#### Introduction to



### What is tensorflow (tf)?

" TensorFlow™ is an open source software library for numerical computation using data flow graphs. Nodes in the graph represent mathematical operations, while the graph edges represent the multidimensional data arrays (tensors) communicated between them. The flexible architecture allows you to deploy computation to one or more CPUs or GPUs in a desktop, server, or mobile device with a single API. TensorFlow was originally developed by researchers and engineers working on the Google Brain Team within Google's Machine Intelligence research organization for the purposes of conducting machine learning and deep neural networks research, but the system is general enough to be applicable in a wide variety of other domains as well".

#### When should I care about tf?

- I need to speed up my math computations and I want to use GPU.
  - Use cuda if you are brave enough
- I am doing some optimization problem
  - Implement gradient computation and optimizers otherwise.
- I want to do big scale machine learning
  - For small scale use scikit-learn, R...

#### Why to choose tf?

- Multi-GPU support
- Cluster/cloud systems supported
- High performance, comparable to other popular frameworks (Torch, Theano)
- "Easy" to deploy for production
- Powerful visualization tool (tensorboard)
- Python and C++ API
- Supported by Google
- Tons of learning resources (Udacity course, playground, tutorials...)
- Easy installation (conda install, pip install...)

#### How does tf work?

- 1) You define desired operations (computation graph)
- 2) You create a session and use it to inject data and to grab results
- 3) Tf will compile your desired operations as soon as you execute your program
- 4) Tf will manage device communication and operations in a very efficient manner

### tf program structure

```
1 import os
 2 import tensorflow as tf
 3 import numpy as np
 5#Placeholder(interface variables) definition
 6 x= tf.placeholder(dtype=tf.float32, shape=[None, 3], name="x")
 7 y= tf.placeholder(dtype=tf.float32, shape=[None, 3], name="y")
 9 #Graph computations definition
10 def simpleModel(x0,v0):
11 results1= tf.add( x0, y0) #same as x0 + y0
12 results2= tf.matmul(results1, tf.transpose(x0))
13 return results1. results2
14 myResult1, myResult2= simpleModel(x,y)
15
16 #Create session and initialize variables
17 session = tf.Session()
18 session.run(tf.global variables initializer())
19
20 #Do actual computations
21 x_input= np.array([[1,2,3],[1,2,3],[1,2,3]])
22 y_input= np.array([[1,1,1],[2,2,2],[3,3,3]])
23 feed dict= {x: x input, y:y_input}
24 res1, res2= session.run([myResult1, myResult2], feed dict=feed dict)
25 print(res1)
26 print(res2)
27 session.close()
28
```

## Computation graph definition

```
1 import os
 2 import tensorflow as tf
 3 import numby as no
 5 #Placeholder(interface variables) definition
                                                                                                                 myResult2
 6 x= tf.placeholder(dtype=tf.float32, shape=[None, 3], name="x")
 7 y= tf.placeholder(dtype=tf.float32, shape=[None, 3], name="y")
 9#Graph computations definition
10 def simpleModel(x0,y0):
11 results1= tf.add( x0, y0) #same as x0 + y0
12 results2= tf.matmul(results1, tf.transpose(x0))
13 return results1. results2
14 myResult1, myResult2= simpleModel(x,y)
                                                                                                                               MatMul
                                                                                                                                                            init
16 #Create session and initialize variaples
17 session = tf.Session()
18 session.run(tf.global variables initializer())
20 #Do actual computations
21x_input= np.array([[1,2,3],[1,2,3],[1,2,3]])
22y_input= np.array([[1,1,1],[2,2,2],[3,3,3]])
                                                                                                                                      transpose
23 feed dict= {x: x input, y:y input}
24 res1, res2= session.run([myResult1, myResult2], feed dict=feed dict)
25 print(res1)
26 print(res2)
27 session.close()
                                                                       myResult1
```

Data will be injected here

## Computation graph definition (2)

- Placeholders (for data injection)
   tf.placeholder(...)
- Constants

```
tf.constant(...), tf.zeros(...), tf.ones(...) ...
```

- Variables (model parameters, several initialization schemes)
   tf.get\_variable(...)
- Operations (can be applied to Variables, Constants and Placeholders)

```
tf.add(...), tf.matmul(...), tf.exp(...), tf.diag_part(...) ...
```

## Session creation and variable initialization

By default, tf.Session() will make use of all available resources.

