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EE 5322 Intelligent Control Systems Assignment no 2

RLS and DFT Analysis

1. RLS System Identification

1. The input u_k and output y_k of a discrete time system are given in the data file. The system is of second order with a delay of $d=2$.

- Write a RLS program to identify the system transfer function.
- Plot the output y_k and the output of your identified system given the input u_k . They should be the same.

Solution :

```
clear all;close all;clc
FileName = ('Hw2.xls')
samples = xlsread(FileName);
x(:,4)=ones(4,1);
P=1000*eye(4);out=zeros(4,601);
sigv=1;
for i=4:601
    out(:,i)=diag(P);
    y(i)=samples((i),4)';
    T1=[-samples((i-1),4) -samples((i-2),4)];
    T2=[samples((i-2),3) samples(i-3,3)];
    H(:,i)=[T1';T2'];
    A = pinv(H(:,i))*P*H(:,i)+sigv
    B = H(:,i)*P;
    P=P-P*H(:,i)*A*B;
    x(:,i+1)=x(:,i)+P*H(:,i)*(y(i)-H(:,i)*x(:,i))/sigv;

end
t=1:602;
plot(t,x(1,:),r',t,x(2,:),g',t,x(3,:),b',t,x(4,:),y');
grid on;
title('Convergence of coefficients')
figure(4)
plot(t(1:601),out(1,:),r',t(1:601),out(2,:),g',t(1:601),out(3,:),b',t(1:601),out(4,:),y');
grid on;
title('Convergence of error covariance');
clear y;
% The model is
coef=x(:,end)
y=zeros(601,1);
for i=40:250
    if i < 4
        y(i)=[-y(i) -y(i-1) samples((i-1),1) 0]*coef;
    else
```

```

y(i)=[-y(i) -y(i-2) samples((i-2),1) samples((i-3),1)]*coef;
end
end
figure(5)
plot(t(1:601),y,'r');
hold on;
plot(t(1:601),samples(:,2),'--');
hold on;
title('Simulated output and Actual output');

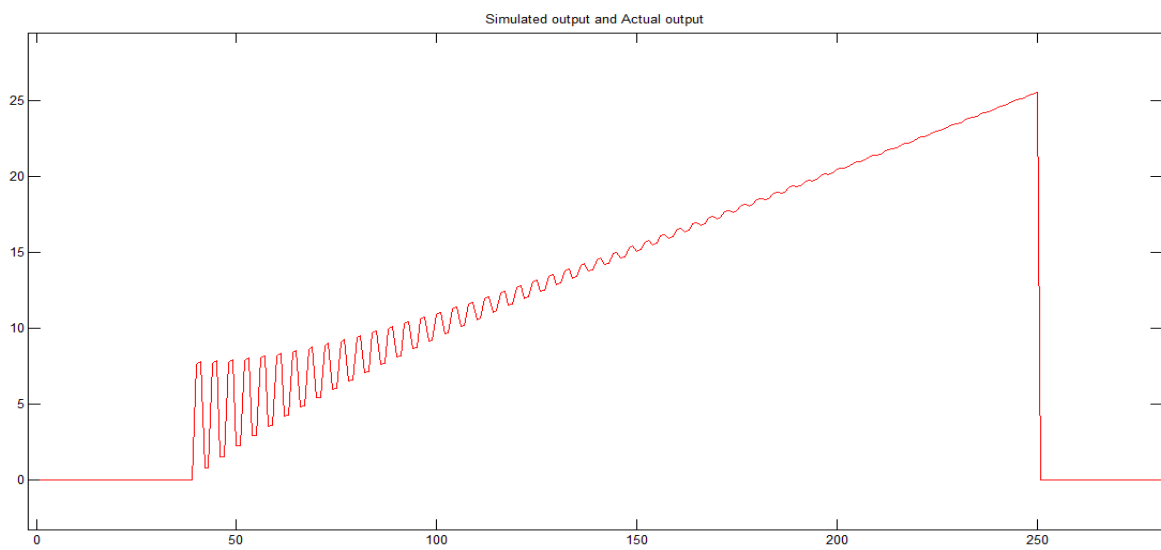
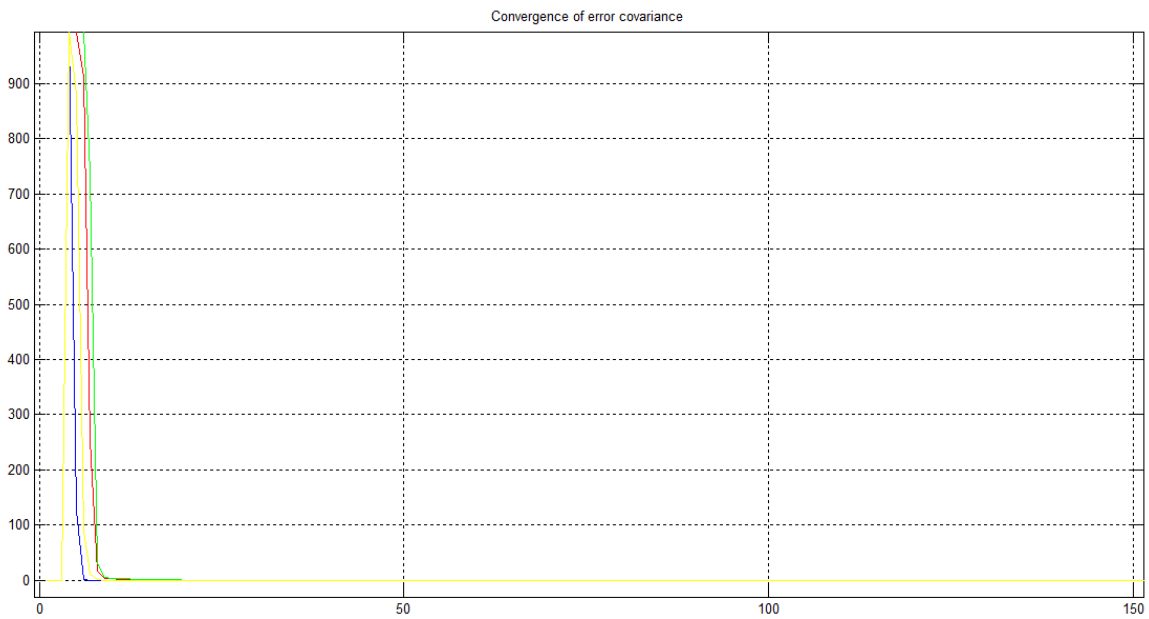
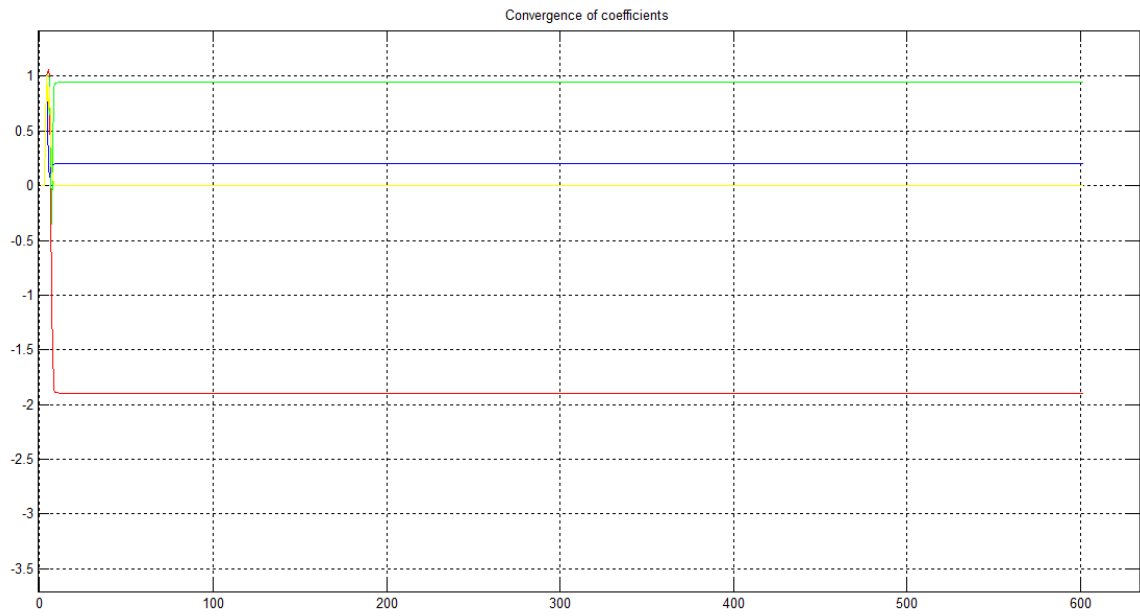
```

Solution:

