

# Computer Vision

ITCS 4152 / 5152

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# Introduction to Computer Vision

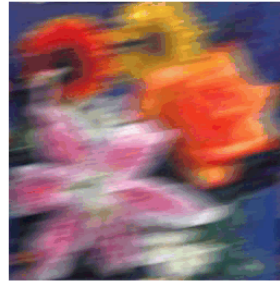
Slides adapted from James Hays, Steve Seitz,  
Amnon Shashua

# What is computer vision?

- Trucco and Verri: computing properties of the 3D world from one or more digital images
- Stockman and Shapiro: To make useful decisions about real physical objects and scenes based on sensed images
- Ballard and Brown: The construction of explicit, meaningful description of physical objects from images
- Forsyth and Ponce: Extracting descriptions of the world from pictures or sequences of pictures

# Related Fields

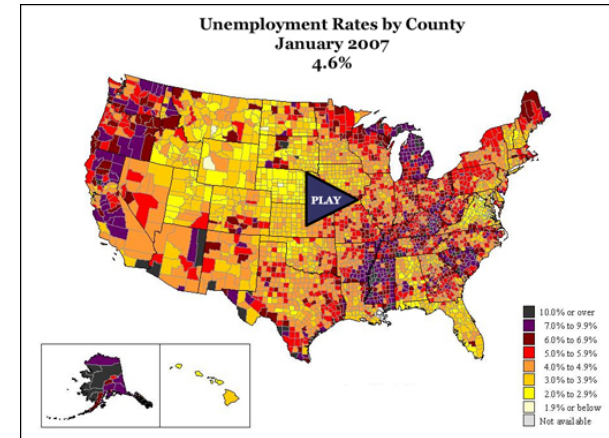
- Image processing
  - images  $\rightarrow$  images
- Visualization
  - data  $\rightarrow$  images
- Graphics
  - models  $\rightarrow$  images
- *Computer Vision*
  - images  $\rightarrow$  models



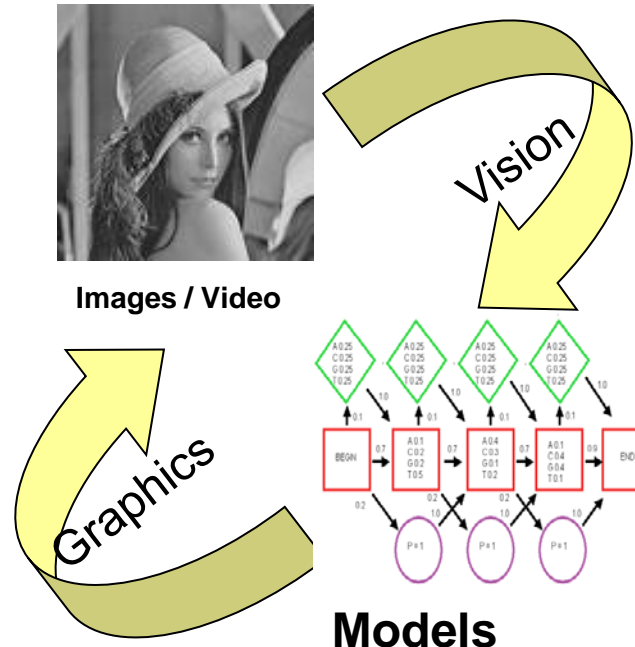
Blurred image



Image restored by Wiener filter



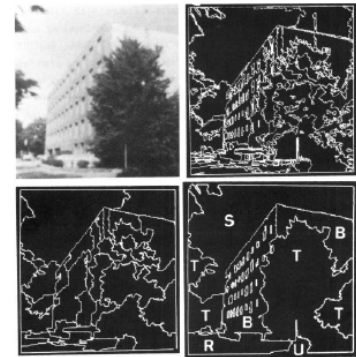
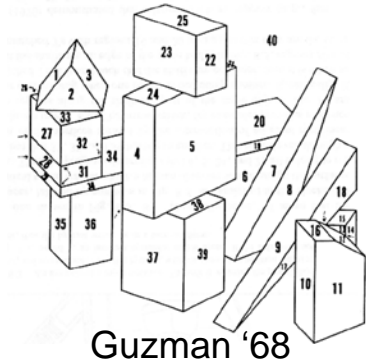
Images / Video