- If several GPUs, all be allocated (although not necessarily used)
  - Select GPU using environmental variable CUDA VISIBLE DEVICE
- If no GPU all CPUs will be used (use tf.ConfigProto as argument to tf.Session() to set desired number)

Variables must be either initialized or loaded from checkpoints before being used

```
1 import os
 2 import tensorflow as tf
 3 import numpy as np
 5#Placeholder(interface variables) definition
 6 x= tf.placeholder(dtype=tf.float32, shape=[None, 3], name="x")
 7 y= tf.placeholder(dtype=tf.float32, shape=[None, 3], name="y")
 9#Graph computations definition
10 def simpleModel(x0.v0):
11 results1= tf.add( x0, y0) #same as x0 + y0
12 results2= tf.matmul(results1, tf.transpose(x0))
13 return results1, results2
14 myResult1, myResult2= simpleModel(x,y)
16 #Create session and initialize variables
17 session = tf.Session()
18 session.run(tf.qlobal variables initializer())
20 #Do actual computations
21x input= np.array([[1,2,3],[1,2,3],[1,2,3]])
22 y_input= np.array([[1,1,1],[2,2,2],[3,3,3]])
23 feed_dict= {x: x_input, y:y_input}
24 res1, res2= session.run([myResult1, myResult2], feed dict=feed dict)
25 print(res1)
26 print(res2)
27 session.close()
```

#### Actual computation

```
1 import os
 2 import tensorflow as tf
 3 import numpy as np
 5 #Placeholder(interface variables) definition
 6 x= tf.placeholder(dtype=tf.float32, shape=[None, 3], name="x")
 7 y= tf.placeholder(dtype=tf.float32, shape=[None, 3], name="y")
 9#Graph computations definition
10 def simpleModel(x0,y0):
11 results1= tf.add(x0, y0) #same as x0 + y0
12 results2= tf.matmul(results1, tf.transpose(x0))
13 return results1, results2
14 mvResult1. mvResult2= simpleModel(x.v)
16 #Create session and initialize variables
17 session = tf.Session()
18 session.run(tf.global variables initializer())
20 #Do actual computations
21x_input= np.array([[1,2,3],[1,2,3],[1,2,3]])
22 y_input= np.array([[1,1,1],[2,2,2],[3,3,3]])
23 feed dict= {x: x input v:v input}
                                                   feed dict=feed dict)
24 res1, res2= session.rur([myResult1, myResult2]
25 print(res1)
26 print(res2)
2/ session.close()
```

Graph variables we want to obtain.

- Tf will do just needed computations to reach these variables.
- MyResults1 and myResults2 state will be save as numpy narrays res1 and res2

WARNING: session.run is not recommended for real Deep Learning situations. See tf.data for recommended data pipelines.

#### Dictionary

- Keys: graph placeholders
- Values: np.array's to inject into placeholders

### One more interesting example

#### FFT usage example (numpy vs tf).

./1\_tf\_intro/examples/e2\_fftExample.py

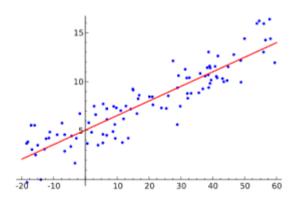
Matplotlib needed for results visualization: conda install matplotlib

```
5 #TF version
7 def tf ffshift2(x):
B n= x.get shape().as list()[1] #Number of shifts
9 p2= (n+1)//2
fftOutShiftedDim1= tf.concat([x[:,p2:n,:], x[:,0:p2,:]], 1)
1 fftOutShiftedFinal= tf.concat([fftOutShiftedDim1[:.:, p2:n], fftOutShiftedDim1[:.:, 0:p2]], 2)
 return fftOutShiftedFinal
4 def tf iffshift2(x):
5 n= x.get shape().as list()[1]
6 p2= n - (n+1)//2
7 ifftOutShiftedDim1= tf.concat([x[:,p2:n,:], x[:,0:p2,:]], 1)
B ifftOutShiftedFinal= tf.concat([ifftOutShiftedDim1[:,:, p2:n], ifftOutShiftedDim1[:,:, 0:p2]], 2)
9 return ifftOutShiftedFinal
1 def tfLPFilter(imgs):
2 #Placeholder(interface variables) definition
3 x= tf.placeholder(dtype=tf.complex64, shape=[None, imgs.shape[1], imgs.shape[2]], name="x")
4 x Real, x Imag = tf.real(x), tf.imag(x)
5 xMod= tf.sqrt(tf.square(x Real)+tf.square(x Imag))
6 #Graph computations definition
7 i x= tf iffshift2(x)
8 fftOut= tf.fft2d(i x)
9 fftOutOReal, fftOutOImag = tf.real(fftOut), tf.imag(fftOut)
fft0Mod= tf.sqrt(tf.square(fft0ut0Real)+tf.square(fft0ut0Imaq))
```

$$y_{pred} = b + x_1 w_1 + x_2 w_2 + ... + x_n w_n = (1, x_1, x_2, ..., x_n)(b, w_1, w_2, ..., w_n)^T$$

