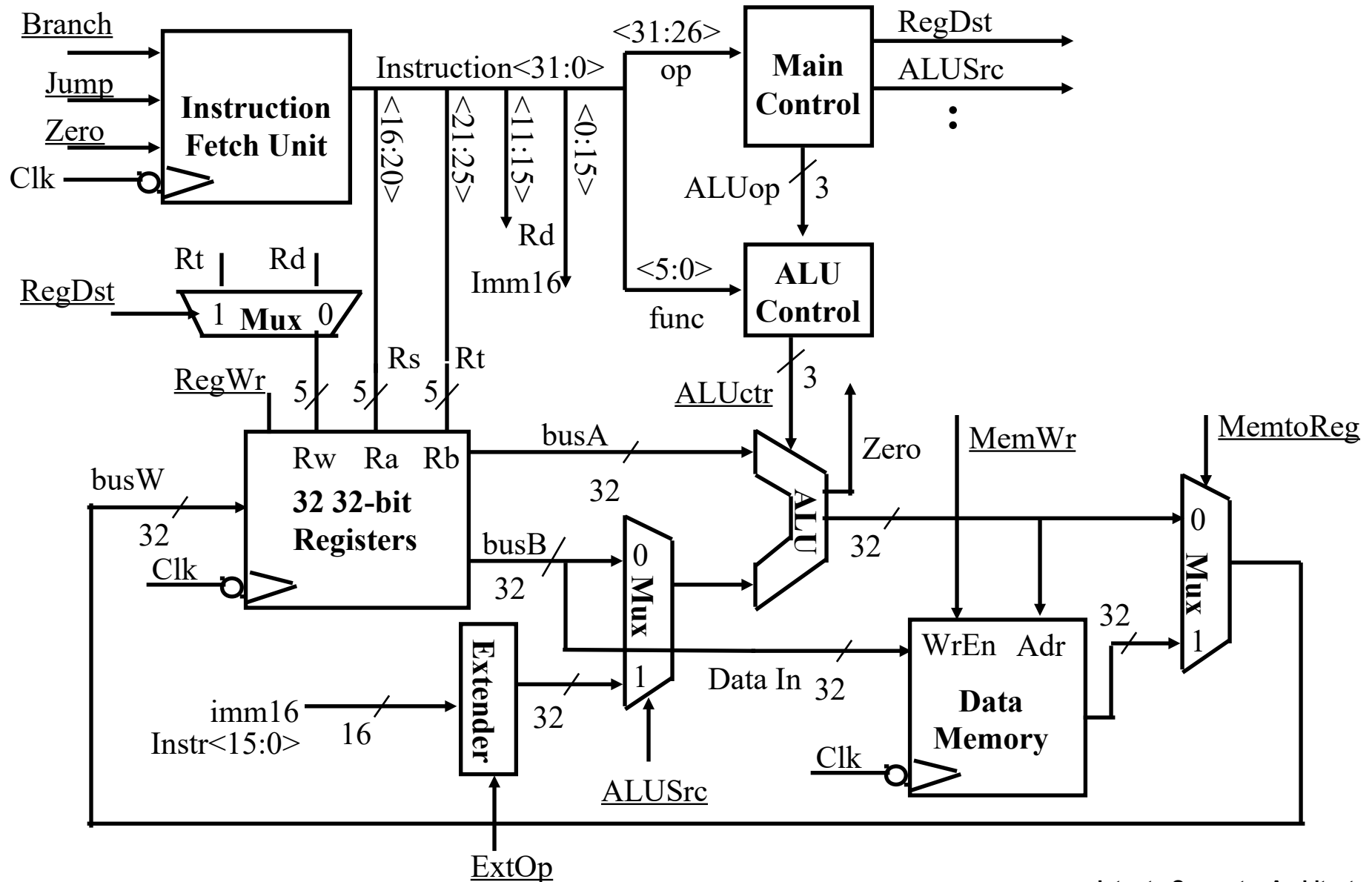


CpE 242
Computer Architecture and
Engineering
Designing a Pipeline Processor

Outline of Today's Lecture

- **Recap and Introduction (5 minutes)**
- **Introduction to the Concept of Pipelined Processor (15 minutes)**
- **Pipelined Datapath and Pipelined Control (25 minutes)**
- **How to Avoid Race Condition in a Pipeline Design? (5 minutes)**
- **Pipeline Example: Instructions Interaction (15 minutes)**
- **Summary (5 minutes)**

A Single Cycle Processor



Drawbacks of this Single Cycle Processor

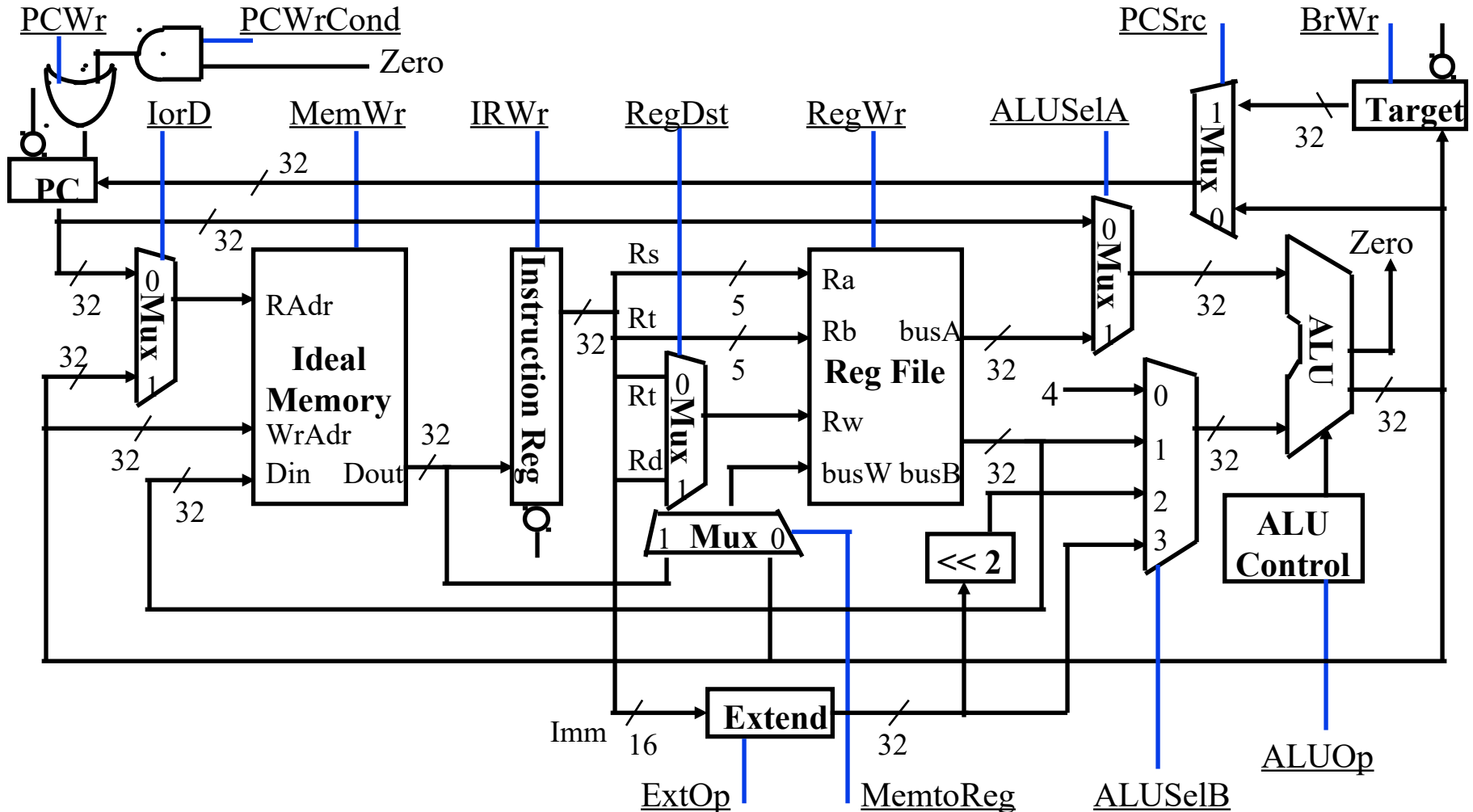
- Long cycle time:
 - Cycle time must be long enough for the load instruction:
 - PC's Clock -to-Q +
 - Instruction Memory Access Time +
 - Register File Access Time +
 - ALU Delay (address calculation) +
 - Data Memory Access Time +
 - Register File Setup Time +
 - Clock Skew
- Cycle time is much longer than needed for all other instructions.
Examples:
 - R-type instructions do not require data memory access
 - Jump does not require ALU operation nor data memory access

Overview of a Multiple Cycle Implementation

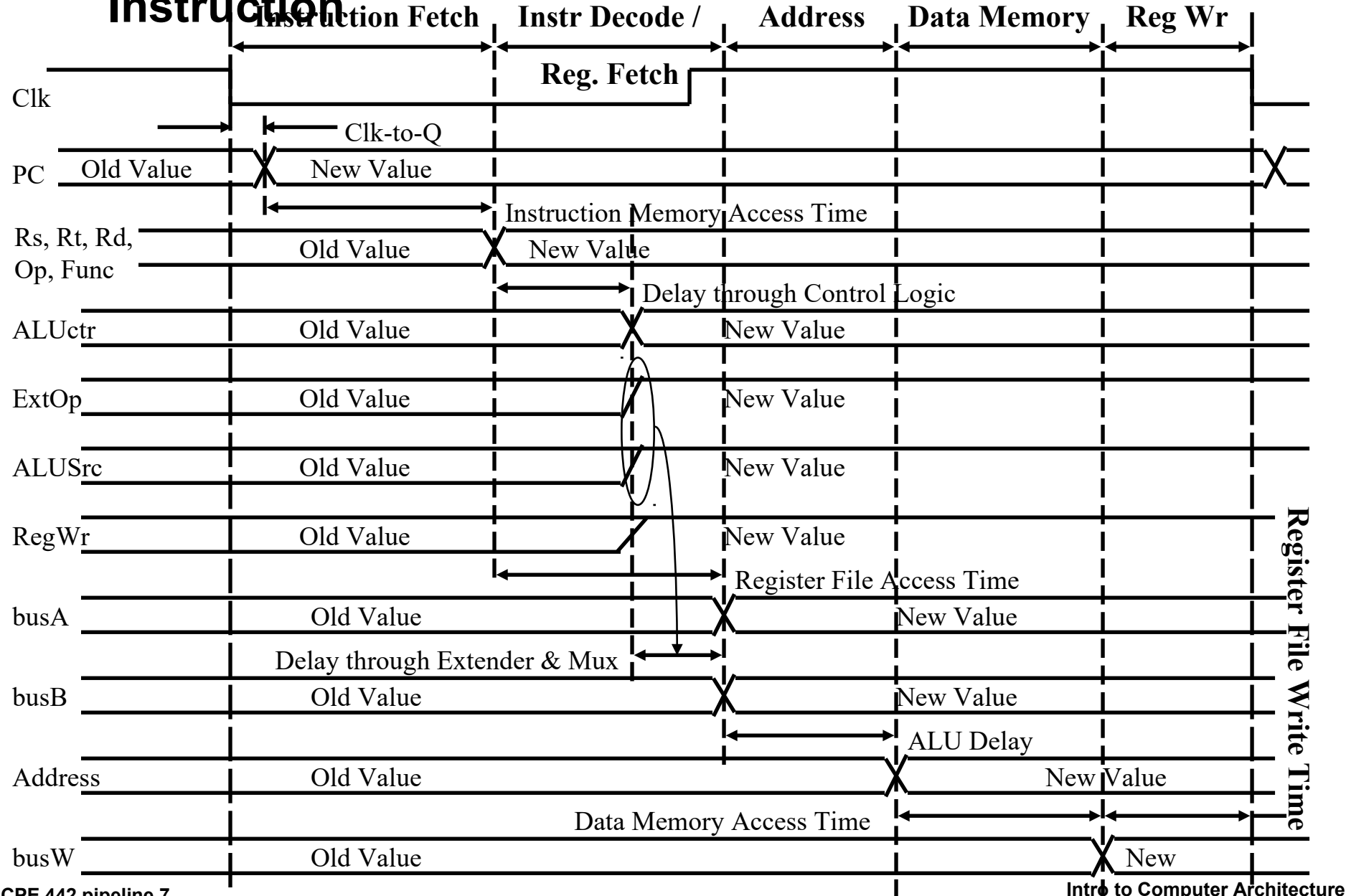
- The root of the single cycle processor's problems:
 - The cycle time has to be long enough for the slowest instruction
- Solution:
 - Break the instruction into smaller steps
 - Execute each step (instead of the entire instruction) in one cycle
 - Cycle time: time it takes to execute the longest step
 - Keep all the steps to have similar length
 - This is the essence of the multiple cycle processor
- The advantages of the multiple cycle processor:
 - Cycle time is much shorter
 - Different instructions take different number of cycles to complete
 - Load takes five cycles
 - Jump only takes three cycles
 - Allows a functional unit to be used more than once per instruction

