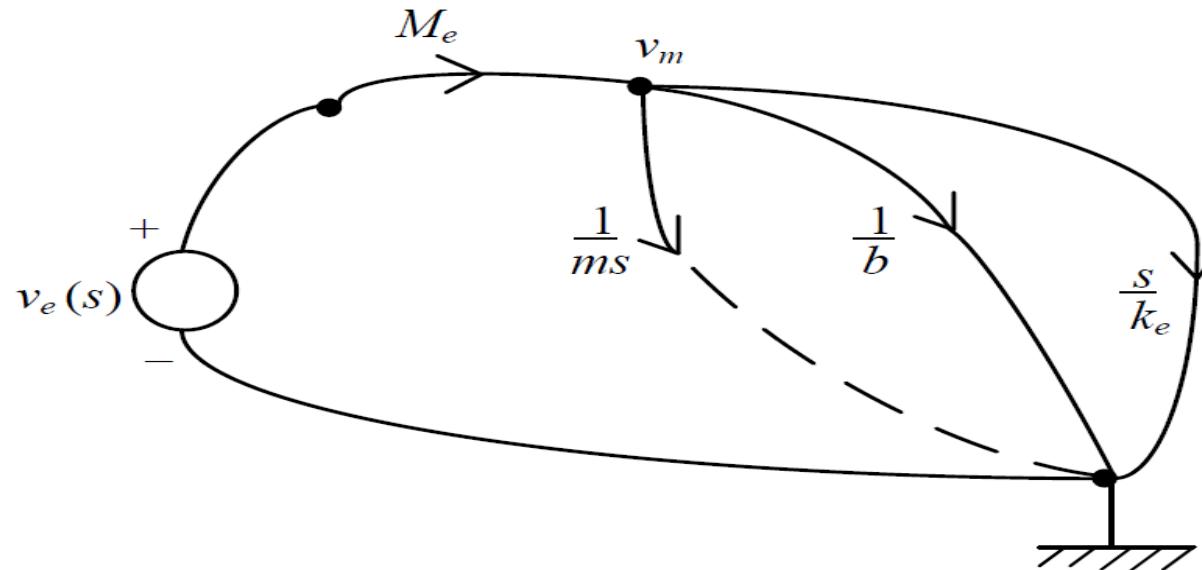


A DC linear motor-driven hydro-mechanical load

An Example to Justify the “Unified” Approach (Cont’d)



Linear Graph (Mixed-domain—electrical, mechanical, fluid)



Equivalent Linear Graph Entirely in the Mechanical Domain

TERMINOLOGY

- **Plant or Process:** System to be controlled
- **Inputs:** Excitations (known/unknown; desirable/undesirable) to the system
- **Outputs:** Responses of the system (desirable/undesirable)
- **Sensors:** Measure system variables (excitations, responses, etc.)
- **Actuators:** Drive various parts of the system
- **Controller:** Device that generates control signal/action
- **Control Law:** Relation or scheme according to which the control signal/action is generated
- **Control System:** Plant and controller, at least (Can include sensors, signal conditioning, communication, etc.)
- **Feedback Control:** Control signal is determined according to (by measuring) actual plant response
- **Open-loop Control:** No feedback of plant response into controller
- **Feed-forward Control:** Control signal is determined according to plant excitations (or a model) without knowing the actual outputs

Questions on System Definition

- Difference between a system and a dynamic system?
- What is a control system?
- Is an engineering system a dynamic system? Why?
- Is an engineering system a control system? Why?
- What things are “sensed” (measured) in a control system?
- Where are the “actuators” used in a control system?

Instrumentation Procedure

Instrumentation Procedure

- Study the instrumented system (plant)
- Identify and group the system components (possibly, according to the physical domain—mechanical, electrical, fluid, thermal, etc.)
- Develop a preliminary System Architecture
- Formulate physical equations (Model)—for computer simulation, design, control, etc.
- Indicate operating requirements (performance specifications) for the plant

System level

Instrumentation Procedure (Cont'd)

- Identify constraints related to cost, size, weight, environment (e.g., operating temperature, humidity, dust-free or clean room conditions, lighting, wash-down needs)
- Select type and nature of sensors/transducers, actuators, signal conditioning devices (including interfacing and data acquisition hardware and software, filters, amplifiers, modulators, ADC, DAC, etc.)
- Establish the associated ratings/specifications of components (signal levels, bandwidths, accuracy, resolution, dynamic range, power, torque, speed, temperature, and pressure characteristics, etc.)
- Identify manufacturers/vendors for the components (model numbers, data sheets, etc.)

