BAYESUVIUS

a visual dictionary of Bayesian Networks and Causal Inference



ROBERT R. TUCCI

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a visual dictionary of Bayesian Networks and Causal Inference

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This book is constantly being expanded and improved. To download the latest version, go to https://github.com/rrtucci/Bayesuvius

Bayesuvius

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Figure 1: View of Mount Vesuvius from Pompeii



Figure 2: Mount Vesuvius and Bay of Naples

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Appendices

Chapter 94

Transformer Networks

The primary reference for this chapter is Ref.[78]. Ref.[78] is the highly influential 2017 paper entitled "Attention is all you need" that introduced **Transformer Networks** (tranets) and Attention into the AI vernacular. Besides Ref.[78], I also read blog posts such as Ref.[28] and the Wikipedia article on tranet (Ref. [158]). For a complete list of the large number of excellent blog post that I read to learn this subject, see my open source software texnn (Ref.[77]).¹

Transformer Networks (tranet) have been taking the fields of Natural Language Processing (NLP) and Large Language Models (LLM) by storm in recent years. They were introduced in 2017 and already are the basis of numerous LLMs. For example, BERT (Bidirectional Encoder Representations from Transformers) and ChatGPT (Generative Pre-trained Transformer), two tranet libraries that have been trained with huge databases such as all of English Wikipedia (2,500M words).

How well ChatGPT works was a huge surprise to most people, including experts in AI/ML. My conjecture is that this surprising LLM performance is due to causality. Let me explain. I believe tranets and the LLM that use them, are just curve-fitters (so are Least Squares, vanilla NNs, Convolutional NNs, etc.). But, we lucked out, because tranets are very good at fitting causal data, and the space of all human generated text, including math equations and computer code, is causality connected (i.e., has a causally connected topology.).

Normally, tranets are drawn as box diagrams that are somewhat cryptic and ambiguous, at least to me. In this chapter, instead of drawing them as box diagrams, I represent them as causal DAGs (bnets). This makes their causal nature more explicit than the box diagrams, and, in my opinion, also makes them less ambiguous and more understandable than the box diagrams.

Recurrent Neural Nets (RNNs) are discussed in Chapter 75. tranets are quickly displacing RNNs, an older method, in NLP. tranets are better than RNNs for doing NLP in several important ways. Whereas RNNs analyze the tokens (words) of a

¹texnn is Python software that I wrote specifically for drawing the bnets of this chapter, but later I generalized it to a stand-alone app that can draw any bnet (including SCMs, NNs and tranets), not just a tranet bnet.

sentence sequentially (like a Kalman Filter), tranets analyze them in parallel, and thus are more amenable to parallel computing. Also, because RNNs analyze the words of a sentence sequentially, they tend to give more importance to the end of a sentence than to its beginning. That's because RNNs start forgetting the beginning of a sentence by the time they reach its end, like a patient with Alzheimer's. tranets do not suffer from this malady.

Dynamical bnets are discussed in Chapter 25. In Chapter 75, we showed that RNNs are dynamical bnets. In this chapter we will show that tranets dynamical bnets too.

In this chapter, we will use the Numpy-like tensor notation discussed in Section C.48. In particular, note that $[n] = [0:n] = \{0,1,\ldots,n-1\}$ and that $T^{[n],[m]}$ is an $n \times m$ matrix.

Recurrent Neural Net with Attention 94.1

94.1.1Single Head Attention

Let

 ℓ be the maximum number of words allowed in a sentence. Some words might be blanks (padding).

d be the so called **hidden or embedding dimension**.

 $e^t_{\alpha} \in \mathbb{R}^d$ be a d column vector for word $\alpha \in [\ell]$ at time t. $W^t_q, W^t_{\underline{k}}, W^t_{\underline{v}} \in \mathbb{R}^{d \times d}$ be the weight matrices for time slice t. These matrices are learned by training the net. The letters Q, K, V stand for Query, Key and Value, respectively. They transform e^t_{α} as follows

$$v_{\alpha}^{t} = W_{\nu}^{t} e_{\alpha}^{t} \tag{94.1}$$

$$q_{\alpha}^t = W_q^t e_{\alpha}^t \tag{94.2}$$

$$k_{\alpha}^t = W_k^t e_{\alpha}^t \tag{94.3}$$

Fig. 94.1 represents a tranet of a 3-word sentence as a dynamical bnet. The TPMs, printed in blue, for bnet Fig. 94.1, are as follows:

$$P(v_{\alpha}^t|e_{\alpha}^t) = \mathbb{1}(\quad v_{\alpha}^t = W_v^t e_{\alpha}^t \quad) \tag{94.4}$$

$$P(q_{\alpha}^t|e_{\alpha}^t) = \mathbb{1}(\quad q_{\alpha}^t = W_q^t e_{\alpha}^t \quad) \tag{94.5}$$

$$P(k_{\alpha}^t|e_{\alpha}^t) = \mathbb{1}(\quad k_{\alpha}^t = W_k^t e_{\alpha}^t \quad) \tag{94.6}$$

