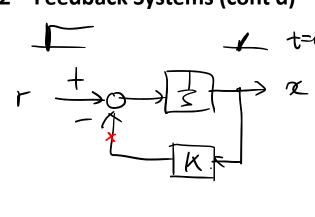
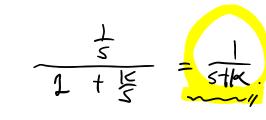
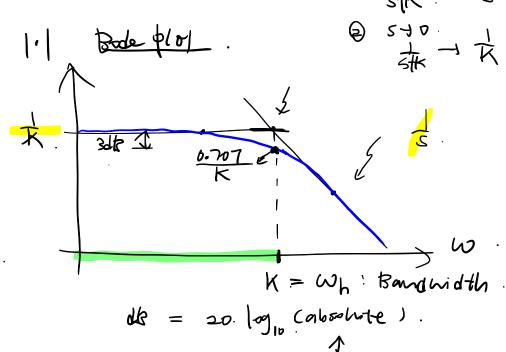
L2 – Feedback Systems (cont'd)



$$\frac{X}{R} = \frac{\frac{1}{5}}{1 - (-1) \cdot \frac{1}{5} \cdot K}$$





XID.

t >>c eActive

ality . Step => Bode

· Time const to

Bandwidth. K.

· Initaal resp x(t) = t.
· Final K.

High-frag 's

O com "infer" Robe -> Step.

@ When feedback effective: G(5) = K

77 not 1 G(5) = 1.

< General Lywy > 1 K = (13)

• Foodback effective $|L_{yw}| \gg 1$ ≈ 9 $|\frac{k}{jw}| = \frac{k}{w} \gg 1$ $\Rightarrow w \ll k$

$$\frac{1}{\omega_{c}}$$

$$\left| \begin{array}{c} L(j^{\omega}) \\ W=Cre \end{array} \right| = 1.$$

$$\frac{1}{1 + L(s)}$$

$$\frac{1}{1 + L(s)}$$

$$\frac{1}{1 + L(s)}$$

$$\begin{cases}
0 | L | \gg 1 & (w \ll a_e) \\
G(S) \simeq \frac{P}{L} = \frac{P}{PK} = \frac{1}{KGL}, \\
0 | L | \ll 1 & (w \gg w_e)
\end{cases}$$

$$G(S) \simeq P(S)$$

< Hactional-order Fritighestor >. Q. Exist? prestion! : PA13 A(5) ~ 51.2 P(5) = 1 Q. How handle? - > Freq. Resp. $\frac{1}{|S|} = \frac{|K|}{|S|} = \frac{$ = K e-j(=x1.5) 11年来 $W = (e^{j\frac{\pi}{2}}) \omega$ -1.5 dec/dec. (G) 1/K.