Component level

Instrumentation Procedure (Cont'd)

- Revise system architecture (include controllers and/or control schemes if necessary). Revise the original computer model as necessary
- Carry out computer simulations. Make modifications to instrumentation until the system performance meets the specifications (A mechatronic optimization scheme may be used)
- Once acceptable results are achieved, acquire and integrate the actual components. Some new developments (designs) may be needed (new devices, interface hardware, fixtures, etc.)

Commercially available components → Instrumentation
New developments → Design

Instrumentation and Design

Design:

Develop a system to meet the performance requirements

1. Basic components of the system are identified during conceptual design
 2. Their details, including parameter values, are decided during detailed design (final optimization is done here)
- Instrumentation is an integral part of design
 - Both have the same end objective (meeting the specified performance)

In Design: Parameter choice can be infinite (in a continuous range), particularly during optimization. Commercially unavailable components may have to be developed new.

In Instrumentation: Component choice is finite, and typically the components are commercially available

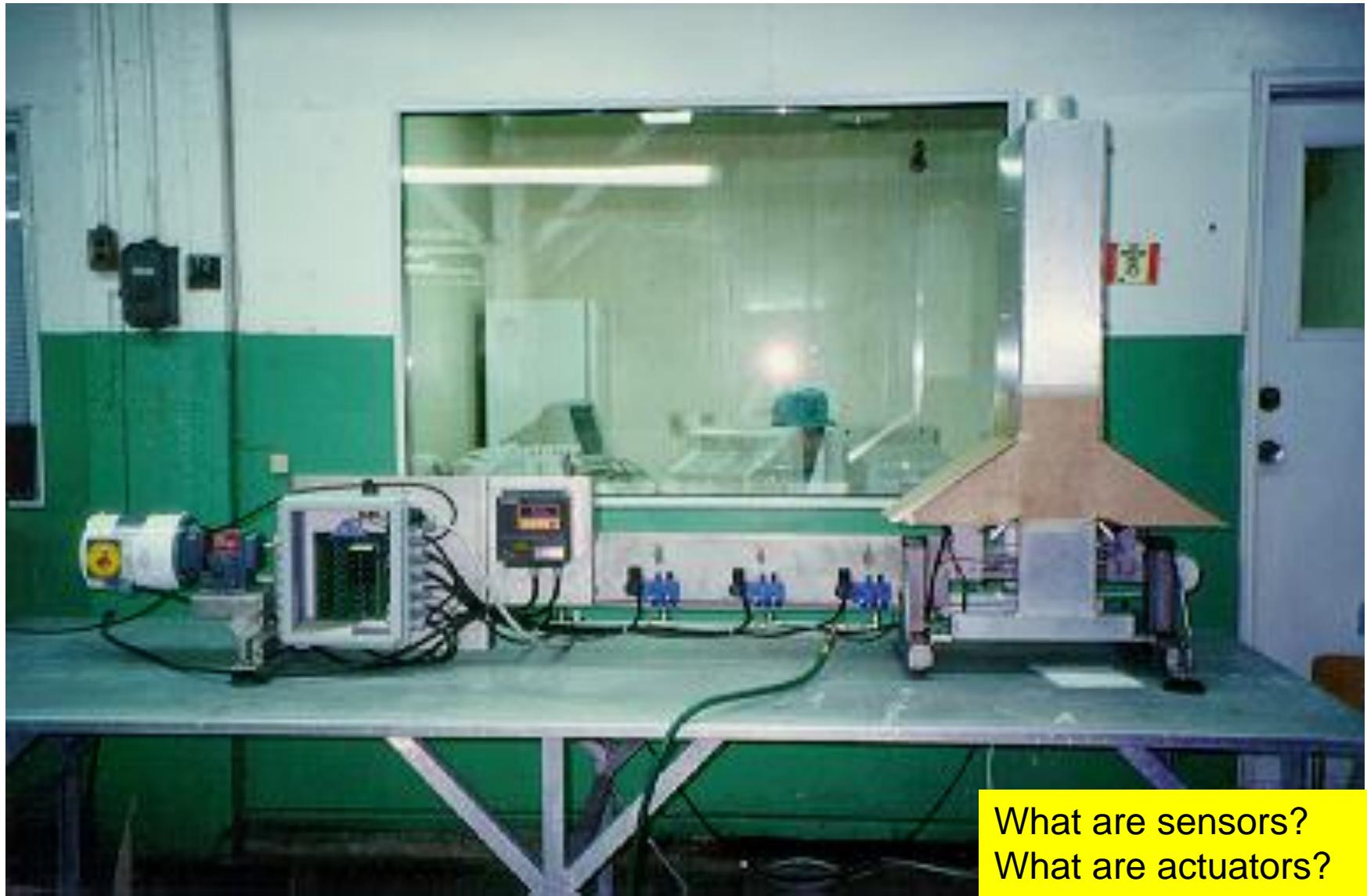
Questions on Mechatronic Instrumentation

