

Design and Analysis of Algorithms

L37: LC Branch and Bound 0-1 Knapsack Problem

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Resources

- Text book 2: Horowitz
 - Sec 8.2
- Text book 1: Levitin
 - Sec 12.1, **12.2**
- R1: Introduction to Algorithms
 - Cormen et al.
- Youtube link for lecture recording
 - <https://www.youtube.com/watch?v=j556E7Lgvbl>
- Youtube (other)
 - https://www.youtube.com/watch?v=yVld-b_NeK8

BB Search: State Space Tree

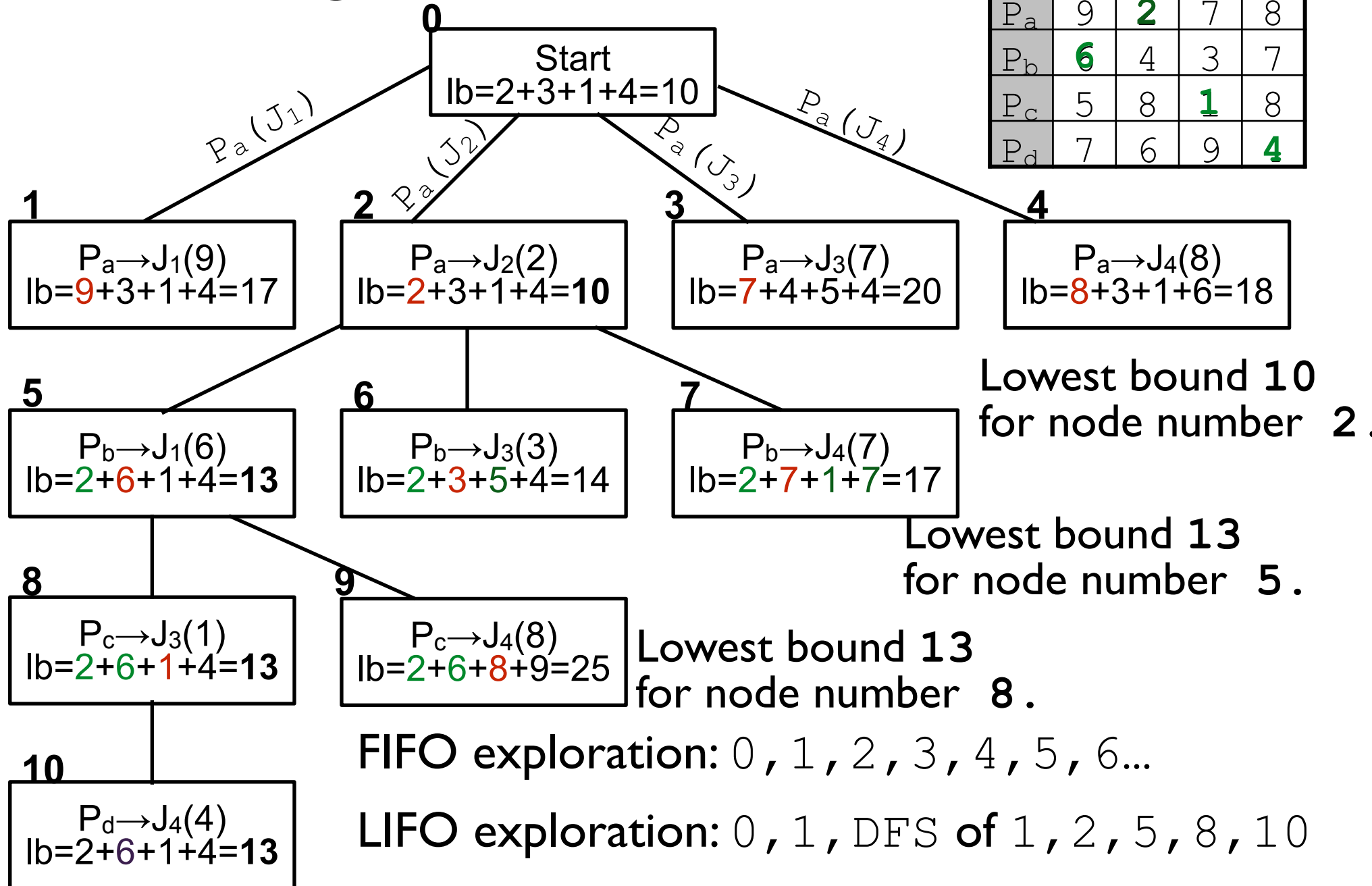
```
Algo BBSearch (node t) // search tree with root at t.  
if t is an answer node  
    output t and return  
E ← t // make t an E-node  
Initialize the list L (of live nodes) to be empty.  
do  
    for each child x of E  
        if x is an answer node  
            output the path from x to t and return  
        Add (x) to list L of live nodes  
        parent (x) ← E  
    if L is empty // there are no more live nodes  
        output “No answer nodes” and return  
    E ← Next (L) // take the next live node from to search  
while True
```

BB Search: State Space Tree

- Three possible implementation of search space
 - Depends upon how the list \mathbb{L} is implemented
 - and how the $\text{Next}(\mathbb{L})$ is taken out
- \mathbb{L} is Queue i.e. FIFO (First In First Out)
 - E-nodes are removed in the order they are added
 - Also called BFS (Breadth First search)
- \mathbb{L} is Stack i.e. LIFO (Last in First Out)
 - E-nodes are removed in the reverse order it is added
 - Also called D-search (Depth First search)
- \mathbb{L} is Heap (can be min or max heap)
 - E-nodes are removed as min (or max) value
 - Called Least Cost (LC) Search

