

# Tutorial 2

## Review

time domain	s domain
$\delta(t)$	1
$u(t)$	$\frac{1}{s}$
$t$	$\frac{1}{s^2}$
$e^{-\alpha t}$	$\frac{1}{s+\alpha}$
$\sin(\omega t)$	$\frac{\omega}{s^2 + \omega^2}$
$\cos(\omega t)$	$\frac{s}{s^2 + \omega^2}$

"Table 3.1, Chapter 3, Lecture Notes"

$$\star) e^{i\omega t} = \cos(\omega t) + i \sin(\omega t)$$

$$\mathcal{L}\{e^{i\omega t}\} = \int_0^{\infty} e^{i\omega t} e^{-st} dt = \int_0^{\infty} e^{(-s+i\omega)t} dt = \frac{1}{s-i\omega}$$

$$\frac{1}{s-i\omega} \times \frac{s+i\omega}{s+i\omega} = \frac{s+i\omega}{s^2 + \omega^2} = \frac{s}{s^2 + \omega^2} + i \frac{\omega}{s^2 + \omega^2}$$

$$\mathcal{L}\{\cos(\omega t)\} + i \mathcal{L}\{\sin(\omega t)\}$$

## Other Cases:

Time domain

$$e^{-\alpha t} \sin(\omega t)$$

$$e^{-\alpha t} \cos(\omega t)$$

$$t e^{-\alpha t}$$

$$\dot{f}(t), f(0)$$

$$\int f(t)$$

"Table 3.1, Chapter 3, Lecture Notes"

s domain

$$\frac{\omega}{(s+\alpha)^2 + \omega^2}$$

$$\frac{s+\alpha}{(s+\alpha)^2 + \omega^2}$$

$$\frac{1}{(s+\alpha)^2}$$

$$sF(s) - f(0)$$

$$\frac{F(s)}{s}$$

1. a)  $G(s) = \frac{3}{3+s}, \quad r(t) = 6$

$$G(s) = \frac{Y(s)}{R(s)} = Y(s) = G(s) R(s)$$

$$r(t) = 6 \quad \longrightarrow \quad R(s) = \frac{6}{s} \quad \Rightarrow \quad Y(s) = \frac{3}{s+3} \cdot \frac{6}{s}$$



## Partial Fractions:

$$F(s) = \frac{A}{(s+p_1)} + \frac{B}{(s+p_2)} + \dots + \frac{Z}{(s+p_z)}$$

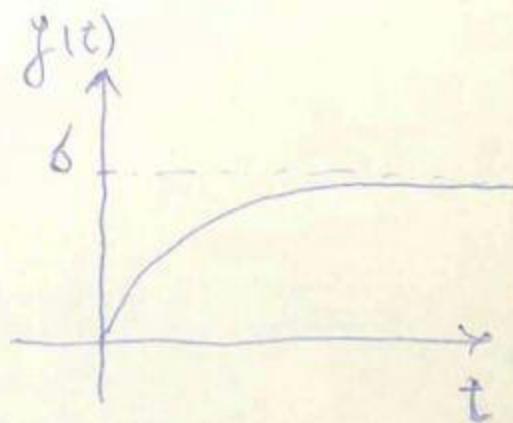
$$A = \lim_{s \rightarrow -p_1} \left\{ (s+p_1) F(s) \right\}$$

$$B = \lim_{s \rightarrow -p_2} \left\{ (s+p_2) F(s) \right\}$$

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$$Y(s) = \frac{3}{s+3} \times \frac{6}{s} = \frac{A}{s+3} + \frac{B}{s}$$

$$A = \lim_{s \rightarrow -3} \left\{ (s+3) Y(s) \right\} = \lim_{s \rightarrow -3} \frac{18}{s} = -6$$



$$B = \lim_{s \rightarrow 0} \left\{ s Y(s) \right\} = \lim_{s \rightarrow 0} \frac{18}{s+3} = 6$$

$$Y(s) = \frac{6}{s} - \frac{6}{s+3} = \mathcal{L}^{-1} \{ Y(s) \} = y(t) = 6 - 6e^{-3t}$$

$$1.6) G(s) = \frac{3}{3+s}, \quad r(t) = 6, \quad y(0) = 10$$

$$G(s) = \frac{Y(s)}{R(s)} = \frac{3}{3+s} = \frac{Y(s)}{R(s)} \Rightarrow \dot{y} + 3y = 3r(t) \Rightarrow$$