0.0000	0.0000	0.0000	0.0000	0.0000	-1.8999	0.9499	0.0000	0.2000	0.0000
0.0000	0.0000	0.0000	0.0000	0.0000	-1.8999	0.9499	0.0000	0.2000	0.0000
0.0000	0.0000	0.0001	0.1998	0.0000	-1.9000	0.9500	0.0000	0.2000	0.0000
-0.0723	0.0000	-0.0004	0.2011	0.3617	-1.9000	0.9500	0.0000	0.2000	0.0000
-0.7016	-0.3371	0.0061	0.1813	0.3038	-1.9000	0.9500	0.0000	0.2000	-0.0000
-1.0146	-0.5643	0.0010	0.1968	0.1879	-1.9000	0.9500	0.0000	0.2000	-0.0000
-1.8927	0.9388	0.0004	0.1997	0.0019	-1.9000	0.9500	0.0000	0.2000	-0.0000
-1.8989	0.9485	0.0001	0.2000	0.0002	-1.9000	0.9500	0.0000	0.2000	0.0000
-1.8991	0.9486	0.0001	0.2001	0.0002	-1.9000	0.9500	0.0000	0.2000	0.0000
-1.8992	0.9486	0.0001	0.2001	0.0002	-1.9000	0.9500	0.0000	0.2000	-0.0000
-1.8992	0.9487	0.0001	0.2001	0.0002	-1.9000	0.9500	0.0000	0.2000	0.0000
-1.8995	0.9493	0.0001	0.2000	0.0001	-1.9000	0.9500	0.0000	0.2000	0.0000
-1.8997	0.9495	0.0000	0.2000	0.0001	-1.9000	0.9500	0.0000	0.2000	-0.0000
-1.8997	0.9497	0.0000	0.2000	0.0001	-1.9000	0.9500	0.0000	0.2000	-0.0000
-1.8998	0.9497	0.0000	0.2000	0.0000	-1.9000	0.9500	0.0000	0.2000	-0.0000
-1.8998	0.9497	0.0000	0.2000	0.0000	-1.9000	0.9500	0.0000	0.2000	-0.0000
-1.8998	0.9498	0.0000	0.2000	0.0000	-1.9000	0.9500	0.0000	0.2000	-0.0000
-1.8998	0.9498	0.0000	0.2000	0.0000..					
..	-1.8999	0.9499	0.0000	0.2000	0.0000				

The Co-efficients are -1.9000 0.9500 0.0000 0.2000 -0.0000

Plots :



In speech, the vowels are characterized by three main frequencies known as formants. The first two formants for each vowel in English are as follows: vowel Formant 1 (Hz)

Formant 2 (Hz)