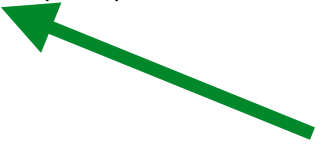
Ex: Assignment Problem

	J ₁	J ₂	J ₃	J ₄
P _a	9	2	7	8
P _b	6	4	3	7
P _c	5	8	1	8
P _d	7	6	9	4



LC Search: State Space Tree

```
Algo LCSearch (node t) // search tree with root at t.  
if t is an answer node  
    output t and return  
E ← t // make t an E-node  
Initialize the list L (of live nodes) to be empty.  
do  
    for each child x of E  
        if x is an answer node  
            output the path from x to t and return  
        Add (x) to list L of live nodes  
        parent (x) ← E  
    if L is empty // there are no more live nodes  
        output “No answer nodes” and return  
    E ← Least (L) // take the next live node from to search  
while True
```



Bound Implementation

- Consider a tree t rooted at node x .
- Let $c(x)$ denotes the cost of minimum cost answer node
 - Typically, this cost is equal to objective function value, e.g.
 - Min cost in job assignment problem, TSP
 - Computing $c(x)$ is the main task to find the answer node
- When exploring state space Tree using LCBB
 - We pick the node with least cost.
 - Finding (computing) it requires exploring the entire tree
 - Leads to exponential cost
 - Thus, we would try to estimate $c(x)$
- Define $\hat{c}(x)$: a heuristic (estimate) value for $c(x)$
 - Use this $\hat{c}(x)$ in picking the next least cost E-node.
 - Thus it must follow $\hat{c}(x) \leq c(x)$
 - Otherwise, we are exploring a path with **cost $> c(x)$**
 - **Reach an answer node which is not min cost**

Bound Implementation

- Defining $\hat{c}(x)$: a heuristic value for $c(x)$
 - Provides a lower bound on solutions obtainable
$$\hat{c}(x) \leq c(x)$$
- Let $upper$: upper bound on cost of min cost solution
 - Then, consider all live nodes with $\hat{c}(x) > upper$
 - These live nodes can be killed, as answer node reachable from these live nodes will have
$$c(x) \geq \hat{c}(x) > upper$$
- Initial value of $upper$ should be more than $c(x)$
 - May even be set as ∞
- Thus, as long as value of $upper$ is $\geq c(x)$
 - Killing of live nodes will not cause killing a node that can reach min cost answer node.

0–1 Knapsack Problem

- Knapsack problem:
 - Given n items of known weights w_1, \dots, w_n , and
 - Values v_1, \dots, v_n and knapsack capacity m
 - Find the most valuable subset of items that fit into the knapsack.
 - i.e. maximize the value of knapsack
 - An item has to be included in full
- (0–1 knapsack problem)
 - Note: All the weights w_i 's and knapsack capacity m are integers, but values v_i 's can be real numbers.
- 0–1 knapsack is a maximization problem
 - Branch and Bound solves minimization problem.
 - So convert knapsack to minimization problem

0–1 Knapsack Problem

- 0–1 Knapsack problem (maximization problem)
 - Maximize $\sum_{1 \leq i \leq n} V_i X_i$,
 - Subject to $\sum_{1 \leq i \leq n} W_i X_i \leq m$
 - x_i is 0 or 1, and $1 \leq i \leq n$
- Problems of TSP and Job Assignment were minimization problem solved using Branch-n-Bound
- Convert knapsack maximization to minimization
 - Minimize $-\sum_{1 \leq i \leq n} V_i X_i$, (call it cost)
 - It maximizes $\sum_{1 \leq i \leq n} V_i X_i$ (values)
 - subject to $\sum_{1 \leq i \leq n} W_i X_i \leq m$ (knapsack constraint)
- State space tree formation
 - Using fixed tuple size, one variable for each weight
 - Using variable tuple size, uses the index of weight

0–1 Knapsack Problem

- State space tree formation
 - Using fixed tuple size, one variable for each weight
 - Each variable has two values 0 or 1
 - Thus, Each node has two children
 - Using variable tuple size, uses the index of weight
 - Can be easily built from fixed tuple size case
- Implementation: define two terms:
 - Cost per node (what can be reached theoretically)
 - Upper bound per node (what can be achieved)
 - Define $C(x) = -\sum_{1 \leq i \leq n} V_i X_i$ for each answer node x
 - $C(x) = \infty$ for infeasible leaf nodes
 - For non-leaf nodes, define $C(x)$ recursively as
 - $\min\{C(\text{Lchild}(x)), C(\text{Rchild}(x))\}$
 - Thus, computation recursively becomes exponential

Example: LCBB 0–1 Knapsack

- Consider knapsack instance with $n=4$, $m=15$, and
 - Values $(v_1, v_2, v_3, v_4)=(10, 10, 12, 18)$, and
 - Weights $(w_1, w_2, w_3, w_4)=(2, 4, 6, 9)$
 - v_i/w_i ratios are $5 > 2.5 > 2 \geq 2$
- Using fixed tuple implementation, trace LCBB
 - Fixed implementation implies 4 tuple variables
 - x_1, x_2, x_3, x_4 and each can take value 0 or 1.
- We need to compute following values for each node
 - $\hat{c}(x)$, $u(x)$, upper
- Consider root node i.e. start node at level 1.
 - Least Cost (LC) approach
 - Among all live nodes, choose the node with lowest cost to explore (i.e. it becomes E-node)
 - List L of live nodes is implemented as Heap

