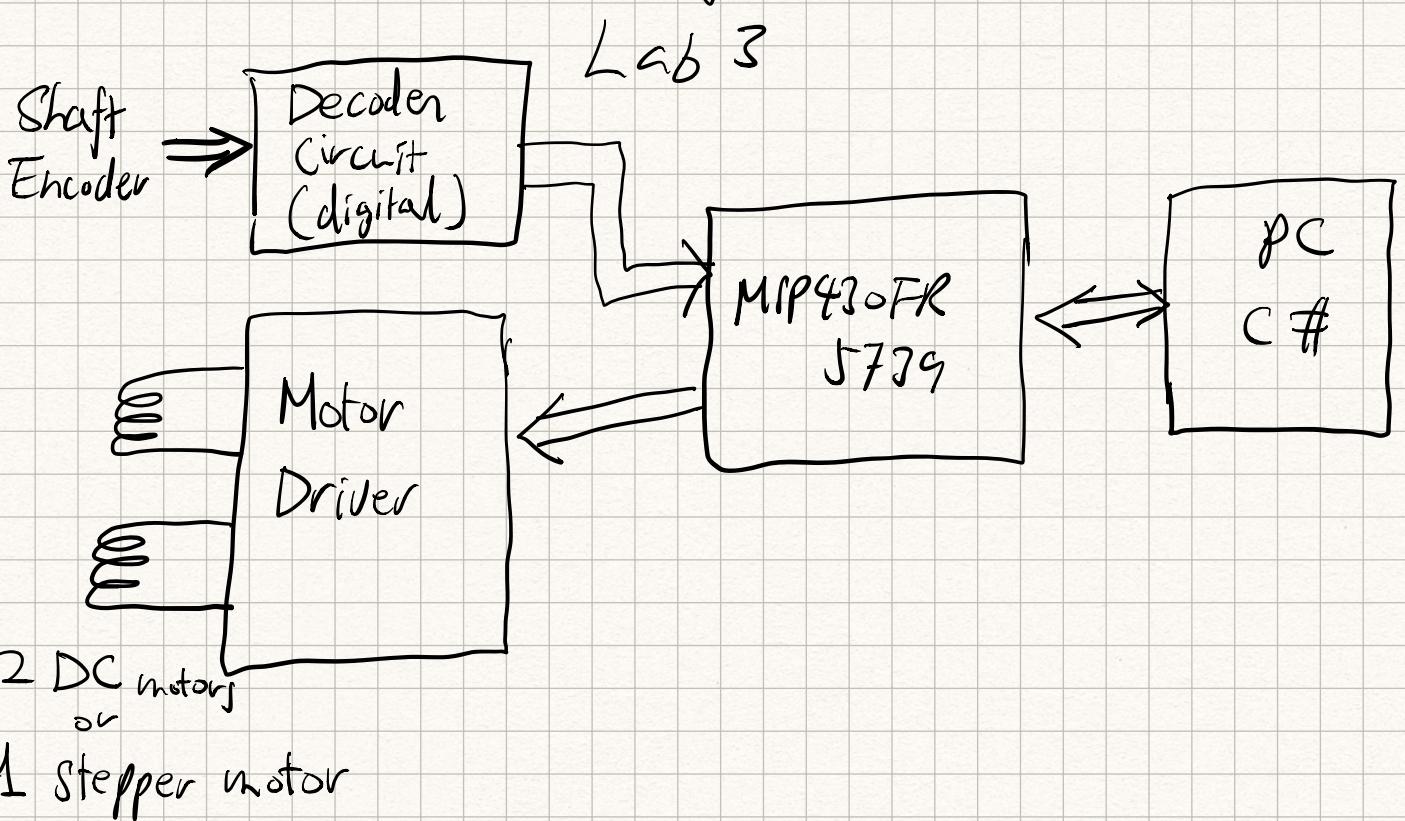
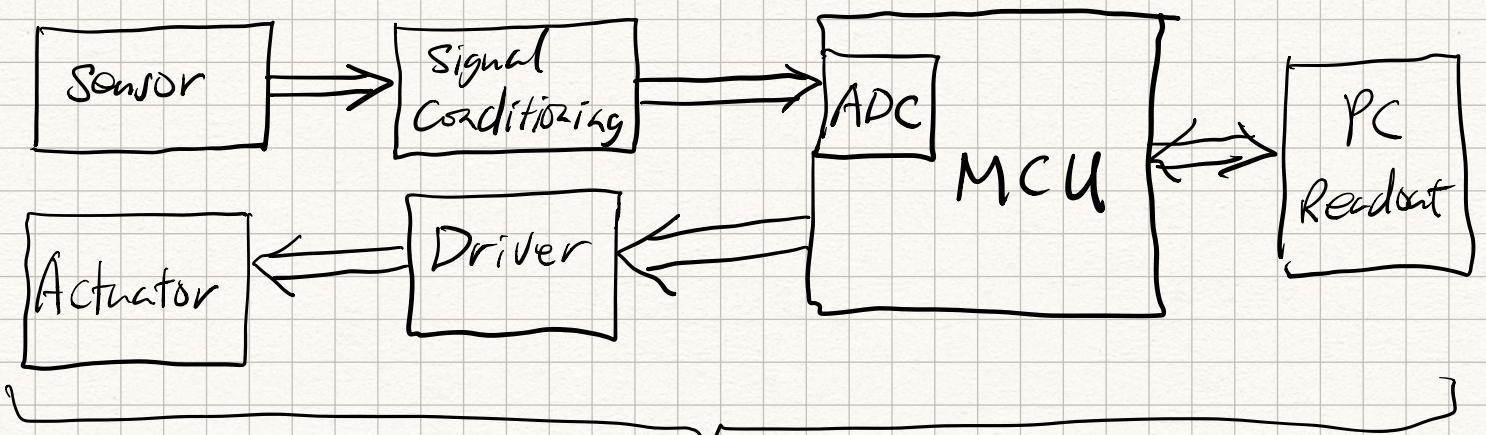