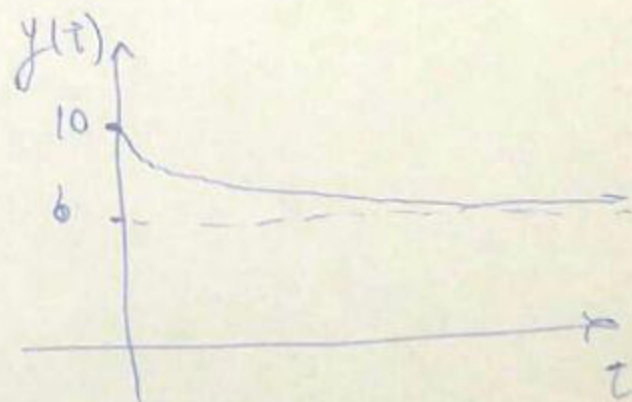
$$\mathcal{L}\{\dot{y} + 3y\} = \mathcal{L}\{3r(t)\} = sY(s) - y(0) + 3Y(s) = 3R(s) \Rightarrow$$

$$Y(s)(s+3) = \frac{18}{s} + 10 \Rightarrow Y(s)(s+3) = \frac{10s+18}{s} \Rightarrow Y(s) = \frac{10s+18}{s(s+3)}$$

$$*) \quad \frac{3}{3+s} = \frac{Y(s)}{R(s)} \Rightarrow 3R(s) = 3Y(s) + sY(s) \Rightarrow$$

$$\mathcal{L}^{-1}\{3R(s)\} = \mathcal{L}^{-1}\{3Y(s) + sY(s)\} \Rightarrow 3r(t) = 3y(t) + \dot{y}(t)$$

$$Y(s) = \frac{10s+18}{s(s+3)} = \frac{A}{s} + \frac{B}{(s+3)}$$



$$A = \lim_{s \rightarrow 0} (sY(s)) = \lim_{s \rightarrow 0} \left( \frac{10s+18}{s+3} \right) = 6$$

$$B = \lim_{s \rightarrow -3} ((s+3)Y(s)) = \lim_{s \rightarrow -3} \left( \frac{10s+18}{s} \right) = \frac{-30+18}{-3} = 4$$

$$Y(s) = \frac{6}{s} + \frac{4}{s+3} \Rightarrow y(t) = 6 + 4e^{-3t}$$



$$2. \quad G(s) = \frac{1}{s+10}, \quad y(0)=0, \quad r(t) = 3 \cos(10t)$$

$$G(s) = \frac{Y(s)}{R(s)} \Rightarrow Y(s) = G(s) R(s) = \frac{1}{(s+10)} \times \frac{3s}{s^2+100} =$$

$$Y(s) = \frac{A}{s+10} + \frac{Bs+C}{s^2+100}$$

$$A = \lim_{s \rightarrow -10} \left( (s+10) Y(s) \right) = \lim_{s \rightarrow -10} \left( \frac{3s}{s^2+100} \right) = -0.15$$

$$\frac{3s}{(s+10)(s^2+100)} = \frac{A}{s+10} + \frac{Bs+C}{s^2+100} = \frac{A(s^2+100) + (Bs+C)(s+10)}{(s+10)(s^2+100)} =$$

$$3s = As^2 + 100A + Bs^2 + (C+10B)s + 10C \Rightarrow 3s = (A+B)s^2 +$$

$$(C+10B)s + (10C+100A)$$

$$\begin{cases} A+B=0 \\ 10B+C=3 \\ 10C+100A=0 \end{cases} \Rightarrow \begin{aligned} B &= 0.15 \\ C &= +1.5 \end{aligned}$$

