# BAYESUVIUS QUANTICO

a visual dictionary of Quantum Bayesian Networks



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#### Bayesuvius Quantico,

a visual dictionary of Quantum Bayesian Networks

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This book is constantly being expanded and improved. To download the latest version, go to

https://github.com/rrtucci/bayes-quantico

#### **Bayes Quantico**

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# Appendices

### Appendix A

## Notational Conventions and Preliminaries

#### A.1 Group

A group  $\mathcal{G}$  is a set of elements with a multiplication map  $\mathcal{G} \times \mathcal{G} \to \mathcal{G}$  such that

1. the multiplication is **associative**; i.e.,

$$(ab)c = a(bc) \tag{A.1}$$

for  $a, b, c \in \mathcal{G}$ .

2. there exists an **identity element**  $e \in \mathcal{G}$  such that

$$ea = ae = a \tag{A.2}$$

for all  $a \in \mathcal{G}$ 

3. for any  $g \in \mathcal{G}$ , there exists an **inverse**  $a^{-1} \in \mathcal{G}$  such that

$$aa^{-1} = a^{-1}a = e (A.3)$$

The number of elements in any set S is denoted by |S|.  $|\mathcal{G}|$  is called the **order** of the group.

If multiplication is **commutative** (i.e., ab = ba for all  $a, b \in \mathcal{G}$ , the group is said to be **abelian**.

A subgroup  $\mathcal{H}$  of  $\mathcal{G}$  is a subset of  $\mathcal{G}$  ( $\mathcal{H} \subset \mathcal{G}$ ) which is also a group. It's easy to show that any  $\mathcal{H} \subset \mathcal{G}$  is a group if it contains the identity and is **closed under multiplication** (i.e.,  $ab \in \mathcal{H}$  for all  $a, b \in \mathcal{H}$ )

#### A.2 Group Representation

A group representation of a group  $\mathcal{G}$  is a map  $\phi: \mathcal{G} \to \mathbb{C}^{n \times n1}$  such that

$$\phi(a)\phi(b) = \phi(ab) \tag{A.4}$$

Such a map is called a **homomorphism**. When a group is defined using matrices, those matrices are called the **defining representation**. The map  $\phi$  partitions  $\mathcal{G}$  into disjoints subsets (equivalence classes), such that all elements of  $\mathcal{G}$  in a disjoint set are represented by the same matrix.

For example, the group of **General Linear Transformations** is defined by

$$GL(n, \mathbb{C}) = \{ M \in \mathbb{C}^{n \times n} : \det M \neq 0 \}$$
 (A.5)

#### A.3 Vector Space and Algebra over a field $\mathbb{F}$

A vector (or linear) space  $\mathcal{V}$  is defined as a set endowed with two operations: vector addition  $+: \mathcal{V} \times \mathcal{V} \to \mathcal{V}$ , and scalar multiplication  $\mathbb{F} \times \mathcal{V} \to \mathcal{V}$ , such that

- $\mathcal{V}$  is an abelian group under + with identity 0 and inverse of  $x \in \mathcal{V}$  equal to  $-x \in \mathcal{V}$
- For  $\alpha, \beta \in \mathbb{F}$  and  $x, y \in \mathcal{V}$

$$\alpha(x+y) = \alpha x + \alpha y \tag{A.6}$$

$$(\alpha + \beta)x = \alpha x + \beta y \tag{A.7}$$

$$\alpha(\beta x) = (\alpha \beta)x \tag{A.8}$$

$$1x = x \tag{A.9}$$

$$0x = 0 (A.10)$$

In this book, we will always use either  $\mathbb{C}$  or  $\mathbb{R}$  for  $\mathbb{F}$ . Both of these fields are infinite but some fields are finite.

An algebra  $\mathcal{A}$  is a vector space which, besides being endowed with vector addition and scalar multiplication with which all vector spaces are, it has a **bilinear vector product**. A bilinear vector product is a product that is linear on both sides; i.e.,

$$(\alpha x + \beta y) \cdot z = \alpha x \cdot z + \beta y \cdot z \tag{A.11}$$

and

$$z \cdot (\alpha x + \beta y) = \alpha z \cdot x + \beta z \cdot y \tag{A.12}$$

<sup>&</sup>lt;sup>1</sup>More generally, the  $\mathbb{C}^{n\times n}$  can be replaced by  $\mathbb{R}^{n\times n}$  or by  $\mathbb{F}^{n\times n}$  for any field  $\mathbb{F}$ 

for  $x, y, z \in \mathcal{A}$  and  $\alpha, \beta \in \mathbb{C}$ . The cross product (but not the dot product) for vectors in  $\mathbb{R}^3$ , the multiplication of 2 complex numbers, and the commutator for square matrices, are all good examples of bilinear vector products.

Let  $B = \{\tau_i : i = 1, 2, ..., r\}$  be a basis for the vector space  $\mathcal{A}$ . Then note that B is closed under vector multiplication.

$$\tau_i \cdot \tau_j = \sum_k c_{ij}^{\ k} \tau_k \tag{A.13}$$

where  $c_{ij}^{\ k} \in \mathbb{C}$ . The  $c_{ij}^{\ k}$  are called **structure constants** of B. An **associative algebra** satisfies  $(x \cdot y) \cdot z = x \cdot (y \cdot z)$  for  $x, y, z \in A$ .