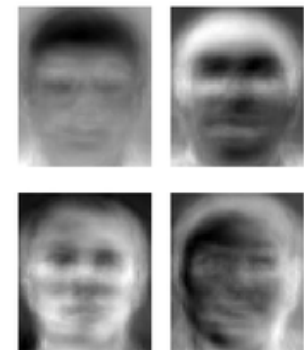
Models

# Ridiculously brief history of computer vision

- David Marr (1945-1980): integrated results from psychology, artificial intelligence, and neurophysiology into new models of visual processing. (Marr Prize in ICCV)
- 1966: Minsky assigns computer vision as an undergrad summer project
- 1960's: interpretation of synthetic worlds
- 1970's: some progress on interpreting selected images
- 1980's: ANNs come and go; shift toward geometry and increased mathematical rigor
- 1990's: face recognition; statistical analysis in vogue
- 2000's: broader recognition; large annotated datasets available; video processing starts
- Now: Deep learning such as deep CNN, Examples of state-of-the-art



Ohta Kanade '78

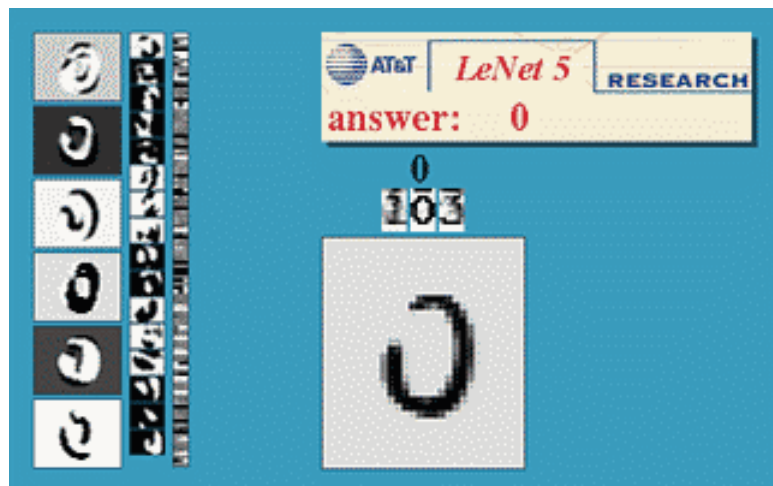


Turk and Pentland '91

# Optical character recognition (OCR)

Technology to convert scanned docs to text

- If you have a scanner, it probably came with OCR software



Digit recognition, AT&T labs

<http://www.research.att.com/~yann/>



License plate readers

[http://en.wikipedia.org/wiki/Automatic\\_number\\_plate\\_recognition](http://en.wikipedia.org/wiki/Automatic_number_plate_recognition)