Or alternatively

$$y = XW + b$$



Data preparation:  $f(x,y,z) = x+y+z + uniform_noise$ 

```
1 import tensorflow as tf
 2 import numpy as np
 3 from keras.datasets import boston housing
 4 from sklearn import cross validation
 5 from sklearn.utils import shuffle
 6 from sklearn.metrics import r2 score
 8 N EPOCHS= 2
 9 BATCH SIZE= 32
10 LEARNING RATE= 1e-10 #PLAY with learning rate. try 1e-1, 1e-2 ...
11
12 #load data. We will be using f(x,y,z) = x+y+z + unif noise as datapoints
13 def generateData1(size=1024):
    x= np.random.rand(size, 3)*10
    y= np.expand dims( np.sum(x, axis=1) + np.random.rand(size)*.1, axis=-1)
   x train, x test, y train, y test = cross validation.train test split(x, y, test size=0.1, random state=121)
    return (x train, y train), (x test, y test)
17
19 (x train, y train), (x test, y test) = generateData1()
21 x_train, x_validation, y_train, y_validation = cross_validation.train_test_split(x_train, y_train, test_size=0.1, random_state=121)
22 print(x train.shape, v train.shape)
```

$$y_{pred} = b + x_1 w_1 + x_2 w_2 + x_3 w_3 = (1, x_1, x_2, x_3)(b, w_1, w_2, w_3)^T$$

```
24 #Model definition
25
                                                                                                   Nx3 tensor
26 inputPh= tf.placeholder(dtype=tf.float32, shape=[None, x train.shape[1]], name="inputData")
27 labelsPh= tf.placeholder(dtype=tf.float32, shape=[None, 1], name="labelsData")
                                                                                       Nx1 tensor
29 w= tf.qet variable(name="weights", shape=[x train.shape[1],1], dtype=tf.float32,
                      initializer=tf.truncated_normal_initializer(mean=0.0, stddev=0.1, dtype=tf.float32, seed=None),
                      regularizer=None, trainable=True)
31
                                                                                         3x1 tensor
32
33 b= tf.get variable(name="bias", shape=[1], dtype=tf.float32,
                      initializer=tf.constant initializer(value=0.01, dtype=tf.float32),
34
                      regularizer=None, trainable=True)
35
                                                                                          scalar tensor
36
37 v pred= tf.matmul(inputPh.w) + b
                                         Nx1 tensor
39
40 error = tf.reduce_mean(( tf.square(labelsPh -y_pred) ) ) 41 #error = tf.losses.mean_squared_error(labelsPh, y_pred) #Equivalent but prefered MSE = \frac{1}{n} \sum_{i=1}^{n} (Y_i - \hat{Y}_i)^2.
43 optimizer= tf.train.GradientDescentOptimizer(learning rate= LEARNING RATE)
44 #optimizer= tf.train.AdamOptimizer(learning rate= LEARNING RATE) #Smarter optimizer
                                                                          Optimization iteration counter
46 global_step = tf.Variable(0, name='global_step', trainable=False)
47 train step = optimizer.minimize(error, global step=global step)
49
                                                                        Optimization step operation. Ask
                                                                        tensorflow to compute it in order to
                                                                        update parameters
```