- Not associative: cross product for vectors in  $\mathbb{R}^3$ .
- Associative: the commutator for square matrices and product of complex numbers

#### Tensors A.4

$$(x_1,x_2,\ldots,x_n)=x^{:n}\in V^n=\mathbb{C}^{n\times 1}$$
  
Reverse of vector  $rev(x_1,x_2,\ldots,x_n)=(x_n,x_{n-1},\ldots,x_1)$   
 $y^b=\sum_b g^{ba}x^{:n}$   
 $(y^1,y^2,\ldots,y^n)=\bar{y}^{:n}\in \bar{V}^n=\mathbb{C}^{n\times 1}.\ V^n \ \text{and}\ \bar{V}^n \ \text{are}\ \mathbf{dual}\ \mathbf{vector}\ \mathbf{spaces}.$   
 $M_a^{\ b}\in\mathbb{C}^{n\times n},\ a,b\in\mathbb{Z}_{[1,n]}$   
Implicit Summation Convention

$$M_a{}^b x_b = \sum_{b=1}^n M_a{}^b x_b \tag{A.14}$$

$$(M^{\dagger})_b^{\ a} = (M^*)_a^{\ b}$$
 (A.15)

$$= M_b^a$$
 (only if  $M$  is a unitary matrix) (A.16)

For  $x_a \in V^n$ ,

$$(x')_a = M_a{}^b x_b \tag{A.17}$$

For  $x^a \in \bar{V}^n$ ,

$$(x'^*)^a = x^{*b}(M^*)^a_b$$
 (A.18)  
=  $x^{*b}(M^{\dagger})^a_b$  (A.19)

$$= x^{*b} (M^{\dagger})_b^{\ a} \tag{A.19}$$

SO

Suppose  $a_i, b_i, c_i, d_i \in \mathbb{Z}_{[1,n]}$ . From Fig.A.1

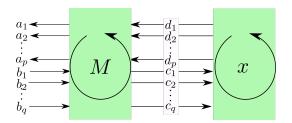


Figure A.1: Index labels for Mx where  $M \in \mathbb{C}^{n^{p+q} \times n^{p+q}}$  and  $x \in V^{n^p} \otimes \bar{V}^{n^q}$ 

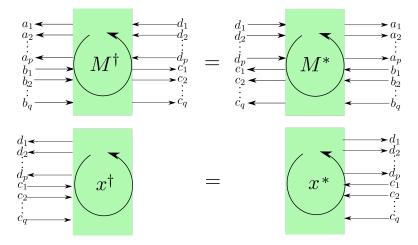


Figure A.2: Index labels for  $M^{\dagger}$  where  $M \in \mathbb{C}^{n^{p+q} \times n^{p+q}}$ 

$$y_{a:p}^{b:q} = M_{a:p}^{b:q} rev(c:q)^{rev(d:p)} x_{d:p}^{c:q}$$
(A.20)

$$X_{\alpha} = X_{a^{:p}}^{b^{:q}}, \quad X^{\alpha} = X_{rev(b^{:q})}^{rev(a^{:p})}$$
 (A.21)

$$x_{\alpha} = M_{\alpha}{}^{\beta} x_{\beta} \tag{A.22}$$

Hermitian conjugation (see Fig.A.2)

$$\begin{cases} (M^{\dagger})_a{}^d = (M_a^d)^* \\ (M^{\dagger})_{\alpha}{}^{\delta} = (M_{ev(\delta)}^{rev(\delta)})^* \end{cases}$$
(A.23)

Hermitian matrix

$$M^{\dagger} = M, \quad \left\{ \begin{array}{l} (M_a^d)^* = M_a^d \\ (M^{rev(\delta)}_{rev(\alpha)})^* = M_{\alpha}^{\ \delta} \end{array} \right. \tag{A.24}$$

Note that for  $x \in V^n$ ,  $y \in \overline{V}^n$ , and  $G \in \mathcal{G} \subset GL(n, \mathbb{C})$ ,

$$(x')_a(y')^b = G^b_{\ c} G_a^{\ d} x_d y^c \tag{A.25}$$

If  $x \in V^{n^p} \otimes \bar{V}^{n^q}$ ,  $\mathbb{G} \in \mathcal{G} \subset GL(n^{p+q}, \mathbb{C})$ ,

$$(x')_{a:p}^{b:q} = \mathbb{G}_{a:p}^{b:q} rev(c:q)^{rev(d:p)} x_{d:p}^{c:q}$$
(A.26)

where we define

$$\mathbb{G}_{a^{:p}} \xrightarrow{rev(c^{:q})} \xrightarrow{rev(d^{:p})} \stackrel{\text{def}}{=} \prod_{i=1}^{q} G^{b_i}_{c_i} \prod_{i=1}^{p} G_{a_i}^{d_i}$$
(A.27)

An issue that arises with tensors is this: When is it permissible to represent a tensor by  $T_{ab}^{cd}$ ? If we define  $T_{ab}^{cd}$  by

$$T_{ab}^{cd} = T_{ab}^{\quad cd} \tag{A.28}$$

then it's always permissible. Then one can define tensors like  $T_a^{\ \ bcd}$  as

$$T_a^{bcd} = g^{bb'} T_{ab'}^{cd} = g^{bb'} T_{ab'}^{cd}$$
 (A.29)

Hence, one drawback of using the notation  $T_{ab}^{cd}$  is that if one is interested in using versions of  $T_{ab}^{cd}$  with some indices raised or lowered, one has to write down explicitly the metric tensors that do the lowering and raising. Instead of writing  $T_a^{bcd}$ , you'll have to write  $g^{bb'}T_{ab'}^{cd}$ . This is not very onerous when explaining a topic in which not much lowering and raising of indices is done. But in topics like General Relativity that do use a lot of raising and lowering of indices, it might not be too elegantly concise.