A	70	110
E	50	180
I	40	200
O	60	80
U	30	80

Code:

```

clc;

clear all;

close all;

FileName = ['homework 2 data 2.xls'];

x = xlsread(FileName);

x2=x(:,3);

win=1000;k=1;

for i=1:8

    k;

    temp=k+win-1;

    y(:,i)=fft(x2(k:k+win-1),1024);

    py=y.*conj(y)/1024.*conj(y)/1024;

    k=k+win;

figure(1)

subplot(2,4,i);

waterfall(abs(py'))

title('Iterations of DFT using Bin ');

hold on;

axis([0,100,0,10,0,400])

w=1000*(0:1023)/1024;

py=y.*conj(y)/1024.*conj(y)/1024.*conj(y)/1024.*conj(y)/1024.*conj(y)/1024;

figure(2)

plot3(ones(1,1024).*i,w',abs(py))

hold on

grid on;

title('DFT of Bins');

xlabel('second');

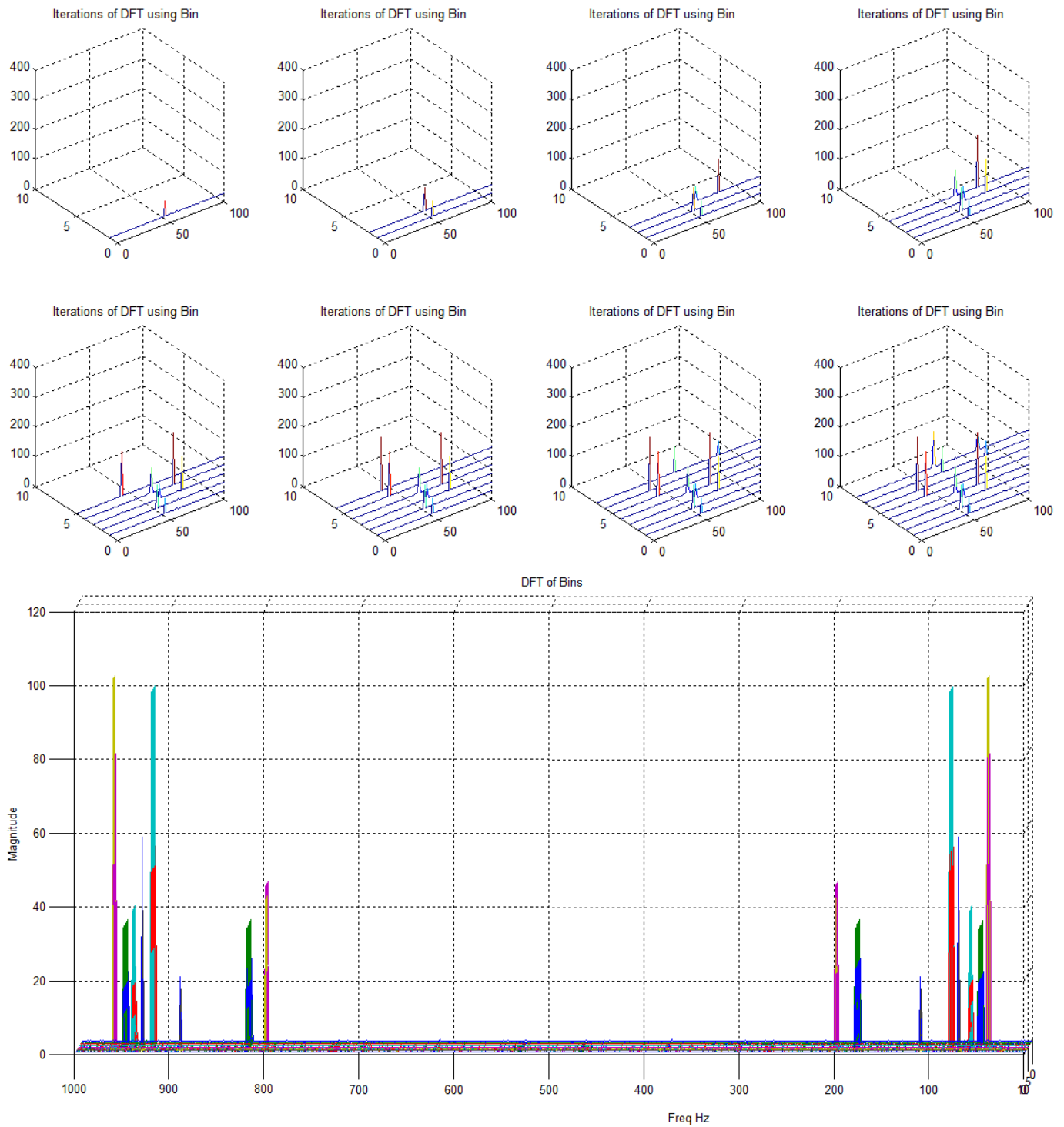
ylabel('Freq Hz');

zlabel('Magnitude');

```

end

Plot:



Machinery Monitoring

3. An induction motor drive has a base rotation frequency of $f = 50$ Hz, a frequency of $3f$ due to a three-bladed fan, and a component at $4f$ due to a 4:1 gearbox. When a certain pinion gear wears badly enough, a prominent frequency component of 277 Hz appears. Soon after that, the amplitude of the frequency component at $4f$ significantly increases due to the failure of a gear tooth. In the 6 sec data file, the sampling period is 1 msec. Find out when the two anomaly failure events occur. Plot the DFT vs. time as a 3-D plot. Use moving average window for the DFT of length $\frac{1}{2}$ sec. Use N = a power of two

Solution:

```
clc;
clear all;
close all;
FileName = ['homework 2 data 3.xls'];
samples = xlsread(FileName);
x = samples(:,3);
win=500;
time = 0.001;
for k = 500:6001
    t=k-win+1;
    y(:,k)=fft(x(t:k),512);
    py(:,k)=y(:,k).*conj(y(:,k));
end
w=1000*(0:511)/512;
figure(1)
waterfall(w,x,abs(py));
title('Iterations of DFT using moving window ');
hold on;
grid on;
title('DFT ');
xlabel('freq');
ylabel('time');
zlabel('DFT');
```

DFT

