



Image Registration With Fourier-Based Image Correlation: A Comprehensive Review of Developments and Applications

IMA204

Julián Alvarez

Rafael Benatti

Vitor França





Summary

- **Introduction;**
- **Background;**
- **Sub-pixel methods;**
- **Application Examples:**
 - **Fingerprint matching;**
 - **Rotation and translation of moving cells;**
- **Conclusion.**



Introduction

- **The goal:**
 - **Detailed review of the literature of Image Registration with Fourier-Based Image Correlation**
- **How they organized it:**
 - **Overview of the fundamentals;**
 - **Developments;**
 - **Some applications.**



Introduction

- **What is Image Registration?**
 - Image registration is the process of overlaying images of the same scene.
- **What's Fourier-based image correlation?**
 - Is an area-based method;
 - Utilize information in the frequency domain;
 - Theoretical accuracy and high computational efficiency;

Background

- Cross correlation in the frequency domain (CCF)
- Phase correlation

$$g(x, y) = \bar{f}(x - \Delta x, y - \Delta y)$$

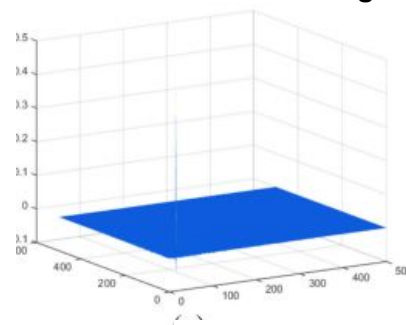
$$CC = F^{-1}(F(u, v)^* G(u, v))$$

$$PC = F^{-1}(Q(u, v)) = F^{-1} \left\{ \frac{F(u, v)^* G(u, v)}{|F(u, v)^* G(u, v)|} \right\}$$
$$= F^{-1} \{ \exp(-i(u\Delta x + v\Delta y)) \}$$

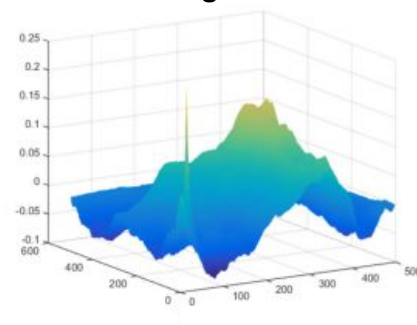
$$PC = F^{-1}(Q(u, v)) = F^{-1} \{ \exp(-i(u\Delta x + v\Delta y)) \}$$
$$= \delta(x - \Delta x, y - \Delta y).$$



Translated image with different magnitudes



Phase correlation



Cross correlation

Background

- **Fourier-Mellin transform**

Log-polar coordinates

$$\theta = \arctan \frac{y}{x}$$

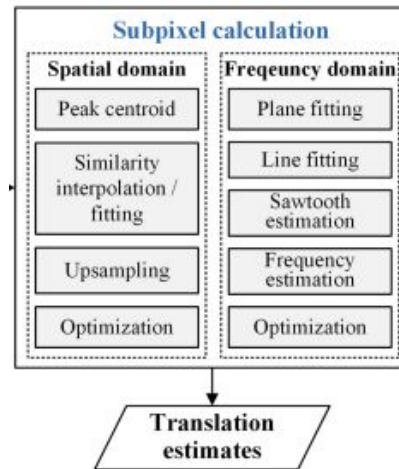
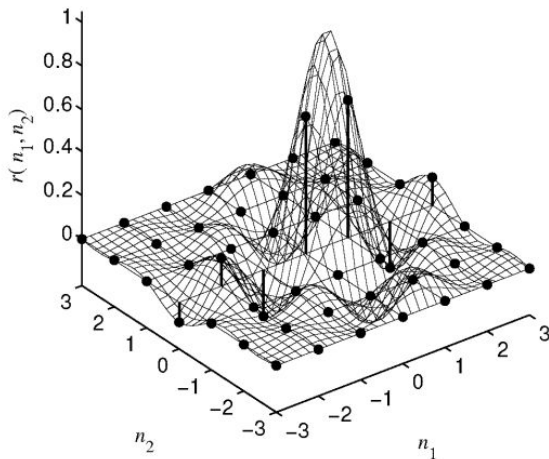
$$\lambda = \log \sqrt{x^2 + y^2}$$

$$g(x, y) = f(s(x \cos \theta_0 + y \sin \theta_0) \\ - \Delta x, s(-x \sin \theta_0 + y \cos \theta_0) - \Delta y).$$

$$M_G(u, v) = s^{-2} M_F[s^{-1}(u \cos \theta_0 + v \sin \theta_0), \\ s^{-1}(-u \sin \theta_0 + v \cos \theta_0)]$$

$$M_{\text{Glp}}(\lambda, \theta) = s^{-2} M_{\text{Flp}}(\lambda - \log s, \theta - \theta_0)$$