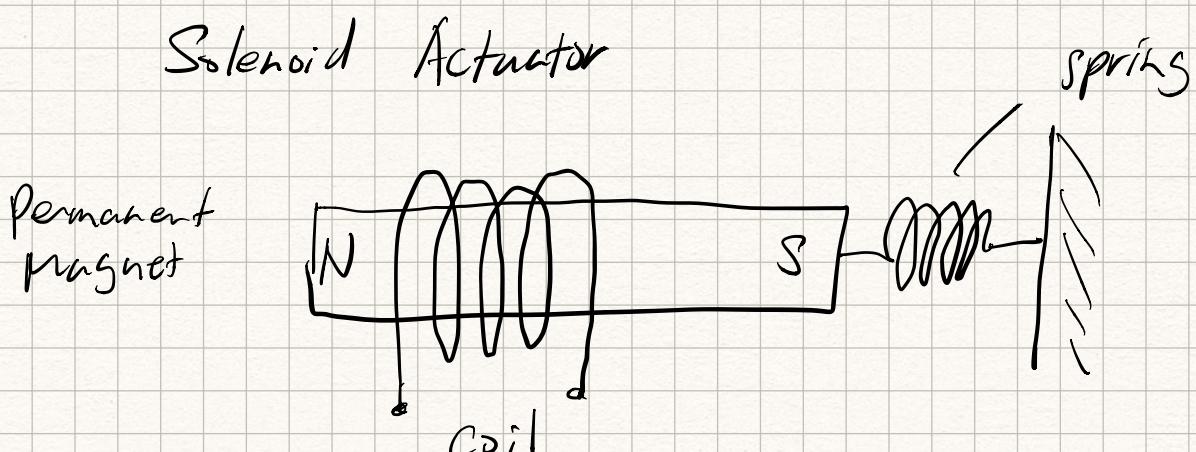