Multiple Cycle Processor

- ° MCP: A functional unit to be used more than once per instruction



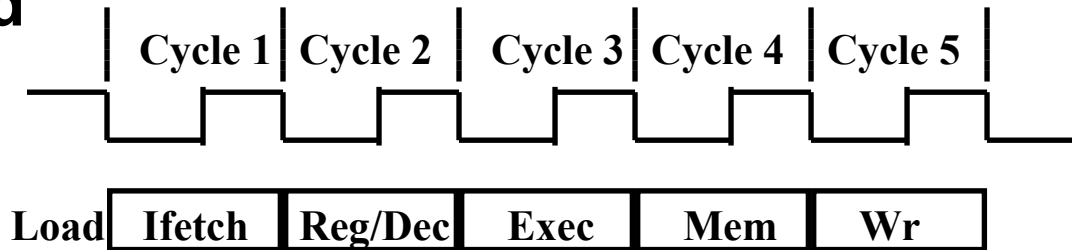
Timing Diagram of a Load Instruction



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The Five Stages of Load



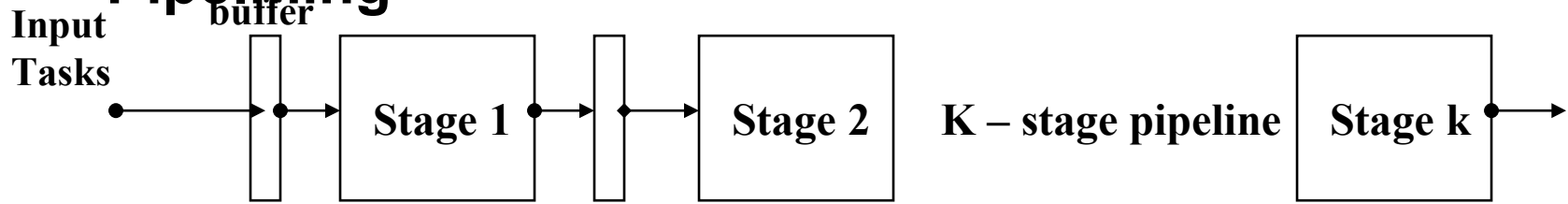
- **Ifetch: Instruction Fetch**
 - Fetch the instruction from the Instruction Memory
- **Reg/Dec: Registers Fetch and Instruction Decode**
- **Exec: Calculate the memory address**
- **Mem: Read the data from the Data Memory**
- **Wr: Write the data back to the register file**

Key Ideas Behind

Pipelining

- Grading the Final exam for a class of 100 students:
 - 5 problems, five people grading the exam
 - Each person **ONLY** grade one problem
 - Pass the exam to the next person as soon as one finishes his part
 - Assume each problem takes 12 min to grade
 - Each individual exam still takes 1 hour to grade
 - But with 5 people, all exams can be graded five times quicker
- The load instruction has 5 stages:
 - Five independent functional units to work on each stage
 - Each functional unit is used only once
 - The 2nd load can start as soon as the 1st finishes its Ifetch stage
 - Each load still takes five cycles to complete
 - The throughput, however, is much higher

Key Ideas Behind Pipelining

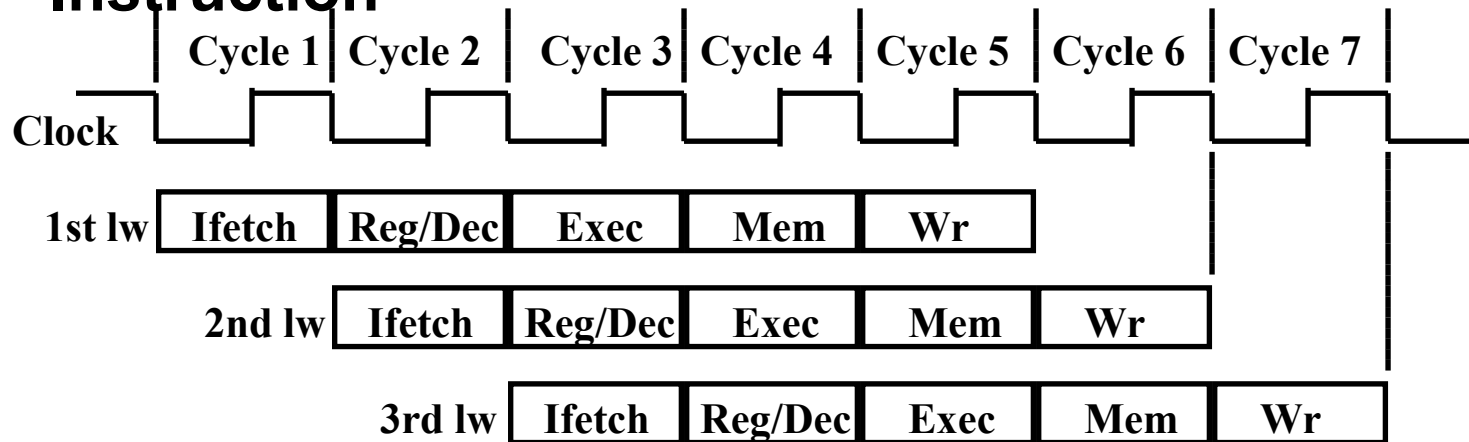


- Let n be number of tasks or exams (or instructions)
- Let k be number of stages for each task
- Let T be the time per stage
- Time per task = $T \cdot k$
- Total Time per n tasks for non-pipelined solution = $T \cdot k \cdot n$
- Total Time per n tasks for pipelined solution = $T \cdot k + T \cdot (n-1)$
- Speedup = pipelined perform/ non-pipelined performance

$$= \text{Total Time non-pipelined} / \text{Total Time for pipelined}$$

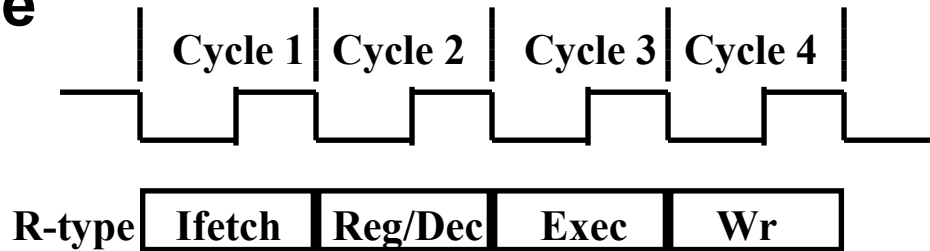
$$= k \cdot n / k + n - 1 = k \text{ approx. when } n \gg k$$

Pipelining the Load Instruction



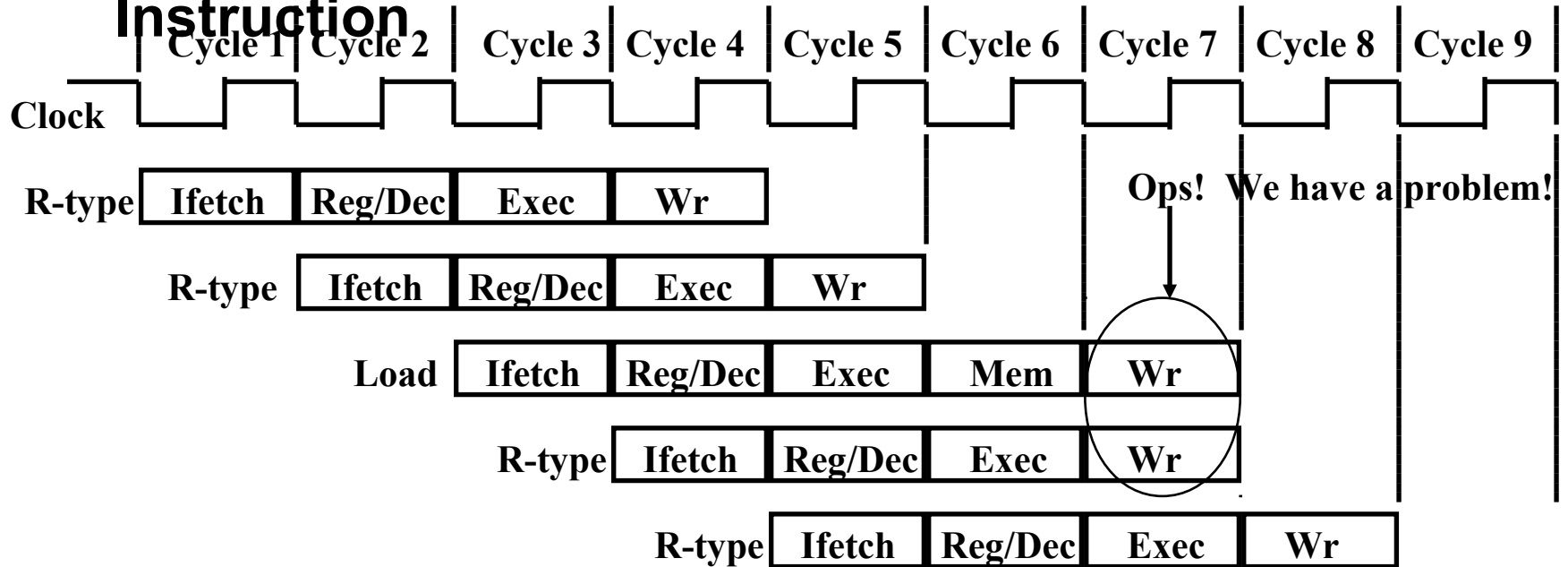
- The five independent functional units in the pipeline datapath are:
 - Instruction Memory for the Ifetch stage
 - Register File's Read ports (bus A and busB) for the Reg/Dec stage
 - ALU for the Exec stage
 - Data Memory for the Mem stage
 - Register File's Write port (bus W) for the Wr stage
- One instruction enters the pipeline every cycle
 - One instruction comes out of the pipeline (complete) every cycle
 - The "Effective" Cycles per Instruction (CPI) is 1

The Four Stages of R-type



- **Ifetch: Instruction Fetch**
 - **Fetch the instruction from the Instruction Memory**
- **Reg/Dec: Registers Fetch and Instruction Decode**
- **Exec: ALU operates on the two register operands**
- **Wr: Write the ALU output back to the register file**

Pipelining the R-type and Load Instruction

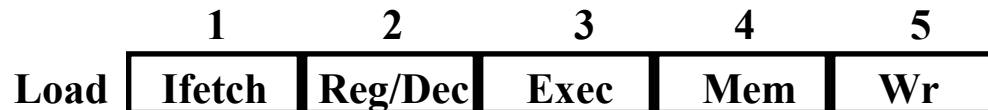


◦ We have a problem:

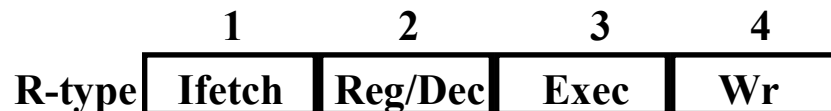
- Two instructions try to write to the register file at the same time!

Important Observation

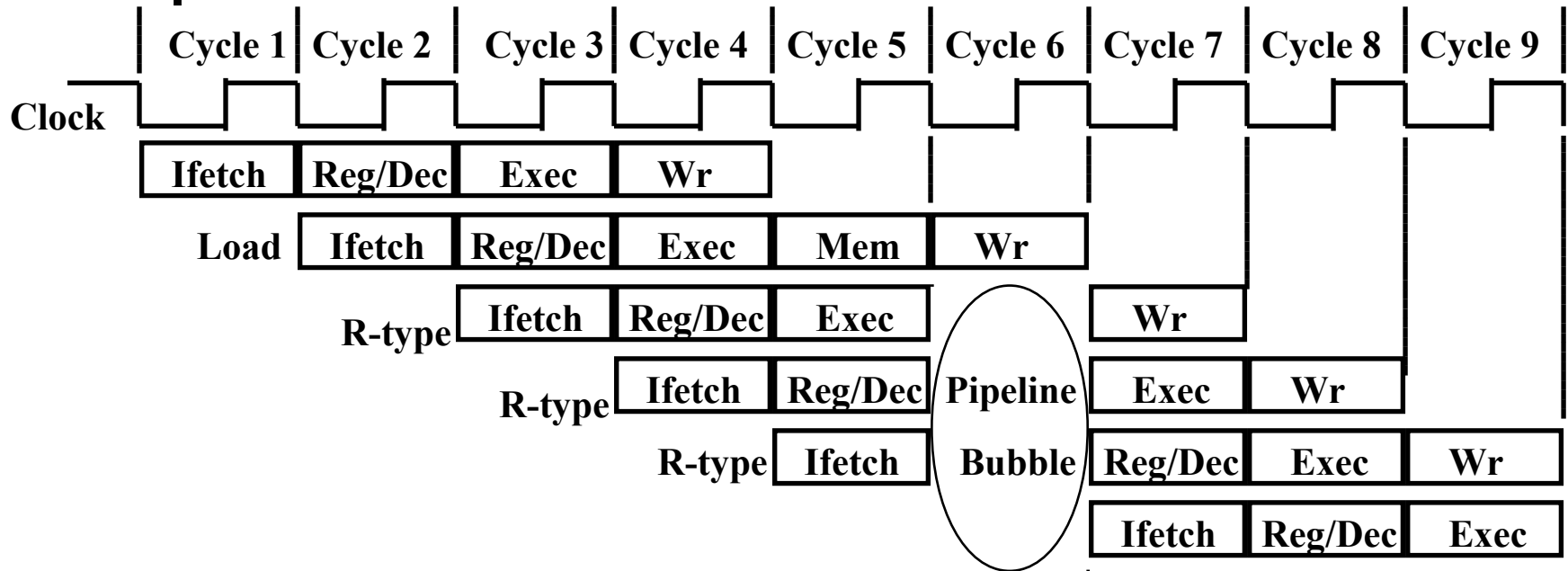
- Each functional unit can only be used once per instruction
- Each functional unit must be used at the same stage for all instructions:
 - Load uses Register File's Write Port during its 5th stage