# Face Detection

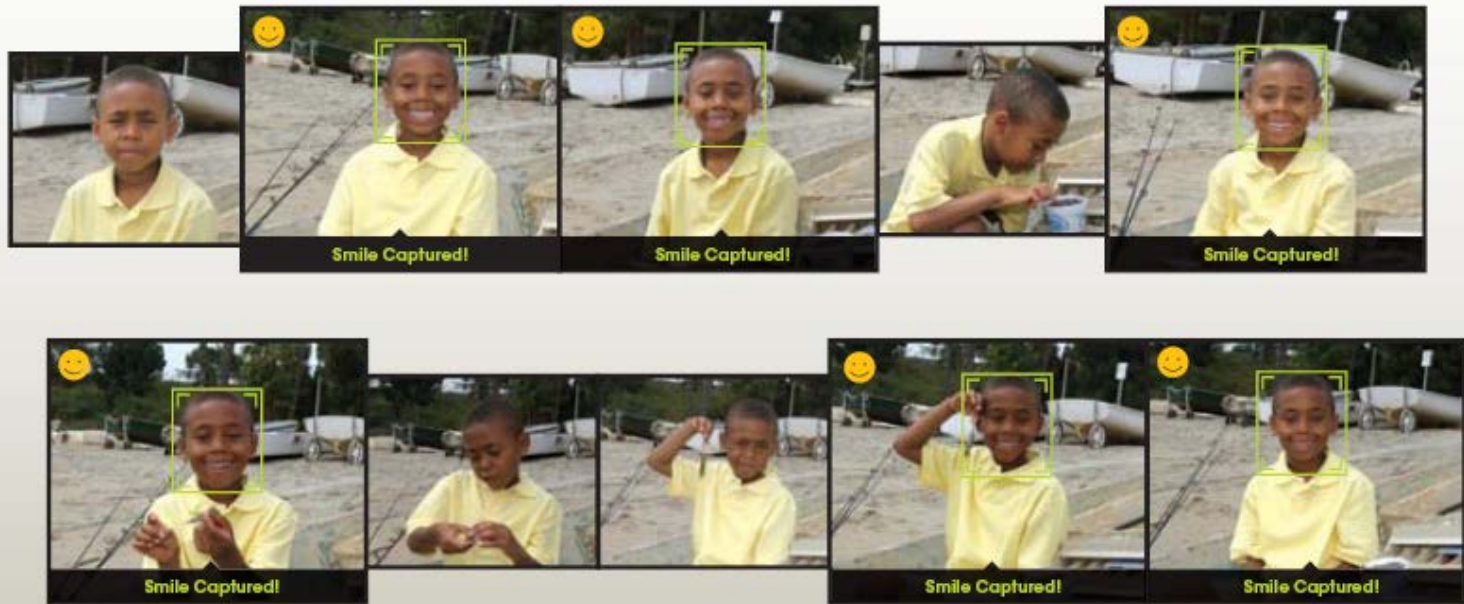


- Many new digital cameras now detect faces
  - Canon, Sony, Fuji, ...

# Smile detection

## The Smile Shutter flow

Imagine a camera smart enough to catch every smile! In Smile Shutter Mode, your Cyber-shot® camera can automatically trip the shutter at just the right instant to catch the perfect expression.



[Sony Cyber-shot® T70 Digital Still Camera](#)



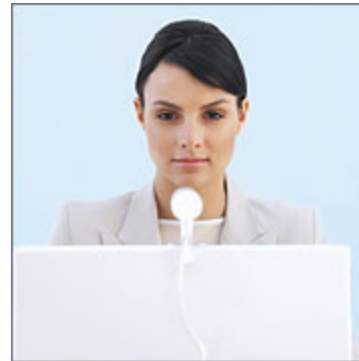
# 3D from thousands of images



# Login without a password...



Fingerprint scanners on  
many new laptops,  
other devices



Face recognition systems now  
beginning to appear more widely  
<http://www.sensiblevision.com/>

# Object recognition (in mobile phones)



Point & Find, Nokia  
Google Goggles

# Sports



*Sportvision* first down line  
Nice [explanation](#) on [www.howstuffworks.com](http://www.howstuffworks.com)

<http://www.sportvision.com/video.html>

# Business Analytics



**Reveal** (Auckland, New Zealand). Systems for counting and tracking pedestrians using overhead cameras.



# Smart Cars

The screenshot displays the Mobileye website with a top navigation bar containing 'manufacturer products' and 'consumer products'. The main header reads 'Our Vision. Your Safety.' Below this is a top-down view of a car with four camera fields of view highlighted: 'rear looking camera', 'forward looking camera', and 'side looking camera'. The bottom section is divided into three columns: 'EyeQ Vision on a Chip' featuring a chip image, 'Vision Applications' showing a pedestrian in a bounding box, and 'AWS Advance Warning System' with a circular display showing a car icon and the number '0.8'. A right sidebar contains 'News' and 'Events' sections with links to various press releases and events.