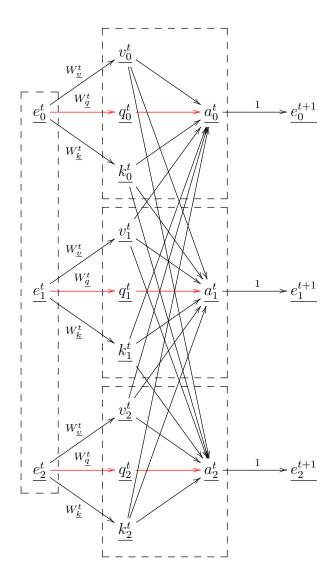


Figure 94.1: Dynamical bnet with single-head Attention for 3 words. Time-slice t. Note that k^t_{α} for all α points to $\underline{a}^t_{\alpha'}$ for all α' . Likewise, \underline{v}^t_{α} for all α points to $\underline{a}^t_{\alpha'}$ for all α' . However, \underline{q}^t_{α} points only to \underline{a}^t_{α} .

$$P(e_{\alpha}^{t+1}|a_{\alpha}^{t}) = \mathbb{1}(\quad e_{\alpha}^{t+1} = a_{\alpha}^{t} \quad) \tag{94.7}$$

$$P(a_{\alpha}^{t+1}|v_{\cdot}^{t}, q_{\alpha}^{t}, k_{\cdot}^{t}) = \mathbb{1}(\quad a_{\alpha}^{t+1} = \sum_{\alpha' \in [\ell]} v_{\alpha'}^{t} P(\alpha'|\alpha) \quad)$$

$$(94.8)$$

where the conditional probability $P(\alpha'|\alpha)$ is called defined as

$$P(\alpha'|\alpha) = \operatorname{softmax} \left[\sum_{\delta \in [d]} (k^t)^{\delta, [\ell]} (q^t)^{\delta, \alpha} \right] (\alpha'|\alpha)$$

$$= \frac{e^{(k_{\alpha'}^t)^T q_{\alpha}^t}}{\sum_{\alpha'' \in [\ell]} e^{(k_{\alpha''}^t)^T q_{\alpha}^t}}$$
(94.10)

$$= \frac{e^{(k_{\alpha'}^t)^T q_{\alpha}^t}}{\sum_{\alpha'' \in [\ell]} e^{(k_{\alpha''}^t)^T q_{\alpha}^t}}$$

$$(94.10)$$

The right hand side of Eq.(94.8) constitutes an average over all the word vectors $\{\underline{v}_{\alpha}^t : \alpha \in [\ell]\}$ in a sentence. This average is called the **Attention** (for a single head).²

Attention^{$$\delta,\alpha$$} $\left((v^t)^{[d],[\ell]}, (k^t)^{[d],[\ell]}, (q^t)^{[d],[\ell]} \right) = \sum_{\alpha' \in [\ell]} (v^t)^{\delta,\alpha'} P(\alpha'|\alpha)$ (94.11)

On first encounter, the structure of an Attention bnet seems a bit mysterious. Then one realizes that this is an old friend. If the dashed boxes in Fig.94.1 are each "shrunk" to single nodes, then it becomes a TAN Bayes Net. Each of the 3 subgraphs $\underline{e}^t, (\underline{v}^t, q^t, \underline{k}^t), \underline{a}^t$ also constitutes a TAN Bayes net. ^{3.4} In broad terms, Fig.94.1 can be described by saying that each word undergoes a special kind of 3-class (q,k,v) Naive Bayes classification, and the results of that classification are sent to the new version of each word (except the q class which only sends info to one word, not all of them).

It's also useful to think of Attention as a filter with input signal $(e^t)^{[d],[\ell]}$ and output signal $(e^{t+1})^{[d],[\ell]}$.

Fig.94.1 can be "folded" (i.e., the 3 words can be represented by as single node). When folded, Fig.94.1 becomes Fig.94.2. Note that in Fig.94.2, we have started indicating the shapes of tensors by a superscript, using the tensor notation explained in Section C.48. We will continue doing this henceforth in this chapter.

The structural equations for Fig. 94.2, printed in blue, are as follows.

$$(a^t)^{[d],[\ell]} = \text{Attention}((v^t)^{[d],[\ell]}, (k^t)^{[d],[\ell]}, (q^t)^{[d],[\ell]})$$
(94.12a)

$$(e^t)^{[d],[\ell]} = \text{prior} (94.12b)$$

²Variations of this definition of Attention have been proposed. This particular one is the original one from the "Attention is all you need paper". Some people call it the "scaled dot product Attention".

³Tree Augmented Naive (TAN) Bayes nets were introduced in Chapter 9.

⁴A **reverse or upside down tree** is obtained by reversing the directions of all the arrows of a tree directed graph. A TAN Bayes net is normally defined as in Chapter9, as a Naive Bayes net augmented with a tree. In an Attention bnet, the Naive Bayes Net is augmented with a reverse tree (RT) instead of a tree (T), so technically Attention bnets contain RTAN Bayes nets, not TAN Bayes nets.