- R-type uses Register File's Write Port during its 4th stage



Solution 1: Insert “Bubble” into the Pipeline

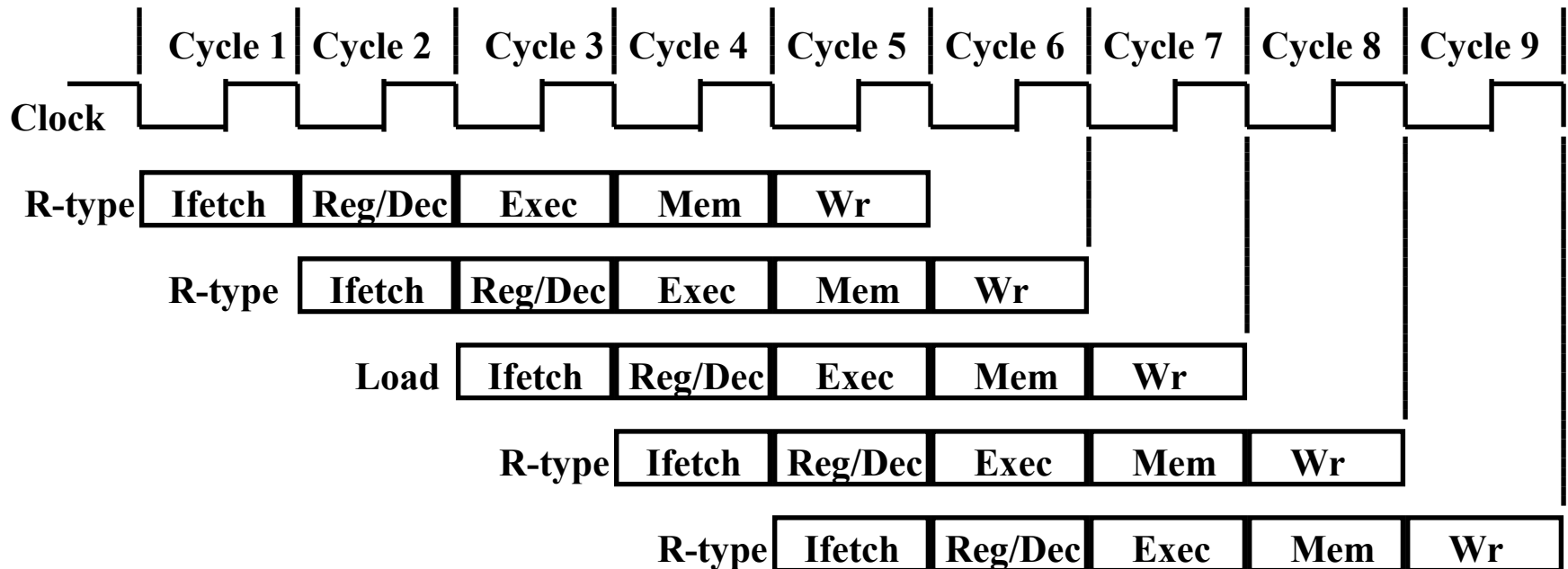
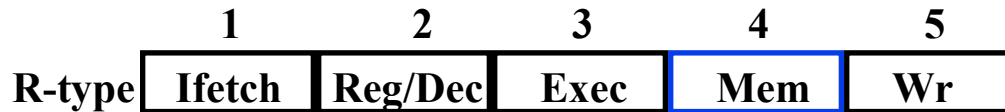


- Insert a “bubble” into the pipeline to prevent 2 writes at the same cycle
 - The control logic can be complex
- No instruction is completed during Cycle 5:
 - The “Effective” CPI for load is 2

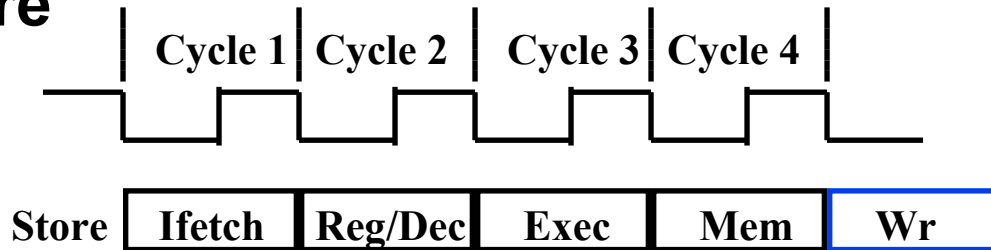
Solution 2: Delay R-type's Write by One Cycle

- Delay R-type's register write by one cycle:

- Now R-type instructions also use Reg File's write port at Stage 5
- Mem stage is a NOOP stage: nothing is being done

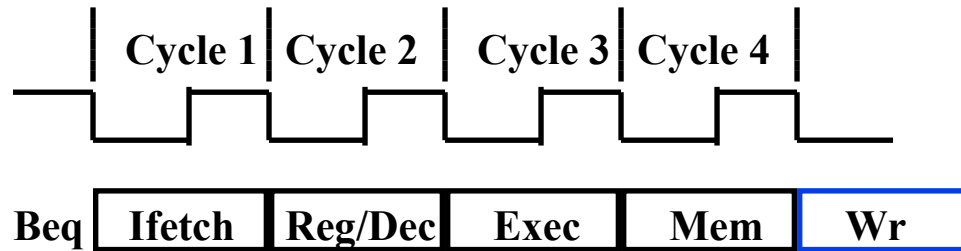


The Four Stages of Store



- **Ifetch: Instruction Fetch**
 - Fetch the instruction from the Instruction Memory
- **Reg/Dec: Registers Fetch and Instruction Decode**
- **Exec: Calculate the memory address**
- **Mem: Write the data into the Data Memory**

The Four Stages of Beq

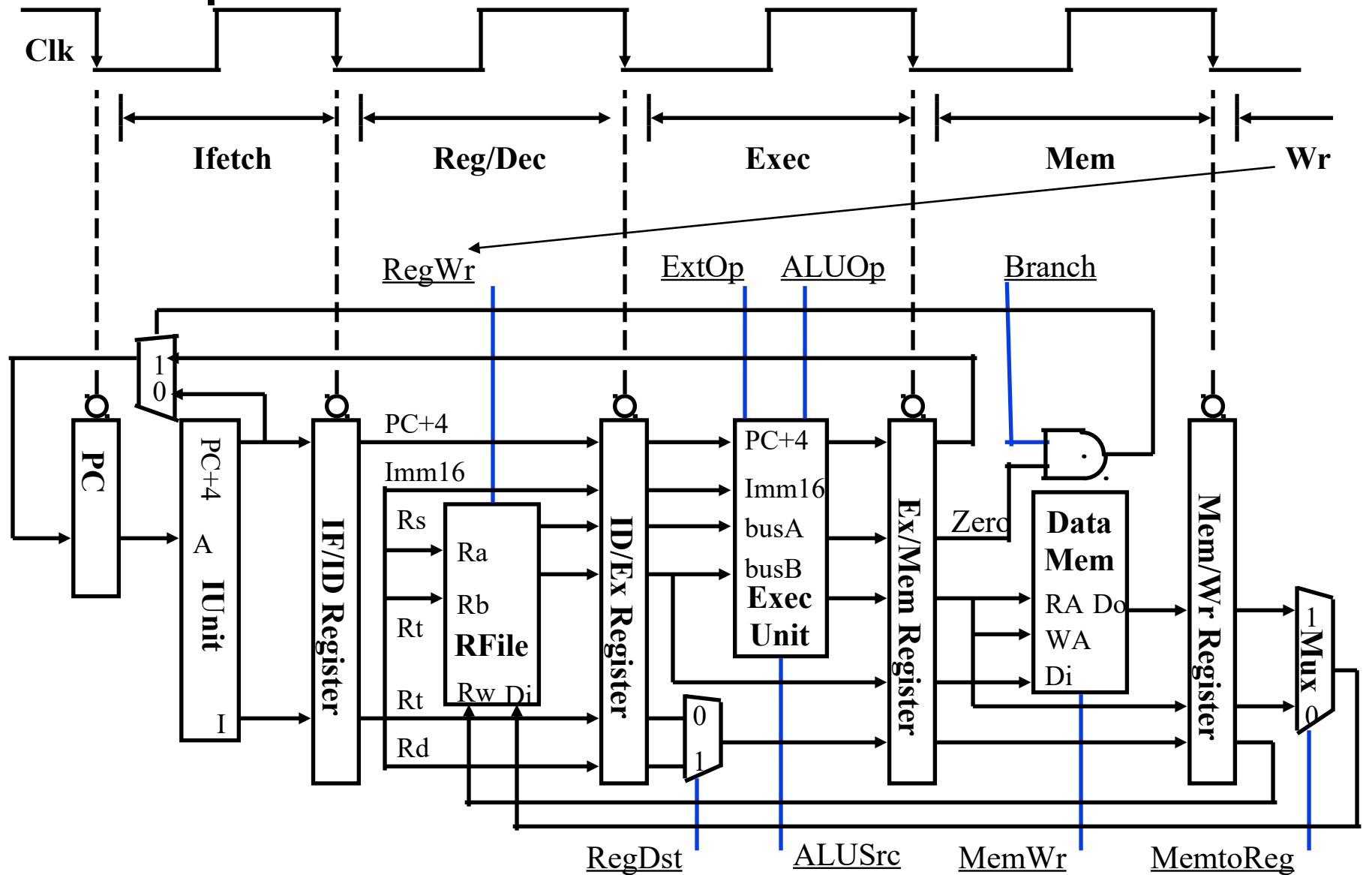


- **Ifetch: Instruction Fetch**
 - Fetch the instruction from the Instruction Memory
- **Reg/Dec: Registers Fetch and Instruction Decode**
- **Exec: ALU compares the two register operands**
 - Adder calculates the branch target address
- **Mem: If the registers we compared in the Exec stage are the same,**
 - Write the branch target address into the PC

Outline of Today's Lecture

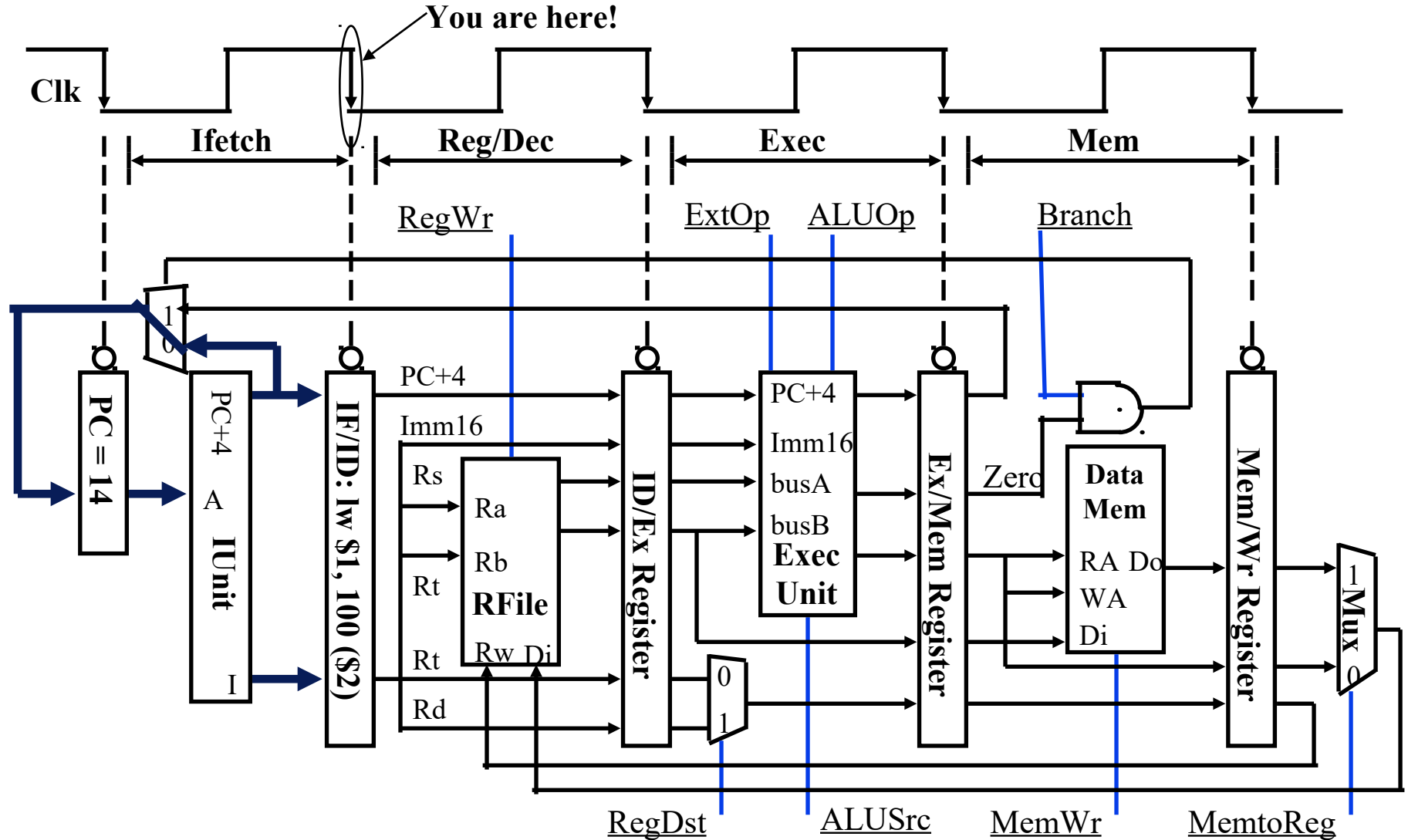
- **Recap and Introduction (5 minutes)**
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- **Summary (5 minutes)**