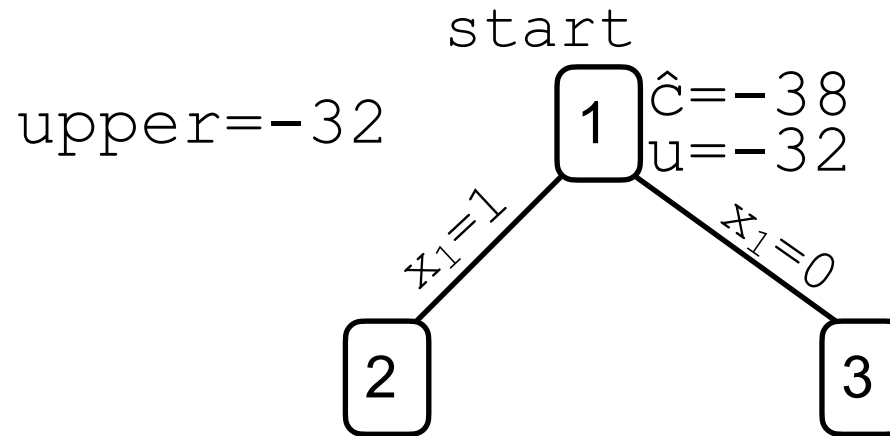
LCBB: 0–1 Knapsack

- Assume items are sorted in the non-increasing order of max profits per unit of weight i.e.
$$p[i]/w[i] \geq p[i+1]/w[i+1] \quad , \quad 1 \leq i < n$$
- Defining $\hat{c}(x)$ for 0–1 knapsack
 - Cost till the first node which doesn't fit the knapsack
 - But including its partial value to max the knapsack
- Define $u(x)$: an upper bound for node x .
 - Cost till the first node which doesn't fit the knapsack,
 - But excluding the partial value.
- Thus, for node x , we have $\hat{c}(x) \leq c(x) \leq u(x)$
 - #note cost is –ve, removing partial value makes it more
- Maintain single upper variable.
 - This indicates minimum cost solution achieved so far.
- Thus, for any node when $\hat{c}(x) > \text{upper}$
 - Discard that path (i.e. kill that node), prune the tree

LCBB: 0-1 Knapsack

	1	2	3	4
v	10	10	12	18
w	2	4	6	9

$n=4, m=15$



- Start with node 1:

$\hat{c}(x)$: w_1, w_2 , and w_3 contributes fully, w_4 exceeds knapsack

$$\hat{c} = - (10 + 10 + 12 + ((15 - 12) / 9) * 18) = -38$$

$u(x)$: w_1, w_2 , and w_3 contributes fully, w_4 exceeds knapsack

$$u = - (10 + 10 + 12 + 0) = -32$$

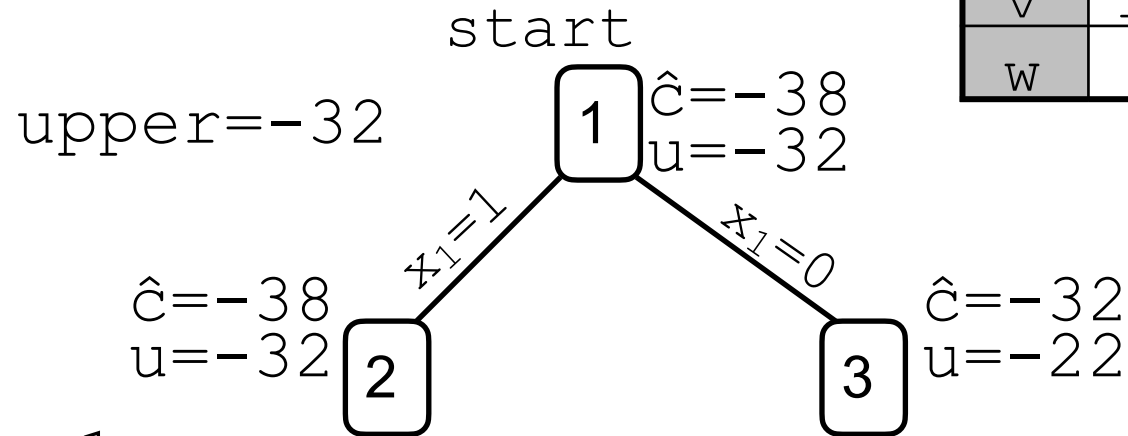
upper=-32

- This node is live node ($\hat{c} \leq \text{upper}$) and only node so far,
- Explore this node, two children
 - $x_1=1$ (include w_1), $x_1=0$ (exclude w_1)