manufacturer products consumer products

**Our Vision. Your Safety.**

rear looking camera forward looking camera side looking camera

**EyeQ** Vision on a Chip

**Vision Applications**  
Road, Vehicle, Pedestrian Protection and more

**AWS** Advance Warning System

**News**

- > **Mobileye Advanced Technologies Power Volvo Cars World First Collision Warning With Auto Brake System**
- > **Volvo: New Collision Warning with Auto Brake Helps Prevent Rear-end**
- > all news

**Events**

- > **Mobileye at Equip Auto, Paris, France**
- > **Mobileye at SEMA, Las Vegas, NV**
- > read more

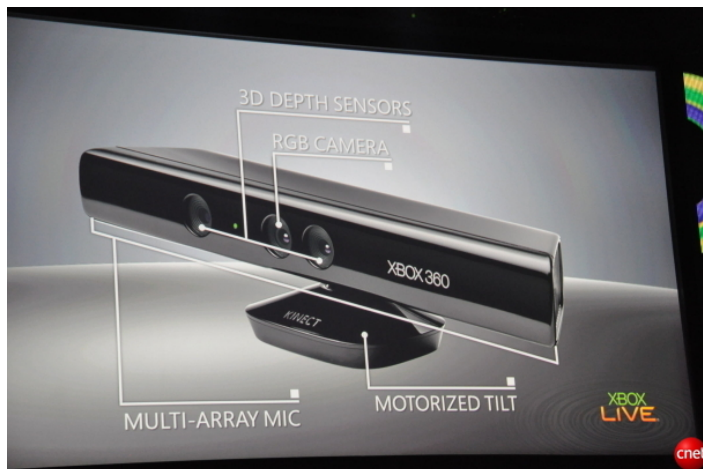
- [Mobileye](#)
  - Vision systems currently in high-end BMW, GM, Volvo models
  - 2010: ~70% of car companies use smart cams

# Google Self-Driving Cars



# Interactive Games: Kinect

- Object Recognition:  
<http://www.youtube.com/watch?feature=iv&v=fQ59dXOo63o>
- Mario: <http://www.youtube.com/watch?v=8CTJL5IUjHg>
- 3D: <http://www.youtube.com/watch?v=7QrnwoO1-8A>
- Robot: <http://www.youtube.com/watch?v=w8BmgtMKFbY>





# Vision in space



[NASA'S Mars Exploration Rover Spirit](#) captured this westward view from atop a low plateau where Spirit spent the closing months of 2007.

## Vision systems (JPL) used for several tasks

- Panorama stitching
- 3D terrain modeling
- Obstacle detection, position tracking
- For more, read “[Computer Vision on Mars](#)” by Matthies et al.

