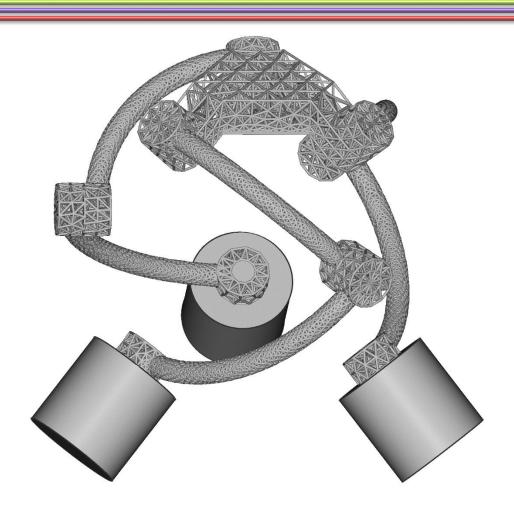
(Automatic Dynamic Analysis of Mechanical Systems)



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AGENDA

Part I. A brief answer to these questions:

- Why do we need another tool to analyze dynamics and vibrations?
- How to access the software?
- Available resources to learn the software?

Part II. A few Demos:

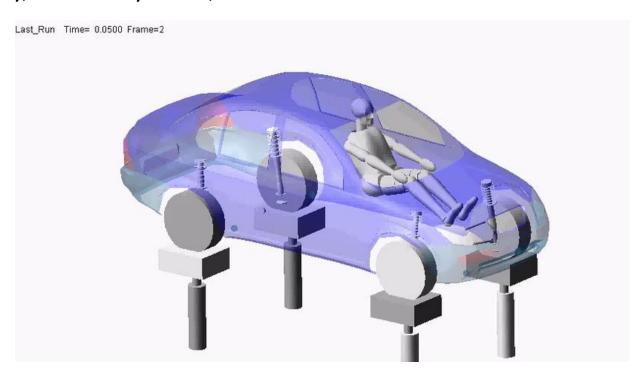
- Human Head and Neck Modeling
- Spherical Parallel Mechanism Simulation

Part III A Brief Intro to the Software

- Software environment
- A Mass-Spring-Damper Example

Why do we need another tool to analyze dynamics and vibrations?

- Virtual prototyping can save time and money.
- Sometimes visual simulation can help to understand the dynamic behaviour of a system better.
- Equations of Motion can get very complicated, due to high DOF, Complex Geometry, Flexible systems, Non-linear behaviour.



A Very Simple Model of the Car (8 DOF)

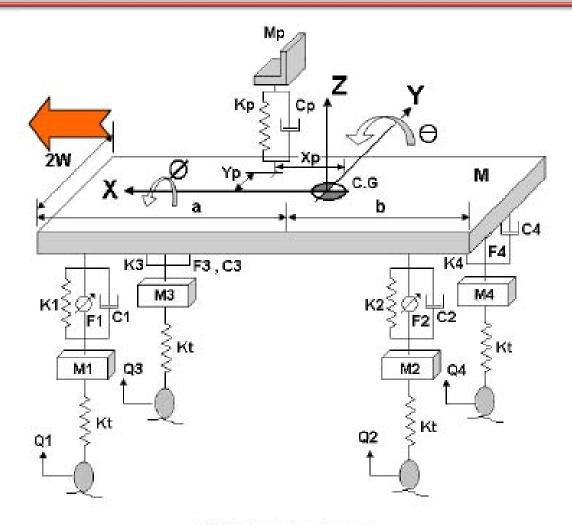


Figure 1. Full car model.

Figure from: http://www.scielo.br/scielo.php?script=sci arttext&pid=S1678-58782008000100010

We need to consider the complex geometry of the chassis!

