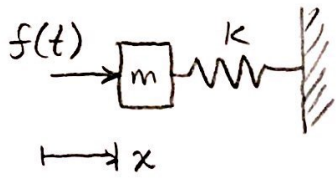
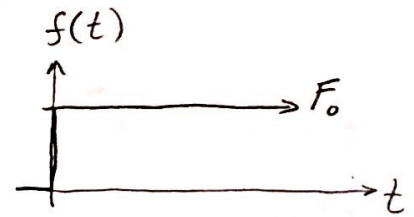


Non-Harmonic Forced Vibrations



$f(t)$ is a step function:



Equation of motion: $m\ddot{x} + kx = F_0$

Solution: $x(t) = \underbrace{A\cos(\omega t) - B\sin(\omega t)}_{\text{complementary}} + \underbrace{\frac{F_0}{k}}_{\text{particular}}$

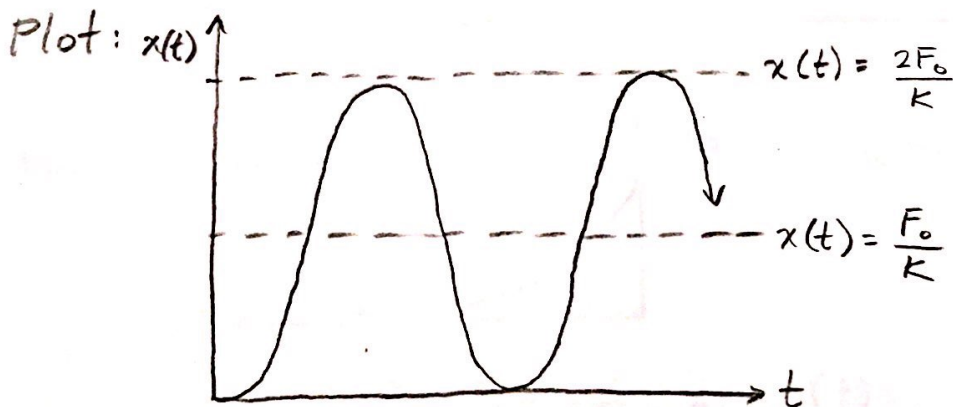
Initial conditions: $x(0)$ and $\dot{x}(0)$ equal 0.

$$\Rightarrow x(0) = A - 0 + \frac{F_0}{k}$$

$$\Rightarrow \dot{x}(0) = -\omega A \sin(\omega t) - \omega B \cos(\omega t)$$

$$\Rightarrow A = -\frac{F_0}{k} \quad \text{and} \quad B = 0$$

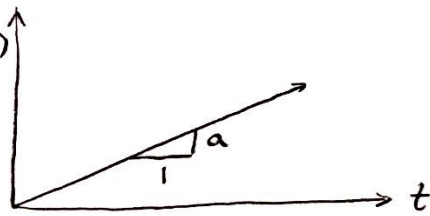
Full solution: $x(t) = \frac{F_0}{k} (1 - \cos(\omega t))$



If the system is damped, it oscillates around, and settles on, $\frac{F_0}{k}$.

