



European Research Council  
Established by the European Commission

# Ensuring unbiased sampling of HMC schemes for non separable Hamiltonian systems

Régis SANTET

(CERMICS, École des Ponts & MATHERIALS Team, Inria Paris)

1st year PhD student, Supervisors: G. Stoltz, T. Lelièvre

MCQMC 2022

- **Aim: Unbiased** estimation of  $\mathbb{E}_\pi[f] = \int_{\mathcal{X}} f(q)\pi(q)\mathrm{d}q$ ,  $\pi \propto e^{-\beta V}$  with the estimator

$$\hat{I}_N := \frac{1}{N} \sum_{i=1}^N f(q^i), \quad q^i \sim \pi$$

# Diffusion dependent Overdamped Langevin dynamics

- **Aim:** Unbiased estimation of  $\mathbb{E}_\pi[f] = \int_{\mathcal{X}} f(q)\pi(q)\mathrm{d}q$ ,  $\pi \propto e^{-\beta V}$  with the estimator

$$\hat{I}_N := \frac{1}{N} \sum_{i=1}^N f(q^i), \quad q^i \sim \pi$$

- **Difficulty:** explore **anisotropic** potentials with **multiple minima**

# Diffusion dependent Overdamped Langevin dynamics

- **Aim:** Unbiased estimation of  $\mathbb{E}_\pi[f] = \int_{\mathcal{X}} f(q)\pi(q)dq$ ,  $\pi \propto e^{-\beta V}$  with the estimator

$$\hat{I}_N := \frac{1}{N} \sum_{i=1}^N f(q^i), \quad q^i \sim \pi$$

- **Difficulty:** explore **anisotropic** potentials with **multiple minima**
- **Solution:** **Position dependent positive definite symmetric matrix  $D$** <sup>1</sup>

$$dq_t = \left( -D(q_t)\nabla V(q_t) + \beta^{-1}\text{div } D(q_t) \right) dt + \sqrt{2\beta^{-1}D(q_t)} dW_t$$

---

<sup>1</sup>Bou-Rabee/Donev/Vanden-Eijnden (2014)

# Diffusion dependent Overdamped Langevin dynamics

- **Aim:** **Unbiased** estimation of  $\mathbb{E}_\pi[f] = \int_{\mathcal{X}} f(q)\pi(q)dq$ ,  $\pi \propto e^{-\beta V}$  with the estimator

$$\hat{I}_N := \frac{1}{N} \sum_{i=1}^N f(q^i), \quad q^i \sim \pi$$

- **Difficulty:** explore **anisotropic** potentials with **multiple minima**
- **Solution:** **Position dependent positive definite symmetric matrix  $D$** <sup>1</sup>

$$dq_t = \left( -D(q_t)\nabla V(q_t) + \beta^{-1}\text{div } D(q_t) \right) dt + \sqrt{2\beta^{-1}D(q_t)} dW_t$$

- **Challenge:** **Efficient unbiased numerical integration**

---

<sup>1</sup>Bou-Rabee/Donev/Vanden-Eijnden (2014)

# Which diffusion coefficient? Metastable case

- Approach mainly used in Bayesian Inference<sup>2</sup>:  $D \equiv (\nabla^2 V)^{-1}$
- Various works<sup>3</sup> suggest  $D \propto e^{\beta V} I_d$

---

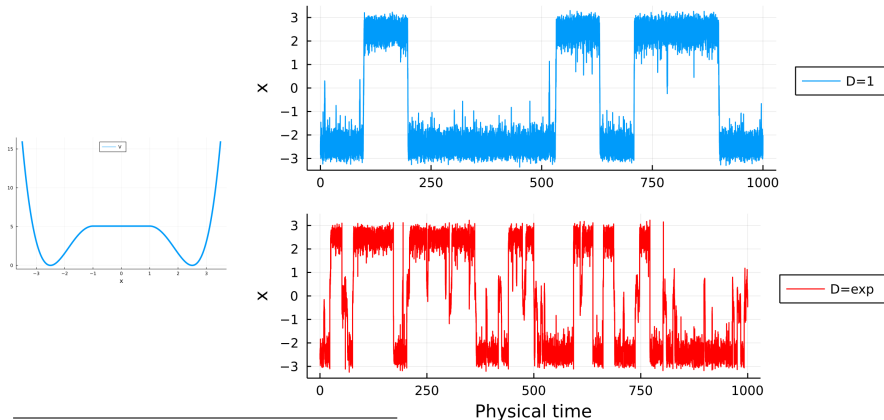
<sup>2</sup>Girolami/Calderhead (2011)