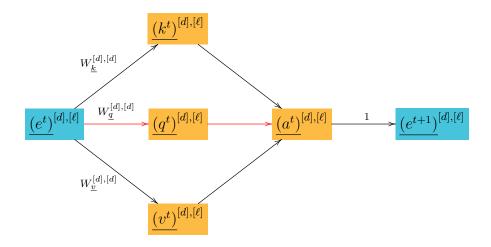


Figure 94.2: Folded version of Fig. 94.1 when $\ell = 3$. Note that all orange nodes have the same tensor shape.

$$(e^{t+1})^{[d],[\ell]} = (a^t)^{[d],[\ell]}$$
 (94.12c)

$$(k^t)^{[d],[\ell]} = W_k^{[d],[d]}(e^t)^{[d],[\ell]}$$
(94.12d)

$$(q^t)^{[d],[\ell]} = W_q^{[d],[d]}(e^t)^{[d],[\ell]}$$
 (94.12e)

$$(v^t)^{[d],[\ell]} = W_v^{[d],[d]}(e^t)^{[d],[\ell]}$$
(94.12f)

94.1.2 Multi-Head Attention

In this section, we will generalize the single head Attention, as defined in the previous section, to multi-head Attention.

Let

 $n_h = \text{number of heads. } \nu \in [n_h].$

 $d = \text{same as before, the hidden, embedding dimension. } \delta \in [d]$ $D = n_{\underline{h}}d. \ \Delta \in [D].$ We will do some tensor reshaping: $T^{[n_{\underline{h}}],[d]} \to T^{[D]}$, or, in component form, $T^{\nu,\delta} \to T^{\Delta}$.

Consider weight matrices $W_{\underline{k}}^{[D],[d]},W_{\underline{q}}^{[D],[d]},$ and $W_{\underline{v}}^{[D],[d]}$ such that

$$(k^t)^{\nu,\delta,\alpha} = \sum_{\delta' \in [d]} W_{\underline{k}}^{\nu,\delta,\delta'}(e^t)^{\delta',\alpha}$$
(94.13)

$$(q^t)^{\nu,\delta,\alpha} = \sum_{\delta' \in [d]} W_{\underline{q}}^{\nu,\delta,\delta'}(e^t)^{\delta',\alpha}$$
(94.14)

$$(v^t)^{\nu,\delta,\alpha} = \sum_{\delta' \in [d]} W_{\underline{v}}^{\nu,\delta,\delta'}(e^t)^{\delta',\alpha}$$
(94.15)

We define the **Multi-head Attention** by

Attention^{$$\nu,\delta,\alpha$$} $\left((v^t)^{[D],[\ell]},(k^t)^{[D],[\ell]},(q^t)^{[D],[\ell]}\right) = \sum_{\alpha'\in[\ell]} (v^t)^{\nu,\delta,\alpha'} P(\alpha'|\alpha,\nu)$ (94.16)

where

$$P(\alpha'|\alpha,\nu) = \operatorname{softmax} \left[\sum_{\delta \in [d]} (k^t)^{\nu,\delta,[\ell]} (q^t)^{\nu,\delta,\alpha} \right] (\alpha'|\alpha,\nu)$$

$$= \frac{e^{(k^t)^{\nu,\delta,\alpha'} (q^t)^{\nu,\delta,\alpha}}}{\sum_{\delta \in [d]} \sum_{\alpha'' \in [\ell]} e^{(k^t)^{\nu,\delta,\alpha''} (q^t)^{\nu,\delta,\alpha}}}$$
(94.18)

$$= \frac{e^{(k^t)^{\nu,\delta,\alpha'}(q^t)^{\nu,\delta,\alpha}}}{\sum_{\delta \in [d]} \sum_{\alpha'' \in [\ell]} e^{(k^t)^{\nu,\delta,\alpha''}(q^t)^{\nu,\delta,\alpha}}}$$
(94.18)

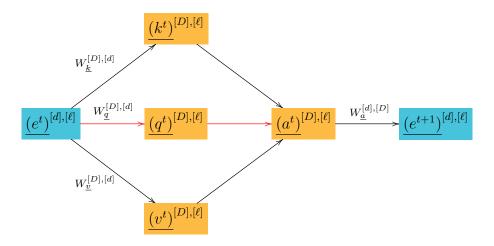


Figure 94.3: Dynamical bnet with single-head Attention for 3 words. Time-slice t. This is a generalization of the single head Attention of Fig. 94.2. Note that all orange nodes have the same tensor shape.

The structural equations, printed in blue, for the bnet Fig. 94.3, are as follows. Note that Attention() always has the same tensor shape as its 3 arguments. Note also that the 3 weight matrices $W^{[D],[d]}_{\underline{k}}$, $W^{[D],[d]}_{\underline{q}}$, and $W^{[D],[d]}_{\underline{v}}$ raise the hidden dimension, whereas the weight matrix $W^{[d],[D]}_{\underline{a}}$ lowers it. $W^{[d],[D]}_{\underline{a}}=1$ in the single head case.

$$(a^t)^{[D],[\ell]} = \text{Attention}((v^t)^{[D],[\ell]}, (k^t)^{[D],[\ell]}, (q^t)^{[D],[\ell]})$$
 (94.19a)

$$(e^t)^{[d],[\ell]} = \text{prior} (94.19b)$$

$$(e^{t+1})^{[d],[\ell]} = W_{\underline{a}}^{[d],[D]}(a^t)^{[D],[\ell]}$$
(94.19c)

$$(k^t)^{[D],[\ell]} = W_{\underline{k}}^{[D],[d]}(e^t)^{[d],[\ell]}$$
(94.19d)

$$(q^t)^{[D],[\ell]} = W_q^{[D],[d]}(e^t)^{[d],[\ell]}$$
 (94.19e)

$$(v^t)^{[D],[\ell]} = W_v^{[D],[d]}(e^t)^{[d],[\ell]}$$
(94.19f)

94.2 Vanilla tranet

In this section, we will discuss the tranet of the "Attention is all you need" paper, Ref. [78]. As is common in the literature, we will refer to that tranet as the "Vanilla" tranet. Ref. [78] describes its tranet graphically with Fig. 94.4. Our goal is to find a causal DAG (bnet) version of that figure.