LCBB: 0-1 Knapsack

	1	2	3	4
v	10	10	12	18
w	2	4	6	9

$n=4, m=15$

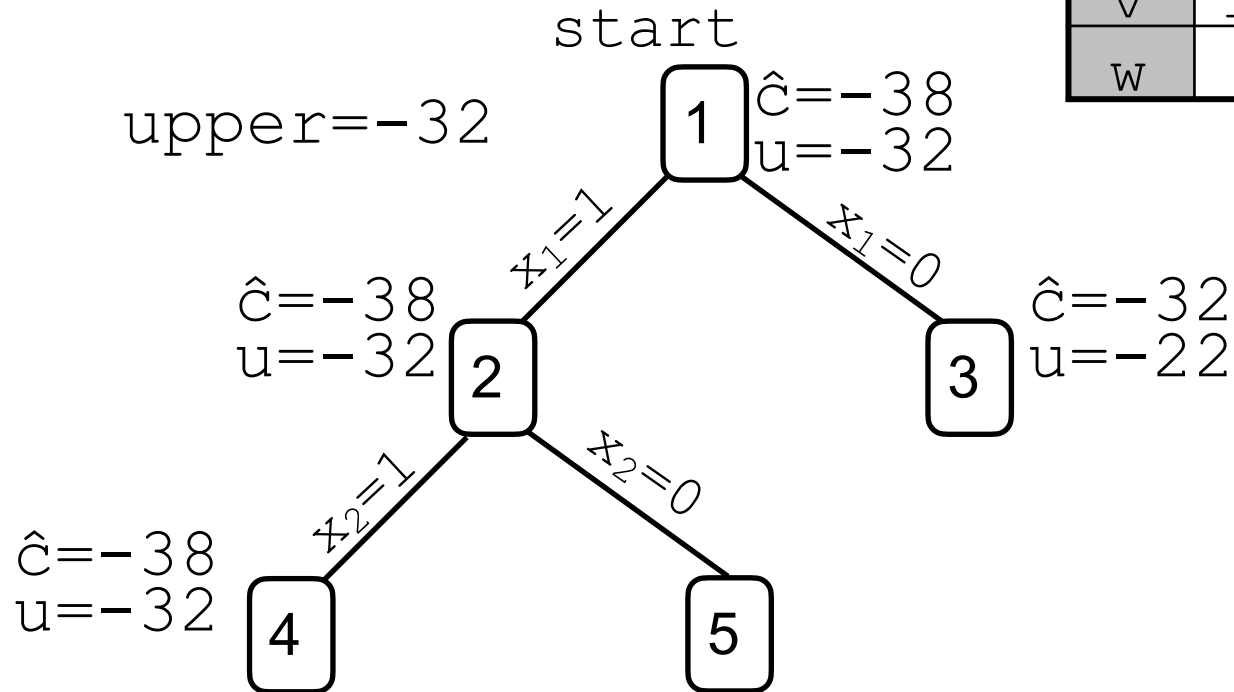


- **node 2: $x_1=1$**
 - $\hat{c}(x)$: w_1, w_2 , and w_3 contributes fully, w_4 exceeds knapsack
 $\hat{c} = -(10+10+12 + ((15-12)/9) * 18) = -38$
 - $u(x)$: w_1, w_2 , and w_3 contributes fully, w_4 exceeds knapsack
 $u = -(10+10+12+0) = -32$
 - $\hat{c}(x), u(x), \text{upper}$ don't change
- **node 3: $x_1=0$ (partial weight of w_4 becomes 5)**
 - $\hat{c} = -(0+10+12 + ((15-10)/9) * 18) = -32$
 - $u = -(0+10+12+0) = -22$
 - upper remains -32 (doesn't change)
- **Alives nodes are: 2 and 3 ($\hat{c}(x) \leq \text{upper}$)**

LCBB: 0-1 Knapsack

	1	2	3	4
v	10	10	12	18
w	2	4	6	9

$n=4, m=15$

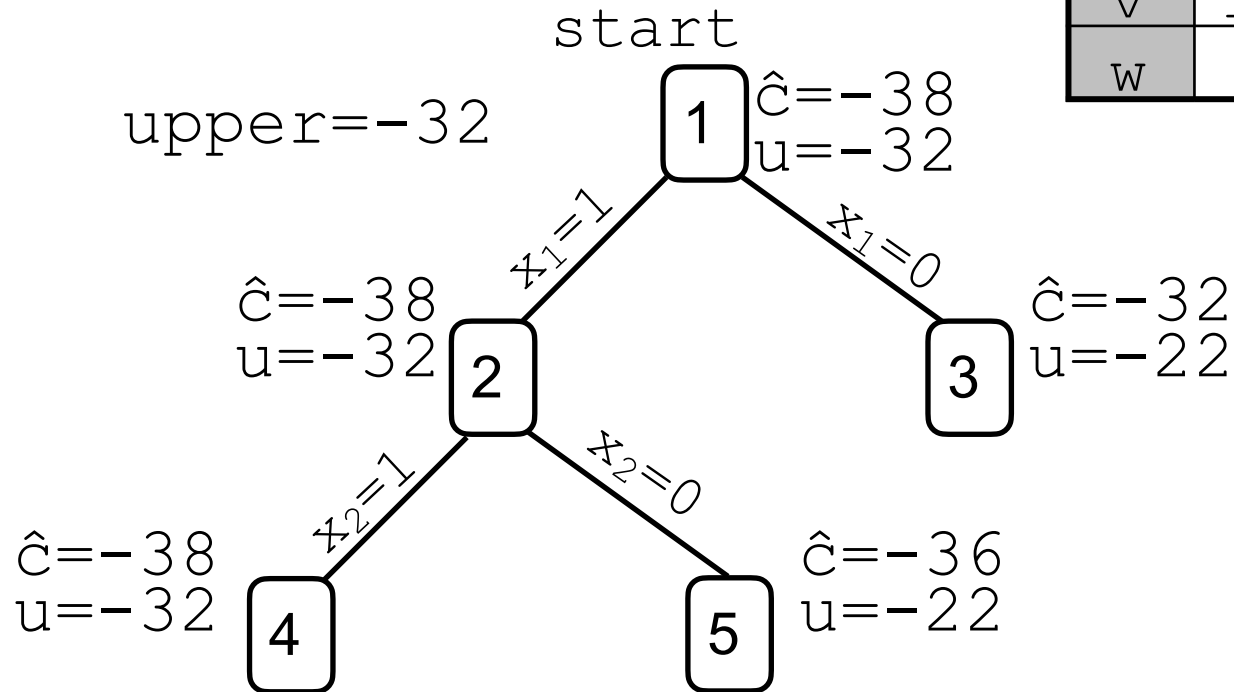


- Least Cost \hat{c} among live nodes(2, 3) is -38 for node 2.
- Explore node 2 (2 becomes E-node, 3 remains live node)
 - $x_2=1$ (node 4), and $x_2=0$ (node 5)
- Node 4:
 - $\hat{c} = -(10+10+12+((15-12)/9)*18) = -38$
 - $u = -(10+10+12+0) = -32$
 - upper remains same and doesn't change

