

Contents

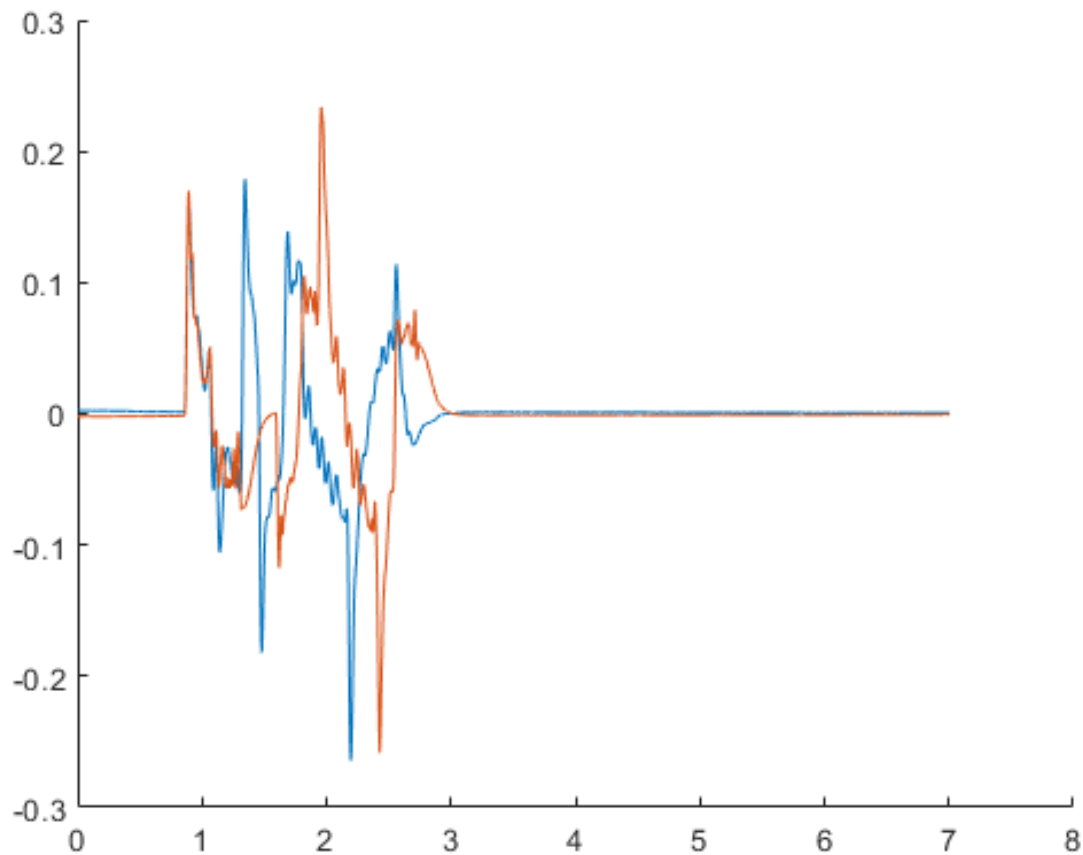
- [low feedrate](#)
- [high feedrate](#)
- [plot formatting](#)

low feedrate

```
name = 'lli.mat';
lli = load(name);
time = lli.lli.X.Data;
x_act = lli.lli.Y(1).Data;
y_act = lli.lli.Y(2).Data;
x_ref = lli.lli.Y(3).Data;
y_ref = lli.lli.Y(4).Data;

e_x_lowFR = x_ref - x_act;
e_y_lowFR = y_ref - y_act;

clf();
hold on;
plot(time, e_x_lowFR);
plot(time, e_y_lowFR);
```