- Difference between instrumentation and mechatronic instrumentation?
- Key objectives of mechatronic instrumentation?
- Main steps of mechatronic instrumentation?

Examples

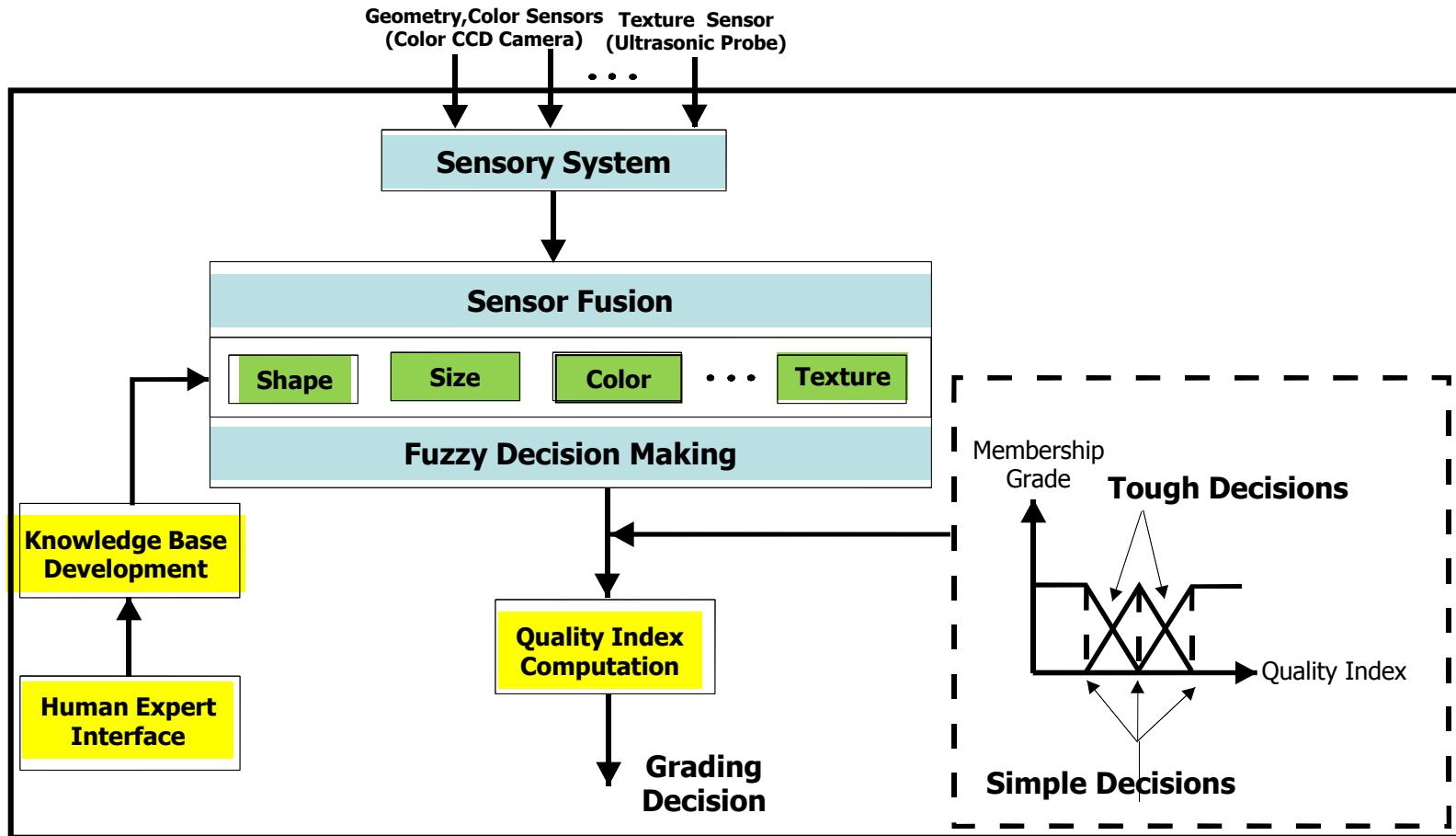
Intelligent Herring-Roe Grader

Is this an instrumentation problem or a design problem?



What are sensors?
What are actuators?

Architecture of the Grading System



Operation of the Roe Grading Machine



Herring Roe Grading Machine

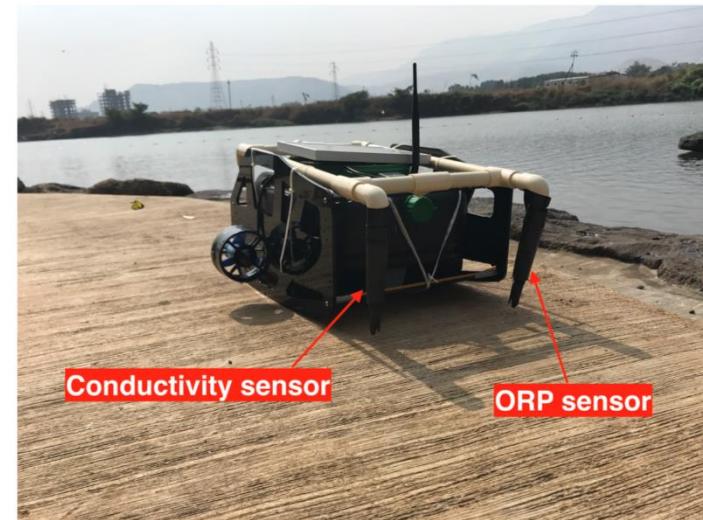
Questions on Herring Roe Grader

- Is this a mechatronic system? Why?
- If not a mechatronic system, how would you make it one?