Let

 $\ell = \text{maximum number of words in a sentence segment. } \alpha \in [\ell], \ \ell \sim 100$

 $L = \text{number of words in vocabulary, } \beta \in [L], L >> \ell$

 $d = d_q = d_{\underline{k}} = d_{\underline{v}} = 64$, hidden dimension per head, $\delta \in [d]$.

 $n_{\underline{h}} = \overline{8}$, number of heads, $\nu \in [n_{\underline{h}}]$

 $D = n_h d = 8(64) = 512$, hidden dimension for all heads, $\Delta \in [D]$

 $\Lambda = 6$, number of layers in plate (a.k.a., stack), $\lambda \in [\Lambda]$

Our tensor notation is discussed in Section C.48. Here is a quick review of some of the more essential facts in that section on tensors:

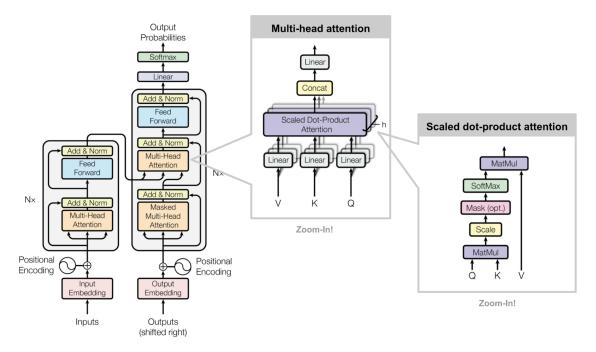


Figure 94.4: Vanilla tranet

• reshaping

$$T^{\nu,\delta} \to T^{\Delta} \left(T^{[n_{\underline{h}}],[d]} \to T^{[D]} \right)$$
 (94.20)

$$T^{\Delta} \to T^{\nu,\delta} \quad \left(T^{[D]} \to T^{[n_{\underline{h}}],[d]}\right)$$
 (94.21)

• concatenation

$$T^{[n]} = (T^0, T^1, \dots, T^{n-1}) = (T^{\nu})_{\nu \in [n]}$$
 (94.22)

• Hadamard product (element-wise, entry-wise multiplication)

$$T^{[n]} * S^{[n]} = (T^{\nu} S^{\nu})_{\nu \in [n]}$$
 (94.23)

• Matrix multiplication

 $T^{[n]} = T^{[n],[1]}$ is a column vector.

$$(T^{[n]})^T S^{[n]} = \operatorname{scalar} \tag{94.24}$$

$$T^{[a],[b]}S^{[b],[c]} = \left[\sum_{\beta \in [b]} T^{\alpha,\beta}S^{\beta,\gamma}\right]_{\alpha \in [a],\gamma \in [c]}$$
(94.25)

Most treatments of tranet, including the "Transformers is All You Need paper", order the operations chronologically from left to right. So if A occurs before B, they write AB. This is contrary to what is done in Linear Algebra, where one orders the operations chronologically from right to left, and one writes BA. We will adhere to the Linear Algebra convention, since it is so prevalent and is the overwhelming precedent.

Before we present the bnet version of Fig.94.4, we discuss some of the definitions needed to understand and motivate Fig.94.4. Below will often accompany an equation in tensor component notation with, in parenthesis, the equivalent matrix equation.

• Encoder Input

$$x^{\beta,\alpha} = \delta(\beta, \beta(\alpha)) \left(x^{[L],[\ell]} \text{ has one hot columns.} \right)$$
 (94.26)

• Embedding (a.k.a. encoding) Matrix

$$e^{\delta,\alpha} = \sum_{\beta} E^{\delta,\beta} x^{\beta,\alpha} \quad \left(e^{[d],[\ell]} = E^{[d],[L]} x^{[L],[\ell]} \right)$$
 (94.27)

• Weight matrices

$$Q^{\nu,\delta,\alpha} = \sum_{s'} W_{\underline{q}}^{\nu,\delta,\delta'} e^{\delta',\alpha} \quad \left(Q^{[D],[\ell]} = W_{\underline{q}}^{[D],[d]} E^{[d],[\ell]} \right)$$
(94.28)

$$K^{\nu,\delta,\alpha} = \sum_{\delta'} W_{\underline{k}}^{\nu,\delta,\delta'} e^{\delta',\alpha} \quad \left(K^{[D],[\ell]} = W_{\underline{k}}^{[D],[d]} E^{[d],[\ell]} \right) \tag{94.29}$$

$$V^{\nu,\delta,\alpha} = \sum_{\delta'} W^{\nu,\delta,\delta'}_{\underline{v}} e^{\delta',\alpha} \quad \left(V^{[D],[\ell]} = W^{[D],[d]}_{\underline{v}} E^{[d],[\ell]} \right) \tag{94.30}$$