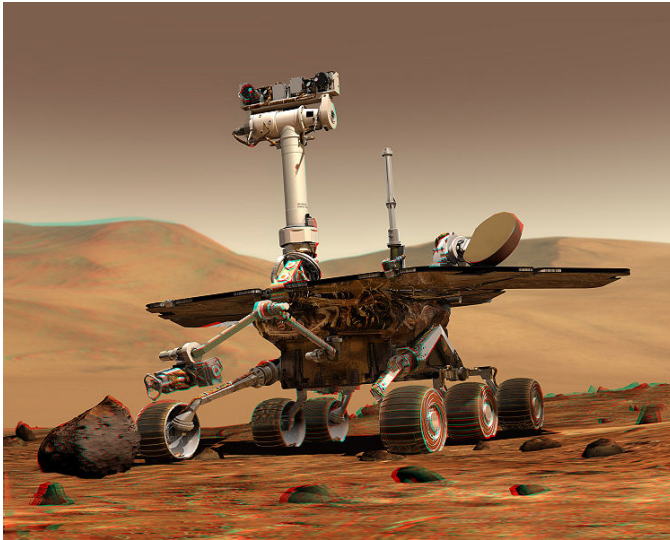
# Industrial Robots

*(Often called Machine Vision)*



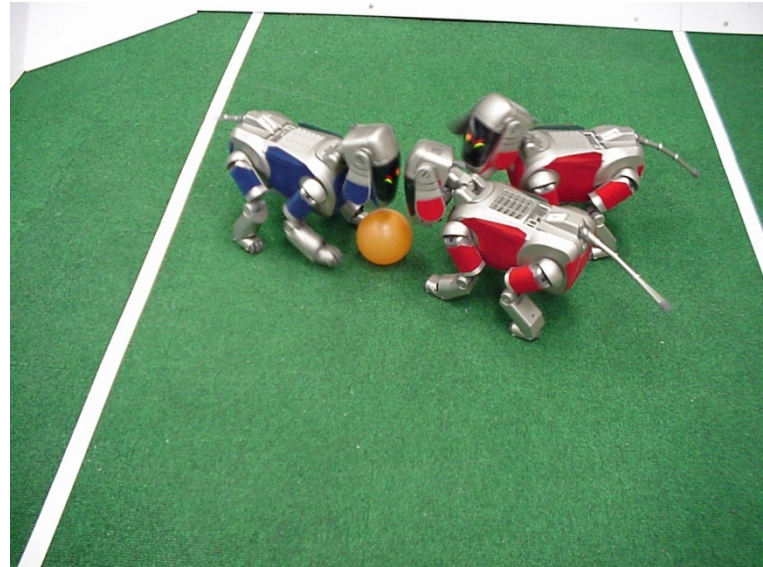
Vision-guided robots position nut runners on wheels

# Mobile Robotics

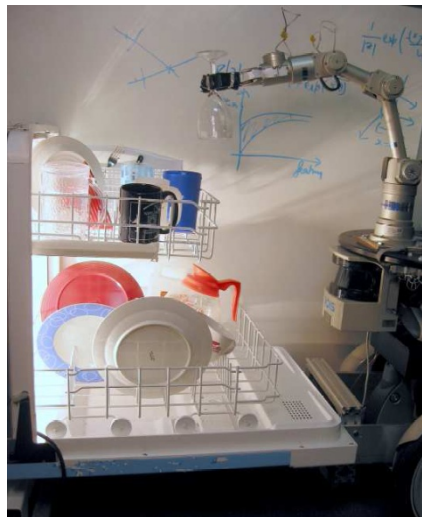


NASA's Mars Spirit Rover

[http://en.wikipedia.org/wiki/Spirit\\_rover](http://en.wikipedia.org/wiki/Spirit_rover)