<sup>3</sup>Roberts/Stramer (2002), Lelièvre/Pavliotis/Robin/Stoltz (In prep.)

# Which diffusion coefficient? Metastable case

- Approach mainly used in Bayesian Inference<sup>2</sup>:  $D \equiv (\nabla^2 V)^{-1}$
- Various works<sup>3</sup> suggest  $D \propto e^{\beta V} I_d$

⇒ Helps to **cross energy barriers**: if  $V \uparrow$ , then  $D \uparrow$



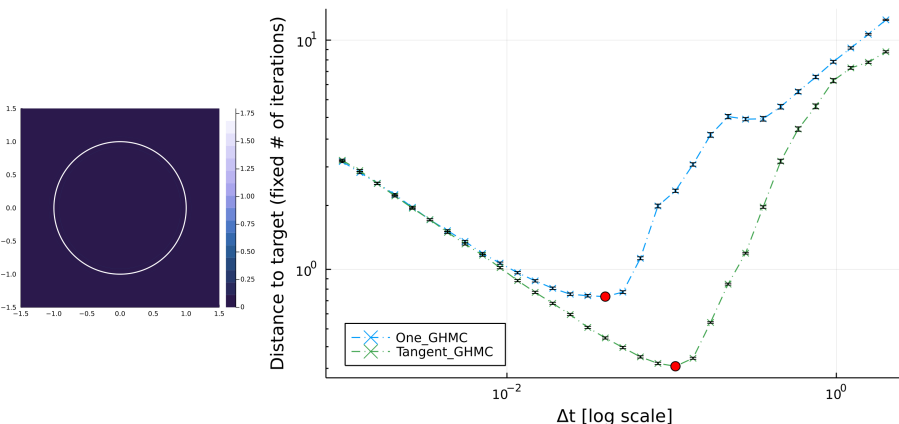
<sup>2</sup>Girolami/Calderhead (2011)

<sup>3</sup>Roberts/Stramer (2002), Lelièvre/Pavliotis/Robin/Stoltz (In prep.)

# Which diffusion coefficient? Anisotropic case

- **Anisotropic diffusion coefficient**  $D_{\text{Tan}}(q) = \varepsilon I_2 + \tilde{q}\tilde{q}^\top / \|q\|^2$ ,  $\tilde{q} = (-y \ x)^\top$
- **Isotropic diffusion coefficient**  $D_{\text{One}} \equiv (1 + \varepsilon)I_2$ ,  $\varepsilon = 0.1$

Computing: after fixed number of iterations, distance to the invariant measure of the angle distribution (uniform on  $[0, 2\pi]$ )