Subpixel methods



Subpixel methods

- **Spatial domain**
 - **Peak centroid**
 - **Interpolation**
 - **Quadratic, gaussian, sinc derivation, dirichlet, modified sinc, modified mexican hat wavelet**
 - **Upsampling**
 - **Optimization**
 - **Minimizing the gradient of the inverse transform of cross-power spectrum**

Subpixel methods

- **Frequency domain**

- **Plane fitting**

$$\varphi(u, v) = \angle Q(u, v) = -(u\Delta x + v\Delta y)$$

- **Line fitting**

$$\begin{aligned} Q(u, v) &= \exp(-i(u\Delta x + v\Delta y)) \\ &= \exp(-iu\Delta x)\exp(-iv\Delta y) = q_x(u)q_y(v) \end{aligned}$$

Subpixel methods

- **Frequency domain**

- **Sawtooth estimation**

$$\hat{\varphi}_{mn} = \begin{cases} 2\pi \left(x_o \frac{n}{N} + y_o \frac{m}{M} \right) & \text{if } m' \frac{2\pi}{M} = m \frac{2\pi}{M} + j \frac{2\pi}{x_o} \\ \hat{\varphi}_{m'n}, & \\ \hat{\varphi}_{mn'}, & \text{if } n' \frac{2\pi}{N} = n \frac{2\pi}{N} + k \frac{2\pi}{y_o} \end{cases}$$

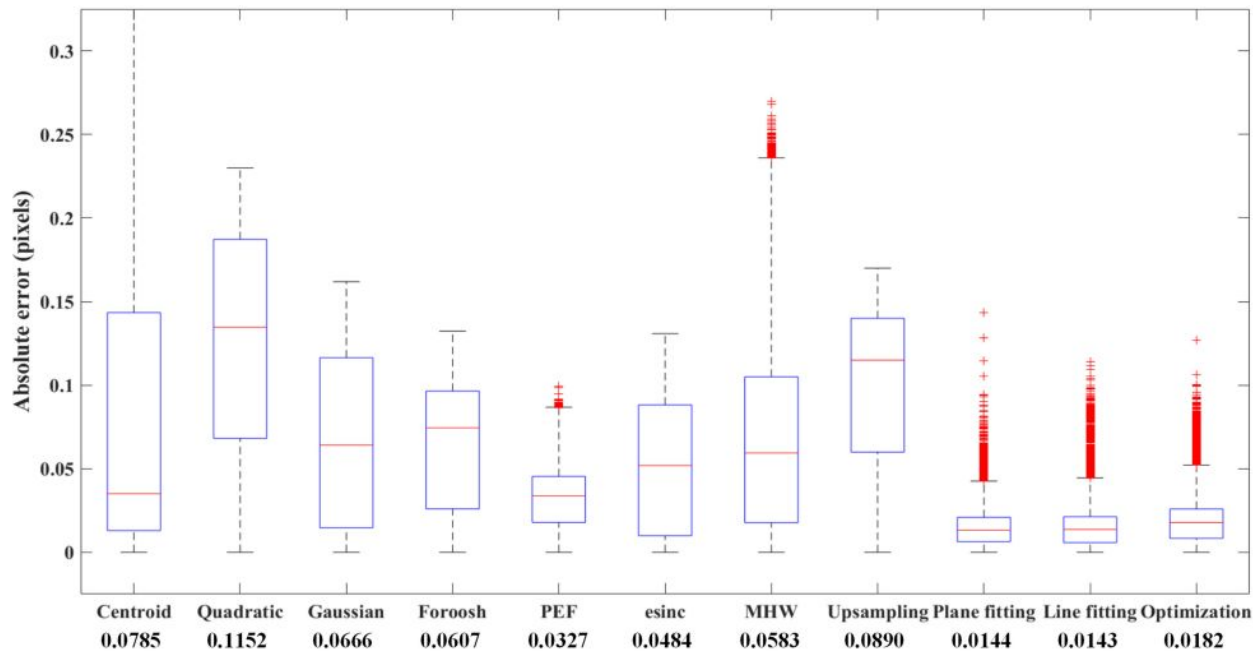
- **Frequency estimation**

- **Optimization**

$$\phi(\Delta x, \Delta y) = \sum_{u=-\pi}^{\pi} \sum_{v=-\pi}^{\pi} W(u, v) \cdot |Q(u, v) - \exp(-i(u\Delta x + v\Delta y))|^2$$