# A.5 Spectral Decomposition and Eigenvalue Projection Operators

 $M \in \mathbb{C}^{d \times d}$ 

$$M|v\rangle = \lambda|v\rangle \tag{A.30}$$

If M is Hermitian  $(H^{\dagger} = H)$ , its eigenvalues are real.  $(\lambda = \langle \lambda | M \lambda \rangle \in \mathbb{R})$ 

$$cp(\lambda) \stackrel{\text{def}}{=} \det(M - \lambda) = 0$$
 (A.31)

If M is a Hermitian matrix, then there exists a unitary matric ( $CC^{\dagger} = C^{\dagger}C = 1$ ) such that

$$CMC^{\dagger} = \begin{bmatrix} D_{\lambda_1} & 0 & 0 & 0 \\ 0 & D_{\lambda_2} & 0 & 0 \\ 0 & 0 & \ddots & 0 \\ 0 & 0 & 0 & D_{\lambda_r} \end{bmatrix}$$
 (A.32)

where

$$D_{\lambda_i} = \operatorname{diag}\underbrace{(\lambda_i, \lambda_i, \dots, \lambda_i)}_{d_i \text{ times}}$$
(A.33)

$$d = \sum_{i=1}^{r} d_i \tag{A.34}$$

$$CMC^{\dagger} = \begin{bmatrix} \lambda_1 & 0\\ 0 & \lambda_2 \end{bmatrix} \tag{A.35}$$

$$CP_1C^{\dagger} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = \frac{CMC^{\dagger} - \lambda_2}{\lambda_1 - \lambda_2}$$
 (A.36)

$$CP_2C^{\dagger} = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \frac{CMC^{\dagger} - \lambda_1}{\lambda_2 - \lambda_1}$$
 (A.37)

If  $I^{d_i \times d_i}$  is the  $d_i$  dimensional unit matrix,

$$P_i = C^{\dagger} diag(0, \dots, 0, I^{d_i \times d_i}, 0, \dots, 0)C \tag{A.38}$$

$$= \prod_{j \neq i} \frac{M - \lambda_j}{\lambda_i - \lambda_j} \tag{A.39}$$

Note that  $P_i$  are Hermitian  $(P_i^{\dagger}=P_i)$  because M is Hermitian and its eigenvalues are real.)

Note that  $P_i$  and M commute

$$[P_i, M] = P_i M - M P_i = 0 (A.40)$$

orthogonal

$$P_i P_j = \delta(i, j) P_j \tag{A.41}$$

complete

$$\sum_{i} P_i = 1 \tag{A.42}$$

$$M = \sum_{i=1}^{r} P_i M P_i \tag{A.43}$$

$$d_i = \operatorname{tr} P_i \tag{A.44}$$

$$CMP_1C^{\dagger} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$
 (A.45)

$$= \lambda_1 \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \tag{A.46}$$

$$MP_i = \lambda_i P_i \text{ (no } i \text{ sum)}$$
 (A.47)

$$f(M)P_i = f(\lambda_i)P_i \text{ (no } i \text{ sum)}$$
 (A.48)

 $M^{(1)}, M^{(2)}$ 

$$[M^{(1)}, M^{(2)}] = 0 (A.49)$$

Use  $M^{(1)}$  to decompose V into  $\bigoplus_i V_i$ . Use  $M^{(2)}$  to decompose  $V_i$  into  $\bigoplus_j V_{i,j}$ . If  $M^{(1)}$  and  $M^{(2)}$  don't commute, let  $P_i^{(1)}$  be the eigenvalue projection operators of  $M^{(1)}$ . The replace  $M^{(2)}$  by  $P_i^{(1)}M^{(2)}P_i^{(1)}$ 

$$[M^{(1)}, P_i^{(1)}M^{(2)}P_i^{(1)}] = 0 (A.50)$$

### Appendix B

#### Birdtracks: COMING SOON

Cvitanovic Birdtracks book [1]

Elliott-Dawber book [2]

My paper "Quantum Bayesian Nets" [3]

# B.1 Classical Bayesian Networks and their Instantiations

TPM (Transition Probability Matrix)  $P(y|x) \in [0,1]$  where  $x \in val(\underline{x})$  and  $y \in val(y)$ 

$$\sum_{y \in val(\underline{y})} P(y|x) = 1 \tag{B.1}$$

$$C = \underbrace{\frac{b}{\underline{c}}}_{\underline{a}} \tag{B.2}$$

$$C(a,b,c) = P(c|b,a)P(b|a)P(a) = b$$

$$C \leftarrow a$$

$$P(a)$$

$$C \leftarrow a$$

$$P(a)$$

$$C \leftarrow a$$

$$a^{:2} = (a_1, a_2)$$

$$C' = \underbrace{\frac{b}{a_1}}_{c \stackrel{\underline{a}_2}{\longleftarrow} \underline{a}:2}$$
(B.4)

$$C'(a^{:2}, b, c) = P(c|b, a_2)P(a_2|a^{:2})P(b|a_1)P(a_1|a^{:2})P(a^{:2}) =$$

$$c = a_2$$

$$a^{:2}$$
(B.5)