• Multi-head Attention

$$B^{\nu,\alpha',\alpha} = \frac{1}{\sqrt{d}} \sum_{\delta} K^{\nu,\delta,\alpha'} Q^{\nu,\delta,\alpha} \quad \left(B^{[n_h],[\ell],[\ell]} = \left[\frac{1}{\sqrt{d}} (K^{\nu,[d],[\ell]})^T Q^{\nu,[d],[\ell]} \right]_{\nu \in [n_h]} \right)$$
(94.31)

$$A^{\nu,\delta,\alpha'} = \sum_{\alpha} V^{\nu,\delta,\alpha'} \underbrace{\operatorname{softmax}(B^{\nu,[\ell],\alpha})(\alpha'|\alpha,\nu)}_{P(\alpha'|\nu,\alpha)}$$
(94.32)

$$\sum_{\alpha' \in [\ell]} P(\alpha'|\nu, \alpha) = 1 \tag{94.33}$$

$$A^{\nu,\delta,\alpha} \to A^{\Delta,\alpha} \left(A^{[n_{\underline{h}}],[d],[\ell]} \to A^{[D],[\ell]} \right) \tag{94.34}$$

Column vector notation:

$$B^{\nu,\alpha',\alpha} = \frac{1}{\sqrt{d}} (K^{\nu,[d],\alpha'})^T Q^{\nu,[d],\alpha}$$
 (94.35)

Important: Note that the softmax() makes the α' component a probability, not the α one!

For example, suppose $\nu=1$ (one head), $\ell=2$ (a 2 word segment), and d=3 (hidden dimension is 3). The $Q^{[3],[2]},K^{[3],[2]},V^{[3],[2]}$ are 3×2 matrices (i.e., two 3-dim column vectors). One uses the $Q^{[3],[2]}$ and $K^{[3],[2]}$ to arrive at a 2×2 matrix $P(\alpha'|\alpha)$ of probabilities. Then one uses that matrix of probabilities to replace

$$\left[V^{[3],0}, V^{[3],1}\right] \to \left[V^{[3],0}P(0|0) + V^{[3],1}P(1|0), V^{[3],0}P(0|1) + V^{[3],1}P(1|1)\right] \tag{94.36}$$

• Positional Embedding Matrix

 $E_{pos}^{[d],[\ell]}$

$$E_{pos}^{\delta,\beta} = \begin{cases} \sin\left(\frac{\beta}{10^{4\delta/d}}\right) = \sin(2\pi\frac{\beta}{\lambda(\delta)}) & \text{if } \delta \text{ is even} \\ \cos\left(\frac{\beta}{10^{4(\delta-1)/d}}\right) = \cos(2\pi\frac{\beta}{\lambda(\delta)}) & \text{if } \delta \text{ is odd} \end{cases}$$
(94.37)

 $E_{pos}^{\delta,\beta}$ changes in phase by $\pi/2$ every time δ changes by 1. Its wavelength λ is independent of β , but increases rapidly with δ , from $\lambda(\delta=0)=2\pi*1$ to $\lambda(\delta=d)=2\pi*10^4$.

Total Embedding equals initial embedding plus positional embedding: $E = E_0 + E_{pos}$

The purpose of positional embedding is to take $e^{\beta,\alpha}$ to $e^{\delta,\alpha} = \sum_{\beta} E_{pos}^{\delta,\beta} e^{\beta,\alpha}$ where $e^{\delta,\alpha}$ changes quickly as δ (i.e., position) changes.

• ReLU

For a tensor T of arbitrary shape

$$ReLU(T) = (T)_{+} = max(0, T)$$
 (94.38)

max element-wise

• Feed Forward neural net

$$F(e^{[1],[\ell]}) = ReLU(e^{[1],[\ell]}W_1^{[\ell],[d]} + b_1^{[1],[d]})W_2^{[d],[\ell]} + b_1^{[1],[\ell]}$$
(94.39)

$$F(e^{[\ell]}) = W_2^{[\ell],[d]} ReLU(W_1^{[d],[\ell]} e^{[\ell]} + b_1^{[d]}) + b_1^{[\ell]}$$
(94.40)

Softmax

softmax() takes a vector and returns a vector of probabilities of the same length

$$e^{[n]} \to P^{[n]}$$
 (94.41)

where

$$P^{\alpha} = \frac{\exp(e^{\alpha})}{\sum_{\alpha \in [n]} \exp(e^{\alpha})} \quad \left(P^{[n]} = \frac{\exp(e^{[n]})}{\|\exp(e^{[n]})\|_{0}}\right)$$
(94.42)

For example,

$$(1,0,0) \to (e,1,1)/norm$$
 (94.43)

$$(10,0,0) \to (e^{10},1,1)/norm \approx (1,0,0)$$
 (94.44)

For any $a \in \mathbb{R}$,

$$(a, a, a) \to (1, 1, 1)/3$$
 (94.45)

• Skip Connection (Add & Normalize)

A skip connection is when you split the input to a filter into two streams, one stream goes through the filter, the other doesn't. The one that doesn't is then merged with the output of the filter via a add & normalize node. The reason for making skip connections is that the signal exiting a filter is usually full of jumps and kinks. By merging that filter output with some of the filter input, one smooths out the filter output to some degree. This makes back-propagation differentiation better behaved.