A Pipelined Datapath



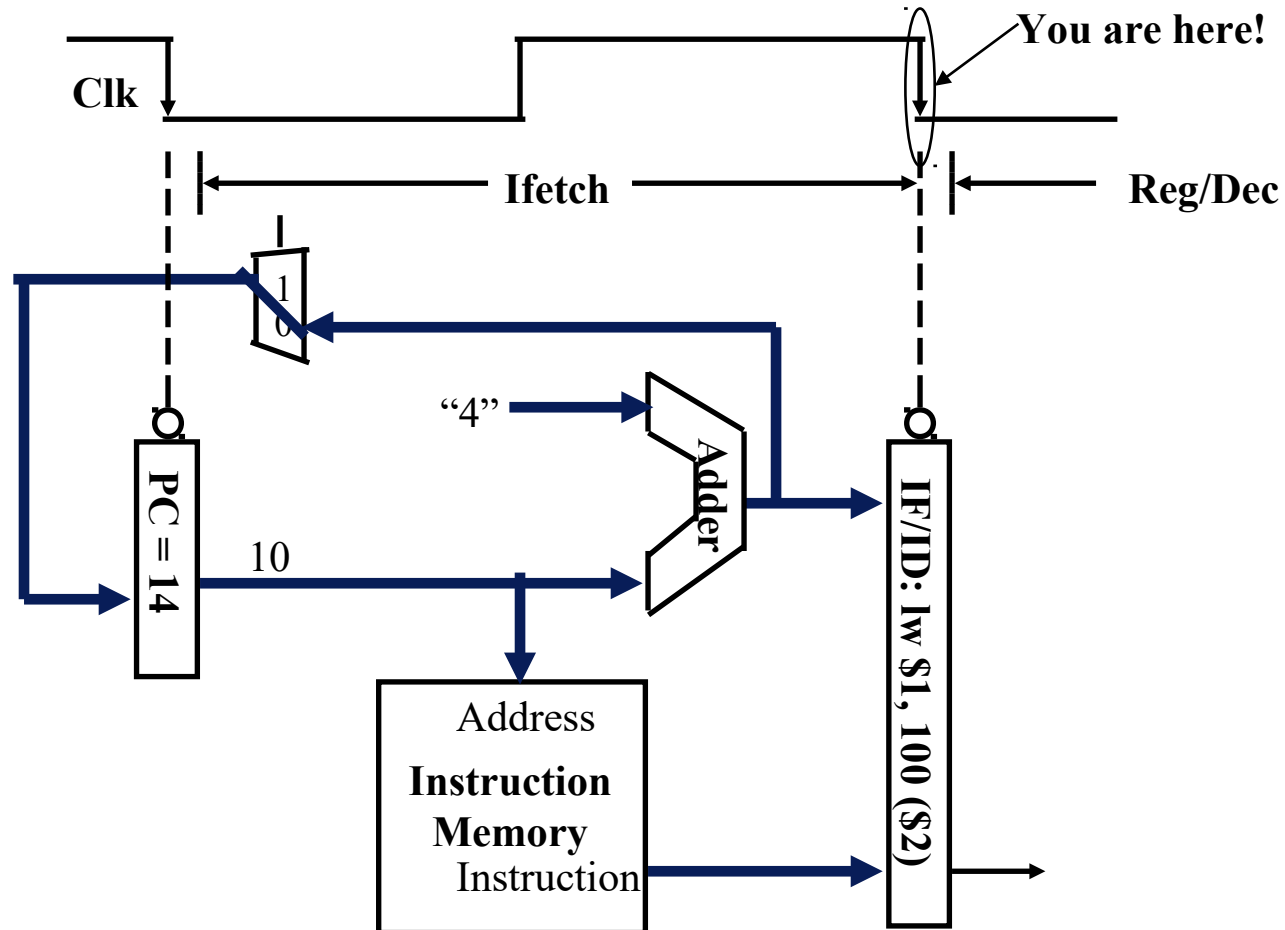
The Instruction Fetch Stage

Location 10: lw \$1, 0x100(\$2) \$1 <- Mem[(\$2) + 0x100]



A Detail View of the Instruction Unit

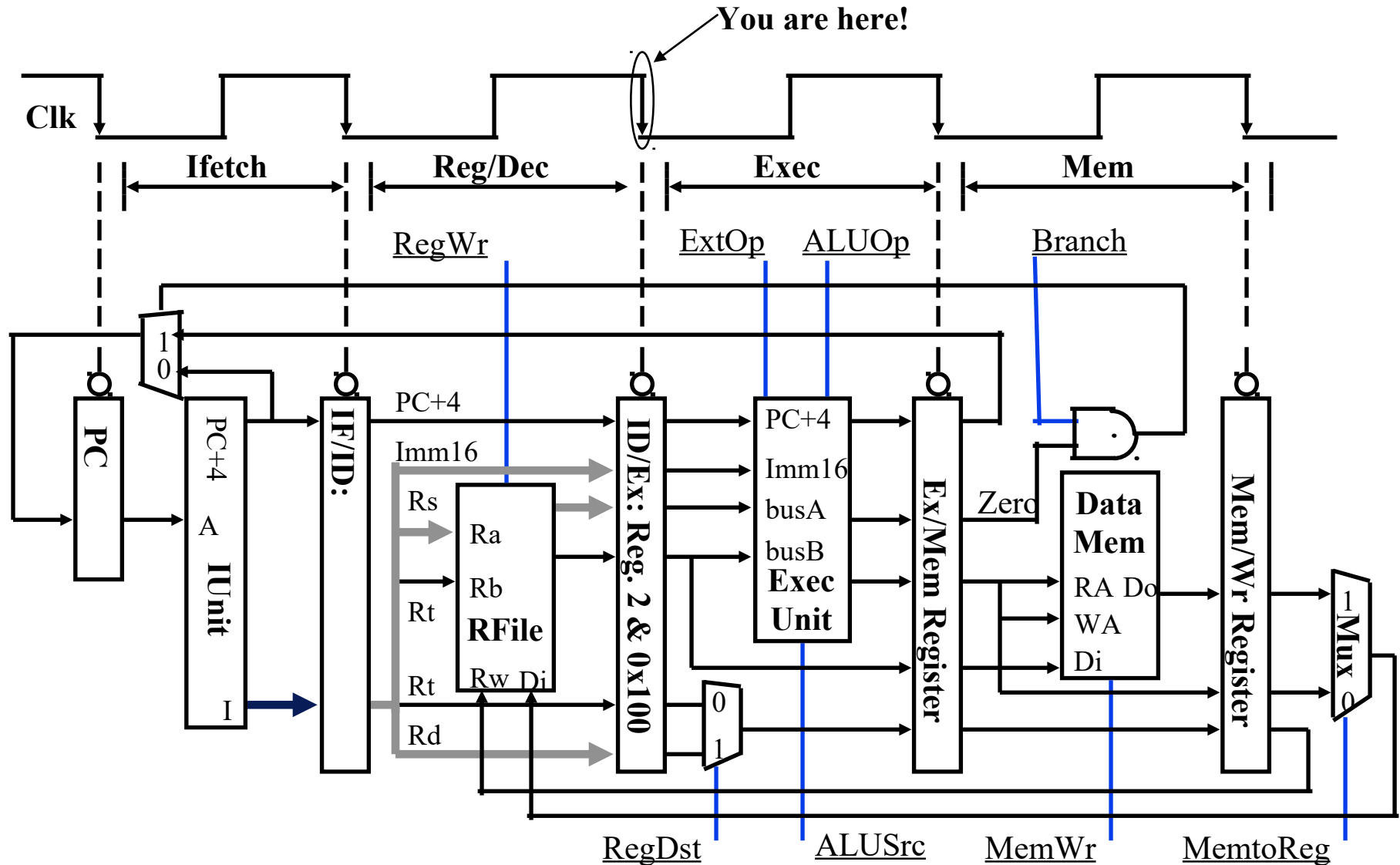
- Location 10: lw \$1, 0x100(\$2)



The Decode / Register Fetch

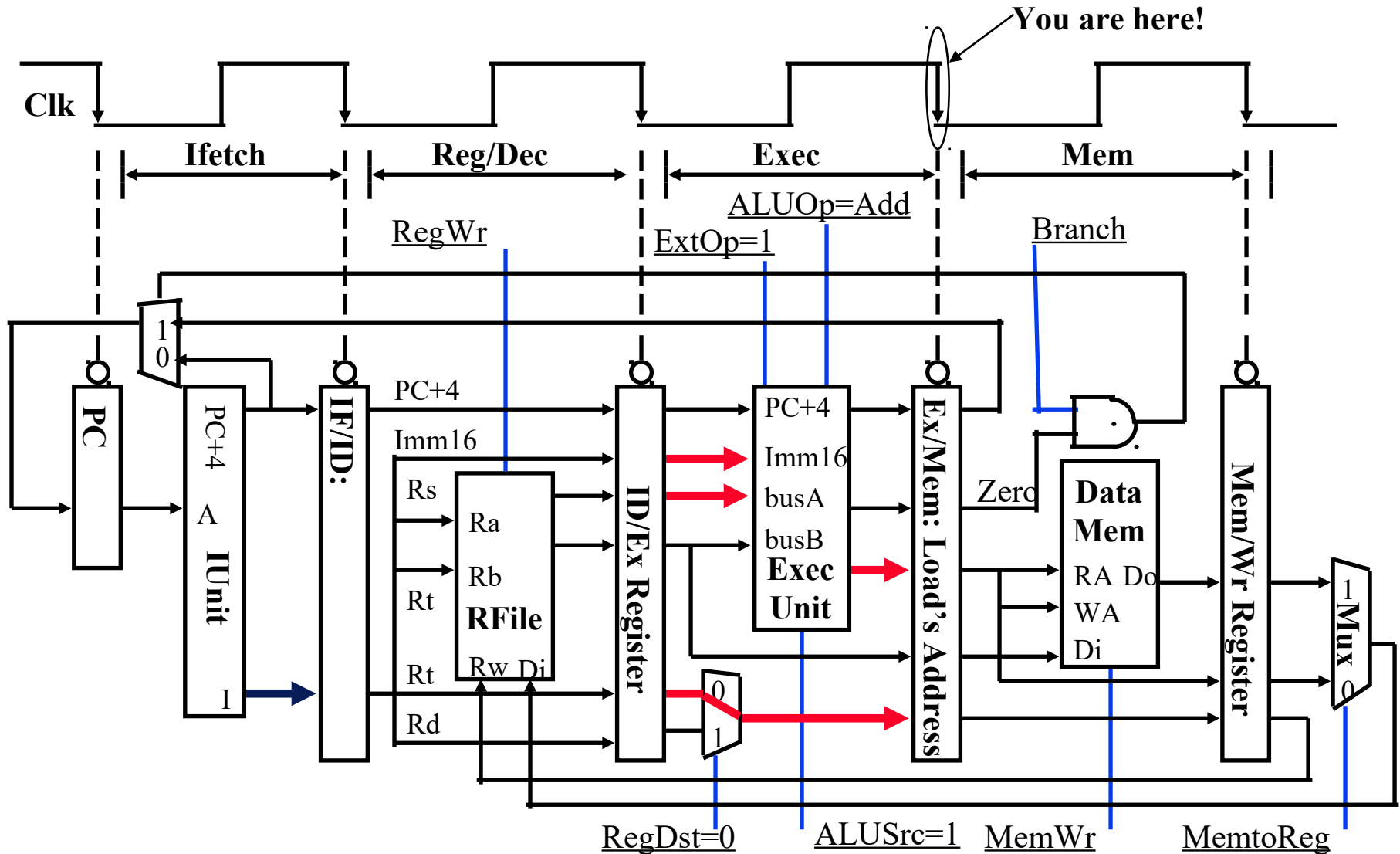
Stage

Location 10: lw \$1, 0x100(\$2) $\$1 \leftarrow \text{Mem}[(\$2) + 0x100]$

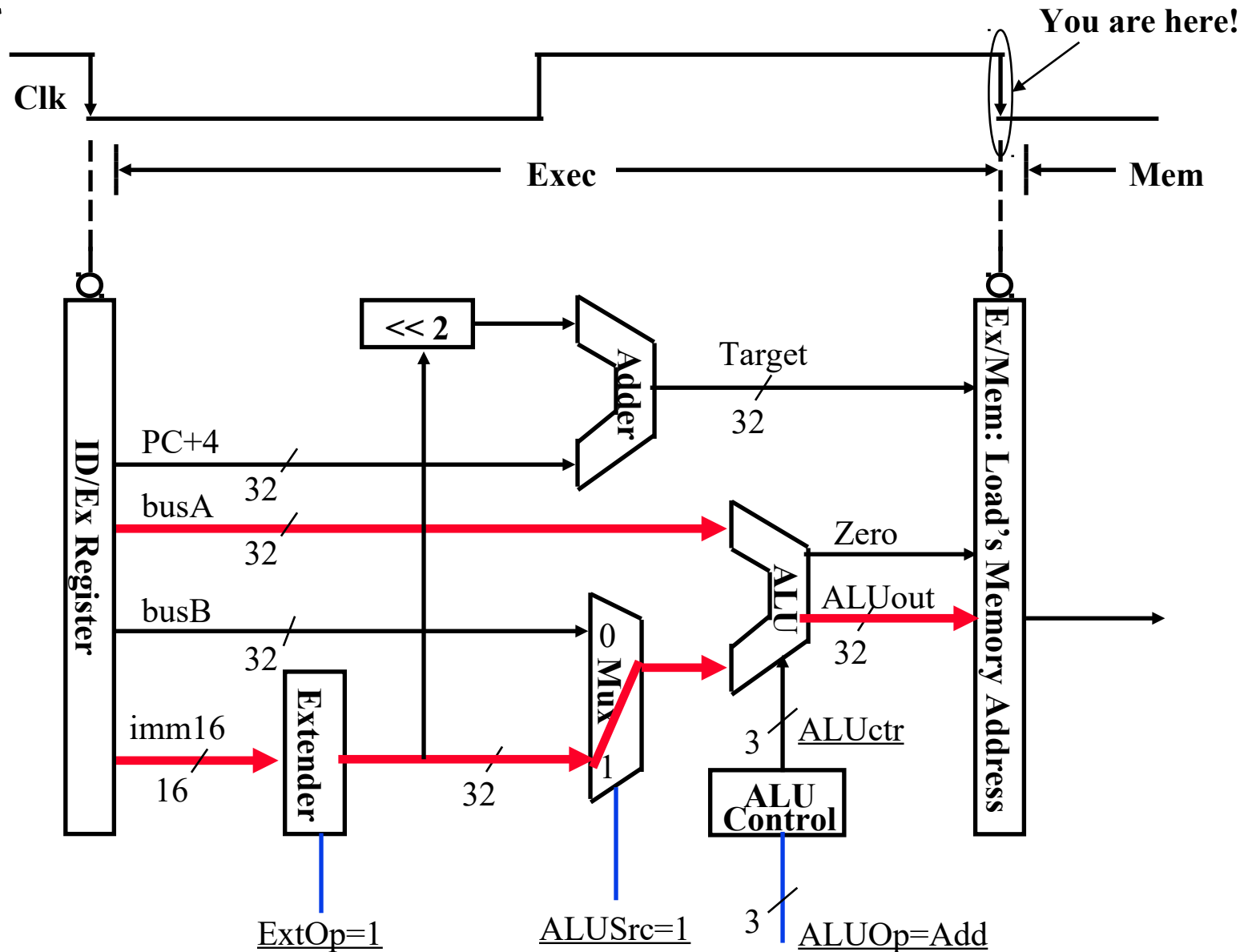


Load's Address Calculation

Stage 10: lw \$1, 0x100(\$2) \$1 <- Mem[(\$2) + 0x100]