Marginalizer nodes  $\underline{a}_1$  and  $\underline{a}_2$  have the TPMs

$$P(a_i'|\underline{a}^{:2} = (a_1, a_2)) = \delta(a_i', a_i)$$
(B.6)

for i = 1, 2

# B.2 Quantum Bayesian Networks and their Instantiations

TPM (Transition Probability Matrix)  $A(y|x) \in \mathbb{C}$  where  $x \in val(\underline{x})$  and  $y \in val(y)$ 

$$\sum_{y \in val(\underline{y})} |A(y|x)|^2 = 1 \tag{B.7}$$

$$Q = \underbrace{\frac{b}{c}}_{a}$$
 (B.8)

$$Q(a,b,c) = A(c|b,a)A(b|a)A(a) =$$

$$c = a$$
(B.9)

$$a^{:2} = (a_1, a_2)$$

$$Q' = \underbrace{\frac{b}{\underline{a}_1}}_{\underline{a}_2 \underline{\underline{a}_2 \underline{a}_2 \underline{a}$$

$$Q'(a^{:2}, b, c) = A(c|b, a_2)A(a_2|a^{:2})A(b|a_1)A(a_1|a^{:2})A(a^{:2}) = b$$

$$c \stackrel{b}{\longleftarrow} a_1 \qquad A(a^{:2})$$
(B.11)

Marginalizer nodes  $\underline{a}_1$  and  $\underline{a}_2$  have the TAMs

$$A(a_i'|\underline{a}^{:2} = (a_1, a_2)) = \delta(a_i', a_i)$$
(B.12)

for i = 1, 2

#### B.3 Birdtracks

$$\delta(b, a) = \mathbb{1}(a = b) = \delta_a^b = a - b \tag{B.13}$$

$$\underline{a} = a \longleftarrow X_{\underline{a}\underline{b}}^{\underline{c}\underline{d}}$$

$$\langle a, b | X_{\underline{a}\underline{b}}^{\underline{c}\underline{d}} | c, d \rangle = X_{ab}^{\underline{c}d} = b$$

$$\underline{c} = c$$

$$d = d$$
(B.14)

$$a \longleftarrow X_{\underline{ab}} \stackrel{cd}{=} \qquad a, b \longleftarrow X_{\underline{ab}} \stackrel{cd}{=}$$

$$b \qquad \qquad \rightarrow \qquad a, b \qquad \qquad (B.15)$$

$$c \qquad \qquad c \qquad \qquad d$$

 $X_{\underline{a}\underline{b}} \stackrel{cd}{\in} V^2 \otimes V_2$ . Sometimes, we will omit denote this node simply by X. This if okay as long as we are not using, X to also denote a different version of  $X_{\underline{a}\underline{b}} \stackrel{cd}{=}$  with some of the indices raised or lowered or their order has been changed. <sup>1</sup>

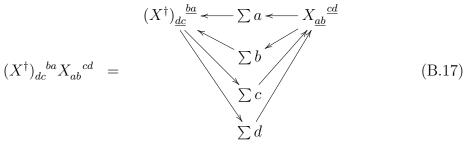
$$(X^{\dagger})_{\underline{dc}} \xrightarrow{\underline{ba}} \underbrace{\underline{a} = a}$$

$$(X^{\dagger})_{dc} \xrightarrow{ba} = \underline{\underline{b} = b}$$

$$\underline{\underline{c} = c}$$

$$\underline{\underline{d} = d}$$
(B.16)

<sup>&</sup>lt;sup>1</sup>For matrices,  $(A^{\dagger})_{i,j} = (A_{j,i})^*$  so taking a Hermitian conjugate involves both taking the complex conjugate of the matrix element and reversing the left-to-right (L2R) order of its indices. This generalizes to  $(X^{\dagger})_{dc}^{\ \ ba} = (X_{ab}^{\ \ cd})^*$ . Besides raising and lowering indices, we reverse their L2R order.



$$= X^{\dagger} - X$$

$$= (B.18)$$

Birdtracks originated as a graphical way to represent the tensors in General Relativity (Gravitation). In General Relativity, one deals with tensors such as  $T_{a\ c}^{\ b}$  which have some indices raised and some lowered. One can use the metric  $g^{a,b}$  to raise all the lowered indices to get  $T^{abc}$ . If we represent this graphically as a node with incoming arrows a, b, c, we need to follow one of the following 2 conventions: either

- 1. label the arrows as  $\underline{a}$ ,  $\underline{b}$ ,  $\underline{c}$ , and define the node as  $T^{\underline{abc}}$ , or
- 2. instead of labelling the arrows explicitly  $\underline{a}, \underline{b}, \underline{c}$ , indicate in the node where is the first arrow  $\underline{a}$ , and draw the arrows  $\underline{a}, \underline{b}, \underline{c}$  so that they enter the node in **counterclockwise** (CC) order. The **left-to-right** (L2R) order of the indices on T corresponds the CC order of the arrows.

If we don't do either 1 or 2, we won't be able to distinguish between the graphical representations of  $T^{1,2,3}$  and  $T^{2,1,3}$ , for example. Cvitanovic's Birdtracks book Ref.[1] follows Convention 2, but most of the time, in this book, we will follow Convention 1 <sup>2</sup> The reason I chose to do so is for the sake of consistency: Convention 2 is closer to the quantum bnet conventions.