The filter might be a Multi-Head Attention or a Feed Forward NN.

Add & Normalize just means (A + B)/norm where A and B are the two input signals and "norm" is some norm of A + B (for instance, $||A + B||_2$).

Normalization keeps the signal from growing too big and saturating the signal entering components upstream. Normalization can also involve subtracting the mean $\langle X \rangle$ of the signal X so as to get a signal $X - \langle X \rangle$ that has zero mean.

• Plates

Fig. 94.4 uses plates (a.k.a. stacks). These are explained in Chapter 71.

Redundancy

For better results, the Decoder contains a pair of multi-head Attentions in series, and Λ of those pairs in parallel (i.e., Λ layers of a plate).

• Right Shifted Outputs

"Outputs (Shifted Right)" in Fig.94.4 refers to what is called **forced teaching** in the RNN (recurrent neural net) literature. We explain forced teaching in Fig.94.5.

INFERENCE

A
$$\rightarrow$$
 enc $AB \rightarrow$ enc $ABC \rightarrow$ enc $ABC \rightarrow$ enc $\# \rightarrow \deg \rightarrow a \#a \rightarrow \deg \rightarrow a \#ab \rightarrow \deg \rightarrow abc \#abc \rightarrow \deg \rightarrow abc$.

TRAINING (forced teaching)

$$A \rightarrow enc$$
 $AB \rightarrow enc$ $ABC \rightarrow enc$ $ABC \rightarrow enc$ $\#ABC \rightarrow abc$ $\#ABC \rightarrow abc$ $\#ABC \rightarrow abc$.

Figure 94.5: Training and Inference for vanilla transformer. "enc" and "dec" denote the encoder and decoder, respectively. A hash character represents the SOS (start of sentence) token, and a period represents the EOS (end of sentence) token. Capital letters represent ground truth tokens, and lower case ones represent predictions.

• Masked Attention

$$P(\alpha'|\nu,\alpha) = 0 \text{ if } \alpha' < \alpha \tag{94.46}$$

 α and α' are sentence positions and α' is in the future (downstream) compared to α . So as to not violate causality, this condition enforces the constraint that no attention is paid to sentence positions in the future α .

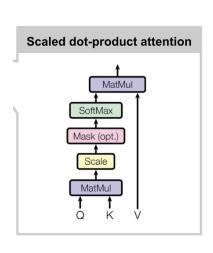
plates

Fig. 94.4 uses plates (a.k.a. stacks). These are explained in Chapter 71.

94.2.1 Single Head Attention

Fig.94.6 gives a bnet representation of the "Single Head Attention" portion of Fig.94.4. The structural equations for that bnet, printed in blue, are as follows.

$$A^{[d],[\ell]} = V^{[d],[\ell]} P^{[\ell],[\ell]}$$
 Note that $\sum_{\alpha \in [\ell]} P^{\alpha,[\ell]} = 1$ (94.47a)



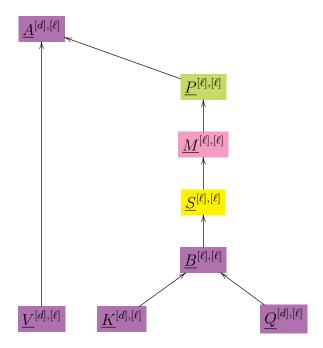


Figure 94.6: Single Head Attention. (Scaled Dot Product)

$$B^{[\ell],[\ell]} = (K^{[d],[\ell]})^T Q^{[d],[\ell]}$$
(94.47b)

$$K^{[d],[\ell]} = \text{prior} \tag{94.47c}$$

$$M^{[\ell],[\ell]} = \text{mask}(S^{[\ell],[\ell]})$$
 (94.47d)

$$P^{[\ell],[\ell]} = \operatorname{softmax}(M^{[\ell],[\ell]}) \quad \left(\text{Note that } \sum_{\alpha \in [\ell]} P^{\alpha,[\ell]} = 1 \right)$$
 (94.47e)

$$Q^{[d],[\ell]} = \text{prior} \tag{94.47f}$$

$$S^{[\ell],[\ell]} = \frac{B^{[\ell],[\ell]}}{\sqrt{d}}$$
 (94.47g)

$$V^{[d],[\ell]} = \text{prior} \tag{94.47h}$$

94.2.2 Multi-Head Attention

Fig.94.7 gives a bnet representation of the "Multi-Head Attention" portion of Fig.94.4. The structural equations for that bnet, printed in blue, are as follows.