Ex: $f(t)$ is ramp function: $f(t)$

$$\Rightarrow f(t) = at$$



Equation of motion: $m\ddot{x} + kx = at$

$$\text{Solution: } x(t) = A\cos(\omega t) - B\sin(\omega t) + \frac{at}{k}$$

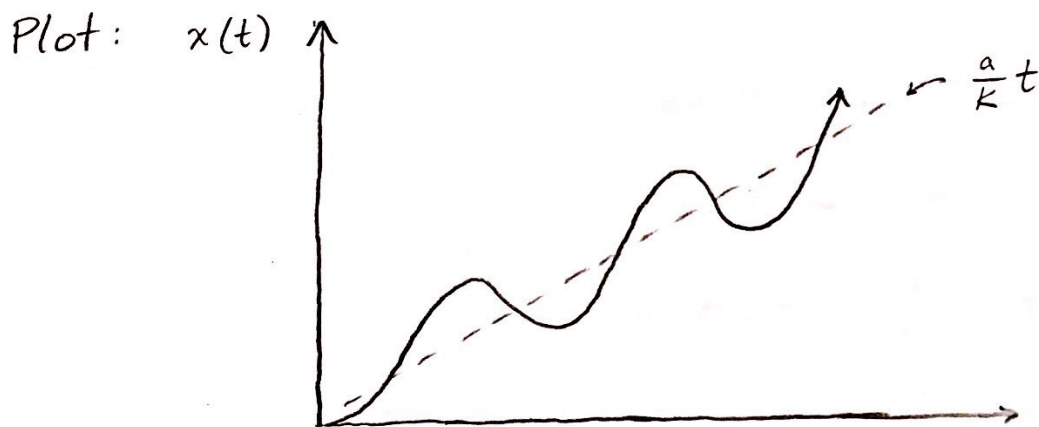
Initial conditions: $x(0)$ and $\dot{x}(0)$ are 0.

$$\Rightarrow x(0) = A - 0 + 0$$

$$\Rightarrow \dot{x}(0) = 0 - \omega B + \frac{a}{k}$$

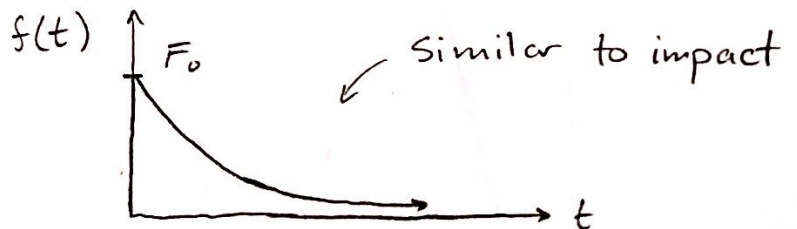
$$\Rightarrow A = 0 \text{ and } B = \frac{a}{\omega k}$$

$$\text{Full solution: } x(t) = \frac{a}{\omega k} (\omega t - \sin(\omega t))$$



Ex: Exponential decay

$$\Rightarrow f(t) = F_0 e^{-at}$$



$$\text{Equation of motion: } x(t) = m\ddot{x} + kx = F_0 e^{-at}$$

$$\text{Solution: } x(t) = A\cos(\omega t) - B\sin(\omega t) + \frac{F_0 e^{-at}}{ma^2 + k}$$

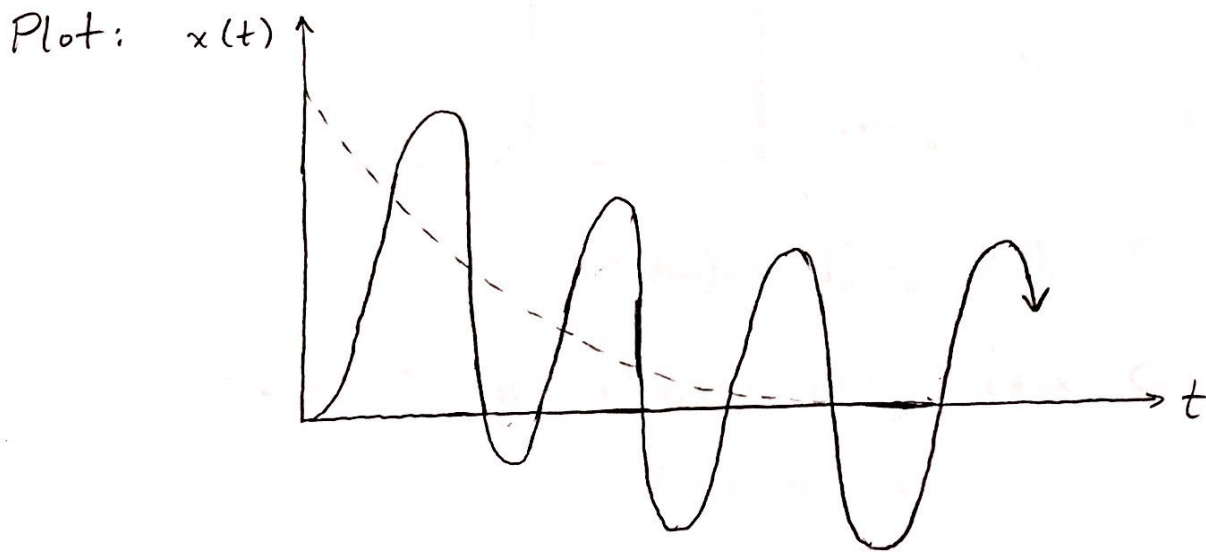
Initial conditions: $x(0)$ and $\dot{x}(0)$ are 0.