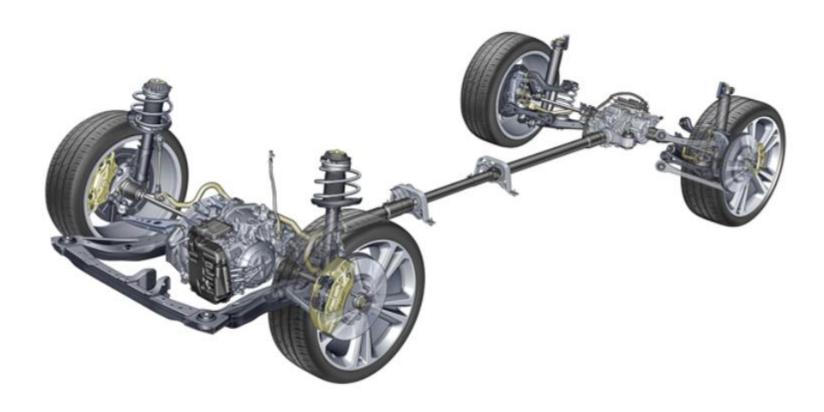
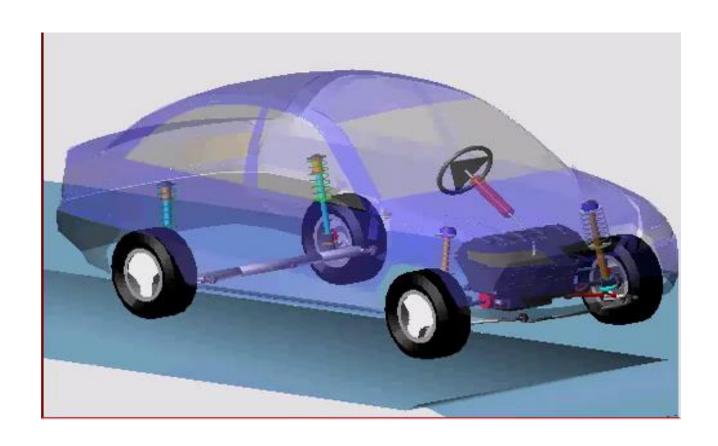
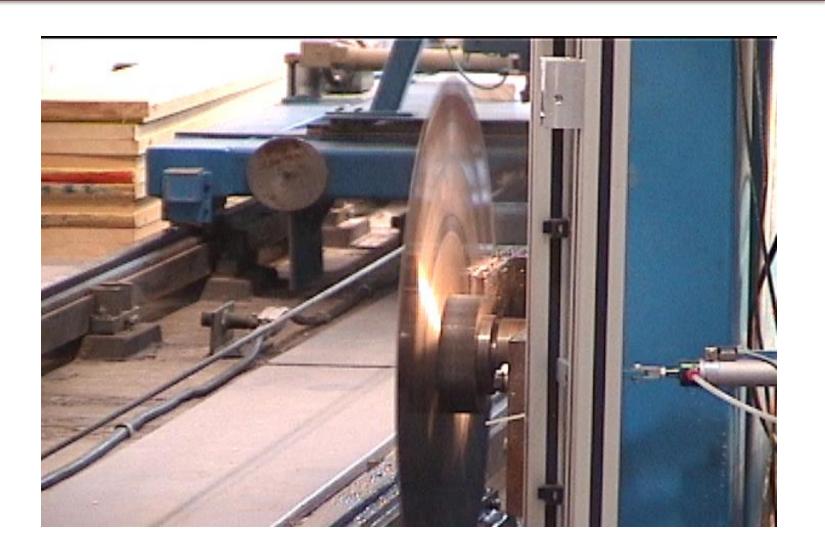
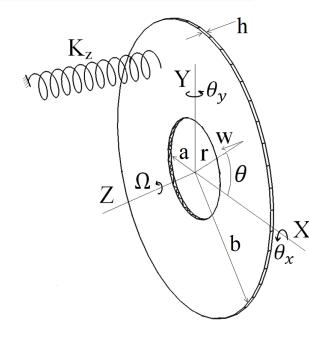


Figure from: http://www.scielo.br/scielo.php?script=sci arttext&pid=S1678-58782008000100010

Transfer Vibrations from Road (a random input)







$$\rho h \left(w_{,tt} + 2\Omega w_{,t\theta} + \Omega^2 w_{,\theta\theta} \right) + D \nabla^4 w - \frac{h}{r} \left(\sigma_{rr} r w_{,r} \right)_{,r} - \frac{h}{r^2} \sigma_{\theta\theta} w_{,\theta\theta} = 0$$

$$\rho h \left(w_{,tt} + 2\Omega w_{,t\theta} + \Omega^2 w_{,\theta\theta} \right) + D \nabla^4 w - \frac{h}{r} \left(\sigma_{rr} r w_{,r} \right)_{,r} - \frac{h}{r^2} \sigma_{\theta\theta} w_{,\theta\theta} + \rho h \ddot{Z}$$

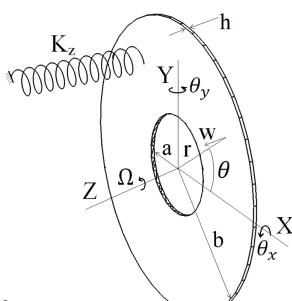
 $+\rho h (r\ddot{\theta}_x \sin \theta - r\ddot{\theta}_y \cos \theta) + \rho h (2\Omega r \cos \theta \dot{\theta}_x + 2\Omega r \sin \theta \dot{\theta}_y)$

$$= -\frac{k_z}{r} \left(w + Z + r_k \sin \theta_k \, \theta_x - r_k \cos \theta_k \, \theta_y \right) + \frac{f_Z}{r}$$