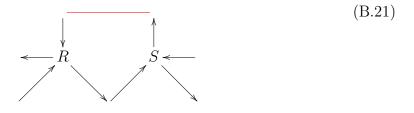
$$a^{:m} \in \mathbb{Z}_+^m$$

$$R_{b_{3}^{m_{3}}, a_{2}^{m_{2}}}^{a_{3}^{m_{3}}, b_{2}^{m_{2}}, b_{1}^{m_{1}}} = \begin{pmatrix} b_{3}^{m_{3}} & R \leftarrow \sum b_{2}^{m_{2}} & S \leftarrow b_{1}^{m_{1}} \\ b_{2}^{m_{3}}, a_{2}^{m_{2}} & S_{b_{2}^{m_{2}}, a_{1}^{m_{1}}}^{a_{2}^{m_{1}}} & A_{1}^{m_{1}} \end{pmatrix}$$

$$= \begin{pmatrix} b_{3}^{m_{3}} & R \leftarrow \sum b_{2}^{m_{2}} & S \leftarrow b_{1}^{m_{1}} \\ a_{3}^{m_{3}} & \sum a_{2}^{m_{2}} & a_{1}^{m_{1}} \end{pmatrix}$$

$$= \begin{pmatrix} b_{3}^{m_{3}} & A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{1}^{m_{1}} \\ a_{3}^{m_{2}} & A \leftarrow b_{1}^{m_{1}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{1}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{1}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{1}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{1}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{1}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{1}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{2}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{2}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{2}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{2}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{2}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{2}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{2}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{2}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{2}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{2}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{2}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{2}^{m_{2}} \\ A \leftarrow \sum b_{2}^{m_{2}} & A \leftarrow b_{2}^{m_$$

<sup>&</sup>lt;sup>2</sup>If we follow Convention 1, we don't need to reverse the L2R order of the indices when taking a Hermitian conjugate. Thus,  $(X^{\dagger})^{\underline{ab}}_{\underline{cd}} = X_{\underline{ab}}^{\underline{cd}} = X^{\underline{dc}}_{\underline{ba}}$ . As long as  $\underline{a}, \underline{b}$  are lower indices and  $\underline{c}, \underline{d}$  are upper indices of X, any L2R order of  $\underline{a}, \underline{b}, \underline{c}, \underline{d}$  is equivalent under Convention 1.



Casimir Operators: COMING SOON

# Clebsch-Gordan Coefficients: COMING SOON

$$\begin{bmatrix} 0 \\ C_{\lambda}^{d_{\lambda} \times d} \\ 0 \end{bmatrix}^{d \times d} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & I^{d_{\lambda} \times d_{\lambda}} & 0 \\ 0 & 0 & 0 \end{bmatrix}^{d \times d} C^{d \times d}$$
 (2.1)

Let  $b^{:nb} = (b_1, b_2, \dots, b_{nb})$  where  $b_i \in Z_{[0,db_i]}$  and  $a \in Z_{[1,d_{\lambda}]}$ . Hence,

$$d_{\lambda} = \prod_{i=1}^{:nb} db_i \tag{2.2}$$

$$(C_{\lambda})_{a}^{b:nb} = a \longleftarrow C_{\lambda} \longleftarrow b_{2}$$

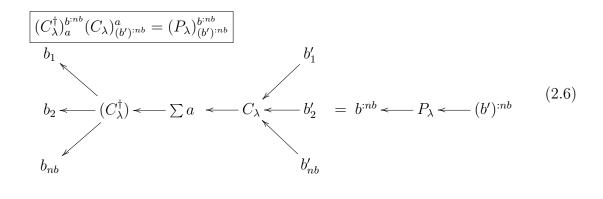
$$b_{nb}$$

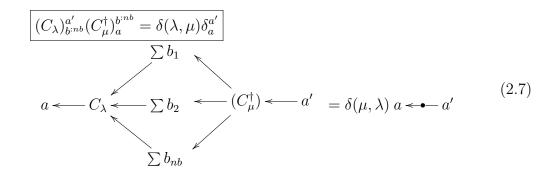
$$(2.3)$$

$$\begin{bmatrix} 0 & (C^{\dagger})_{\lambda}^{d \times d_{\lambda}} & 0 \end{bmatrix}^{d \times d} = (C^{\dagger})^{d \times d} \begin{bmatrix} 0 & 0 & 0 \\ 0 & I^{d_{\lambda} \times d_{\lambda}} & 0 \\ 0 & 0 & 0 \end{bmatrix}^{d \times d}$$
(2.4)

$$(C_{\lambda}^{\dagger})_{b:nb}^{a} = b_{2} \longleftarrow (C_{\lambda}^{\dagger}) \longleftarrow a \tag{2.5}$$

More generally, some of the  $b_i$  indices may lowered and their arrows changed to outgoing instead of ingoing. Each  $b_i$  represents a different rep (or irrep)