$$\Rightarrow x(0) = A - 0 + \frac{F_0}{ma^2 + k}$$

$$\Rightarrow \dot{x}(0) = 0 - \omega B - \frac{F_0 a}{ma^2 + k}$$

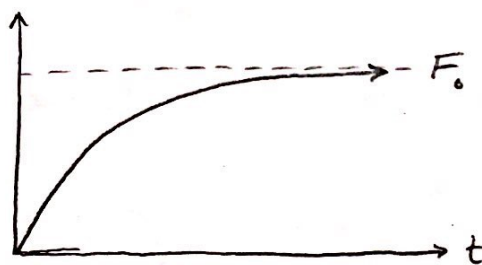
$$\Rightarrow A = \frac{-F_0}{ma^2 + k} \quad \text{and} \quad B = \frac{-F_0 a}{\omega(ma^2 + k)}$$

$$\text{Full solution: } x(t) = \frac{F_0}{ma^2 + k} \left(\frac{a}{\omega} \sin(\omega t) - \cos(\omega t) + e^{-at} \right)$$



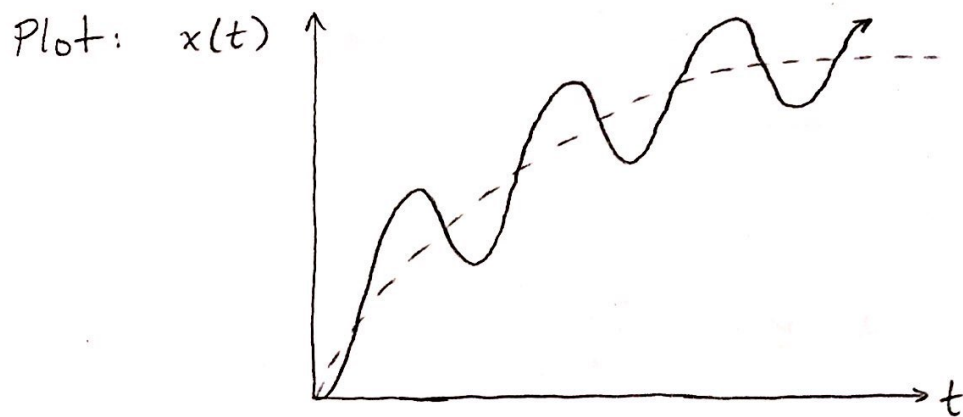
Ex: Exponential step $f(t)$

$$\Rightarrow f(t) = F_0 (1 - e^{-at})$$

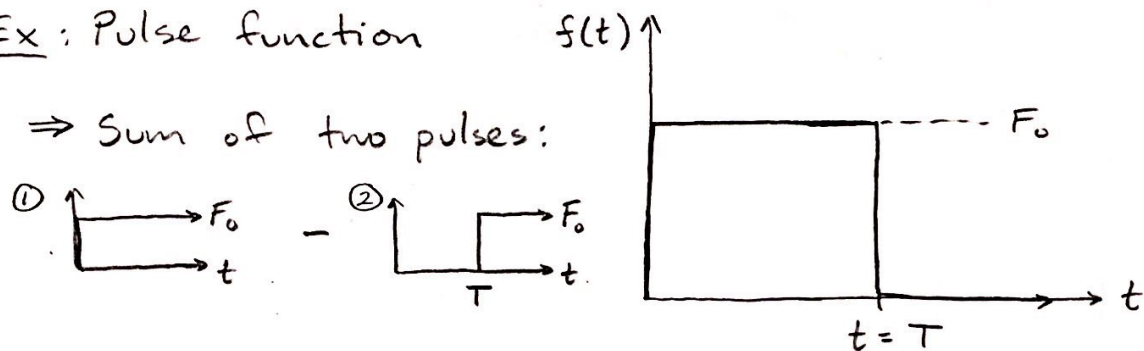


Use superposition. Response is sum of step & -exponential

$$\Rightarrow x(t) = \frac{F_0}{k} (1 - \cos(\omega t)) - \frac{F_0}{ma^2 + k} \left(\frac{a}{\omega} \sin(\omega t) - \cos(\omega t) + e^{-at} \right)$$



Ex: Pulse function