 $\rho hI(\ddot{\theta}_x + 2\Omega\dot{\theta}_y) + \int_0^{2\pi} \int_a^b \rho h \sin\theta \left(w_{,tt} + 2\Omega w_{,t\theta} \right) r^2 dr d\theta = f_s r_k \sin\theta_k + f_Z r_f \sin\theta_f$

$$\rho hI(\ddot{\theta}_y - 2\Omega\dot{\theta}_x) + \int_0^{2\pi} \int_a^b \rho h\cos\theta \left(w_{,tt} + 2\Omega w_{,t\theta}\right) r^2 dr d\theta = -f_s r_k \cos\theta_k - f_Z r_f \cos\theta_f$$

$$m\ddot{Z} + \int_0^{2\pi} \int_a^b \rho h(w_{,tt}) \, r dr d\theta = -k_z \Big(w + Z + r_k \sin \theta_k \, \theta_x - r_k \cos \theta_k \, \theta_y \Big) + f_Z$$



$$\rho h(w_{,tt} + 2\Omega w_{,t\theta} + \Omega^2 w_{,\theta\theta}) + D\nabla^4 w - \frac{h}{r} (\sigma_{rr} r w_{,r})_{,r} - \frac{h}{r^2} \sigma_{\theta\theta} w_{,\theta\theta} = 0$$

$$\rho h(w_{,tt} + 2\Omega w_{,t\theta} + \Omega^2 w_{,\theta\theta}) + D\nabla^4 w - \frac{h}{r} (\sigma_{rr} r w_{,r})_{,r} - \frac{h}{r^2} \sigma_{\theta\theta} w_{,\theta\theta} + \rho h \ddot{Z}$$

$$+ \rho h(r \ddot{\theta}_x \sin \theta - r \ddot{\theta}_y \cos \theta) + \rho h(2\Omega r \cos \theta \dot{\theta}_x + 2\Omega r \sin \theta \dot{\theta}_y)$$

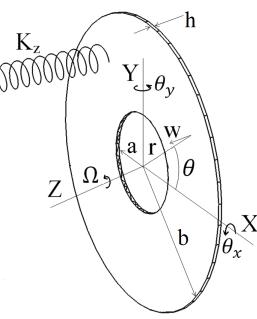
$$= -\frac{k_z}{r} (w + Z + r_k \sin \theta_k \theta_x - r_k \cos \theta_k \theta_y) + \frac{f_Z}{r}$$

$$\rho h I(\ddot{\theta}_x + 2\Omega \dot{\theta}_y) + \int_0^{2\pi} \int_a^b \rho h \sin \theta (w_{,tt} + 2\Omega w_{,t\theta}) r^2 dr d\theta = f_s r_k \sin \theta_k + f_Z r_f \sin \theta_f$$

$$\rho h I(\ddot{\theta}_y - 2\Omega \dot{\theta}_x) + \int_0^{2\pi} \int_a^b \rho h \cos \theta (w_{,tt} + 2\Omega w_{,t\theta}) r^2 dr d\theta = -f_s r_k \cos \theta_k - f_Z r_f \cos \theta_f$$

$$m \ddot{Z} + \int_0^{2\pi} \int_a^b \rho h(w_{,tt}) r dr d\theta = -k_z (w + Z + r_k \sin \theta_k \theta_x - r_k \cos \theta_k \theta_y) + f_Z$$

It took me over a year to solve these!

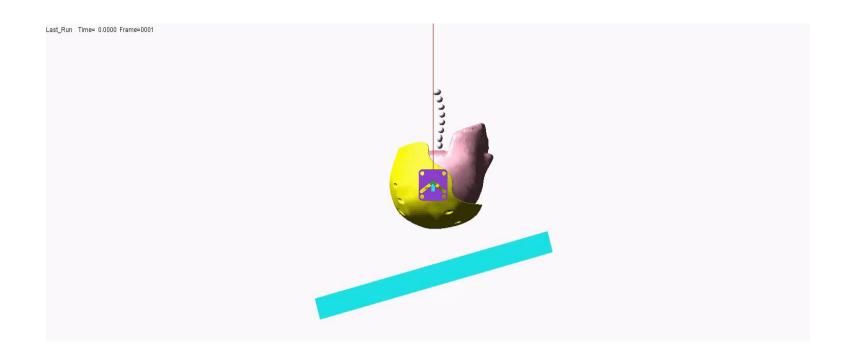


Neck Injury in Sports Simulation



 $Image \ from: https://www.sltrib.com/sports/2018/05/22/helmet-hits-make-for-legendary-nfl-films-highlights-and-this-year-players-will-be-ejected-for-it/$

Simulation of Neck Injury during falling with a Helmet



Access the software

Google ADAMS for students (enjoy the free license, while student!)

Resource to learn the software:

I put a user manual on my website: https://AIntelligentManufacturing.com/