Subpixel methods

- Some results



Application Examples

- K. Ito, H. Nakajima, K. Kobayashi, and T. Higuchi, “A fingerprint matching algorithm using phase-only correlation,” IEICE Trans. Fundam. Electron. Commun. Comput. Sci., vol. 87, no. 3, pp. 682–691, 2004
- Wilson, C.A.; Theriot, J.A. (2006). A correlation-based approach to calculate rotation and translation of moving cells. IEEE Transactions on Image Processing, 15(7), 1939–1951. doi:10.1109/tip.2006.873434

Fingerprint matching.

- POC (PC):

$$\hat{r}_{fg}(n_1, n_2) = \frac{1}{N_1 N_2} \sum_{k_1, k_2} \hat{R}_{FG}(k_1, k_2) W_{N_1}^{-k_1 n_1} W_{N_2}^{-k_2 n_2}.$$

- Band-Limited POC (PC):

$$\hat{r}_{fg}^{K_1 K_2}(n_1, n_2) = \frac{1}{L_1 L_2} \sum_{k_1=-K_1}^{K_1} \sum_{k_2=-K_2}^{K_2} \hat{R}_{FG}(k_1, k_2) \times W_{L_1}^{-k_1 n_1} W_{L_2}^{-k_2 n_2},$$

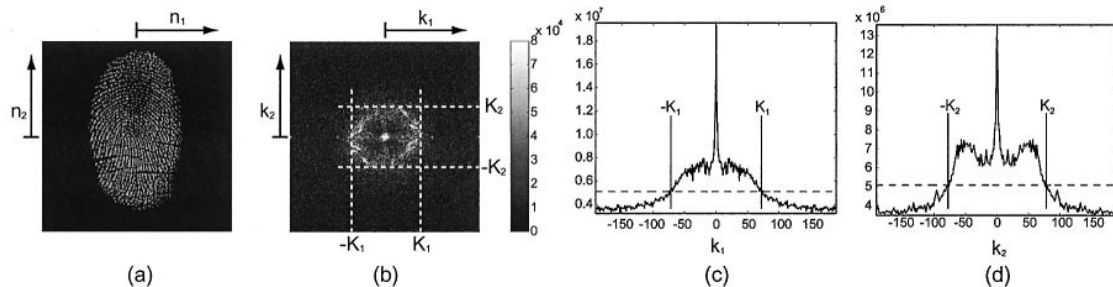


Fig.3 Fingerprint image in space domain (a) and in frequency domain (b) (amplitude spectrum). (c) and (d) are k_2 -axis and k_1 -axis projection of the amplitude spectrum. The dashed lines denote the mean value for each projection.

- $L_1 = 2K_1 + 1$
- $L_2 = 2K_2 + 1$

Fingerprint matching.

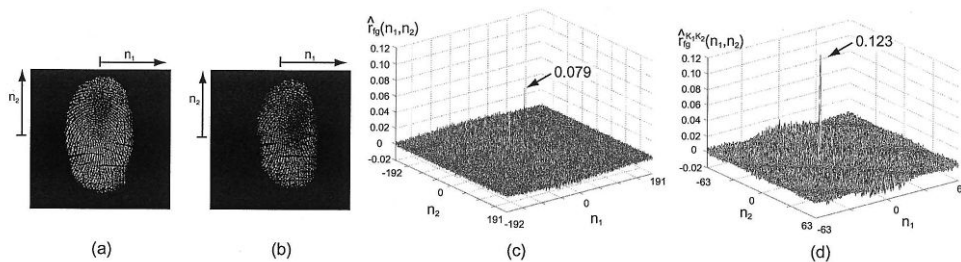


Fig.4 Example of genuine matching using the original POC function and the band-limited POC function: (a) registered fingerprint image $f(n_1, n_2)$, (b) input fingerprint image $g(n_1, n_2)$ captured from the same fingertip, (c) original POC function $\hat{f}_{fg}(n_1, n_2)$ and (d) band-limited POC function $\hat{f}_{fg}^{K_1, K_2}(n_1, n_2)$ where $K_1 = 63$ and $K_2 = 63$.

