



Scene-level Point Cloud Colorization with Semantic-and-Geometric-aware Network

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Problem setting

Given the point cloud coordinates $XYZ \in \mathbb{R}^N \times 3$ (where N is the number of point clouds as input, our method generates RGB values $\mathbb{R}^N \times 3$.

Contribution

- ✓ We propose a novel colorization method, i.e., Semantic- and-Geometric-aware colorization Network (SGNet), for scene-level point cloud colorization.
- ✓ To facilitate the color learning and model training, we also present two novel losses into point cloud colorization, including a colorfulness metric loss to produce visually vibrant colors and boost the performance.
- ✓ We validate the proposed method on indoor scene dataset, and achieve superior performance to the state-of-the-art point cloud approaches quantitatively and qualitatively.

Semantic-and-Geometric-aware Network

SGNet is proposed to do scene-level point cloud colorization task.

- It explores **semantic** and **geometric** features from the point cloud with only coordinate as inputs.
- It is a **sparse** fully convolutional based network which is applicable in complex scenarios.
- Two novel **losses** are proposed to generate visually vibrant colors and boost the learning.

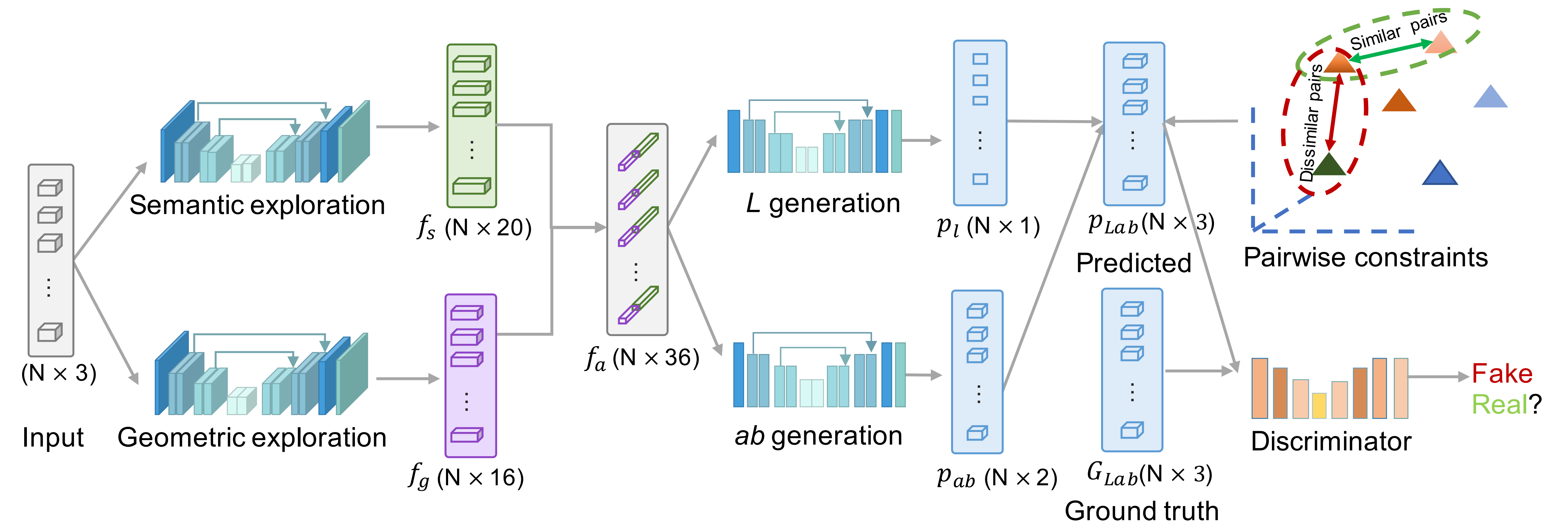
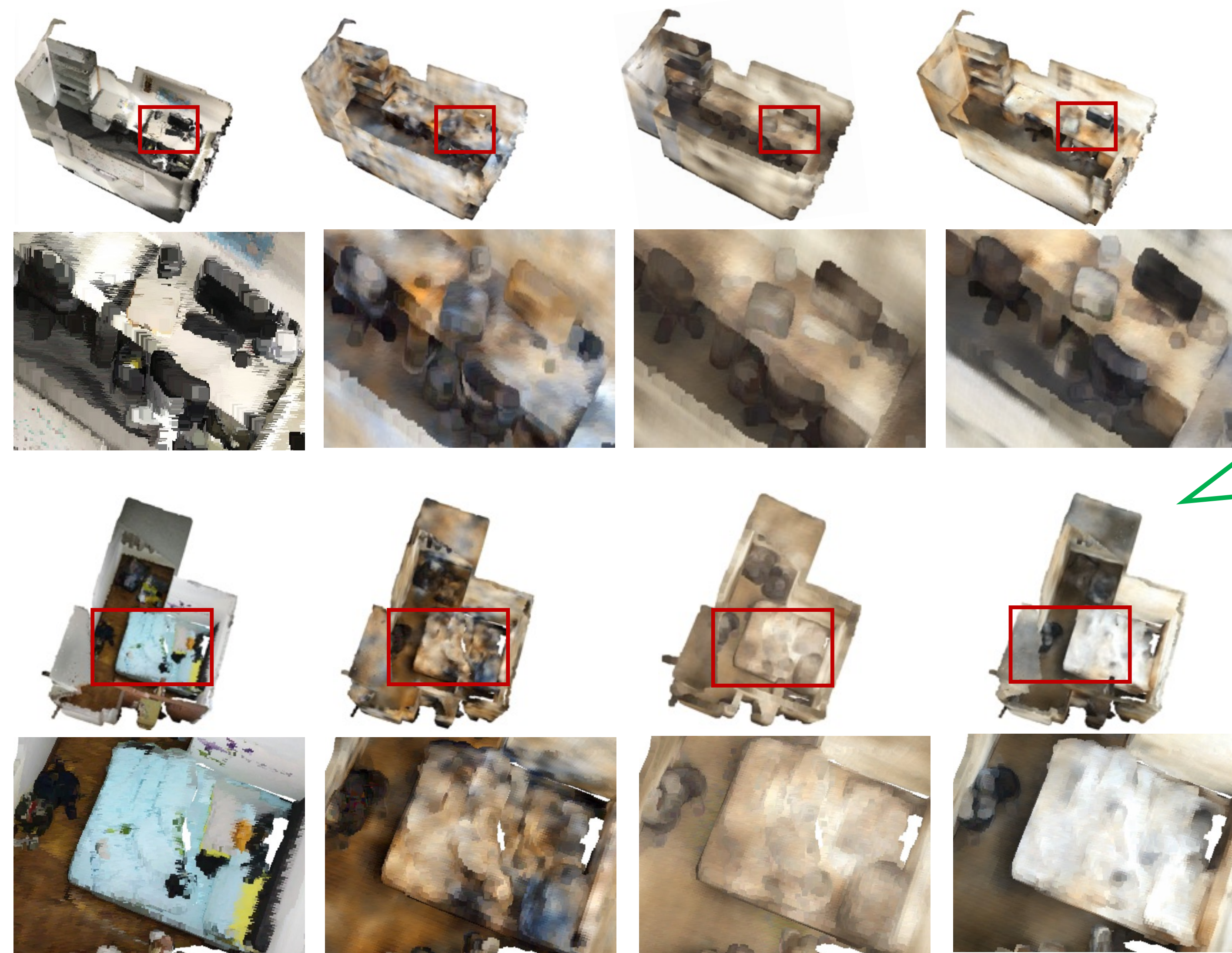


Figure. The overall framework of the proposed SGNet.

Results



State-of-the-art performance.

Good balance on semantic characters and scene colorfulness.

User friendly.

Evaluation

TABLE I: Quantitative comparison with other methods for point cloud colorization using three evaluation metrics. "↓" or "↑" indicates that the method with the smaller or larger metrics is better than the others. The best results are highlighted in bold.

Method	MSE ↓	FPD ↓	CM ↑
Regression	0.084 ± 0.015	3.333 ± 1.676	0.064 ± 0.013
DensePointNet	0.081 ± 0.009	4.106 ± 1.273	0.080 ± 0.010
SGNet (ours)	0.041 ± 0.019	2.116 ± 1.440	0.221 ± 0.008

TABLE II: Preference score in the user study for the colorization results of different methods. The best results are highlighted in bold.

Method	Regression	DensePointNet	Ours
Percentage	3.3%	30.4%	66.3%

Find the project here!

Paper, code, and data are available:

<https://rrgao.github.io/projects/ICRA23/index.html>