LCBB: 0-1 Knapsack

	1	2	3	4
v	10	10	12	18
w	2	4	6	9

$n=4, m=15$

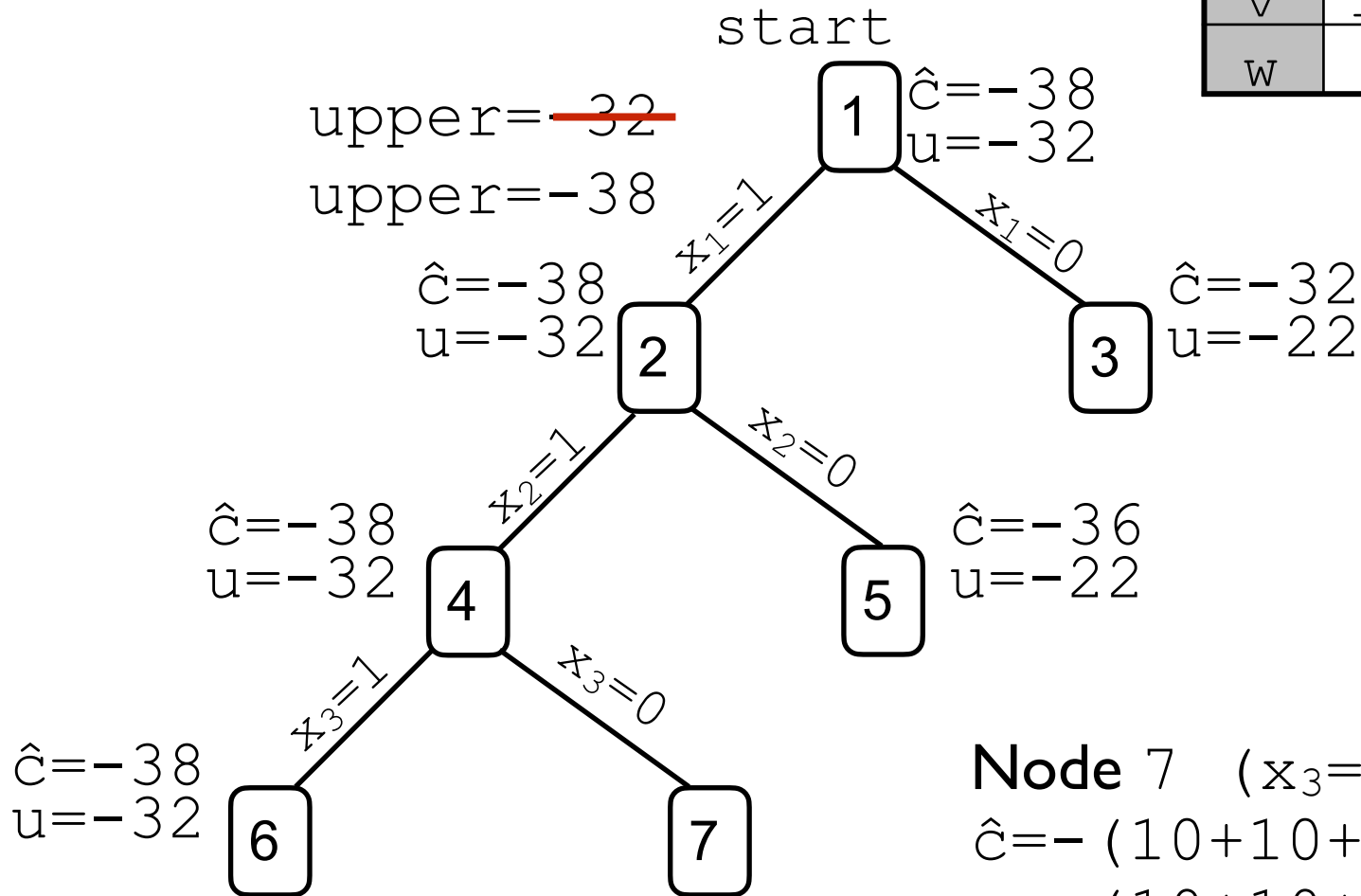


- **Node 5 (partial weight of w_4 changes)**
 $\hat{c} = - (10 + 0 + 12 + ((15 - 8) / 9) * 18) = -36$
 $u = - (10 + 0 + 12 + 0) = -22$
 upper remains same and doesn't change
- **Lives nodes now: 3, 4, 5 ($\hat{c} \leq \text{upper}$)**
- **Least Cost node is 4, $\hat{c} = -38$, explore it**
 - $x_3 = 1$ (node 6), and $x_3 = 0$ (node 7)