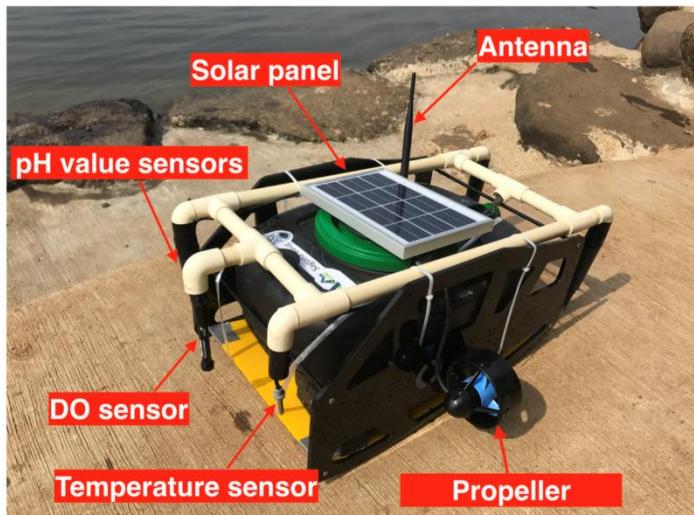
Mobile Autonomous Sensor Module for Water Quality Monitoring



(a) Top view.



(b) Back view.



(c) Front-right view.



(d) Side view.

Is this an instrumentation problem or a design problem?

SLEEP DISORDER MONITORING

Is this an instrumentation problem or a design problem?



Sleep Disorders

- Sleep Apnea (breathing interruption)
- Restless legs syndrome
- Insomnia

Symptoms

- Snoring
- Choking
- Cessation of abdominal & breathing

Risks

- Vulnerability to cardiovascular or metabolic diseases
- In worst cases, strokes or even death (in long term cases)