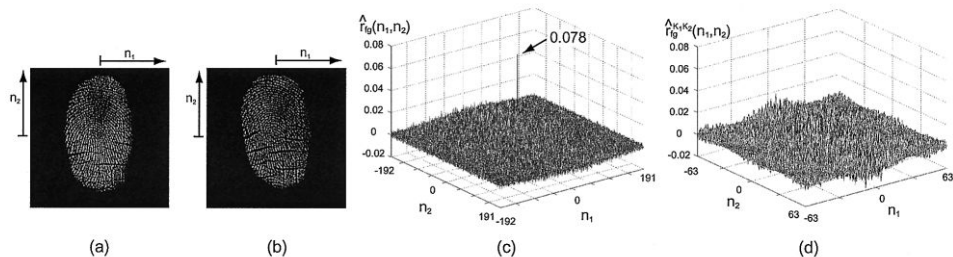


Fig.5 Example of impostor matching using the original POC function and the band-limited POC function: (a) registered fingerprint image $f(n_1, n_2)$, (b) input fingerprint image $g(n_1, n_2)$ captured from the different fingertip, (c) original POC function $\hat{f}_{fg}(n_1, n_2)$ and (d) band-limited POC function $\hat{f}_{fg}^{K_1, K_2}(n_1, n_2)$ where $K_1 = 63$ and $K_2 = 63$.

Fingerprint matching.