LCBB: 0-1 Knapsack

	1	2	3	4
v	10	10	12	18
w	2	4	6	9

$n=4, m=15$



Node 6 ($x_3=1$)
 $\hat{c} = -(10+10+12+((15-12)/9)*18) = -38$

$u = -(10+10+12+0) = -32$

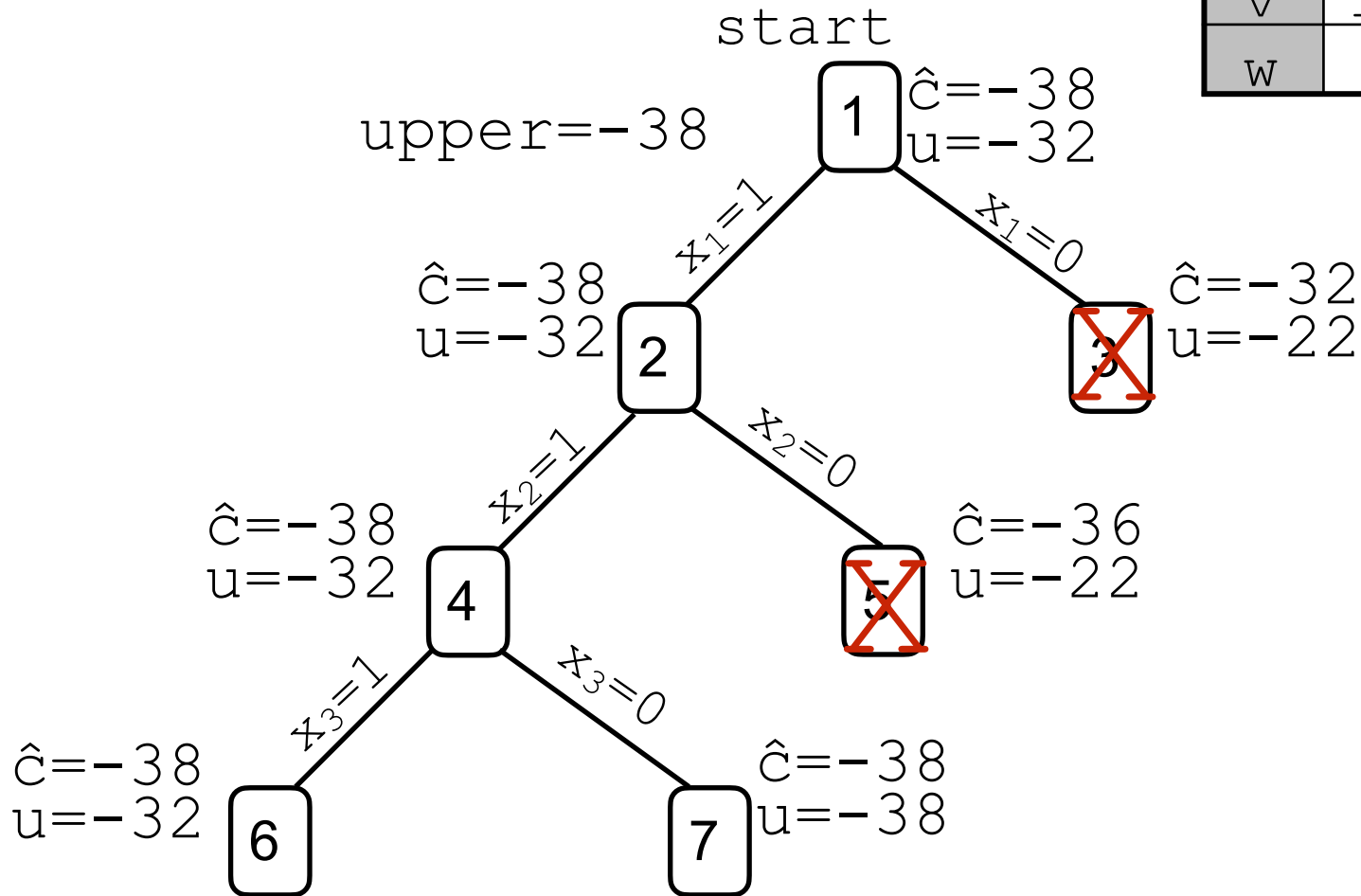
upper remains same, doesn't change

Node 7 ($x_3=0$)
 $\hat{c} = -(10+10+0+18) = -38$
 $u = -(10+10+0+18) = -38$
 upper becomes less and hence changes to -38