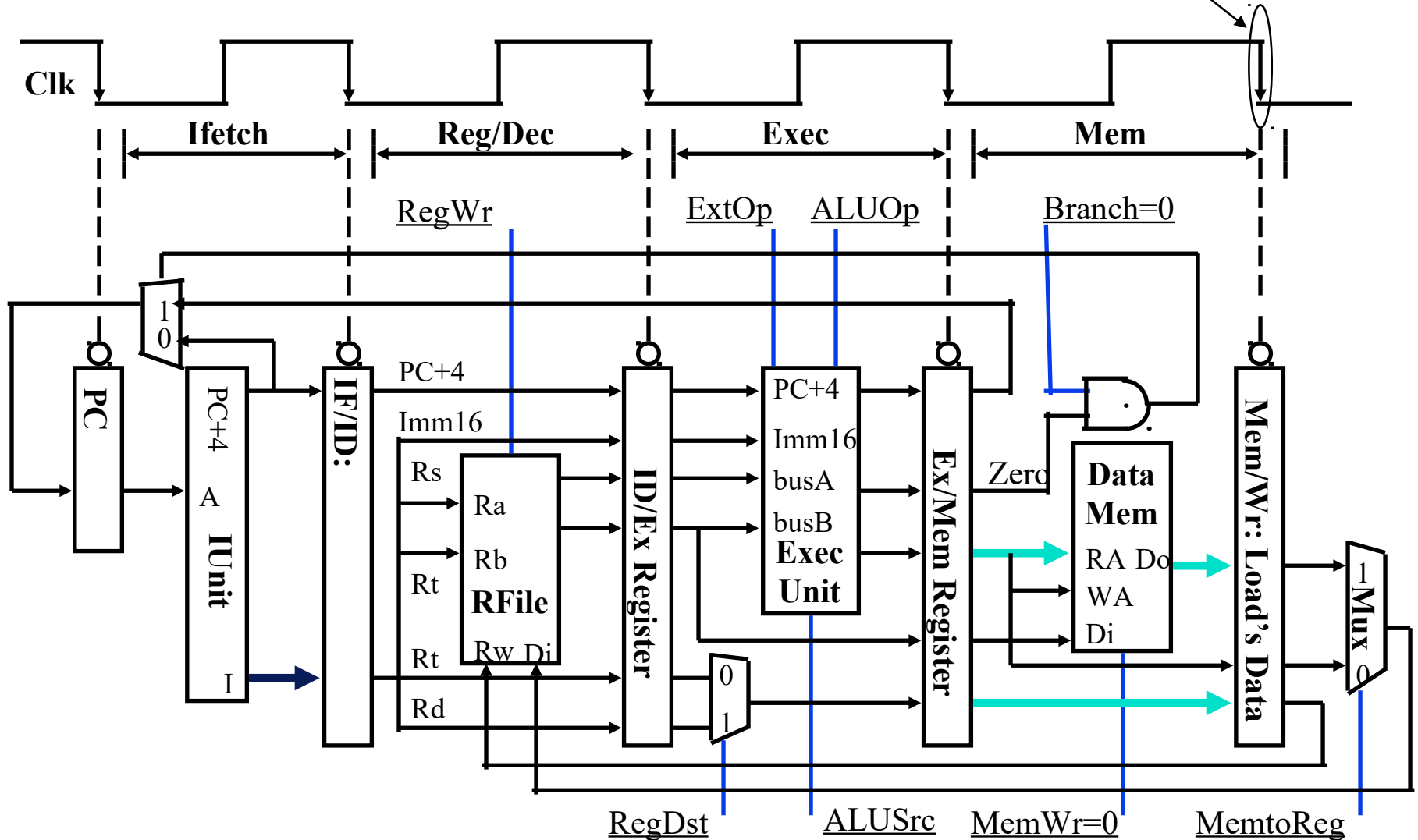
A Detail View of the Execution Unit



Load's Memory Access Stage

° Location 10: lw \$1, 0x100(\$2) \$1 <- Mem[(\$2) + 0x100]

You are here! →

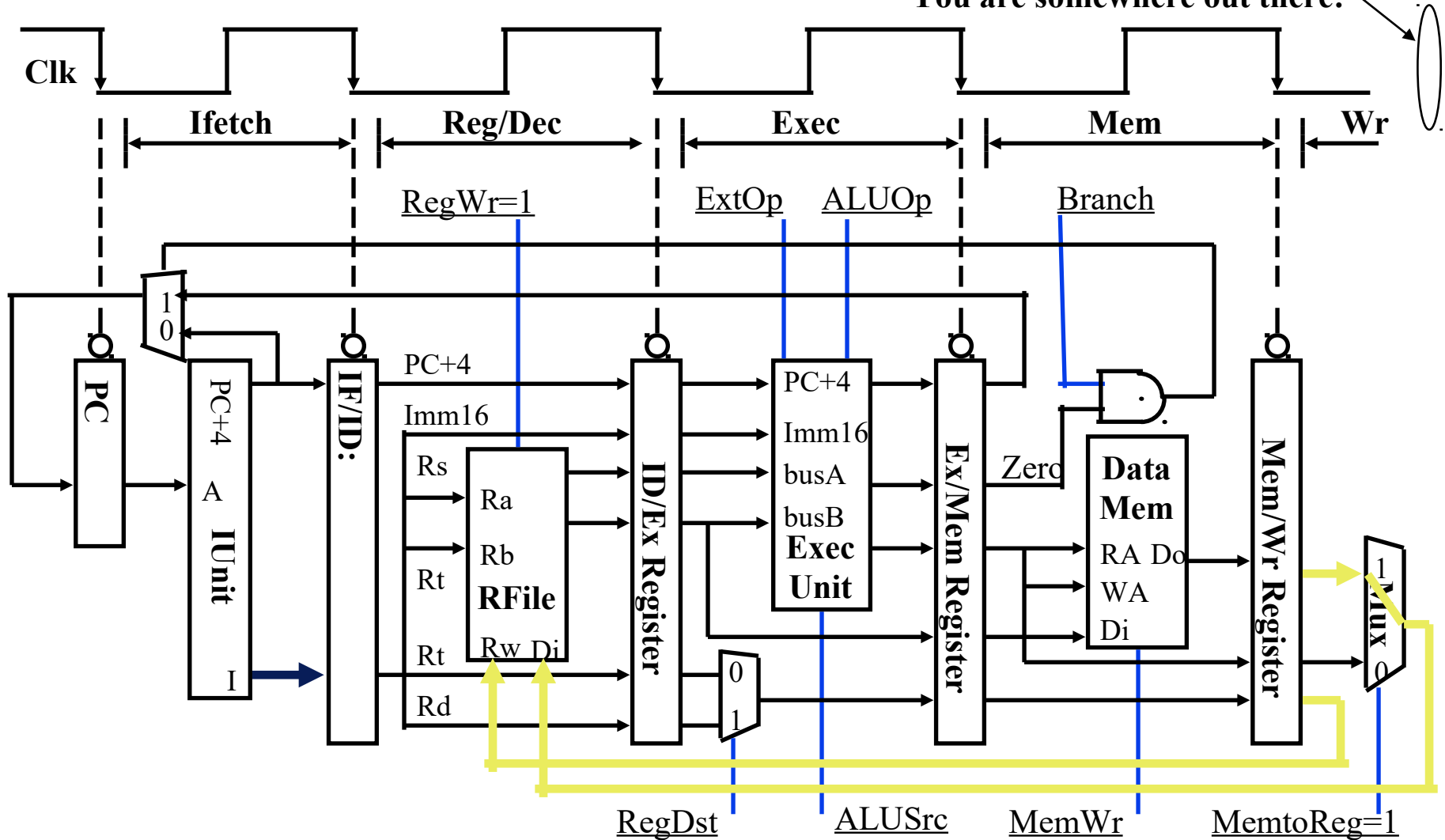


Load's Write Back

Stage

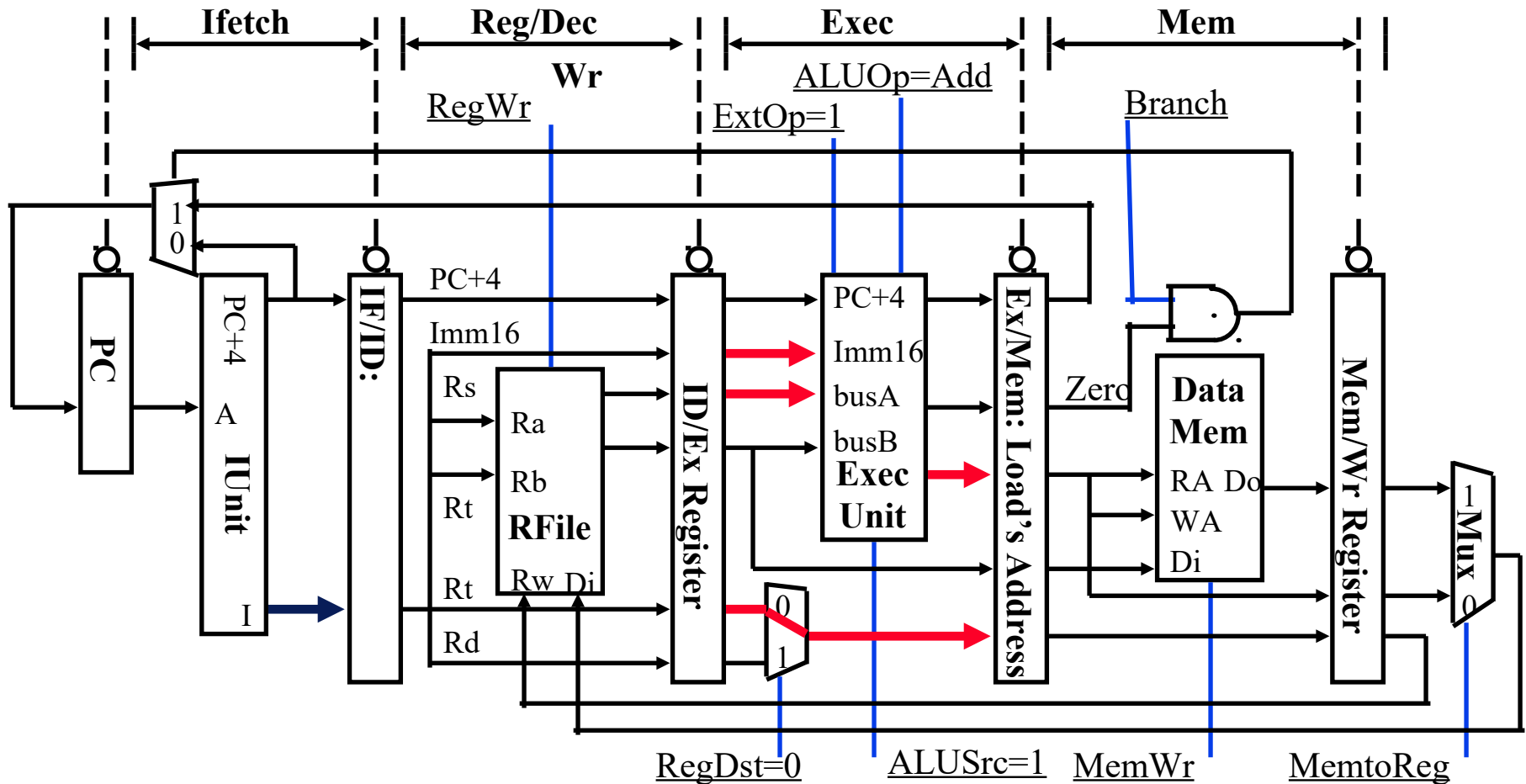
Location 10: lw \$1, 0x100(\$2) \$1 <- Mem[(\$2) + 0x100]

You are somewhere out there!



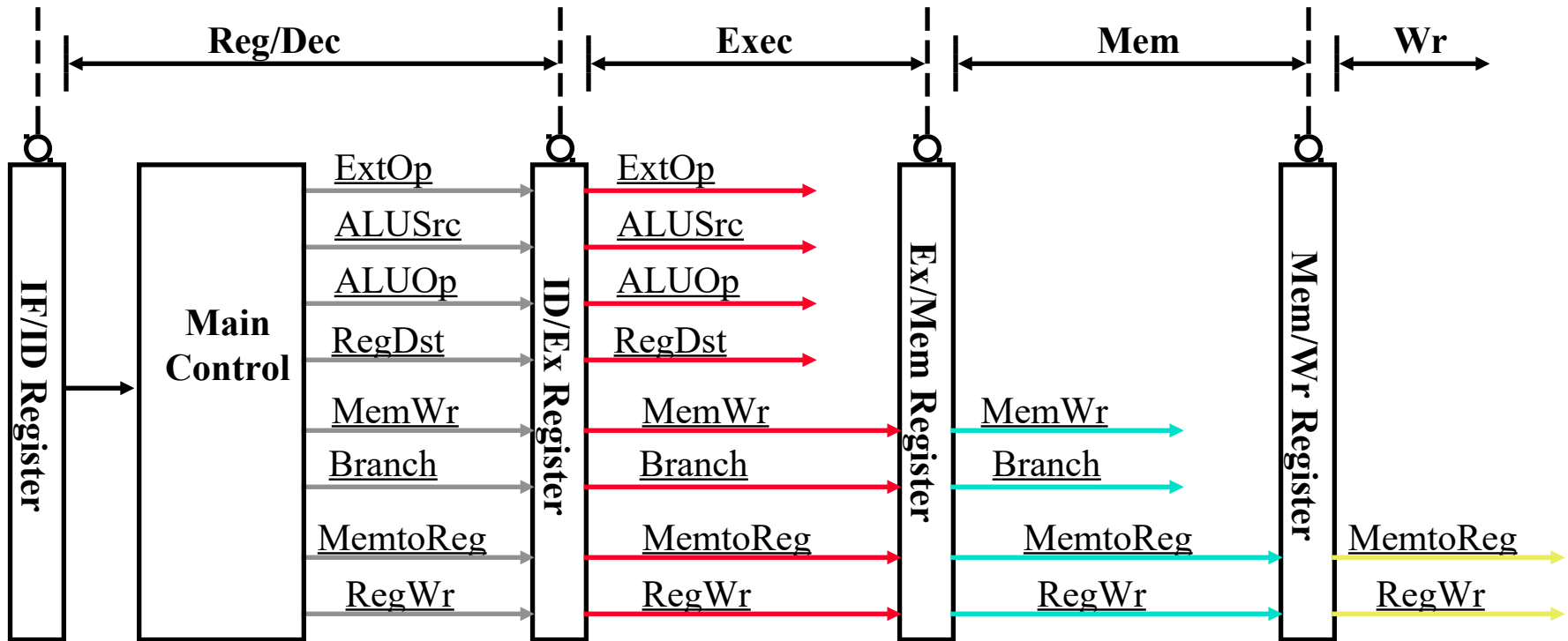
How About Control Signals?