$$Y(s) = \frac{-0.15}{s+10} + \frac{0.15s + 1.5}{s^2 + 100} = \frac{-0.15}{s+10} + \frac{0.15s}{s^2 + 100} + \frac{1.5}{s^2 + 100} \times \frac{10}{10}$$

$$y(t) = -0.15 e^{-10t} + 0.15 \cos(10t) + \frac{1.5}{10} \sin(10t) \quad \text{---}$$

$$y(t) = -0.15 e^{-10t} + 0.15 \cos(10t) + 0.15 \sin(10t)$$

$$A \sin(\omega t) + B \cos(\omega t) = \sqrt{A^2 + B^2} \left( \underbrace{\frac{A}{\sqrt{A^2 + B^2}}}_{\sin(\theta)} \sin(\omega t) + \underbrace{\frac{B}{\sqrt{A^2 + B^2}}}_{\cos(\theta)} \cos(\omega t) \right)$$

$$\theta = \tan^{-1} \left( \frac{A}{B} \right)$$

$$= \sqrt{A^2 + B^2} \cos(\omega t - \theta)$$

$$y(t) = -0.15 e^{-10t} + \underbrace{\sqrt{0.15^2 + 0.15^2}}_{0.212} \cos\left(10t - \frac{\pi}{4}\right)$$



$$3. G(s) = \frac{-4s + 20}{s + 300}, \quad y(0) = 0, \quad r(t) = 10$$

$$\Rightarrow Y(s) = G(s) R(s) = \frac{-4s + 20}{s + 300} \times \frac{10}{s} = \frac{A}{s} + \frac{B}{s + 300}$$

$$A = \lim_{s \rightarrow 0} (Y(s) s) = \lim_{s \rightarrow 0} \left( \frac{10 \times (-4s + 20)}{s + 300} \right) = \frac{2}{3}$$

$$B = \lim_{s \rightarrow -300} ((s + 300) Y(s)) = \lim_{s \rightarrow -300} \left( \frac{10 \times (-4s + 20)}{s} \right) = \frac{12200}{-300} = -40.67$$

$$\Rightarrow Y(s) = \frac{2}{3s} - \frac{40.67}{s + 300} \Rightarrow y(t) = \frac{2}{3} - 40.67 e^{-300t}$$

$$4. G(s) = \frac{3}{s^2 + 0.5s + 4}, \quad y(0) = \dot{y}(0) = 0, \quad r(t) = 2$$

$$Y(s) = G(s) R(s) = \frac{3}{s^2 + 0.5s + 4} \times \frac{2}{s}$$

Trick :  $G(s) = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}, \quad R(s) = \frac{1}{s}$

$$y(t) = 1 - \frac{1}{\sqrt{1-\zeta^2}} e^{-\zeta\omega_n t} \sin(\omega_d t + \phi), \quad \begin{cases} \omega_d = \omega_n \sqrt{1-\zeta^2} \\ \phi = \tan^{-1} \frac{\sqrt{1-\zeta^2}}{\zeta} \end{cases}$$

$$w_n = 2, \quad 2\gamma w_n = 0.5 \Rightarrow \gamma = 0.125$$

$$Y(s) = \frac{6}{4s} \left[ \frac{4}{s^2 + 0.5s + 4} \right] \Rightarrow$$

$$y(t) = \frac{6}{4} \left[ 1 - \frac{1}{\sqrt{1 - 0.125^2}} e^{-0.125 \times 2t} \sin \left( 2\sqrt{1 - 0.125^2} t + \gamma^{-1} \frac{\sqrt{1 - 0.125^2}}{0.125} \right) \right]$$

$$\Rightarrow y(t) = 1.5 - 1.51 e^{-0.25t} \sin(1.98t + 1.4455)$$