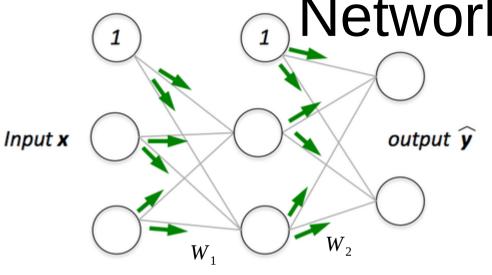
./1\_tf\_intro/examples/e3\_linRegr.py

```
60
61 session = tf.Session()
62 session.run(tf.global variables initializer())
64 nStep=0
65 for nEpoch in range( N EPOCHS ):
66 # x train, y train = shuffle(x train, y train, random state=121)
67 labels train= []
    preds train= []
    for i in range(0, x train.shape[0], BATCH SIZE):
      feed dict= {inputPh: x train[i:i + BATCH_SIZE, ...], labelsPh: y_train[i:i + BATCH_SIZE]}
70
      __, y_pred_train, errorExample= session.run([train_step, y pred, error], feed dict=feed dict)
71
72
      nStep+=1
      labels train.append( y train[i:i + BATCH SIZE])
73
      preds train.append( y pred train)
74
75
    #EVALUATE VALIDATION DATA
76
77 labels val= []
                                                                                 Perform training step
    preds val= []
79 for i in range(0, x validation.shape[0], BATCH SIZE):
      feed dict= {inputPh: x validation[i:i + BATCH SIZE, ...], labelsPh: y validation[i:i + BATCH S
80
      v pred val, errorVal= session.run([v pred, error], feed dict=feed dict)
81
82
      labels val.append( y validation[i:i + BATCH SIZE])
      preds val.append(v pred val)
83
84
                                                                          Validation performance is used
    preds train= np.concatenate(preds train)
                                                                          to decide which model is best
    labels train= np.concatenate(labels train)
    train r2= coefficient of determination(labels train, preds train)
87
                                                                          and to make changes
88
    preds val= np.concatenate(preds val)
89
    labels val= np.concatenate(labels val)
    val r2= coefficient of determination(labels val, preds val)
    print("Epoch %d. train_r2 %f val_r2 %f"%(nEpoch, train_r2, val_r2))
 ./1 tf intro/examples/e3 linRegr.py
```

```
94
 95 #REPORT PERFORMANCE ON TEST SET
96 labels test= []
97 preds test= []
98 for i in range(0, x test.shape[0], BATCH SIZE):
99 feed dict= {inputPh: x test[i:i + BATCH SIZE, ...], labelsPh: y test[i:i + BATCH SIZE]}
     y pred test, errorTest= session.run([y pred, error], feed dict=feed dict)
     labels test.append( y test[i:i + BATCH SIZE])
101
     preds test.append(y pred test)
103 preds test= np.concatenate(preds test)
104 labels test= np.concatenate(labels test)
105 test r2= coefficient of determination(labels test, preds test)
106
107 print("END. test r2 %f"%(test r2))
108 session.close()
109
```

Testing set should be used just once, when reporting performance. No decision must be taken using testing set performance

# Your turn: implement Neural Network for regression

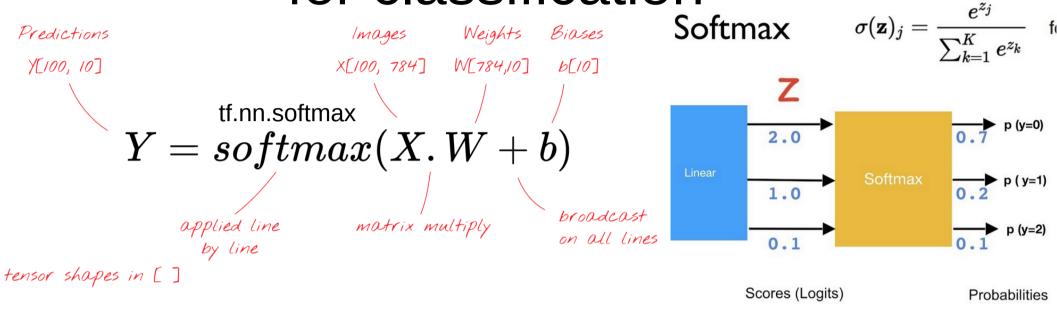


 $y_{pred} = W_2 g(XW_1) \rightarrow g \ can be \ sigmoid$ , tanh, relu...

- If doubts API: https://www.tensorflow.org/api\_docs/python/
- Try different number of layers, different number of neurons, different learning rate... See if your model is capable to overfit.
- If synthetic data is too easy, try to use realistic data
  - Add these 2 lines:
    - from keras.datasets import boston\_housing
    - (x\_train, y\_train), (x\_test, y\_test) = boston\_housing.load\_data()
  - Data scaling can be an issue

My solution: ./1\_tf\_intro/exercises\_sol/sol1\_nNetReg.py

## Your turn: implement logistic model for classification



- New data set: cifar10 → 50K images of 10 categories: dog, cat, car, boat, ...
  - from keras.datasets import cifar10
  - (x\_train, y\_train), (x\_test, y\_test) = cifar10.load\_data()
- Labels must be one-hot-encoded: do it automatically with:
  - sklearn.preprocessing.OneHotEncoder
- Data scaling can be an issue

```
21 #One-hot-encode labels
22 oh_encoder= OneHotEncoder(n_values=10, sparse=False)
23 y_train= oh_encoder.fit_transform(y_train)
24 y_test= oh_encoder.transform(y_test)
```

