

# Rebecca Ramnauth

## Building Intelligent Robots for Social Therapy



I build theories about how people think, learn, and interact with the world around them.

Then, I apply these theories to develop robot-led interventions that support positive social outcomes among users of various cognitive and technical abilities. My research features socially intelligent robots that can operate fully autonomously with vulnerable users in personal, real-world spaces over extended periods.



To combat social isolation during the COVID-19 lockdown for young children [HRI'21]



Month-long, in-home therapy to support gaze and social skills in children with autism [HRI'25]



Week-long, in-home training for adults with autism to practice job-related skills [RSS'25, HRI'22]



Month-long deployment in NYC public schools to support behavioral de-escalation [RO-MAN'25]

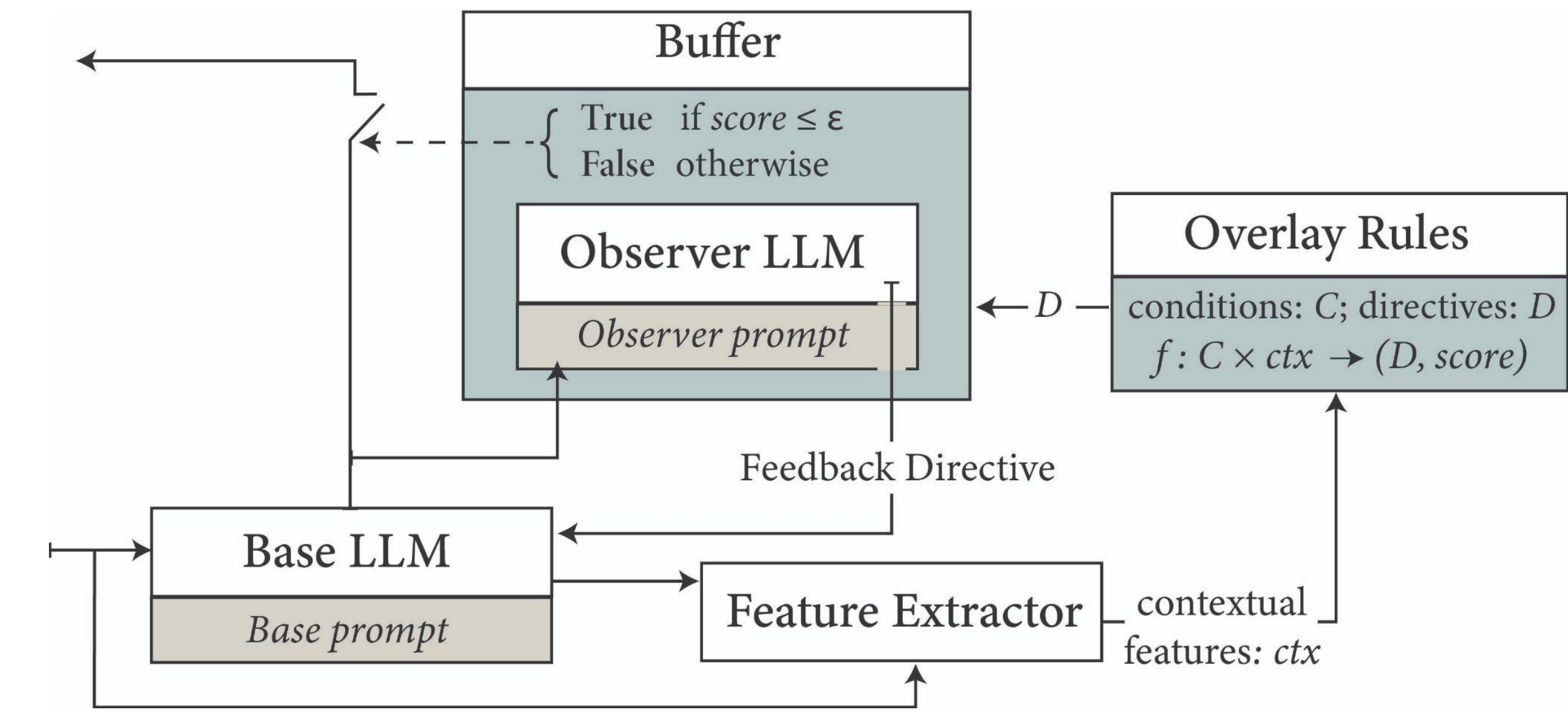
Research Dimension	Current Norm <i>past two decades</i>	What is Needed <b>but Challenging</b>
Location	Controlled laboratory or clinic	Real-world, naturalistic spaces
Duration	Single session, $\leq 1$ hour	Longitudinal, days to months
Interaction Type	1:1, isolated	Multi-user, embedded in context
User Population	Neurotypical adult, “high-functioning”	Neurodiverse, full spectrum
Robot Operation	Scripted, supervised, non-autonomous, one-size-fits-all	Adaptable, unsupervised, fully autonomous, personalized
Study Purpose	Feasibility, proof-of-concept	Efficacy, generalizability

### Contributions of This Work

- First** contactless home deployments during a global pandemic
- First** framework to evaluate when offering help is appropriate
- First** system to assess social presence and when to engage users
- First** system to support behavioral de-escalation in a public setting
- First** study to encompass broader functional diversity among users
- First** in-home, robot therapies for adults with autism
- First** robot that delivers multi-user, personalized therapy agnostic to age and diagnostic profiles
- First** use of foundation models for highly adaptable, unscripted, improvised robot therapies
- First** study to demonstrate continuous learning progression linked to clinical measures of therapeutic efficacy

### Future Work and Lab Vision

To bridge technical innovation with human-centered design, training the next generation of researchers to approach robotics with both computational rigor and social responsibility. We will develop intelligent robots that operate safely and autonomously to foster positive social outcomes that extend into everyday human-human relationships.



**Developing robust guardrails** for foundation-model-driven autonomy that enable ethical robot deployment in socially sensitive domains

**Creating robots for novel users, spaces, and skills**—many remain understudied and under-supported yet hold strong potential to reveal new facets of human cognition and inspire new systemic and methodological paradigms.

**Rethinking robot intelligence** by identifying and challenging the field’s tacit rules about what robots are and how they should behave. Defying such norms can produce interactions that are more ethical, effective, and socially intelligent.

**284 families**

with users ranging from 4 to 104 years old

**12,984 hours**

of fully autonomous robot uptime in real-world spaces

**3,084 sessions**

of personalized therapy and training interventions

**950 hours**

of active therapeutic engagement

**84 TB**

of multimodal data



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The interdisciplinary nature of my work has attracted funding from diverse and competitive sources. It has also fostered collaborations with many mission-aligned foundations.