<http://www.robocup.org/>

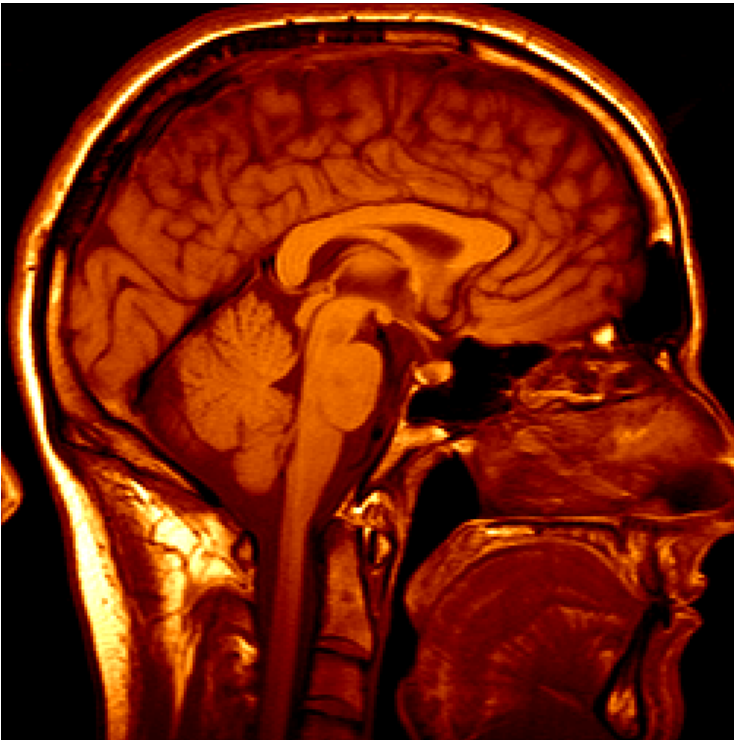


Saxena et al. 2008

[STAIR](#) at Stanford



# Medical imaging



3D imaging  
MRI, CT



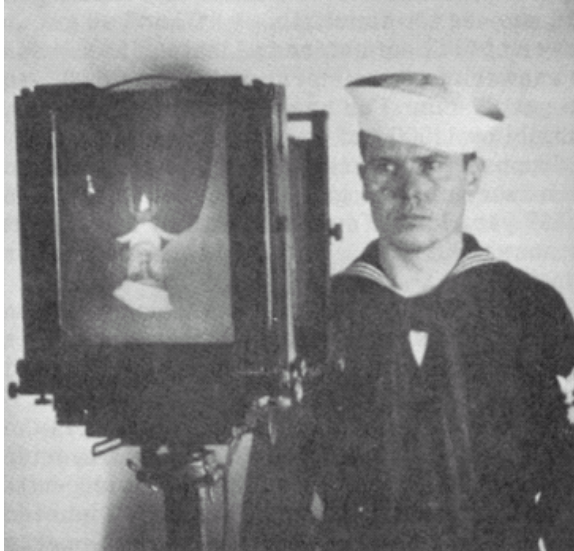
Image guided surgery  
[Grimson et al., MIT](#)

# Sounds like fun...

- What math background do I need for this course?
- What CS background do I need for this course?
- What are we going to learn?

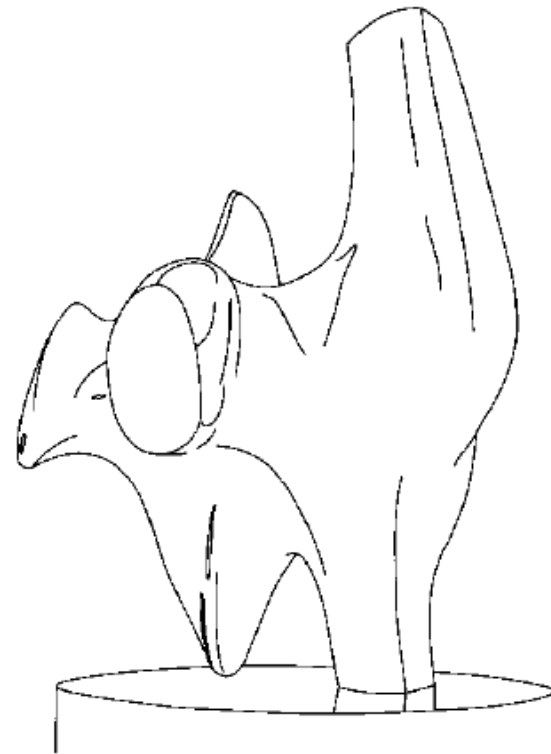
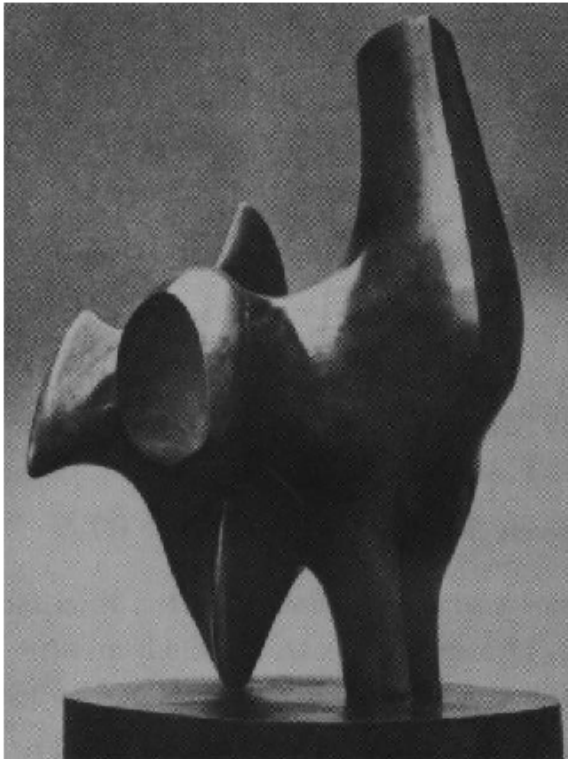
# Image Formation