Determinants: COMING SOON

General Relativity Nets: COMING SOON

Group Integrals: COMING SOON

#### **Invariants**

Given a bilinear form

$$m(\bar{x}^{:n}, y^{:n}) = x^a M_a{}^b y_b \qquad M$$

$$a \qquad b \qquad (6.1)$$

is invariant if

$$m(\bar{x}^{:n}, y^{:n}) = m(\bar{x}^{:n}G^{\dagger}, Gy^{:n})$$
 (6.2)

matrix invariant

$$M_a{}^b = (G^\dagger)_a{}^{a'}G_{b'}{}^b M_{a'}{}^{b'} \qquad M \qquad b \qquad b$$

$$(6.3)$$

$$M = G^{\dagger}MG \tag{6.4}$$

$$GM = MG, \quad [G, M] = 0$$
 (6.5)

multilinear form

$$h(\bar{w}, \bar{x}, y, z) = h_{ab}^{cd} w^a x^b y_c z_d \qquad \qquad \begin{matrix} h \\ \downarrow \\ a \end{matrix} \qquad \qquad \begin{matrix} b \\ b \end{matrix} \qquad \qquad (6.6)$$

is invariant if

$$h(\bar{w}, \bar{x}, y, z) = h(\bar{w}G^{\dagger}, \bar{x}G^{\dagger}, Gy, Gz)$$
(6.7)

tensor invariant

$$h_{ab}^{cd} = (G^{\dagger})_{a}^{a'} (G^{\dagger})_{b}^{b'} h_{a'b'}^{c'd'} G_{c'}^{c} G_{d'}^{d} \qquad h \qquad \qquad b \qquad c \qquad d \qquad \qquad \begin{pmatrix} h \\ G^{\dagger} G^{\dagger} G G \\ a & b & c \end{pmatrix}$$

$$(6.8)$$

Let  $\mathcal{P} = (p_1, p_2, \dots, p_k)$  be a full set of invariant multilinear forms ("primitives"). By "full", we mean no others exist.

An invariance group  $\mathcal G$  is the set of all linear transformation  $G\in\mathcal G$  such that

$$p_1(x,\bar{y}) = p_1(Gx,\bar{y}G^{\dagger}) \tag{6.9}$$

$$p_2(w, x, \bar{y}, \bar{z}) = p_2(Gw, Gx, \bar{y}G^{\dagger}, \bar{z}G^{\dagger})$$

$$(6.10)$$

etc. 
$$(6.11)$$

Example

$$p(\bar{x}, y) = \delta_a^b x^a y_b = x^b y_b \tag{6.12}$$

$$(x')^{a}(y')_{a} = x^{b}(G^{\dagger}G)_{b}^{c}y_{c} = x^{b}y_{b} \tag{6.13}$$

So G must be unitary

$$G^{\dagger}G = 1 \tag{6.14}$$

The group of n dimensional unitary matrices is called U(n)

#### Levi-Civita Tensor

$$\epsilon^{123...p} = \epsilon_{123...p} = 1 \tag{7.1}$$

$$\epsilon_{rev(a^{:p})} = (-1)^{\binom{p}{2}} \epsilon_{a^{:p}} \tag{7.2}$$

where  $rev(a^{p})$  is the reverse of  $a^{p}$ .  $rev(a_1, a_2, \ldots, a_p) = (a_p, a_{p-1}, \ldots, a_1)$ 

$$(C_{\mathcal{A}_p})_1^{a^{:p}} = e^{i\phi} \frac{\epsilon^{a^{:p}}}{\sqrt{p!}} = \mathcal{A}_p \leftarrow a_1$$

$$= a_2$$

$$\vdots$$

$$(C_{\mathcal{A}_{p}}^{\dagger})_{a:p}^{1} = e^{-i\phi} \frac{\epsilon_{a:p}}{\sqrt{p!}} = a_{1} \leftarrow \mathcal{A}_{p}$$

$$a_{2} \leftarrow \parallel$$

$$\vdots$$

$$\underbrace{e^{i2\phi} \frac{1}{p!} \epsilon^{a^{:n}} \epsilon_{a^{:n}} = \delta_1^1 = 1}_{\qquad \qquad \vdots \qquad \qquad } = 1 \tag{7.6}$$

For Convention 1, we will use  $\phi = 0$ . For Convention 2, we must choose

$$e^{i2\phi} = (-1)^{\binom{p}{2}} = e^{i\pi\frac{p(p-1)}{2}}$$
 (7.7)

SO

$$\phi = \frac{\pi}{4}p(p-1) \tag{7.8}$$

# Lie Algebra Definition: COMING SOON

 $i \in \mathbb{Z}_{[1,N]}, a, b \in \mathbb{Z}_{[1,n]}$ 

$$(C_{Adj}^{i})_{b}^{a} = \frac{1}{\sqrt{K}}(T^{i})_{b}^{a} = i \sim C_{Adj}^{i}$$

$$\downarrow$$

$$b$$
(8.1)

The matrices  $T^i$  are called the generators. It's customary to choose them so that they are Hermitian and  $K=\frac{1}{2}$ 

$$\underbrace{(T^i)_b^a (T^j)_a^b = \operatorname{tr}(T^i T^j) = K\delta(i,j)}_{\sum a} \quad i \leadsto T^j \leadsto j = K \longleftarrow (8.2)$$

$$(P_{Adj})_{b,d}^{a,c} = \sum_{i} \frac{1}{K} (T^{i})_{b}^{a} (T^{i})_{d}^{c} = \frac{1}{K} \left| \begin{matrix} a & d \\ \\ \\ b & c \end{matrix} \right|$$
(8.3)