# MECH 423 Lecture 12



Inductive Actuators & How to drive them.

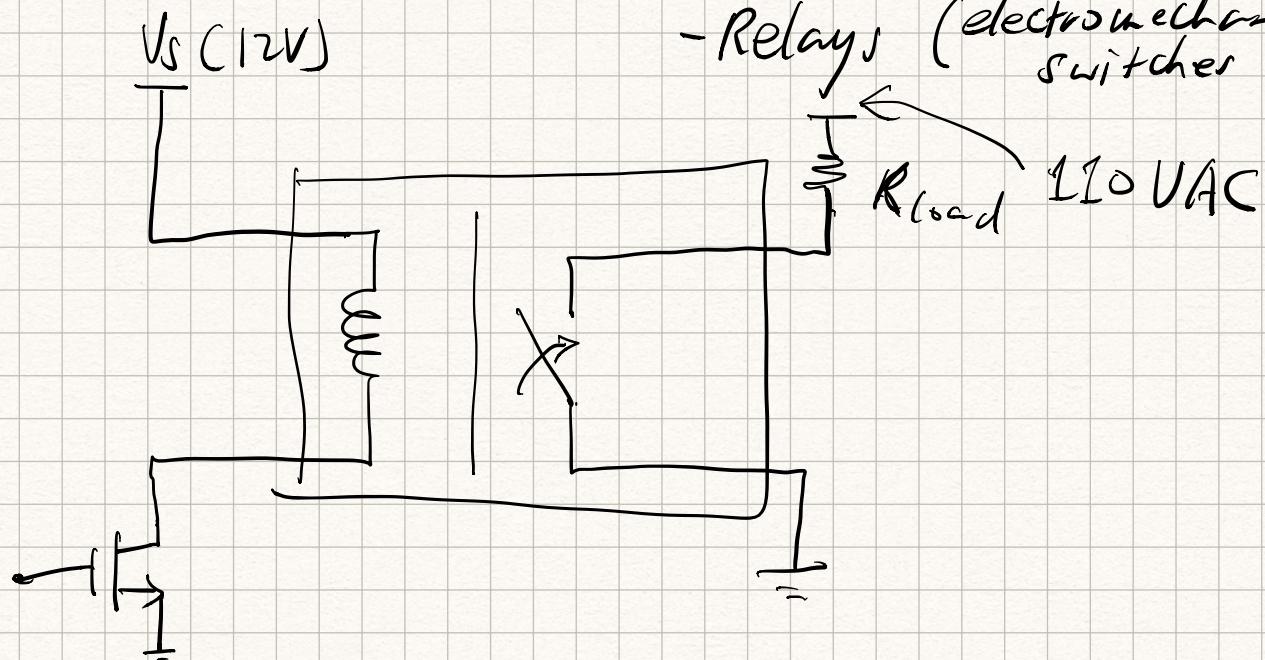


- Bistable linear motion.