- Brief history & progression different cameras and optics.
- This is not a hardware course, but we need to know how images are generated



Geometry, Linear Algebra

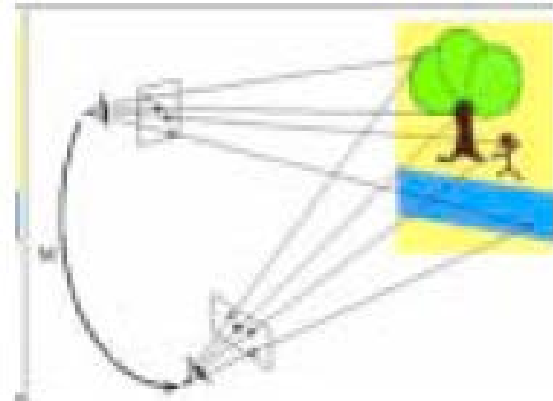
# Finding “Interest Points”



Derivatives and Convolutions

# Stereo

- Humans use stereo... so, it must be a good thing
- What can you do with 2 cameras that you cannot do with one?
- Linear Algebra,
- Geometry,
- Robust Statistics

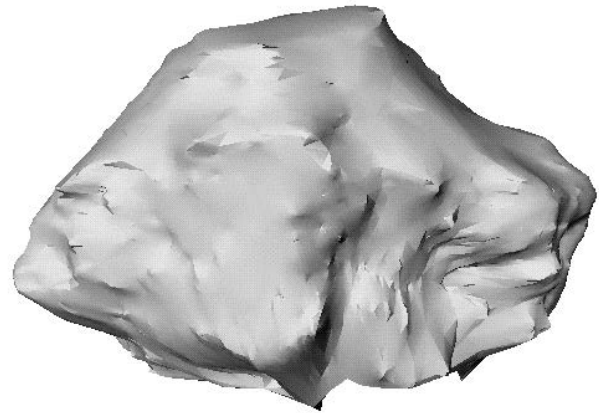
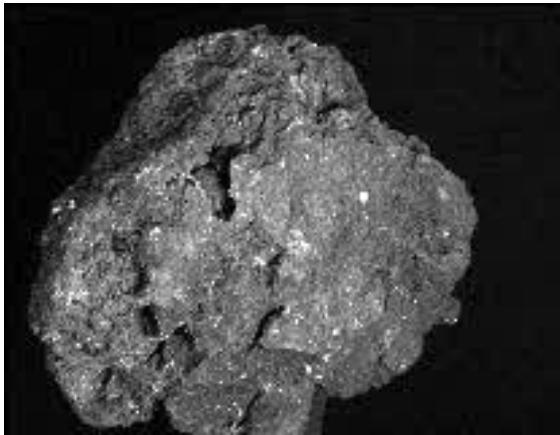




# Motion & Video

- Interpreting motion in video
- Measuring motion
- Relate motion to 3D shape

Linear Algebra,  
Geometry,  
Statistics



# Detection and Classification

## Machine Learning + Computer Vision



What kind of scene?