 $H\in V^{\underline{a}}\otimes V_{\underline{a}}$ 

$$(P_{Adj})_{bd}^{ac} H_c^d = \sum_{i} (T^i)_b^a \underbrace{\left[\frac{1}{K} (T^i)_d^c H_c^d\right]}_{b:\in\mathbb{R}}$$
(8.4)

$$G = 1 + iD \in \mathcal{G}$$
  
$$\epsilon_i \in \mathbb{R}, \ |\epsilon_i| << 1$$

$$D = \sum_{i} \epsilon_{i} T^{i} = V^{\underline{a}} \otimes V_{\underline{a}}$$

$$\mathcal{T}^{i} q = 0 \tag{8.5}$$

Lie Algebra Classification, Dynkin Diagrams: COMING SOON

Orthogonal Groups: COMING SOON

Quantum Shannon Information Theory: COMING SOON

Recoupling Equations: COMING SOON

Reducibility: COMING SOON

Spinors: COMING SOON

## Squashed Entanglement: COMING SOON

Symplectic Groups: COMING SOON

# Symmetrization and Antisymmetrization: COMING SOON

(1,2) transposition, swaps 1 and 2,  $1 \to 2 \to 1$ . (3,2,1) means  $3 \to 2 \to 1 \to 3$ . A reordering of  $(1,2,3,\ldots,p)$  is a permutation on p letters. A permutation can be expressed as a product of transpositions (3,2,1)=(3,2)(2,1) is an even permutation because it can be expressed as a product of an even number of transpositions. An odd permutation can be expressed as a product of an odd number of permutations.

#### 17.1 Symmetrization

$$\mathbb{1}_{a_1,a_2}^{b_2,b_1} = \delta_{a_1}^{b_1} \delta_{a_2}^{b_2} = a_1 \leftarrow b_1$$

$$a_2 \leftarrow b_2$$

$$(17.1)$$

$$(\sigma_{(1,2)})_{a_1,a_2}^{b_2,b_1} = \delta_{a_1}^{b_2} \delta_{a_2}^{b_1} = \begin{pmatrix} a_1 \leftarrow \bullet \leftarrow b_1 \\ \downarrow \\ a_2 \leftarrow \bullet \leftarrow b_2 \end{pmatrix}$$
 (17.2)

$$1 = \underbrace{\hspace{1cm}} (17.3)$$

$$\sigma_{(1,2)} = \begin{array}{c} & & \longleftarrow & \longleftarrow \\ & & \downarrow \\ & & \downarrow \\ & & \downarrow \\ & & \longleftarrow \end{array} \qquad \begin{array}{c} & \longleftarrow \\ & & \downarrow \\ & & \downarrow \\ & & \longleftarrow \end{array} \qquad (17.4)$$

$$\sigma_{(1,3,2)} = \underbrace{\hspace{1cm}}_{\bullet} \underbrace{\hspace{1cm}}_{\bullet}$$

#### Claim 1

**proof:** We only prove it for p = 3.

QED

$$= \frac{n+p-1}{p} \begin{pmatrix} \leftarrow \mathcal{S}_{p-1} \leftarrow \\ \leftarrow \\ \vdots \\ \vdots \\ \vdots \end{pmatrix}$$

$$(17.17)$$

$$\operatorname{tr}_{\underline{a}_{1}} \mathcal{S}_{p} = \frac{n+p-1}{p} \mathcal{S}_{p-1} \tag{17.18}$$

$$\operatorname{tr}_{\underline{a}_1,\underline{a}_2,\dots,\underline{a}_k} \mathcal{S}_p = \frac{(n+p-1)(n+p-2)\dots(n=p-k)}{p(p-1)\dots(p-k+1)} \mathcal{S}_{p-k}$$
 (17.19)

$$d_{S_p} = \operatorname{tr}_{\underline{a}^p} S_p = \frac{(n+p-1)!}{p!(n-1)!} = \binom{n+p-1}{p}$$
 (17.20)

For p=2,

$$d_{\mathcal{S}_2} = \frac{(n+1)n}{2} \tag{17.21}$$

#### 17.2 Antisymmetrization

$$\begin{array}{c|cccc}
\leftarrow \mathcal{A}_p \leftarrow & & \leftarrow \bullet \leftarrow \\
\leftarrow & & \downarrow & \\
\leftarrow & & \leftarrow \bullet \leftarrow \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
\leftarrow & & \leftarrow \bullet \leftarrow \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
\leftarrow & & \leftarrow \bullet \leftarrow \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
\leftarrow & & \leftarrow \bullet \leftarrow \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
\leftarrow & & \leftarrow \bullet \leftarrow \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
\leftarrow & & \leftarrow \bullet \leftarrow \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
\bullet & & \leftarrow \bullet \leftarrow \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
\bullet & & \leftarrow \bullet \leftarrow \\
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\vdots & \vdots & \vdots & \vdots & \vdots \\
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\bullet & \bullet \leftarrow$$