LCBB: 0-1 Knapsack

	1	2	3	4
v	10	10	12	18
w	2	4	6	9

$n=4, m=15$

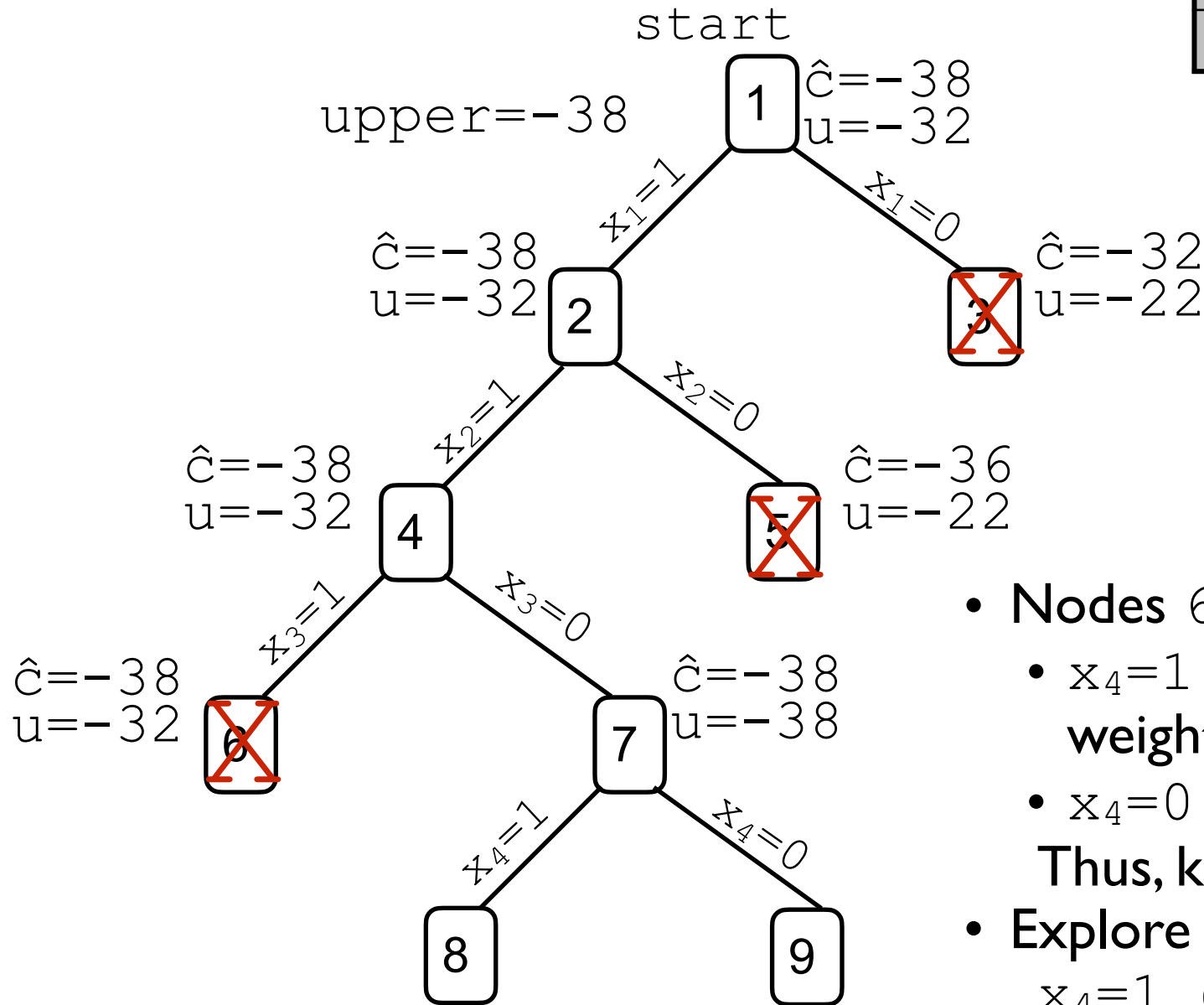


- Nodes 3 and 5 are killed, $\hat{c}(3) > \text{upper}$, $\hat{c}(5) > \text{upper}$
- Live nodes are 6 and 7. ($\hat{c}(6) \leq -38$, $\hat{c}(7) \leq -38$)
- Next Least Cost live node: can be taken either 6 or 7,
- Take 6 as least cost node. (both 6 & 7 are equal.)

LCBB: 0-1 Knapsack

	1	2	3	4
v	10	10	12	18
w	2	4	6	9

$n=4, m=15$



• Nodes 6

- $x_4=1$ makes knapsack weight 21, can't consider
 - $x_4=0$ increases \hat{c} to -32
- Thus, kill the node 6.

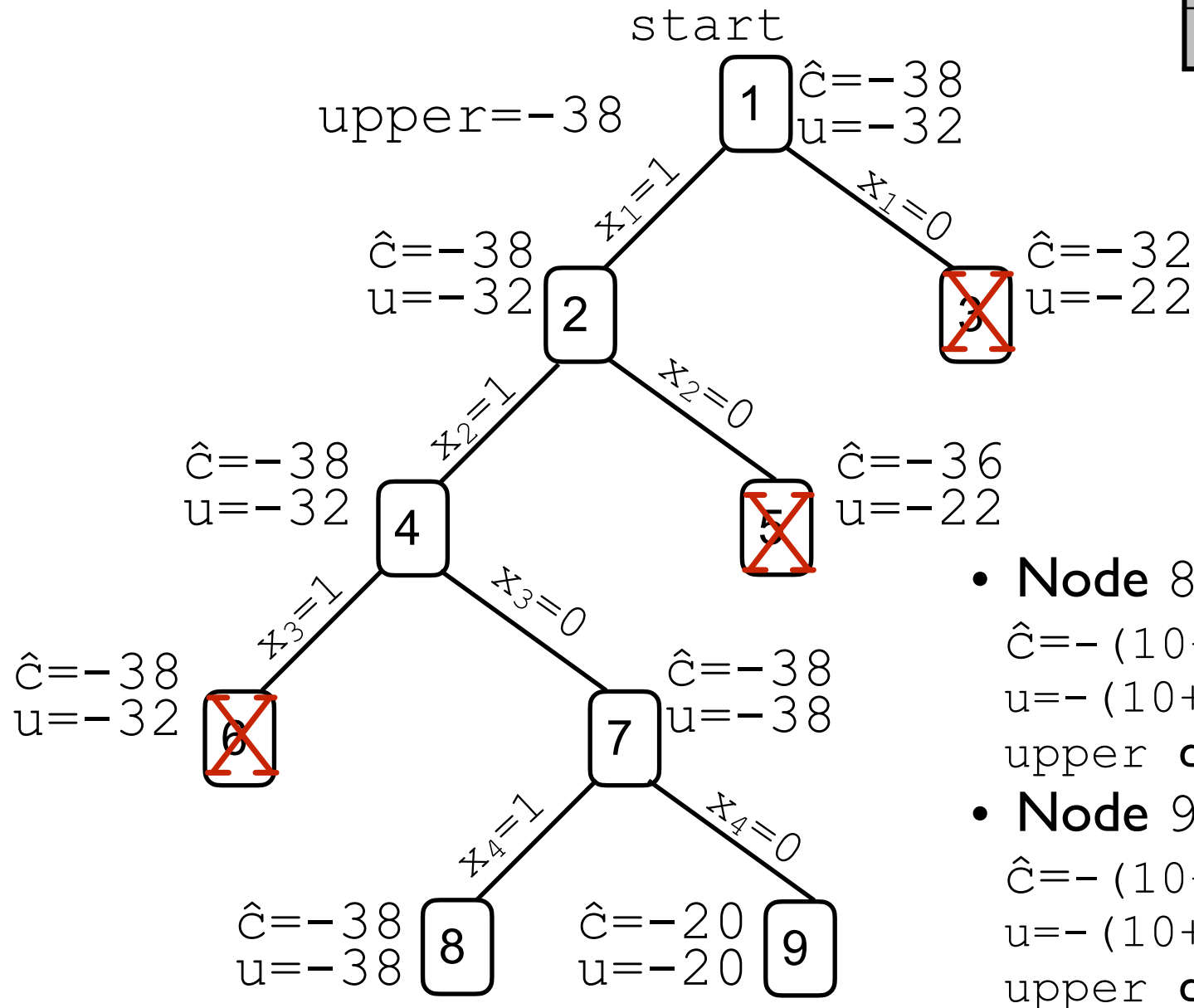
• Explore node 7

- $x_4=1$ (node 8),
- $x_4=0$ (node 9)

LCBB: 0-1 Knapsack

	1	2	3	4
v	10	10	12	18
w	2	4	6	9

$n=4, m=15$



- **Node 8**

$\hat{C} = -(10+10+0+18) = -38$
 $u = -(10+10+0+18) = -38$
 upper **does not change**