- Key Observation: Control Signals at Stage N = Func (Instr. at Stage N)
 - N = Exec, Mem, or Wr
- Example: Controls Signals at Exec Stage = Func(Load's Exec)



Pipeline Control

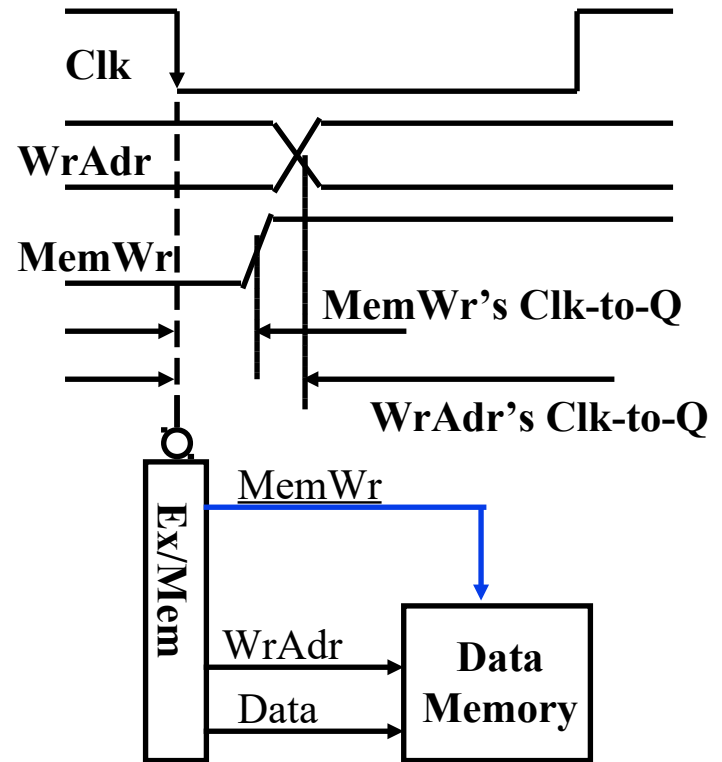
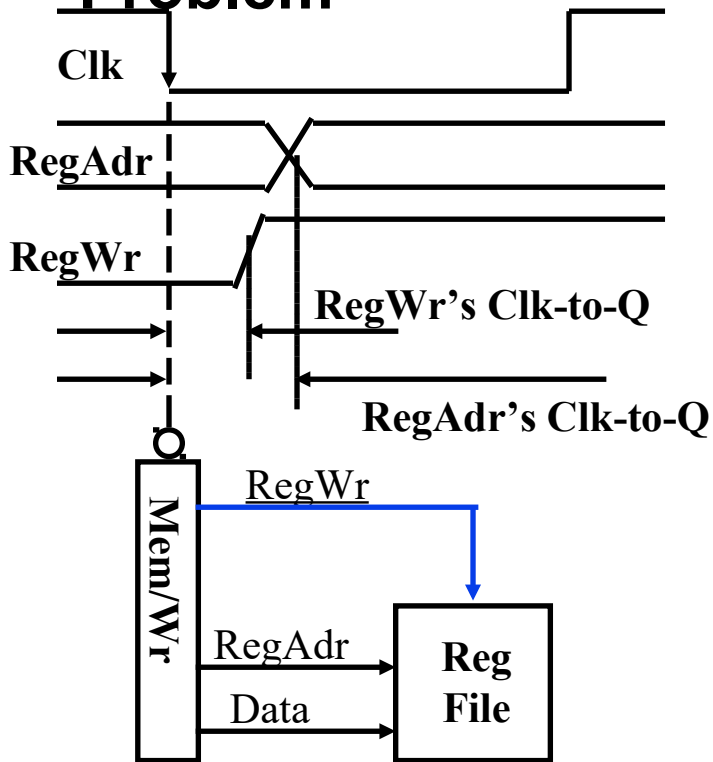
- The Main Control generates the control signals during Reg/Dec
 - Control signals for Exec (ExtOp, ALUSrc, ...) are used 1 cycle later
 - Control signals for Mem (MemWr Branch) are used 2 cycles later
 - Control signals for Wr (MemtoReg MemWr) are used 3 cycles later



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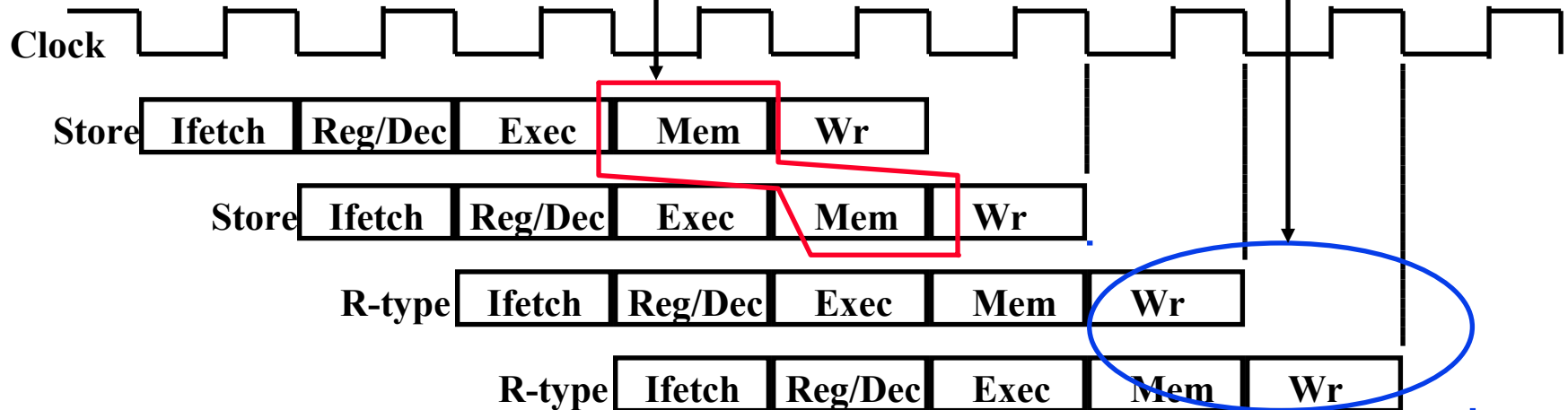
Beginning of the Wr's Stage: A Real World Problem



- At the beginning of the Wr stage, we have a problem if:
 - $\text{RegAdr's (Rd or Rt) Clk-to-Q} > \text{RegWr's Clk-to-Q}$
- Similarly, at the beginning of the Mem stage, we have a problem if:
 - $\text{WrAdr's Clk-to-Q} > \text{MemWr's Clk-to-Q}$
- **We have a race condition between Address and Write Enable!**

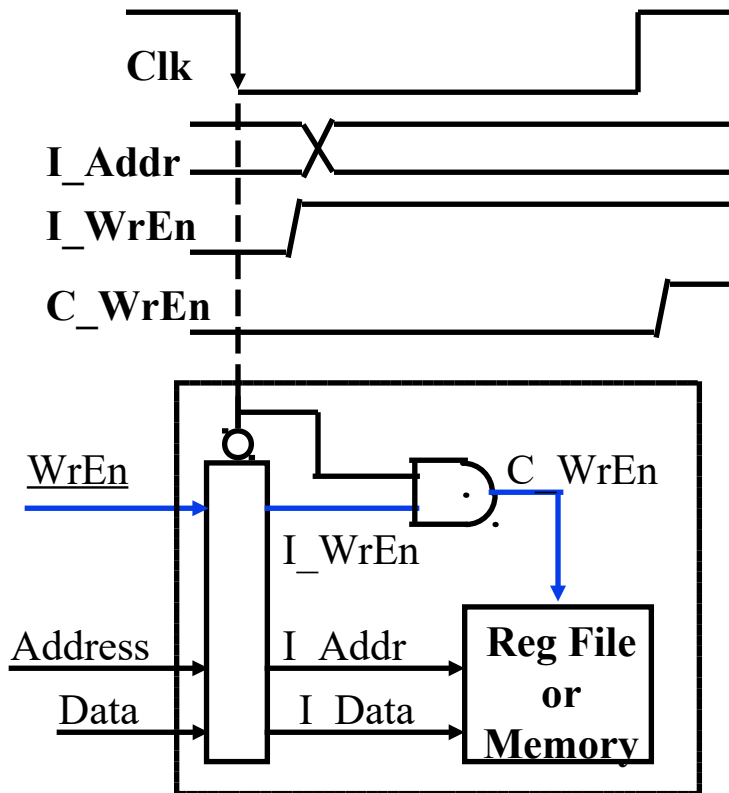
The Pipeline Problem

- Multiple Cycle design prevents race condition between Addr and WrEn:
 - Make sure Address is stable by the end of Cycle N
 - Asserts WrEn during Cycle N + 1
- This approach can NOT be used in the pipeline design because:
 - Must be able to write the register file every cycle
 - Must be able write the data memory every cycle



Synchronize Register File & Synchronize Memory

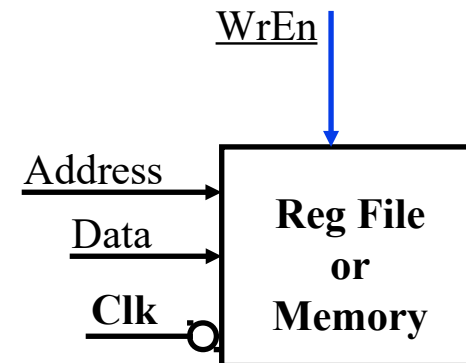
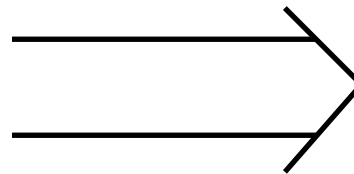
- Solution: And the Write Enable signal with the Clock
 - This is the **ONLY** place where gating the clock is used
 - **MUST** consult circuit expert to ensure no timing violation:
 - Example: Clock High Time > Write Access Delay



Synchronize Memory and Register File

Address, Data, and WrEn must be stable at least 1 set-up time before the Clk edge

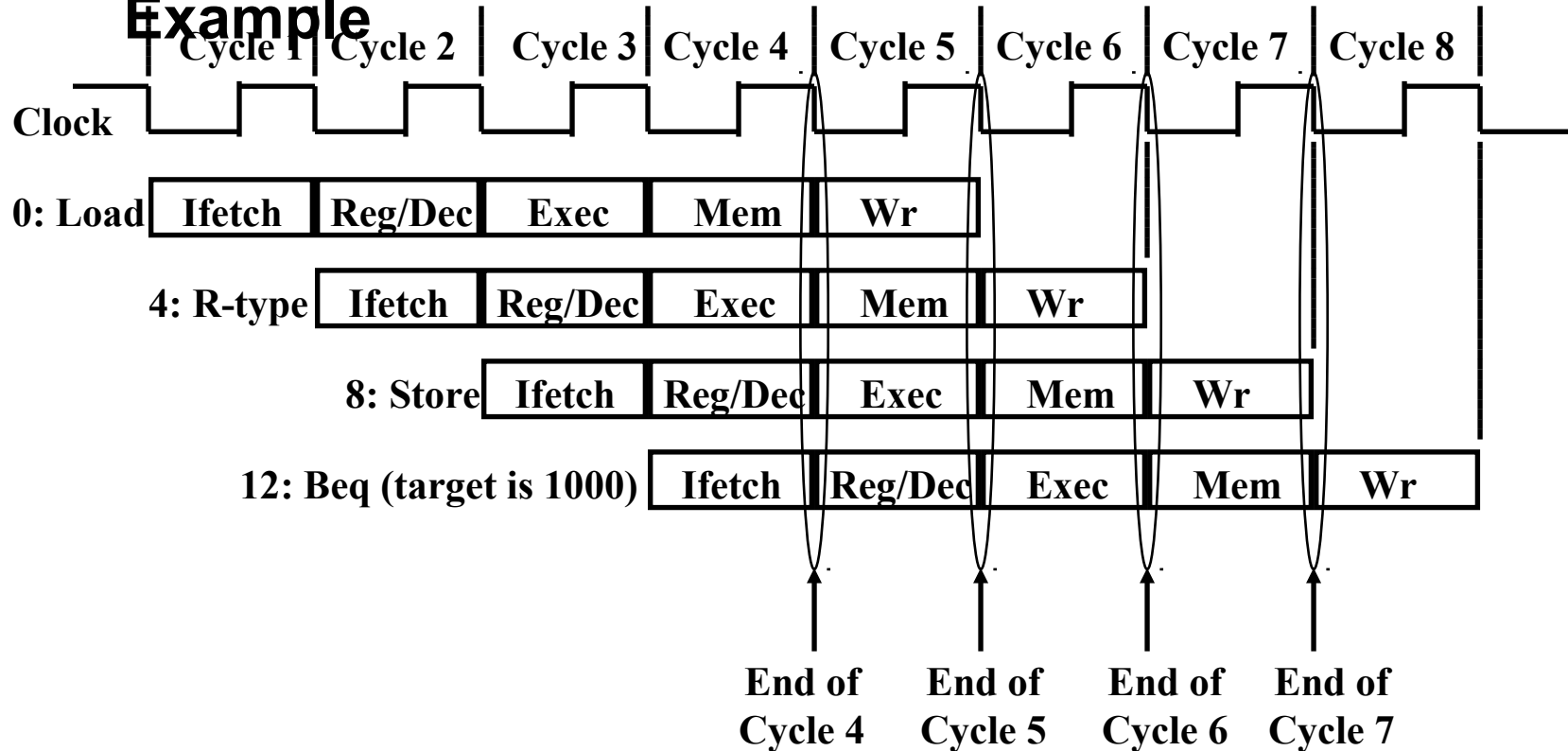
Write occurs at the cycle following the clock edge that captures the signals