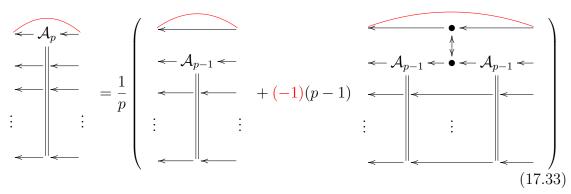
$$\begin{aligned}
S_{p}A_{[1,q]} &= A_{p}S_{[1,q]} = 0 \\
&\leftarrow S_{p} \leftarrow &\leftarrow A_{[1,q]} \leftarrow &\leftarrow &\leftarrow S_{[1,q]} \leftarrow \\
&\leftarrow &\parallel \leftarrow &\leftarrow &\parallel \leftarrow &\leftarrow &\parallel \leftarrow \\
&\leftarrow &\parallel \leftarrow &\leftarrow &\parallel \leftarrow &\leftarrow &\parallel \leftarrow \\
&\leftarrow &\parallel \leftarrow &\leftarrow &\parallel \leftarrow &\leftarrow &\parallel \leftarrow &\leftarrow \\
&\leftarrow &\parallel \leftarrow &\leftarrow &\leftarrow &\parallel \leftarrow &\leftarrow &\parallel \leftarrow &\leftarrow \\
&\vdots &\vdots &\vdots &\vdots &\vdots &\vdots &\vdots
\end{aligned}$$

$$(17.27)$$

#### Claim 2

**proof:** We only prove it for p = 3.

#### QED



$$= \frac{n + (-1)(p-1)}{p} \begin{pmatrix} \leftarrow \mathcal{A}_{p-1} \leftarrow \\ \leftarrow \\ \vdots \\ \vdots \\ \cdots \\ \vdots \end{pmatrix}$$

$$(17.34)$$

$$\operatorname{tr}_{\underline{a}_1} \mathcal{A}_p = \frac{n-p+1}{p} \mathcal{A}_{p-1} \tag{17.35}$$

$$\operatorname{tr}_{\underline{a}_{1},\underline{a}_{2},\dots,\underline{a}_{k}} \mathcal{A}_{p} = \frac{(n-p+1)(n-p+2)\dots(n-p+k)}{p(p-1)\dots(p-k+1)} \mathcal{A}_{p-k}$$
 (17.36)

$$d_{\mathcal{A}_p} = \operatorname{tr}_{\underline{a}^p} \mathcal{A}_p = \frac{\prod_{i=n-p+1}^n i}{p!}$$
(17.37)

$$= \frac{\prod_{i=n}^{n-p+1} i}{p!} \tag{17.38}$$

$$= \begin{cases} \frac{n!}{p!(n-p)!} = \binom{n}{p} & \text{if } p \le n\\ 0 & \text{otherwise} \end{cases}$$
 (17.39)

For  $p = 2 \le n$ ,

$$d_{\mathcal{A}_2} = \binom{n}{2} \tag{17.40}$$

$$\mathcal{A}_p = 0 \text{ if } n$$

For example, for n=2 and p=3

$$\mathcal{A}_{3}|a,a,b\rangle = \frac{1}{6} \begin{pmatrix} |a,a,b\rangle + |a,b,a\rangle + |b,a,a\rangle \\ -|a,b,a\rangle - |a,a,b\rangle - |b,a,a\rangle \end{pmatrix}$$

$$= 0$$

$$(17.43)$$

## Unitary Groups: COMING SOON

#### SU(n) 18.1

$$m(p,q) = \delta_b^a \sum_{a=1}^n (p_a)^* q_a$$
 (18.1)

$$d \leftarrow c$$

$$\mathbb{1}_{d,b}^{a,c} = \delta_b^a \delta_d^c =$$

$$a \rightarrow b$$
(18.2)

$$\uparrow\downarrow_{d,b}^{a,c} = \delta_d^a \delta_b^c = \begin{pmatrix} d & c \\ \uparrow & \downarrow \\ a & b \end{pmatrix}$$
 (18.3)

$$P_i = \sum_{j \neq i} \frac{M - \lambda_j}{\lambda_i - \lambda_j} \tag{18.5}$$

 $\lambda_1 = n$ 

$$P_{1} = \frac{\uparrow \downarrow -n}{0-n} = 1 - \frac{1}{n} \uparrow \downarrow$$

$$c \qquad d \qquad e \qquad b \qquad a \qquad b \qquad b \qquad d$$

$$c \leftarrow -\frac{1}{n} \uparrow \qquad d$$

$$\lambda_{2} = 0 \qquad (18.6)$$

$$P_{2} = \frac{\uparrow \downarrow -0}{n-0} = \frac{1}{n} \uparrow \downarrow$$

$$c$$

$$d$$

$$b$$

$$d$$

$$d$$

$$d$$

$$d$$

$$d$$

$$d$$

$$(18.7)$$

$$tr P_1 = \frac{1}{n}$$

$$(18.8)$$

$$= n^2 - 1 (18.9)$$

$$trP_2 = \frac{1}{n}$$
 (18.10)

$$= 1 \tag{18.11}$$

$$(T_i)_a^b = i \sim T_i$$

$$\downarrow$$

$$a$$
(18.12)

$$T_i^{\dagger} = T_i \tag{18.13}$$

Claim 3

$$C_F \delta_a^b = (T_i T_i)_a^b = \frac{n^2 - 1}{n} \delta_a^b$$
 (18.14)

proof:

$$(T_{i}T_{i})_{a}^{b} = \sum_{i} i \sim T_{i} \qquad T_{i} \sim i$$

$$= \sum_{i} i \sim T_{i} \qquad T_{i} \sim i$$

$$(18.15)$$

$$= \sum_{i} i \sim T_{i} T_{i} \sim i$$
 (18.16)

**QED** 

Wigner Coefficients: COMING SOON

Wigner-Ekart Theorem: COMING SOON

Young Tableau: COMING SOON

## **Bibliography**

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