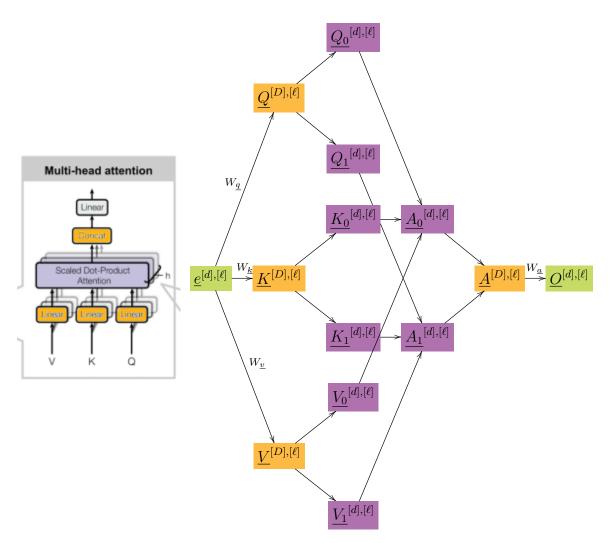


Figure 94.7: Multi-head Attention with 2 heads. Note that the orange nodes all have the same tensor shape.

$$A^{[D],[\ell]} = [A_0^{[d],[\ell]} | A_1^{[d],[\ell]}]$$
 (94.48a)

$$A_0^{[d],[\ell]} = \operatorname{Attention}(V_0^{[d],[\ell]}, K_0^{[d],[\ell]}, Q_0^{[d],[\ell]}) \tag{94.48b}$$

$$A_1^{[d],[\ell]} = \text{Attention}(V_1^{[d],[\ell]}, K_1^{[d],[\ell]}, Q_1^{[d],[\ell]})$$
 (94.48c)

$$K^{[D],[\ell]} = W_k^{[D],[d]} e^{[d],[\ell]}$$
 (94.48d)

$$K_0^{[d],[\ell]} = \operatorname{linear}(K^{[D],[\ell]})$$
 (split, then project a component) (94.48e)

$$K_1^{[d],[\ell]} = \operatorname{linear}(K^{[D],[\ell]})$$
 (split, then project a component) (94.48f)

$$O^{[d],[\ell]} = W_{\underline{a}}^{[d],[D]} A^{[D],[\ell]}$$
 (94.48g)

$$Q^{[D],[\ell]} = W_q^{[D],[d]} e^{[d],[\ell]}$$
 (94.48h)

$$Q_0^{[d],[\ell]} = \text{linear}(Q^{[D],[\ell]}) \text{ (split, then project a component)}$$
(94.48i)

$$Q_1^{[d],[\ell]} = \operatorname{linear}(Q^{[D],[\ell]})$$
 (split, then project a component) (94.48j)

$$V^{[D],[\ell]} = W_v^{[D],[d]} e^{[d],[\ell]}$$
(94.48k)

$$V_0^{[d],[\ell]} = \operatorname{linear}(V^{[D],[\ell]})$$
 (split, then project a component) (94.481)

$$V_1^{[d],[\ell]} = \operatorname{linear}(V^{[D],[\ell]})$$
 (split, then project a component) (94.48m)

$$e^{[d],[\ell]} = \text{prior} \tag{94.48n}$$

94.2.3 Encoder

Fig.94.8 gives a bnet representation of the "Encoder" portion of Fig.94.4. The structural equations for that bnet, printed in blue, are as follows.

$$A^{[\Lambda],[D],[\ell]} = \text{Attention}(Q^{[\Lambda],[D],[\ell]}, K^{[\Lambda],[D],[\ell]}, V^{[\Lambda],[D],[\ell]})$$
(94.49a)

$$F^{[\Lambda],[d],[\ell]} = \text{feed_forward_nn}(N^{[\Lambda],[d],[\ell]})$$
(94.49b)

$$K^{[\Lambda],[D],[\ell]} = W_k^{[D],[d]} e^{[\Lambda],[d],[\ell]}$$
 (94.49c)

$$N^{[\Lambda],[d],[\ell]} = \text{normalize}(e^{[\Lambda],[d],[\ell]} + W_{\underline{a}}^{[d],[D]}A^{[\Lambda],[D],[\ell]}) \tag{94.49d}$$

$$Q^{[\Lambda],[D],[\ell]} = W_q^{[D],[d]} e^{[\Lambda],[d],[\ell]}$$
(94.49e)

$$V^{[\Lambda],[D],[\ell]} = W_v^{[D],[d]} e^{[\Lambda],[d],[\ell]}$$
 (94.49f)

$$e^{[\Lambda],[d],[\ell]} = E^{[\Lambda],[d],[L]} x^{[L],[\ell]}$$
 (94.49g)

$$n^{[\Lambda],[d],[\ell]} = \text{normalize}(N^{[\Lambda],[d],[\ell]} + F^{[\Lambda],[d],[\ell]})$$
 (94.49h)

$$x^{[L],[\ell]} = \text{prior} \tag{94.49i}$$

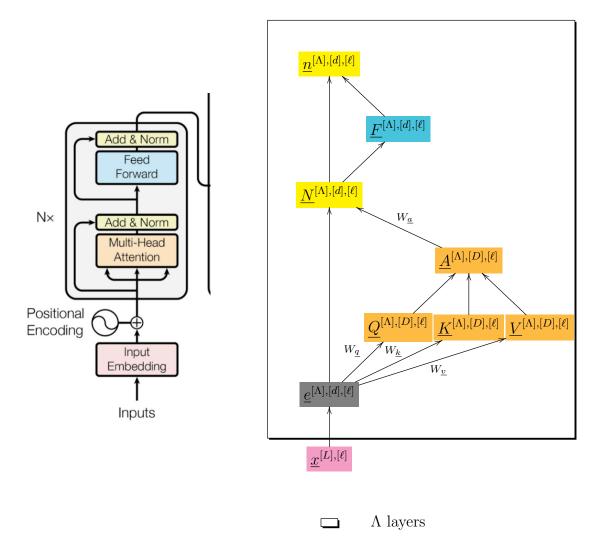


Figure 94.8: Encoder of Vanilla Transformer Net.