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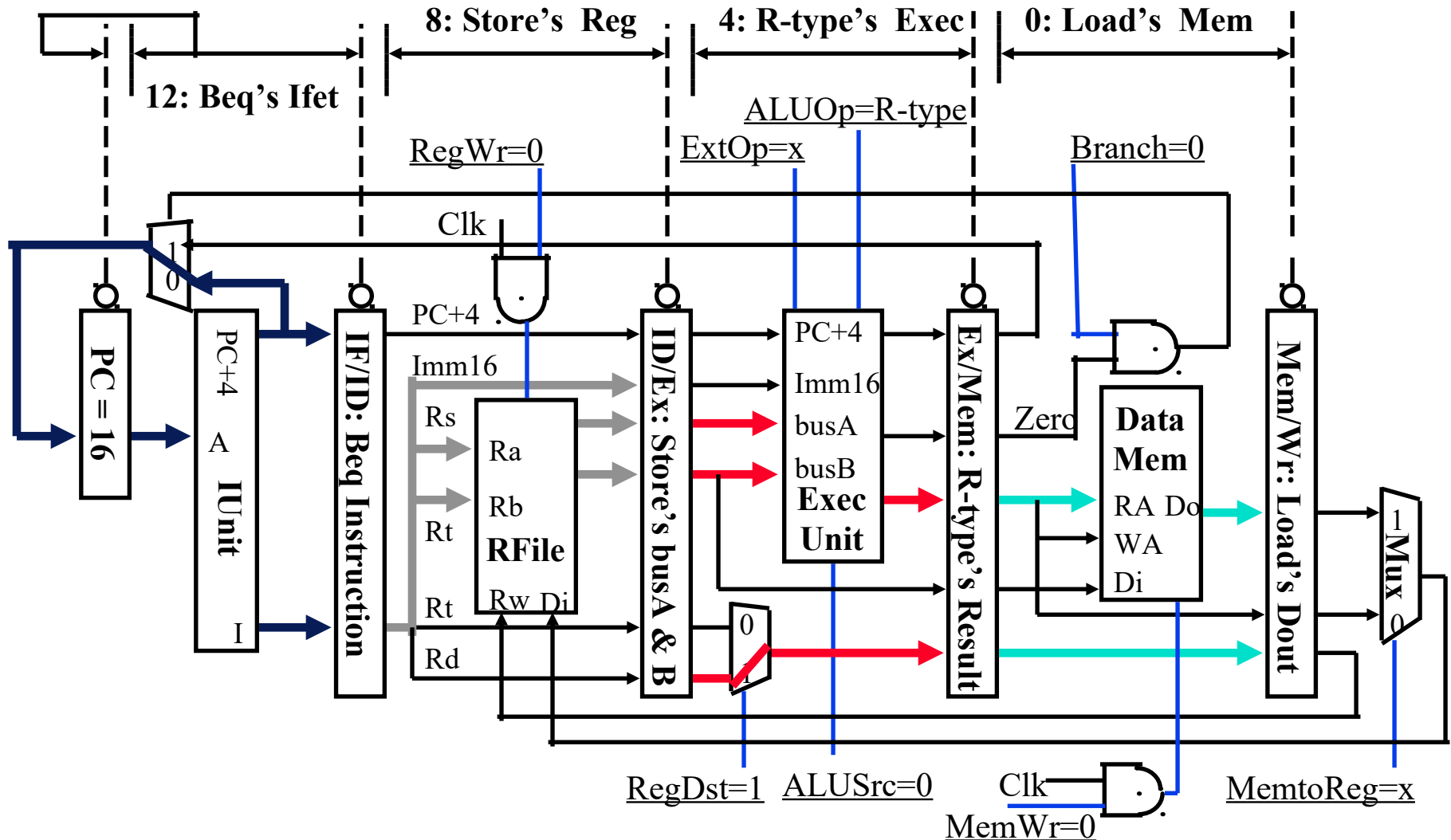
A More Extensive Pipelining Example



- ° End of Cycle 4: Load's Mem, R-type's Exec, Store's Reg, Beq's Ifetch
- ° End of Cycle 5: Load's Wr, R-type's Mem, Store's Exec, Beq's Reg
- ° End of Cycle 6: R-type's Wr, Store's Mem, Beq's Exec
- ° End of Cycle 7: Store's Wr, Beq's Mem