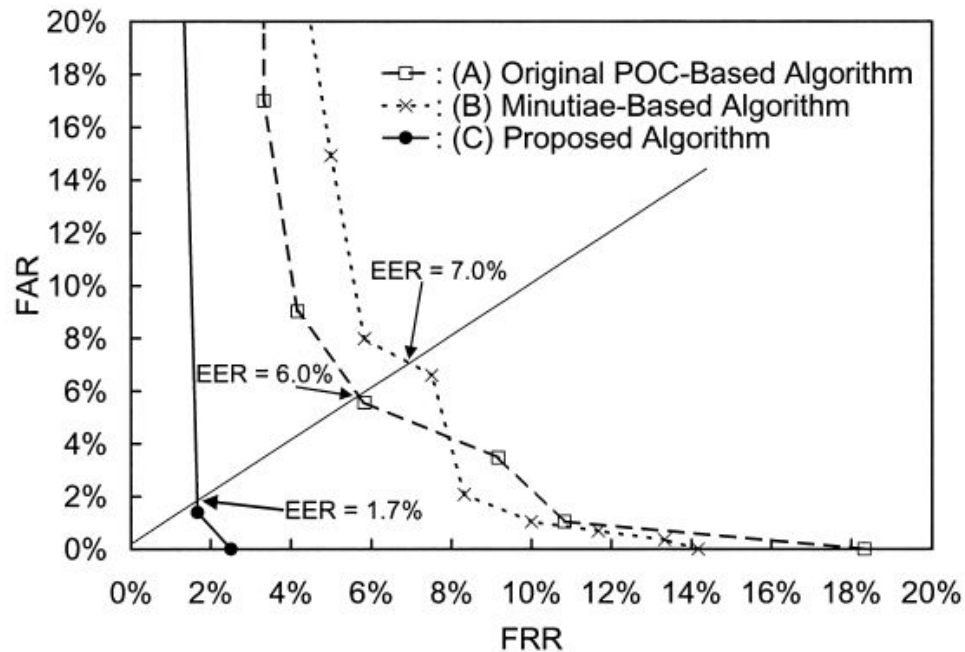
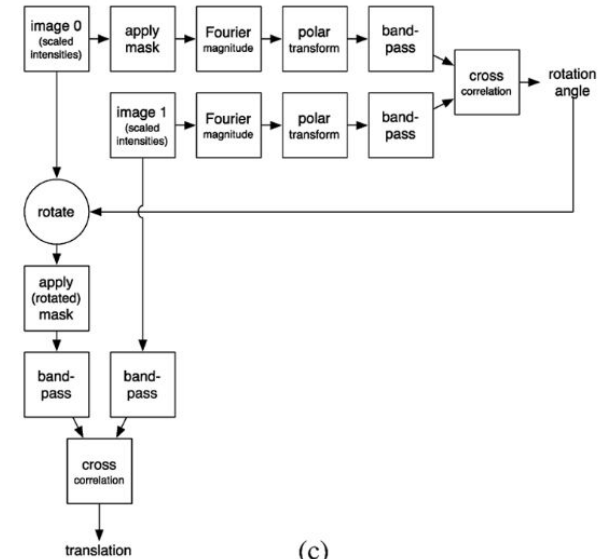
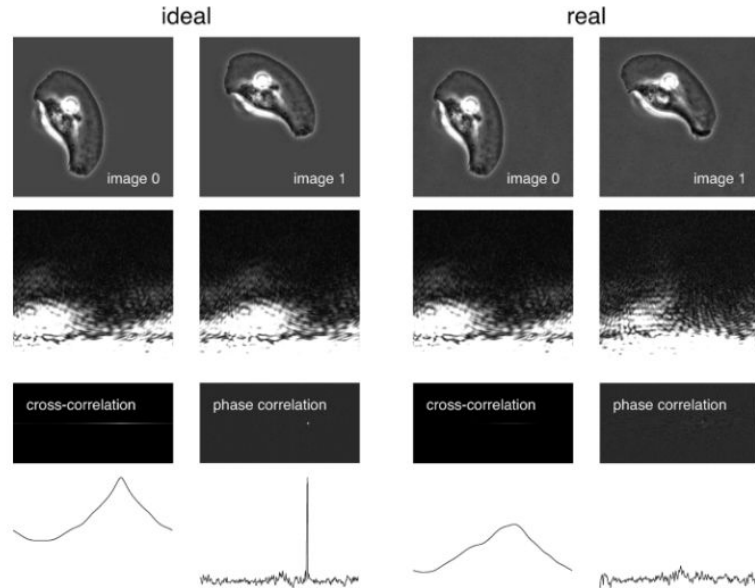
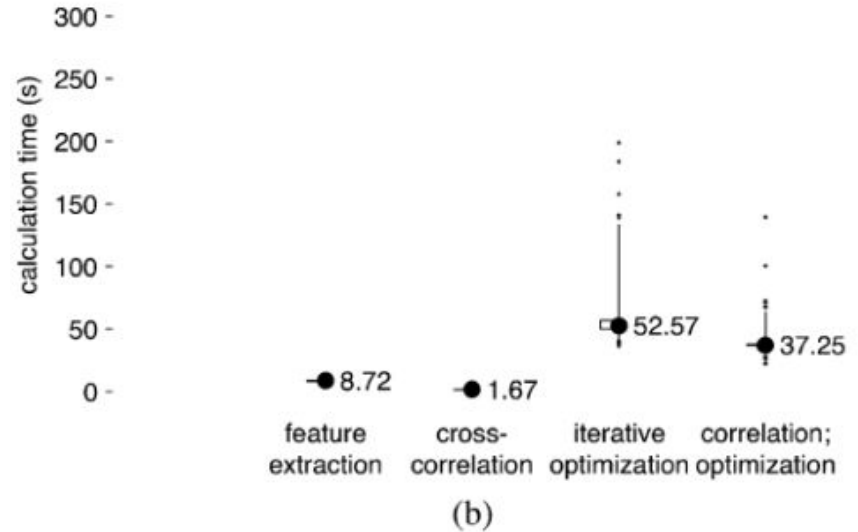
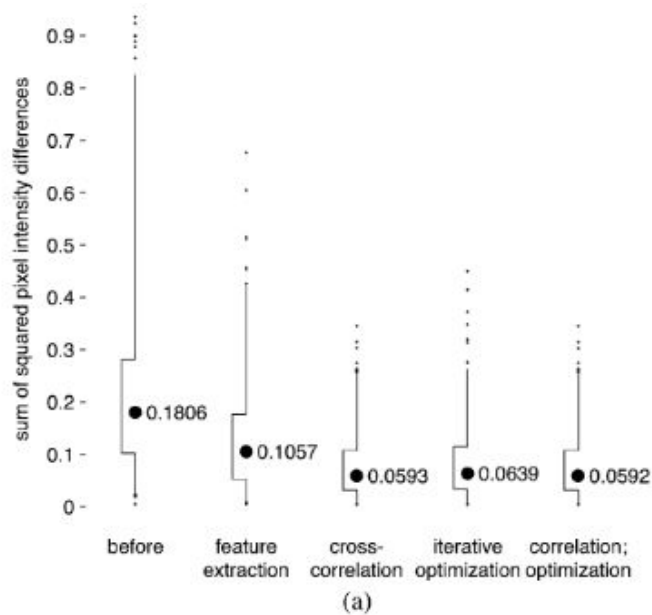


Fig. 11 ROC curve and EER.

Rotation and translation of moving cells



Rotation and translation of moving cells



Potential improvements and applications.

CHALLENGES AND FUTURE TRENDS:

- High-accuracy and high-efficiency subpixel methods.
- Problems with small windows size in frequency domain.
- Quantitative comparison in algorithms, implementations, and progressing frameworks

Improvements:

- Moving cells:
Peak centroid method  PEF (Peak evaluation formula)

Applications fields:

- Autonomous vehicles: Image align to better understanding of the environment .
- Medicine: video stabilizer in long-distance surgeries or laparoscopy.