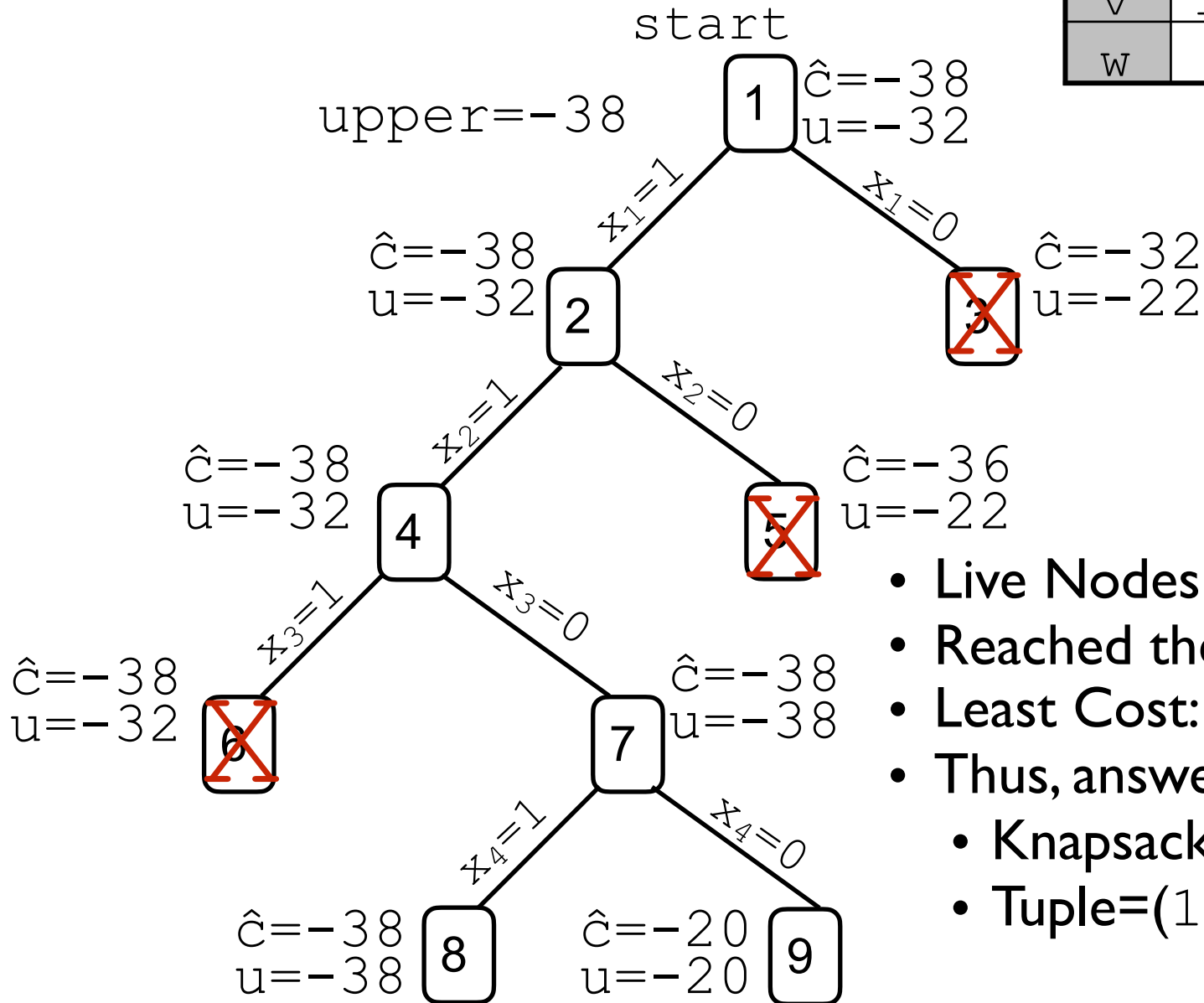
- **Node 9**

$\hat{C} = -(10+10+0+0) = -20$
 $u = -(10+10+0+0) = -20$
 upper **does not change**

LCBB: 0-1 Knapsack

	1	2	3	4
v	10	10	12	18
w	2	4	6	9

$n=4, m=15$



- Live Nodes 8, 9
- Reached the leaf nodes
- Least Cost: node 8
- Thus, answer node is 8
 - Knapsack value=38
 - Tuple=(1, 1, 0, 1)

0-1 Knapsack Implementation

- State space tree is a binary tree with depth $n+1$
 - Define two functions
 - Bound() to compute \hat{c}
 - used to compute estimated cost
 - UBound() to compute u
 - used to compute upper value

$$u(x) = \text{UBound}(-\sum_{1 \leq i < j} V_i x_i, \sum_{1 \leq i < j} W_i x_i, j-1, m)$$
$$c(x) \geq \text{Bound}(\sum_{1 \leq i < j} V_i x_i, \sum_{1 \leq i < j} W_i x_i, j-1)$$

Bound()

```
Proc Bound(float cv, float cw, int k)
// provides an upper bound (partial knapsack) on best
// solution obtainable (by expanding any node Z at level k+1)
// includes the partial value of node which exceeds knapsack
// cp: current total value, cw: current total weight
// k is the index of last removed item of knapsack
    float b=cp; float c=cw;
    for i←k+1 to n do .....B1
        if (c+wi<m) then .....B2
            c=c+wi .....B2
            b = b - vi .....B4
        else // include cost for partial weight
            return (b - (m-c) / wi) * vi .....B5
    return b .....B6
```


UBound()

```
Proc UBound(float cv, float cw, int k, float m)
// provides an upper bound (0-1 knapsack) on best solution
// obtainable by expanding any node Z at level k+1
// does not include the cost last node that exceeds knapsack
// cp: current total value, cw: current total weight
// k is the index of last removed item of knapsack
    float b=cp;
    float c=cw;
    for i←k+1 to n do .....U1
        if (c+wi≤m) then .....U2
            c = c+wi .....U3
            b = b-vi .....U4
    return b .....U5
```

Summary:

- Least Cost Branch and Bound for
 - $0-1$ Knapsack problem
- Next to explore
 - FIFO Branch and Bound