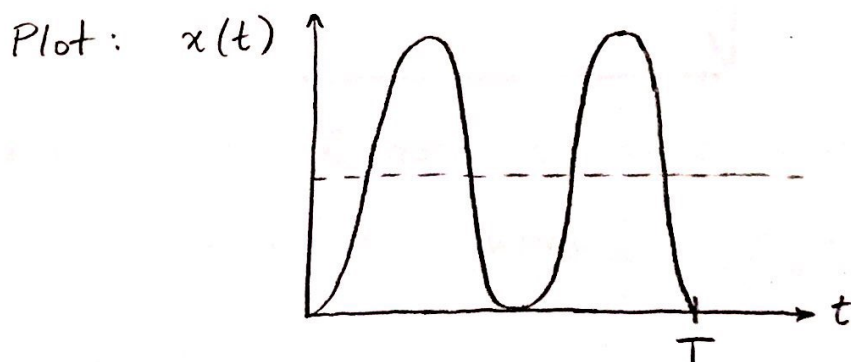


For pulse ①: $x_1(t) = \frac{F_0}{k} (1 - \cos(\omega t))$

For pulse ②: $x_2(t) = -\frac{F_0}{k} (1 - \cos(\omega(t-T)))$ for $t > T$
 $= 0$ for $t < T$

Full solution: $x(t) = \frac{F_0}{k} (\cos(\omega(t-T)) - \cos(\omega t))$ for $t > T$

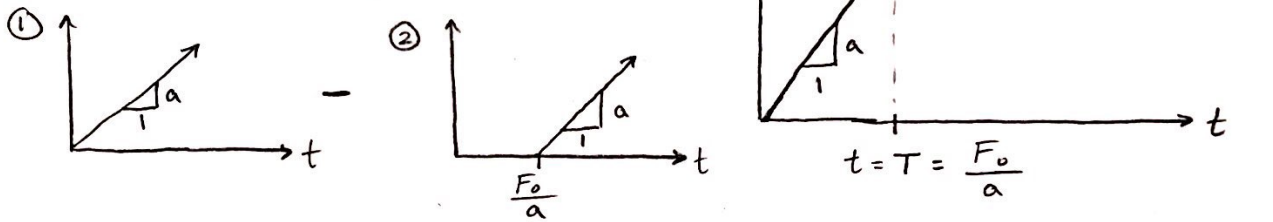
Notice that if $T = \frac{2n\pi}{\omega} \Rightarrow x(t) = 0$ for $t > T$



If we time pulses correctly the system stops oscillating.

Ex: Ramped step $f(t)$

Sum of two pulses:



For $t > T$: $x(t) = \frac{a}{k\omega} (\omega t - \sin(\omega t)) - \frac{a}{k\omega} (\omega(t-T) - \sin(\omega(t-T)))$

Trig identities: $x(t) = \frac{a}{k\omega} (\omega T + \sin(\omega(t-T)) - \sin(\omega(t-T)))$

If $T = \frac{2n\pi}{\omega} \Rightarrow x(t) = \frac{aT}{k} = \frac{F_0}{k}$