My solution: ./1\_tf\_intro/exercises\_sol/sol2\_logRegr.py

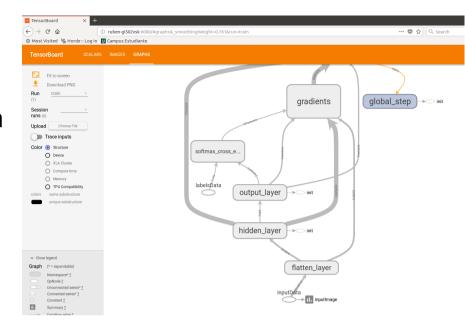
## Your turn: implement Neural Network for classification

 $y_{pred} = softmax(W_2g(XW_1)) \rightarrow g \ can be \ sigmoid$ , tanh, relu...

- You can use logistic regression script as starting point
- Try other architectures
  - Explore convolutional layers in API if you have finished
- Help yourself using tensorboard

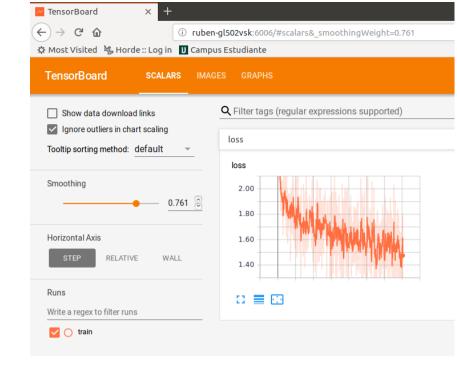
#### tensorboard

- Choose what you want to monitor in your graph
  - Scalar tensor:
    - tf.summary.scalar(name, scalar\_tensor)
  - Images:
    - tf.summary.image(name, image\_tensor)
  - Histograms:
    - tf.summary.histogram(name, any\_tensor)
- Right after variables initialization
  - merged\_summary= tf.summary.merge\_all()
  - train\_writer = tf.summary.FileWriter(dir/for/logs/train, session.graph)
  - validation\_writer = tf.summary.FileWriter(dir/for/logs/test, session.graph)
- When training, ask for merged\_summary and save it:
  - \_\_\_, m\_summary= session.run([train\_step, merged\_summary], feed\_dict=feed\_dict)
  - train\_writer.add\_summary(m\_summary, nStep)
- Do the same when computing validation
- Launch tensorboard from command line: tensorboard --logdir dir/for/logs/test
- Visualize it using your web browser and the url reported by tensorboard