- Speed  $\sim 100\text{ms}$

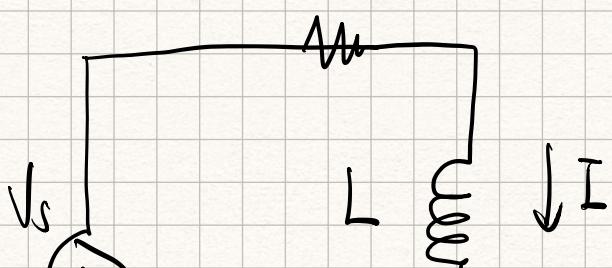
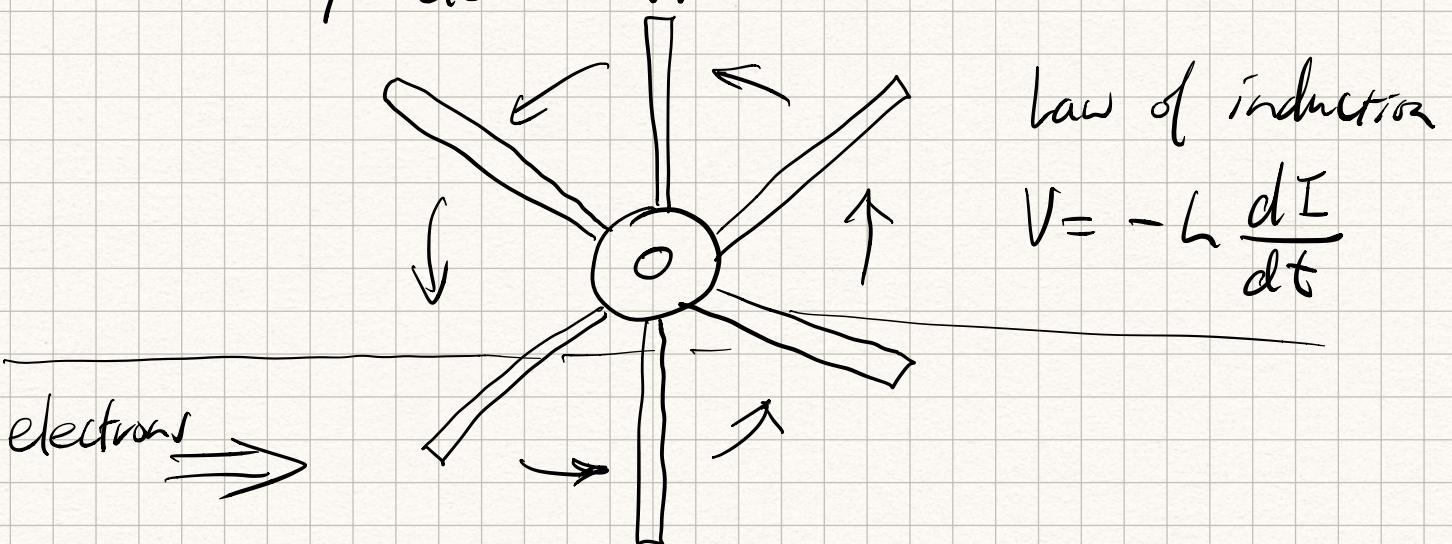
## Application Examples:

- Door lock
- Flow control valves
- Relays (electromechanical) switches



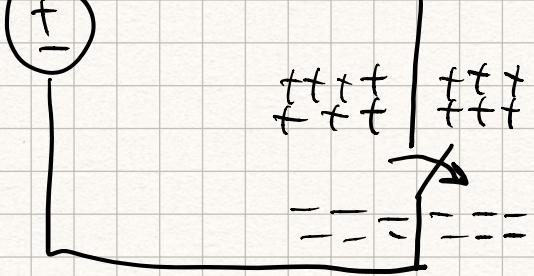
\* An inductor is an energy storage device

⇒ Inductor stores energy in the momentum of electrons.



\* Initially, switch is closed  
- current  $I$  through the inductor

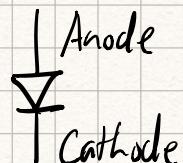
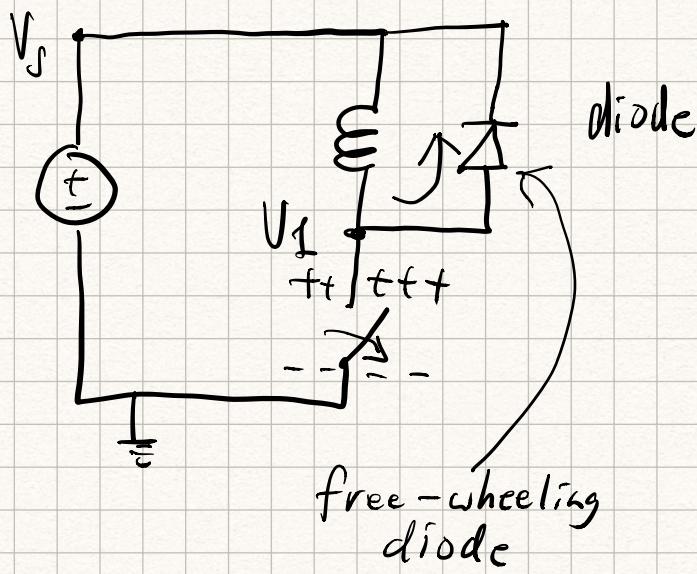
\* Open the circuit