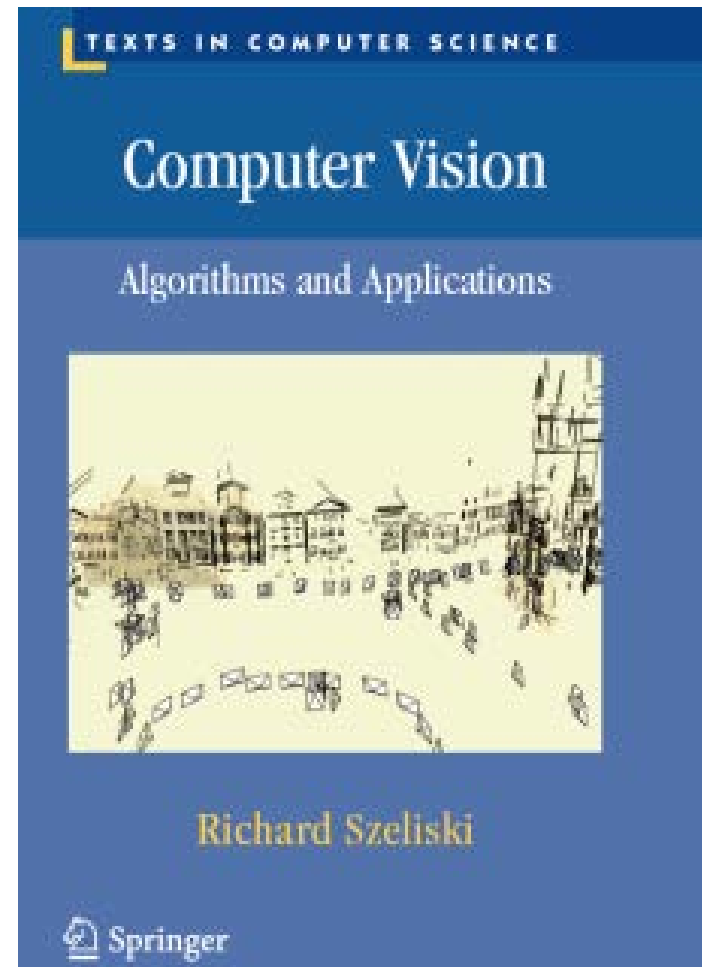
Where are the cars?

Which part of the  
image corresponds  
to “sky”?

...

# Course Textbook

- Should I buy it?
  - If you hate reading PDFs that you can get online for free, sure.
- Computer Vision: Algorithms and Applications  
*by Richard Szeliski*
  - PDF available online
  - You can also buy hardcopy
- \$60 on Amazon.com



# Slides, Lectures, Attendance

- Attendance is required
  - Most of the material is in the book
  - You are responsible for any announcements made in class.
  - Productive participation in class is a criteria for resolving borderline final grades
- Slides are posted on Moodle *after*\* class

# Homework & Exams

- The 3-5 homework assignments will generally take the form of programming assignments where you implement methods we cover
- The 1-2 exams will cover the theoretical / mathematical aspects of the methods
- There may be a final project
  - More details later

# Programming Language

- Matlab is the programming language for this course\*
  - Pros: Rapid prototyping, widely used by the CV community, lots of available code, familiar syntax
  - Cons: Expensive
- Installed on UNCC computer lab machines
- Open-source alternative: Octave

*\*One exception is for the final project if another language is more suitable (e.g., mobile, real-time)*

# How can I learn Matlab for this course?

- It's not too hard. Syntax should be familiar to Java / C / C++ user. (You can make direct Java calls, in fact.)
- Lots of tutorials on the web
  - Some resources on Moodle page
- *There will be one Recitation on Matlab primer*

# Additional Course Information

- For hw0, you must read the syllabus on UNCC Policy on Academic Integrity
- Cheating, plagiarism are taken very seriously and dealt with harshly.
- Be familiar with the course policies as stated on the syllabus available online.



# How should I go about getting help?

- Depends on the problem
- Ex: “How do I open an image using Matlab?”
  - Google
- Ex: “I don’t understand why we are multiplying this matrix by this vector.”
  - Ask TA, or come to my office hours
- Ex: “I would like to patent / publish this great idea!”
  - Ask the TA for my cell phone number and contact me immediately!

# Next Steps

- 2 Assignments posted
  - Hw0: read the syllabus and academic integrity policy
  - Hw1: Image Processing, Computer Vision, “Grand Challenge”: Eye localization (due in two weeks).