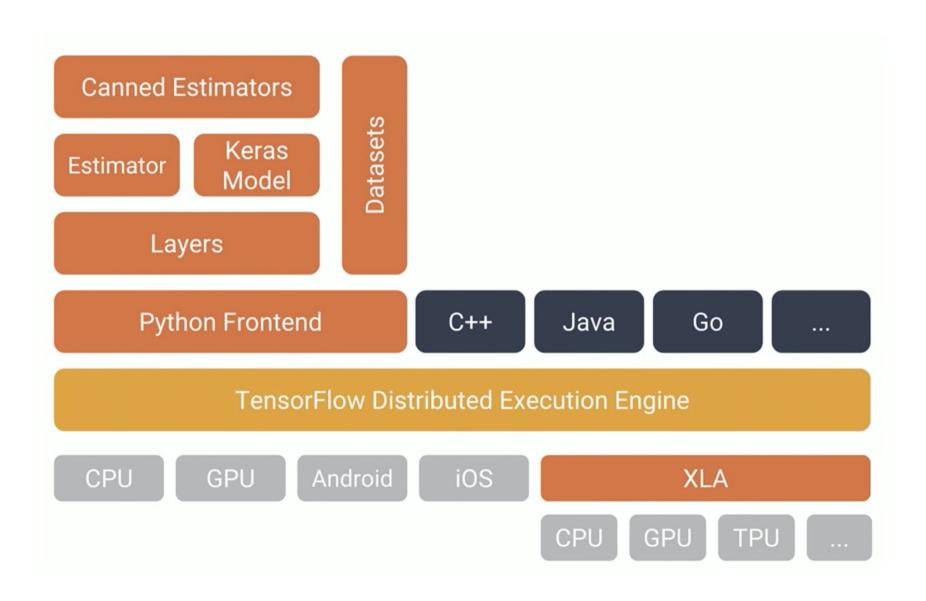


#### tensorboard

- Choose what you want to monitor in your graph
  - Scalar tensor:
    - tf.summary.scalar(name, scalar\_tensor)
  - Images:
    - tf.summary.image(name, image\_tensor)
  - Histograms:
    - tf.summary.histogram(name, any\_tensor)
- Right after variables initialization
  - merged\_summary= tf.summary.merge\_all()
  - train\_writer = tf.summary.FileWriter(dir/for/logs/train, session.graph)
  - validation\_writer = tf.summary.FileWriter(dir/for/logs/test, session.graph)
- When training, ask for merged\_summary and save it:
  - \_\_\_, m\_summary= session.run([train\_step, merged\_summary], feed\_dict=feed\_dict)
  - train\_writer.add\_summary(m\_summary, nStep)
- Do the same when computing validation
- Launch tensorboard from command line: tensorboard --logdir dir/for/logs/test
- Visualize it using your web browser and the url reported by tensorboard



## High level tf



### Layers level tf

- No need to define weights and bias variables
- No need to care about tensor shapes except for the placeholders

```
33 inputPh= tf.placeholder(dtype=tf.float32, shape=[None] + list(x_train.shape[1:]) , name="inputData")
34 labelsPh= tf.placeholder(dtype=tf.float32, shape=[None, y_train.shape[-1]], name="labelsData",)
35 tf.summary.image('inputImage', inputPh)
36
37 conv2d_out= tf.layers.Conv2D(filters=32, kernel_size=5, strides=1, padding="same", activation=tf.nn.relu) (inputPh)
38 conv2d_out= tf.layers.MaxPooling2D(pool_size=4, strides=2) (conv2d_out)
39
40 input_flatten= tf.layers.Flatten() (conv2d_out)
41
42 h1_out= tf.layers.Dense(units=N_HIDDEN, activation=tf.nn.relu ) (input_flatten)
43
44 with tf.variable_scope("output_layer"):
45 logits= tf.layers.Dense(units= y_train.shape[-1], activation=None ) (h1_out)
46 y_pred= tf.nn.softmax(logits)
```

• Training, evaluation, checkpointing, etc. it is still cumbersome

My solution: ./1\_tf\_intro/examples/e4\_nNet\_tfLayers.py

#### keras

- Easy model definition
- Easy model training, evaluation, checkpointing

```
19 #Rescale data.
20 x train= x train /255.0
21 x test= x test /255.0
23 print(x_train.shape, y_train.shape, x_train.max(), x_train.min() )
24 #One-hot-encode labels
25 oh encoder= OneHotEncoder(n values=10, sparse=False)
26 y train= oh encoder.fit transform(y train)
27 y test= oh encoder.transform(y test)
28 print(x train.shape, y train.shape)
30 #No longer needed as keras can split validation automatically
31 \#x train, x validation, y train, y validation = cross validation.train test split(x train, y train, test size=0.1, random state=121)
33 print("data ready")
34 #Model definition
36 model = keras.models.Sequential()
37 model.add( layers.Conv2D(filters=32, kernel_size= 5, strides=1,padding='same', activation='relu', input_shape= x_train.shape[1:] ))
38 model.add( layers.MaxPooling2D(pool_size=4, strides=2 ) )
39 model.add( layers.Flatten() )
40 model.add( layers.Dense(N HIDDEN, activation='relu'))
41 model.add( layers.Dense(y train.shape[-1], activation='softmax'))
42 sgd= keras.optimizers.SGD(lr=LEARNING_RATE, decay=0., momentum=0., nesterov=False)
44 #Advanced topic: use tensorflow directly inside keras we won't discuss now
45 def roc auc(y true, y pred):
46 auc = tf.metrics.auc(y_true, y_pred)[1]
    keras.backend.get session().run(tf.local variables initializer())
48
    return auc
50 model.compile(loss='categorical crossentropy',optimizer=sqd, metrics=['accuracy', roc auc])
51 print("network created")
52 print("training begin")
53 model.fit(x train, y train,epochs=N EPOCHS, batch size=BATCH SIZE, validation split=0.1)
54 score = tuple(model.evaluate(x test, y test, batch size=BATCH SIZE))
55 print("Testing evaluation loss %f acc %f roc_auc %f"%score)
```

My solution: ./1 tf intro/examples/e5 nNet keras.py

#### To be continued