- \* The inductor pushes charges on to either side of the switch
- \* Kaboom! Electrical breakdown

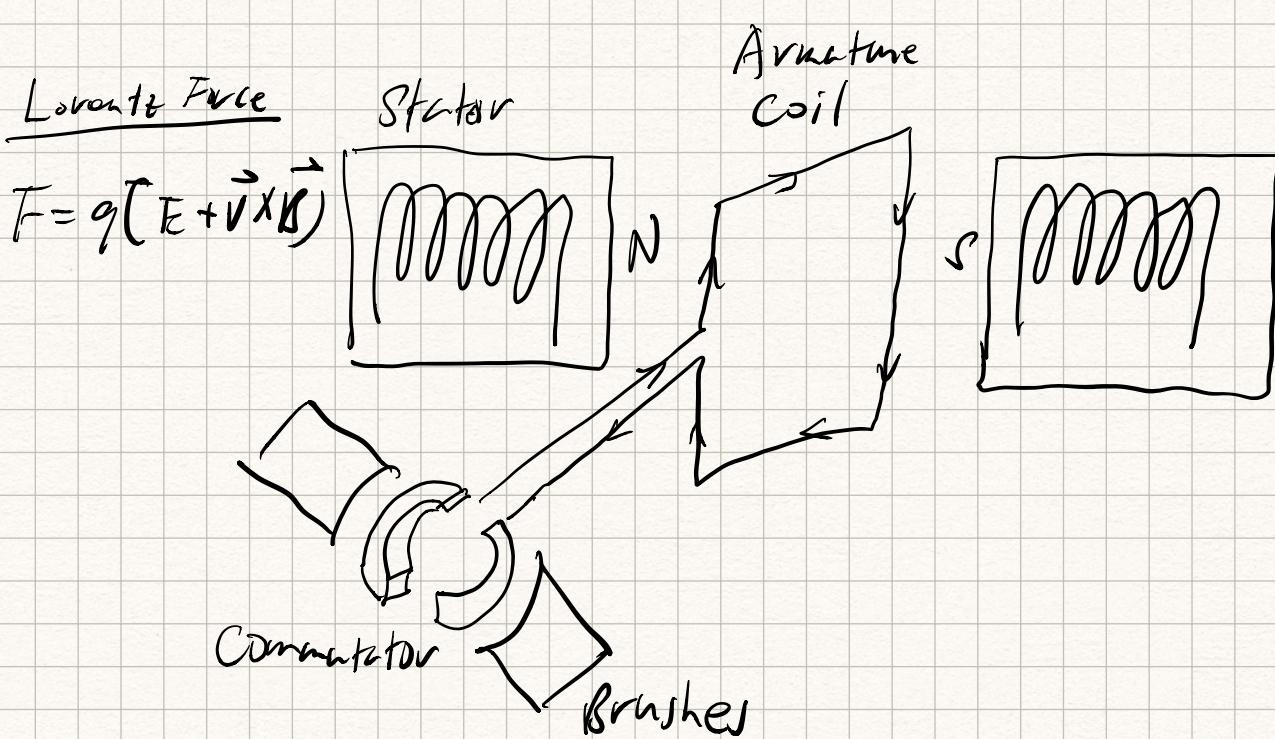
$$V = -L \frac{dI}{dt} \quad \frac{dI}{dt} \rightarrow \infty \quad V \rightarrow -\infty$$

How to fix this problem:

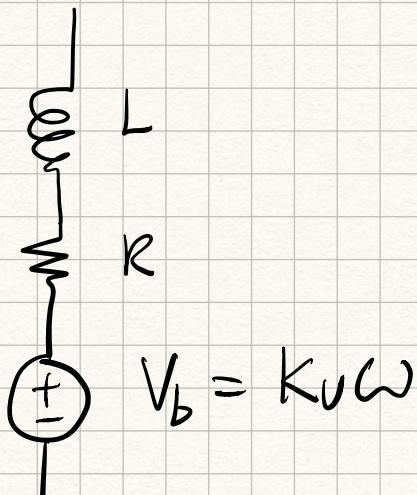


- \* When the switch is closed
  - diode has no effect
- \* When the switch is opened
  - $V_1 \uparrow$  but the diode clamps
  - $V_1 \leq V_s + V_D$
  - $V_D \sim 0.7V$

## Brushed DC Motors

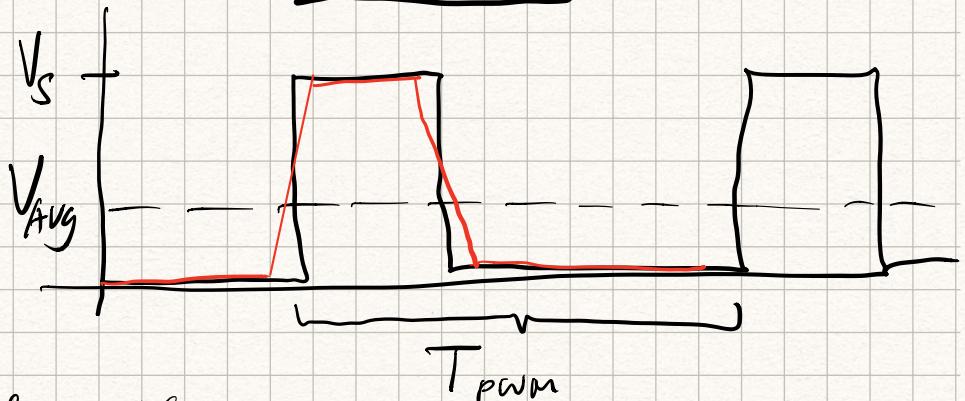


## Electrical Model



How to select the PWM freq?

$$f_{\text{PWM}} = \frac{1}{T_{\text{PWM}}}$$



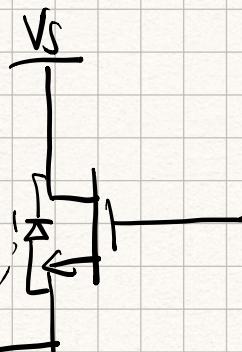
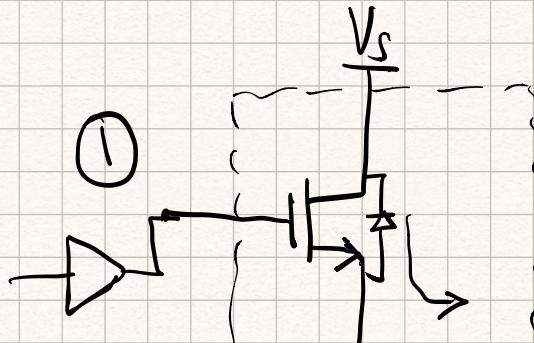
- \*  $T_{\text{PWM}}$  should be less than the mech. response time.
- \*  $T_{\text{PWM}}$  should be greater than the elec. response time.
  - Prevent energy loss in the switch

$$\begin{aligned} T_{\text{elec}} &< T_{\text{PWM}} &< T_{\text{mech}} \\ 10\text{kHz} &> f_{\text{PWM}} &> 100\text{Hz} \end{aligned}$$

↑  
PWM Noise

## Bidirectional Drive

- Need an H-bridge



### Forward

- ① 1 ③ ON
- ② 2 ④ OFF

### Reverse

- ② ③ ④ ON

