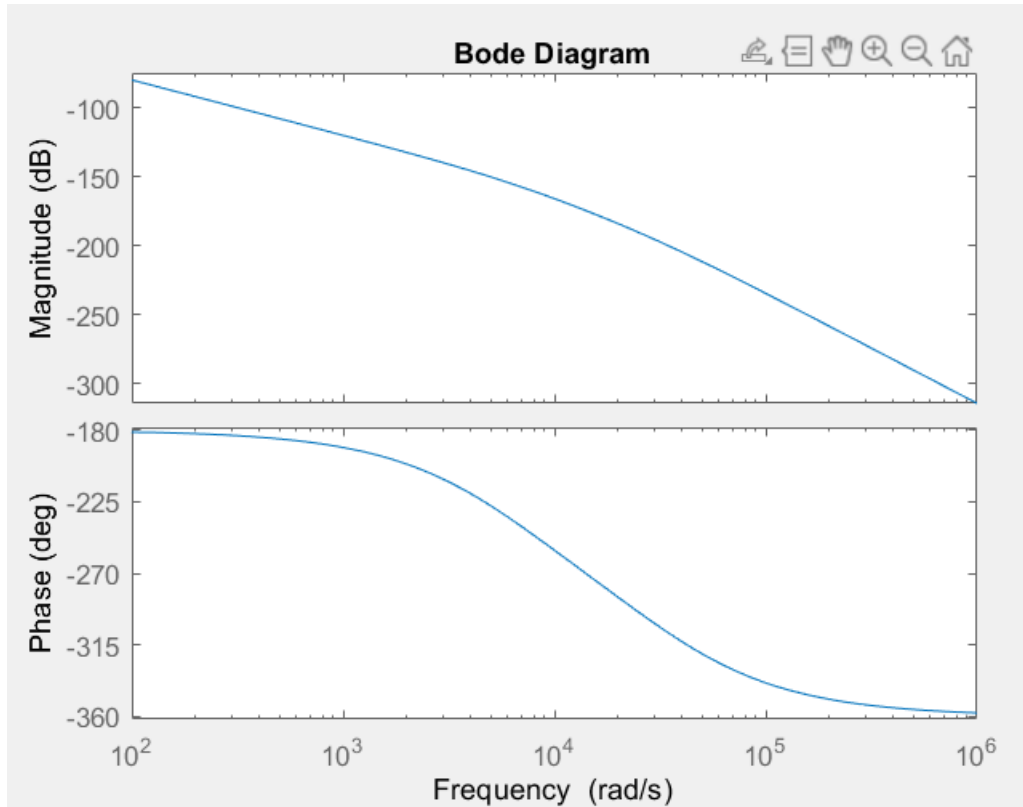


MECH421 HW 7
Ratthamnoon Prakitpong
#63205165

A.

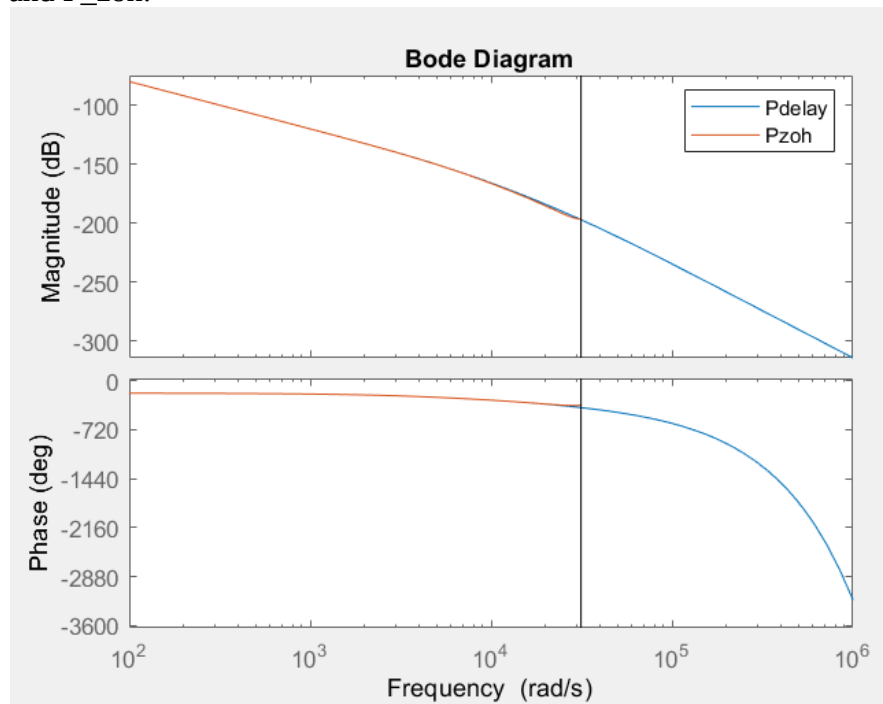
Bode of P:



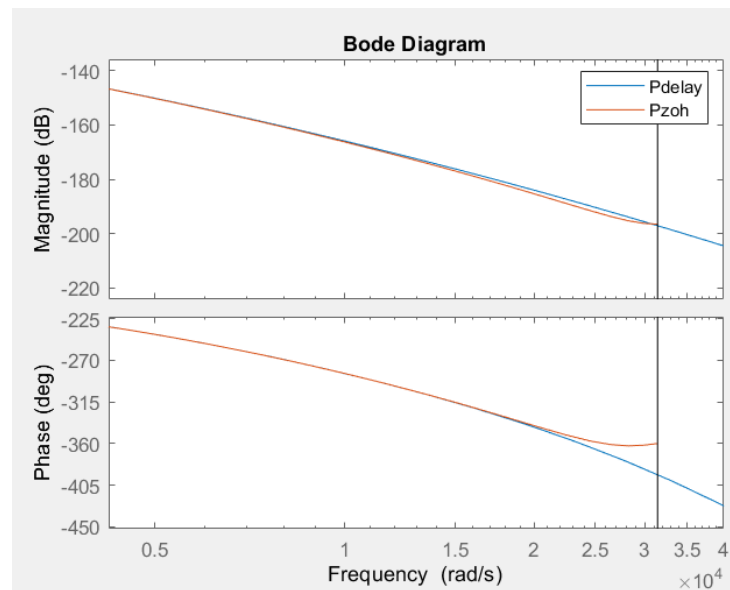
```
% q1  
wa = 2*pi*10^3;  
ws = 10*pi*10^3;  
m = 1;  
Kf = 1;  
Ga = tf(1,[1/wa 1]);  
Gs = tf(1,[1/ws 1]);  
Gm = tf(1,[m 0 0]);  
fs = 10000;  
T = 1/fs;  
P = Ga*Kf*Gm*Gs;  
bode(P);
```

B.

Bode of P_delay and P_zoh:



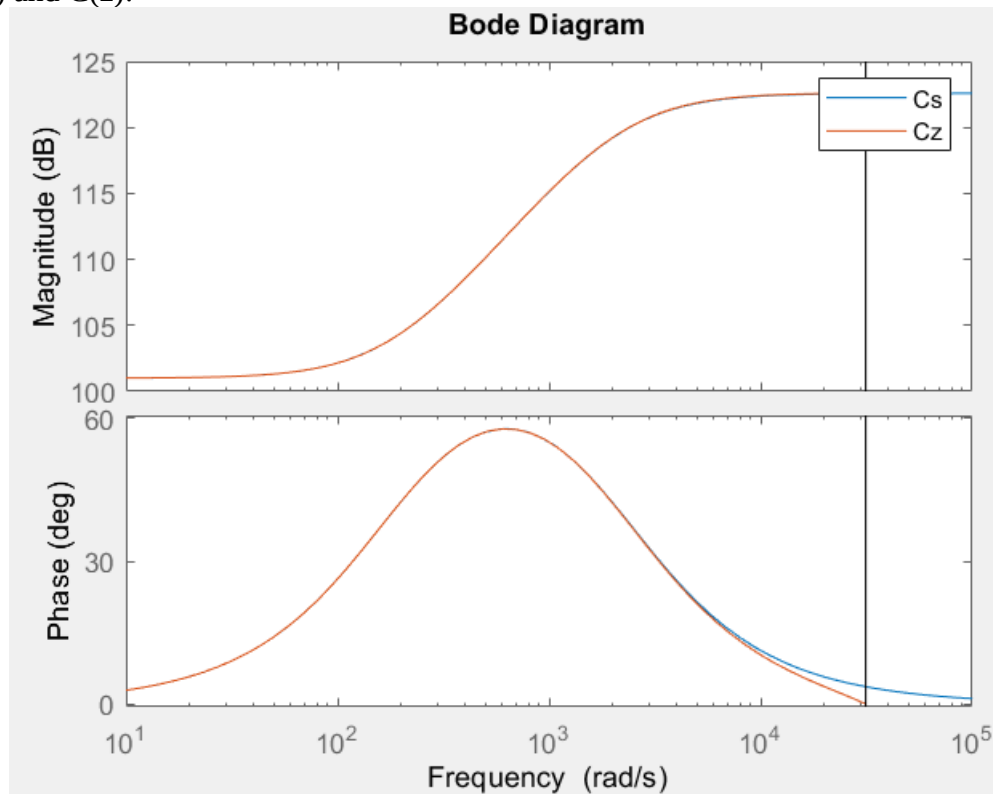
Zoomed in at P_zoh:



```
% q2
Pdelay = P*tf([1],[1], 'InputDelay',T/2);
Pzoh = c2d(P, T, 'zoh');
hold on;
legend on;
bode(Pdelay);
bode(Pzoh);
```

C.

Bode of $C(s)$ and $C(z)$:



```
% q3
w = 100*2*pi; % from hw6, convert from hz to rad/s
phi = 45; % from hw6, deg
phi = phi * pi/180;
a = 12; % from hw6, guess and check
t = 1/(sqrt(a)*w);
Kp = 112202; % from hw6, at 100Hz, this K make gain ~= 0db
Cs = tf([Kp*a*t Kp], [t 1]);
Cz = c2d(Cs, T, 'tustin');
hold on;
legend on;
bode(Cs);
bode(Cz);
```

D.

$$P(s) = 1 + \frac{1}{T_i s}$$

$$P(z) = P(s) \Big|_{\frac{1}{s} = \frac{T}{1-z^{-1}}}$$

$$= 1 + \frac{1}{T_i} \left(\frac{T}{1-z^{-1}} \right)$$

$$= 1 + \frac{T}{T_i} \left(\frac{1}{1-z^{-1}} \right)$$