high feedrate

init variables to be loaded into simulink model

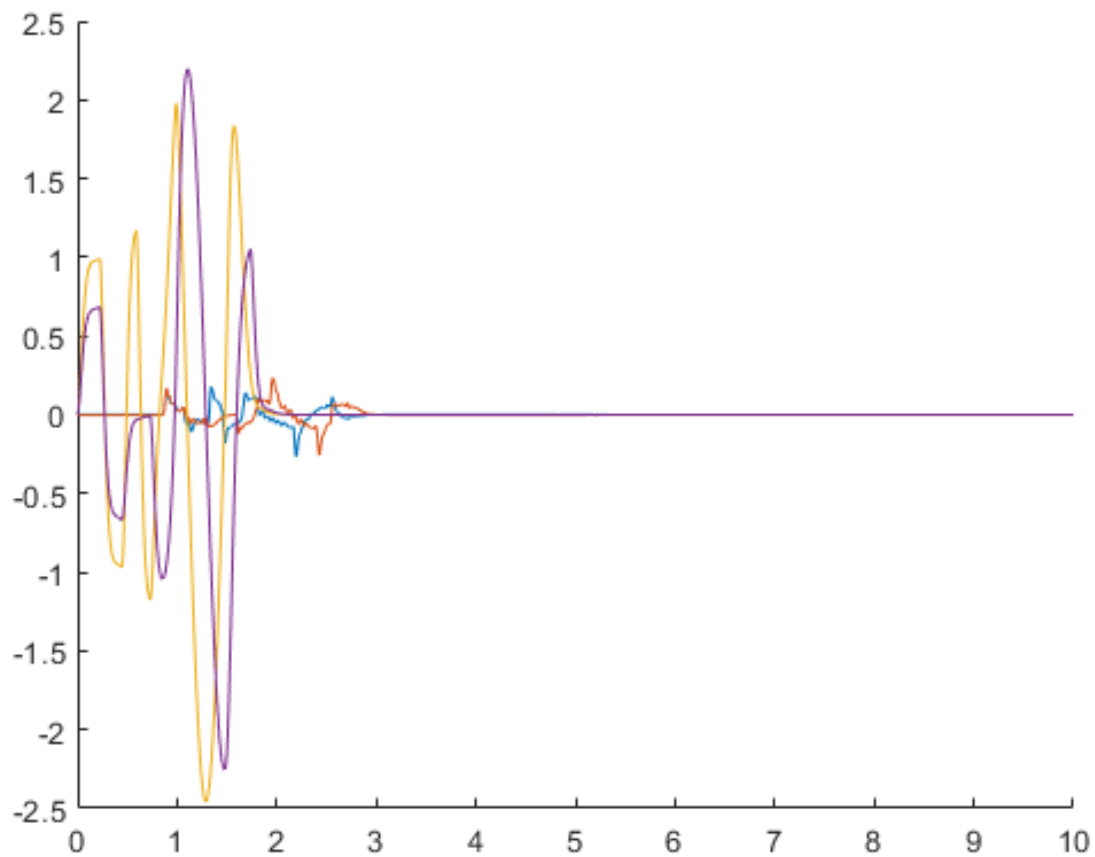
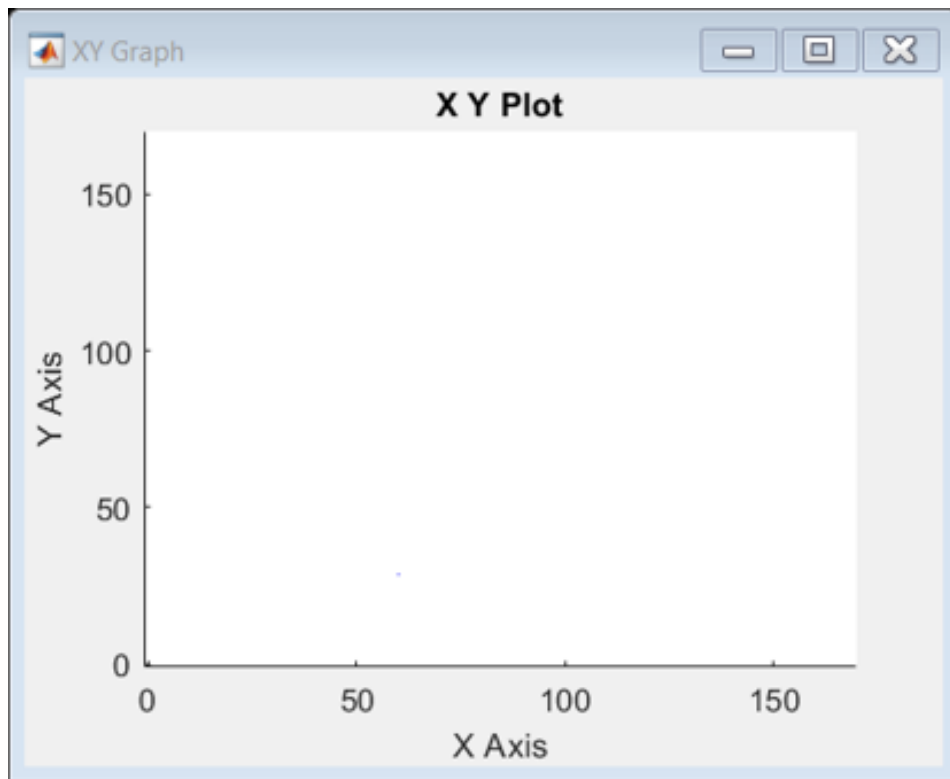
```

T = 0.0001;
Ka = 1;
Kt = 0.49;
Ke = 1.59;
Jx = 0.000436;
Bx = 0.0094;
Jy = 0.0003;
By = 0.0091;

% use LBW LLI controller
a = 13.9282;
T_ = 0.0021323;
Kx = 0.75858;
Ky = 0.82224;
Ki = 12.5664;

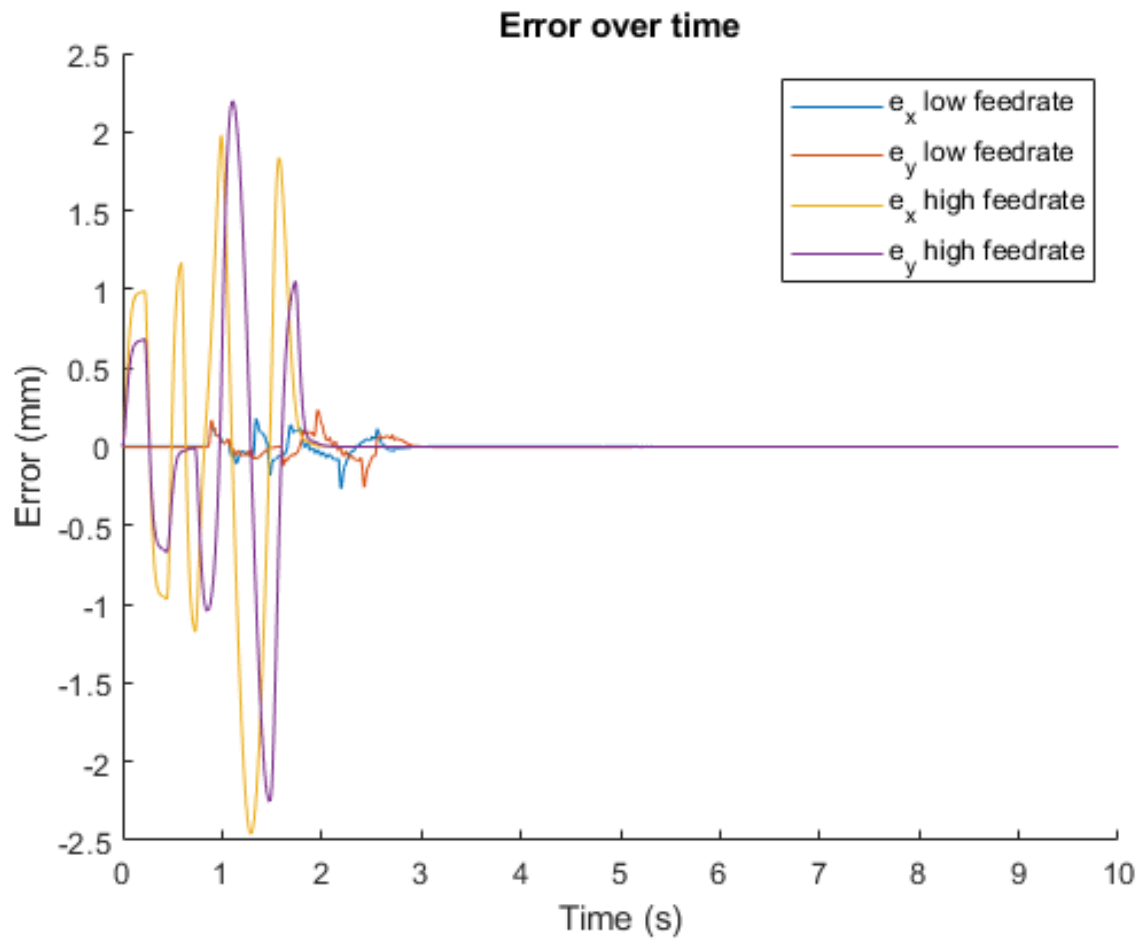
LL = tf([a*T_ 1],[T_ 1]);
I = tf([1 Ki],[1 0]);
LLI_Lx_z = Kx*c2d(LL*I, T, 'tustin');
LLI_Ly_z = Ky*c2d(LL*I, T, 'tustin');
```

```
name = 'f1.mat';  
data = load(name);  
Tplot = data.txy.t;  
xplot = data.txy.x;  
yplot = data.txy.y;  
  
sim('e2_sim.slx');  
  
t = ans.sim.Data(:,1);  
e_x_hiFR = ans.sim.Data(:,2) - ans.sim.Data(:,3);  
e_y_hiFR = ans.sim.Data(:,4) - ans.sim.Data(:,5);  
plot(t, e_x_hiFR);  
plot(t, e_y_hiFR);
```



plot formatting

```
legend('e_x low feedrate', 'e_y low feedrate', 'e_x high feedrate', 'e_y high feedrate');  
title('Error over time');  
xlabel('Time (s)');  
saveas(gcf, 'F2.png');  
ylabel('Error (mm)');
```



Published with MATLAB® R2020b