94.2.4 Decoder

Fig.94.9 gives a bnet representation of the "Decoder" portion of Fig.94.4. The structural equations for that bnet, printed in blue, are as follows.

$$A^{[\Lambda],[D],[\ell]} = \text{Attention}(Q^{[\Lambda],[D],[\ell]}, K^{[\Lambda],[D],[\ell]}, V^{[\Lambda],[D],[\ell]})$$
(94.50a)

$$F^{[\Lambda],[d],[\ell]} = \text{feed_forward_nn}(j^{[\Lambda],[d],[\ell]})$$
(94.50b)

$$I^{[L],[\ell]} = W^{[L],[\Lambda],[d]}Y^{[\Lambda],[d],[\ell]}$$
 (94.50c)

$$J^{[\Lambda],[d],[\ell]} = \text{normalize}(W_{\underline{a}}^{[d],[D]} A^{[\Lambda],[D],[\ell]} + e^{[\Lambda],[d],[\ell]})$$
(94.50d)

$$K^{[\Lambda],[D],[\ell]} = W_k^{[D],[d]} e^{[\Lambda],[d],[\ell]}$$
 (94.50e)

$$P^{[L],[\ell]} = \text{softmax}(I^{[L],[\ell]}) \ (\sum_{\alpha \in [\ell]} P^{[L],\alpha} = 1)$$
 (94.50f)

$$Q^{[\Lambda],[D],[\ell]} = W_q^{[D],[d]} e^{[\Lambda],[d],[\ell]}$$
 (94.50g)

$$V^{[\Lambda],[D],[\ell]} = W_v^{[D],[d]} e^{[\Lambda],[d],[\ell]}$$
(94.50h)

$$Y^{[\Lambda],[d],[\ell]} = \text{normalize}(F^{[\Lambda],[d],[\ell]} + J^{[\Lambda],[d],[\ell]})$$
 (94.50i)

$$a^{[\Lambda],[D],[\ell]} = \text{Attention}(v^{[\Lambda],[D],[\ell]}, k^{[\Lambda],[D],[\ell]}, q^{[\Lambda],[D],[\ell]})$$
 (94.50j)

$$e^{[\Lambda],[d],[\ell]} = E^{[\Lambda],[d],[L]} x^{[L],[\ell]}$$
 (94.50k)

$$j^{[\Lambda],[d],[\ell]} = \operatorname{normalize}(U_{\underline{a}}^{[d],[D]}a^{[\Lambda],[D],[\ell]} + J^{[\Lambda],[d],[\ell]}) \tag{94.50l}$$

$$k^{[\Lambda],[D],[\ell]} = U_{\underline{k}}^{[D],[d]} n^{[\Lambda],[d],[\ell]}$$
 (94.50m)

$$n^{[\Lambda],[d],[\ell]} = \text{Prior coming from Encoder.}$$
 (94.50n)

$$q^{[\Lambda],[D],[\ell]} = U_q^{[D],[d]} J^{[\Lambda],[d],[\ell]}$$
(94.50o)

$$v^{[\Lambda],[D],[\ell]} = U_{\underline{v}}^{[D],[d]} n^{[\Lambda],[d],[\ell]}$$
 (94.50p)

$$x^{[L],[\ell]} = \text{prior, right shifted output}$$
 (94.50q)

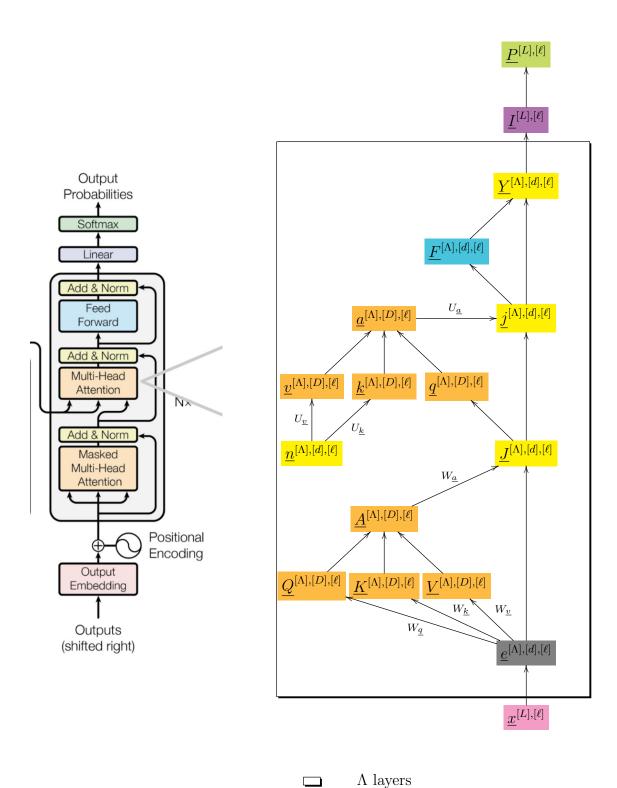


Figure 94.9: Decoder of Vanilla Transformer Net.

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