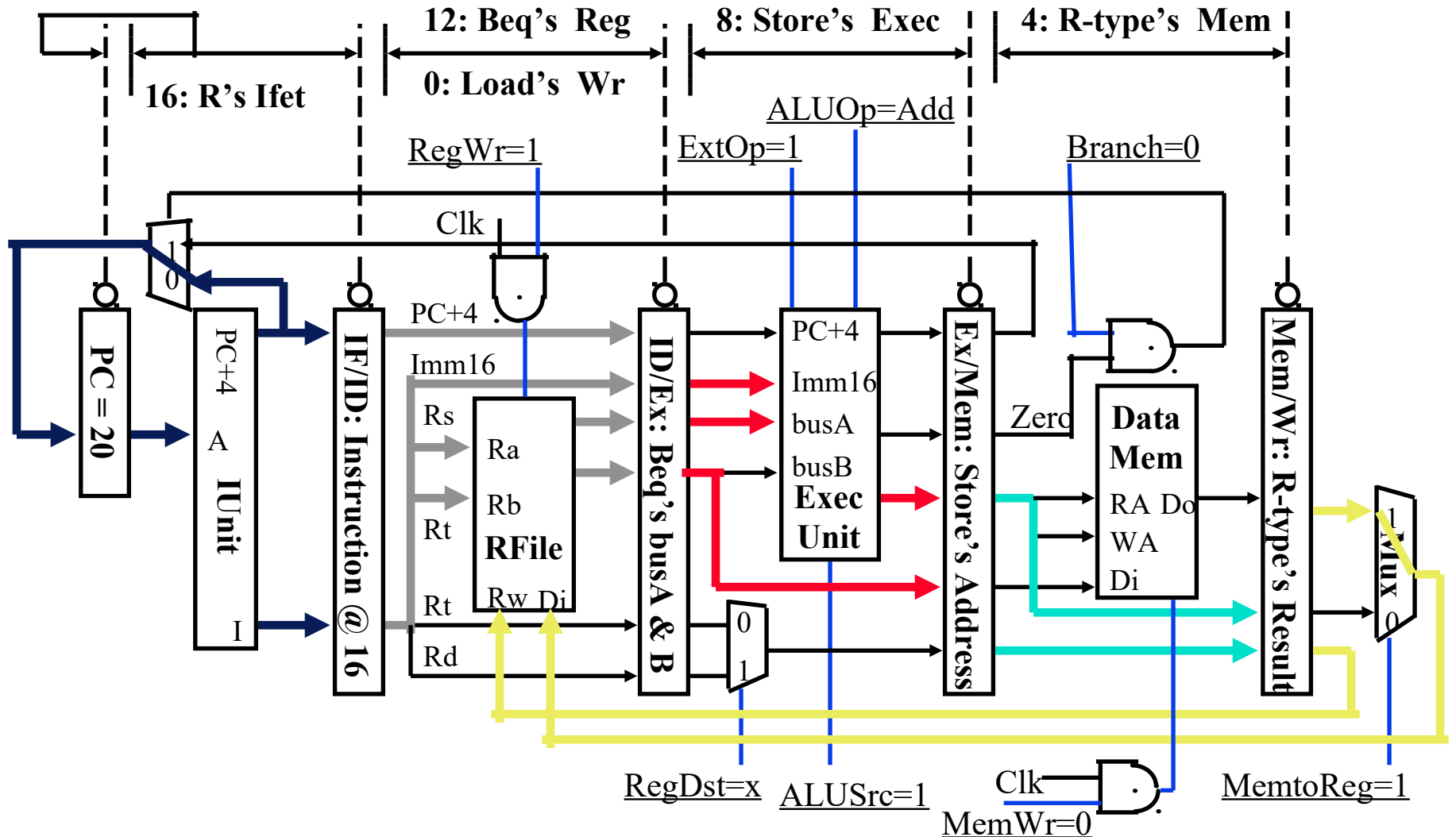
Pipelining Example: End of Cycle

- 4
 ° 0: Load's Mem 4: R-type's Exec 8: Store's Reg 12: Beq's Ifetch



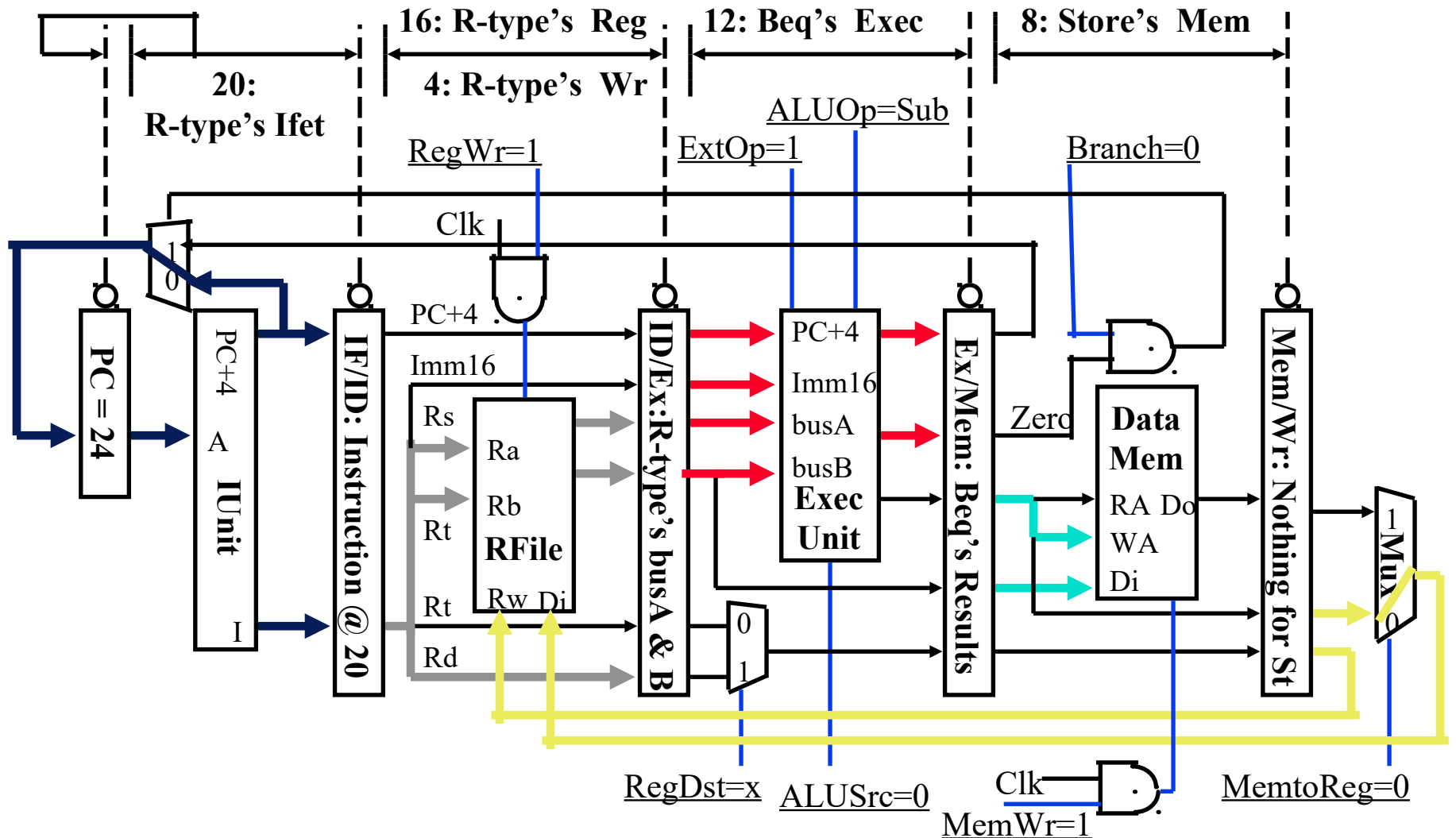
Pipelining Example: End of Cycle

- 5
 ° 0: Lw's Wr 4: R's Mem 8: Store's Exec 12: Beq's Reg 16: R's Ifetch



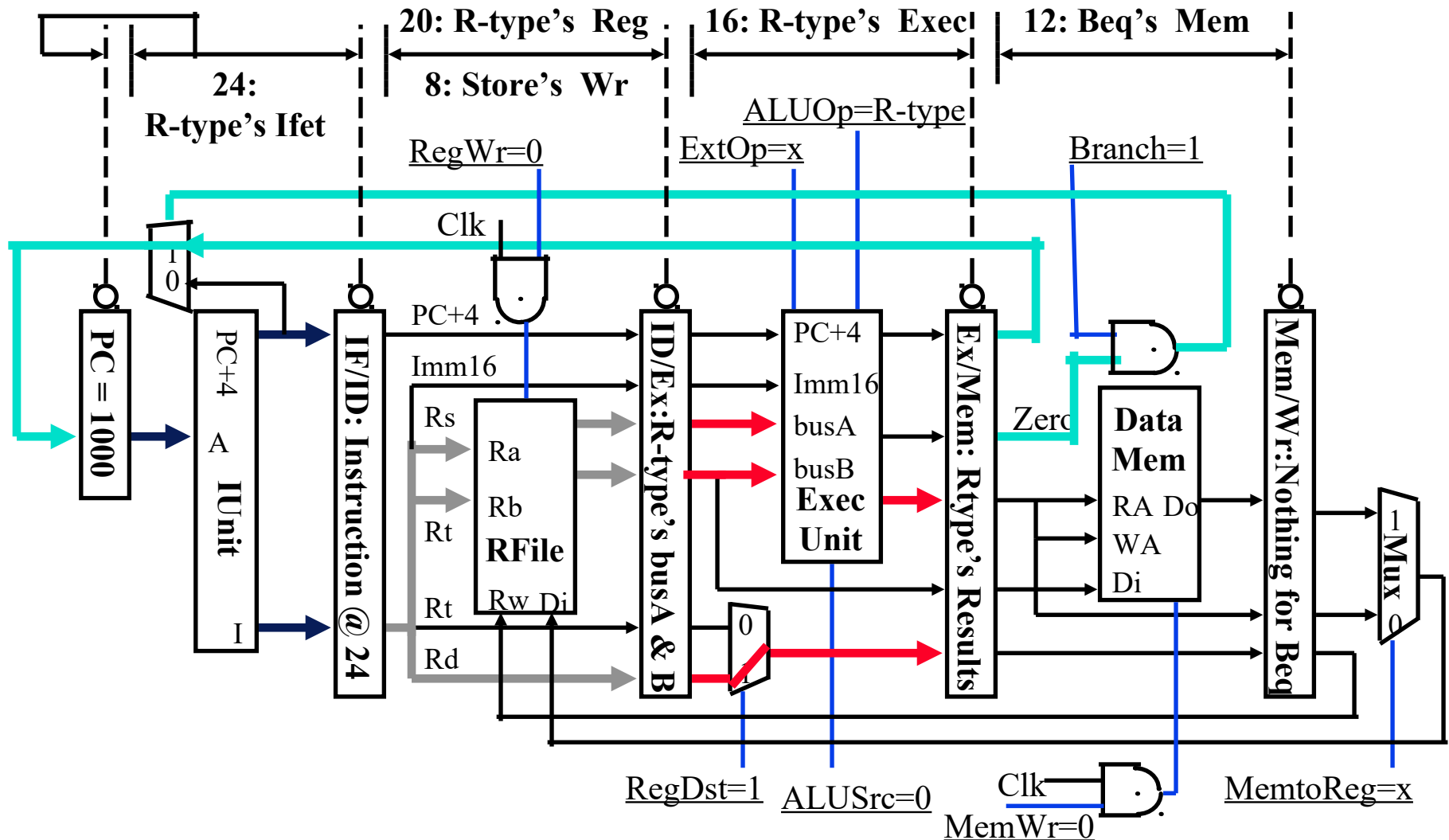
Pipelining Example: End of Cycle

- 6
 ° 4: R's Wr 8: Store's Mem 12: Beq's Exec 16: R's Reg 20: R's Ifet

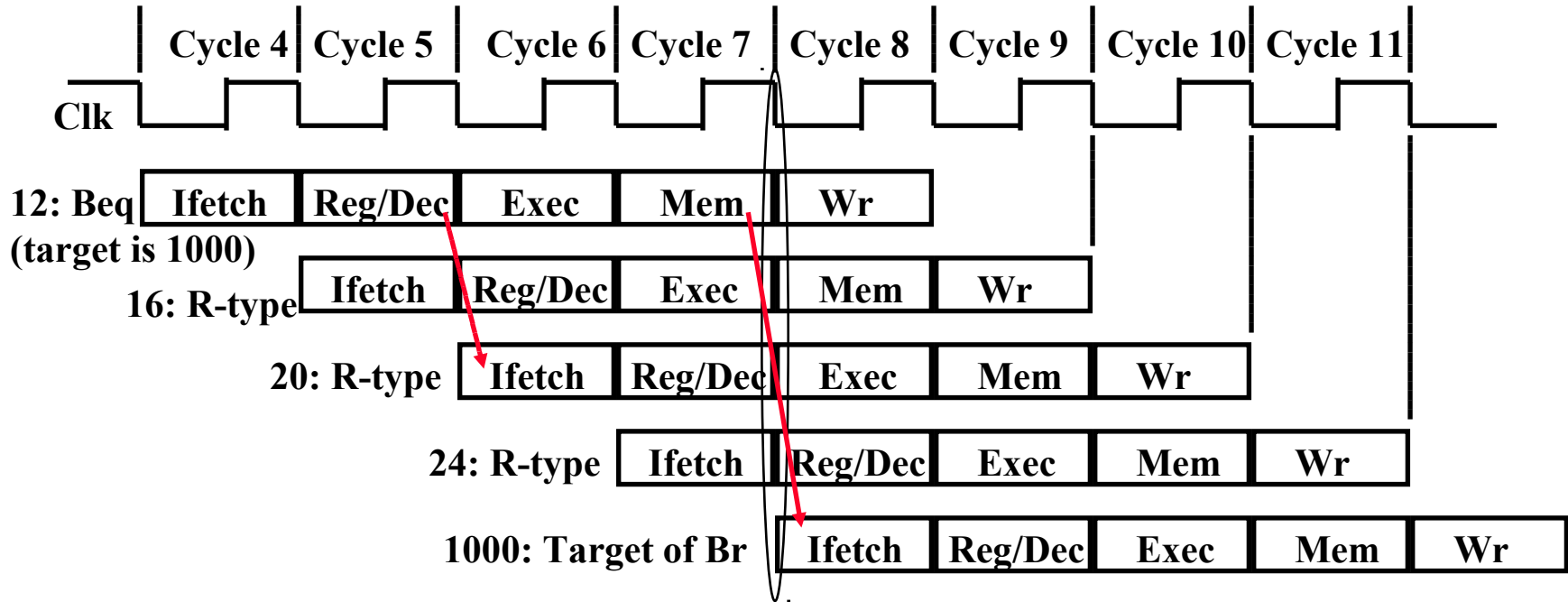


Pipelining Example: End of Cycle

- 7
 ° 8: Store's Wr 12: Beq's Mem 16: R's Exec 20: R's Reg 24: R's Ifet

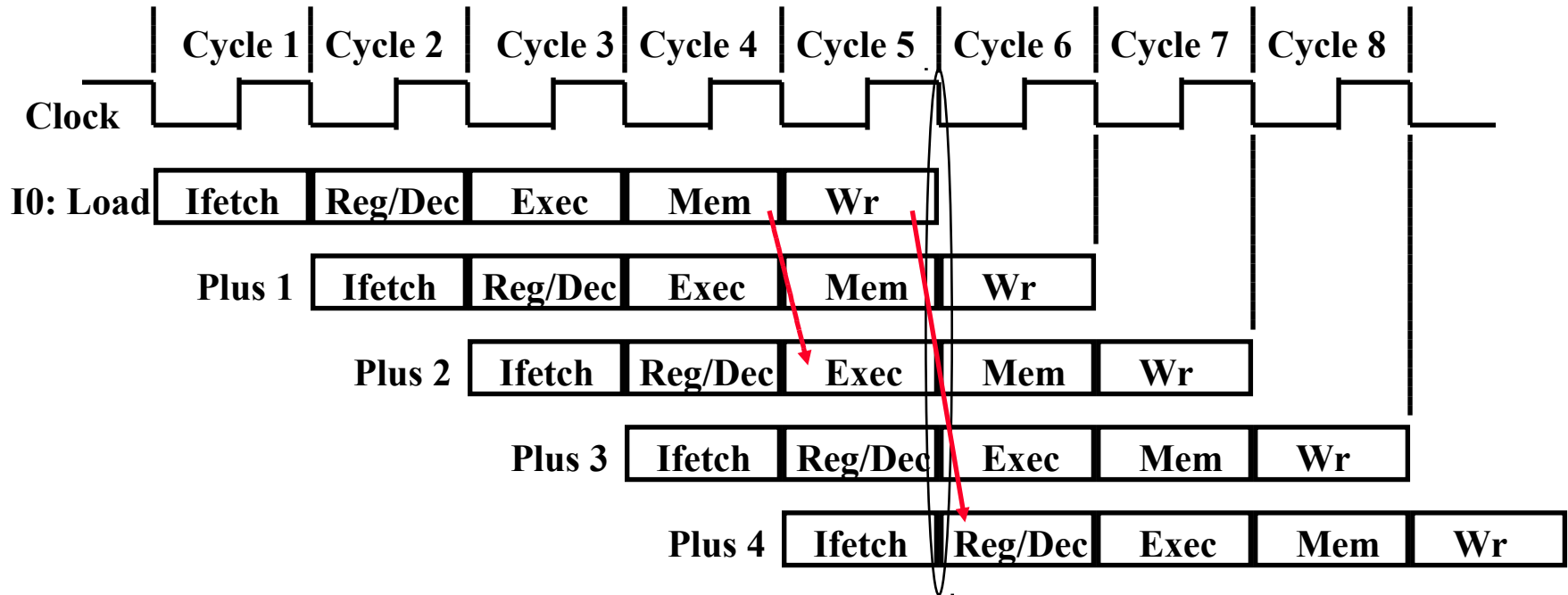


The Delay Branch Phenomenon



- Although Beq is fetched during Cycle 4:
 - Target address is NOT written into the PC until the end of Cycle 7
 - Branch's target is NOT fetched until Cycle 8
 - 3-instruction delay before the branch take effect
- This is referred to as Branch Hazard:
 - Clever design techniques can reduce the delay to ONE instruction

The Delay Load Phenomenon

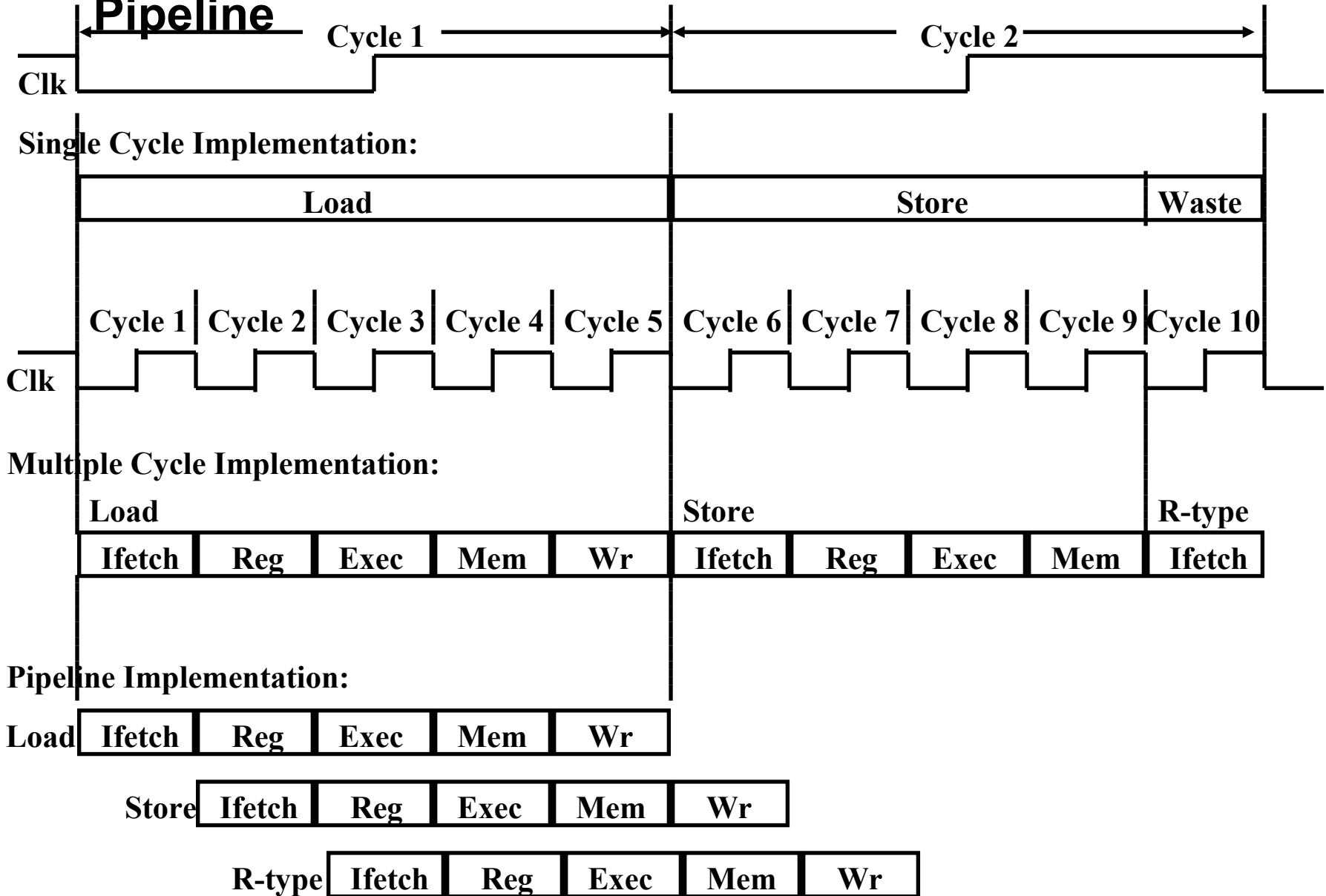


- Although Load is fetched during Cycle 1:
 - The data is NOT written into the Reg File until the end of Cycle 5
 - We cannot read this value from the Reg File until Cycle 6
 - 3-instruction delay before the load take effect
- This is referred to as Data Hazard:
 - Clever design techniques can reduce the delay to ONE instruction

Summary

- **Disadvantages of the Single Cycle Processor**
 - Long cycle time
 - Cycle time is too long for all instructions except the Load
- **Multiple Clock Cycle Processor:**
 - Divide the instructions into smaller steps
 - Execute each step (instead of the entire instruction) in one cycle
- **Pipeline Processor:**
 - Natural enhancement of the multiple clock cycle processor
 - Each functional unit can only be used once per instruction
 - If a instruction is going to use a functional unit:
 - it must use it at the same stage as all other instructions
 - Pipeline Control:
 - Each stage's control signal depends **ONLY** on the instruction that is currently in that stage

Single Cycle, Multiple Cycle, vs. Pipeline



Where to get more information?

- **Everything You Need to know about Pipeline Computer:**
 - **Peter Kogge, “The Architecture of Pipeline Computers,” McGraw Hill Book Company, 1981**
- **Some Classic References on RISC Pipelines:**
 - **Manolis Katevenis, “Reduced Instruction Set Computer Architectures for VLSI,” PhD Thesis, UC Berkeley, 1984.**
- **Other references:**
 - **David. A Patterson, “Reduced Instruction Set Computers,” Communications of the ACM, January 1985.**
 - **Shing Kong, “Performance, Resources, and Complexity,” PhD Thesis, UC Berkeley, 1989.**