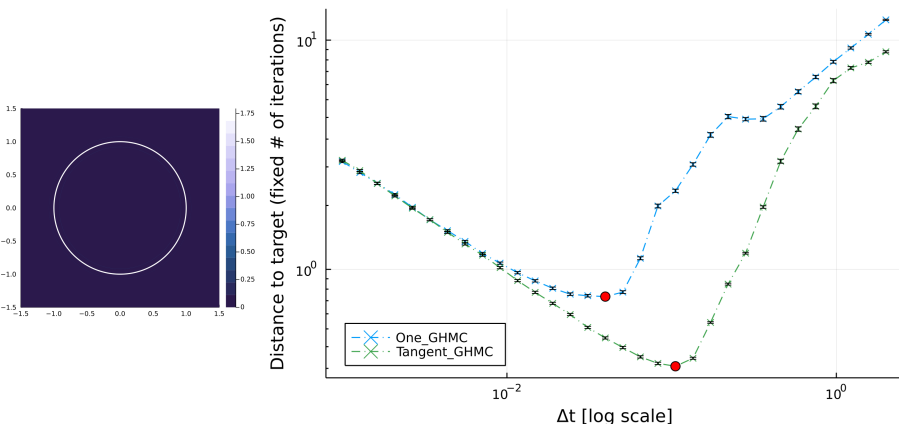




# Which diffusion coefficient? Anisotropic case

- **Anisotropic diffusion coefficient**  $D_{\text{Tan}}(q) = \varepsilon I_2 + \tilde{q}\tilde{q}^\top / \|q\|^2$ ,  $\tilde{q} = (-y \ x)^\top$
- **Isotropic diffusion coefficient**  $D_{\text{One}} \equiv (1 + \varepsilon)I_2$ ,  $\varepsilon = 0.1$

Computing: after fixed number of iterations, distance to the invariant measure of the angle distribution (uniform on  $[0, 2\pi]$ )



⇒ Compromise: **small**/**large** time steps (exploration vs rejection)

# Unbiased sampling with Metropolis schemes

- **Metropolis-Hastings**: accept/reject with proba  $\min \left( 1, \frac{\pi(q')T(q', dq)}{\pi(q)T(q, dq')} \right)$

# Unbiased sampling with Metropolis schemes

- **Metropolis-Hastings**: accept/reject with proba  $\min \left( 1, \frac{\pi(q')T(q', dq)}{\pi(q)T(q, dq')} \right)$
- Natural candidate: **Large** rejection rates<sup>4</sup>  $\mathcal{O}(\Delta t^{1/2})$

$$q' = q + \left( -D(q)\nabla V(q) + \beta^{-1}\text{div } D(q) \right) \Delta t + \sqrt{2\Delta t\beta^{-1}D(q)}G$$

---

<sup>4</sup>Rosky/Doll/Friedman (1978), Fathi/Stoltz (2017)

# Unbiased sampling with Metropolis schemes

- **Metropolis-Hastings**: accept/reject with proba  $\min \left( 1, \frac{\pi(q')T(q', dq)}{\pi(q)T(q, dq')} \right)$
- Natural candidate: **Large** rejection rates<sup>4</sup>  $\mathcal{O}(\Delta t^{1/2})$

$$q' = q + (-D(q)\nabla V(q) + \beta^{-1}\text{div } D(q)) \Delta t + \sqrt{2\Delta t\beta^{-1}D(q)}G$$

- **Better choice**: **(Generalized) Hamiltonian Monte Carlo**<sup>5</sup> based on

$$\begin{cases} dq_t = \nabla_p H(q_t, p_t) dt \\ dp_t = -\nabla_q H(q_t, p_t) dt - \gamma \nabla_p H(q_t, p_t) dt + \sqrt{2\gamma\beta^{-1}} dW_t \end{cases}$$

with

$$H(q, p) = V(q) - \frac{1}{2} \ln(\det D(q)) + \frac{1}{2} p^\top D(q) p$$

- $p \sim \mathcal{N}(0, D(q)^{-1})$ , marginal in position of  $e^{-\beta H}$  is  $\pi$
- **Consistent approximation** of overdamped Langevin dynamics

---

<sup>4</sup>Rosky/Doll/Friedman (1978), Fathi/Stoltz (2017)

<sup>5</sup>Duane/Kennedy/Pendleton/Roweth (1987), Neal (1993)

i) Sample momenta (Ornstein-Uhlenbeck or direct sampling)

ii) Integrate Hamiltonian dynamics

⇒ Generalized Störmer–Verlet<sup>6</sup> (time-reversible, symplectic but implicit)

$$\begin{cases} p^{n+1/2} = p^n - \frac{\Delta t}{2} \nabla_q H(q^n, p^{n+1/2}) \\ q^{n+1} = q^n + \frac{\Delta t}{2} \left( \nabla_p H(q^n, p^{n+1/2}) + \nabla_p H(q^{n+1}, p^{n+1/2}) \right) \\ p^{n+1} = p^{n+1/2} - \frac{\Delta t}{2} \nabla_q H(q^{n+1}, p^{n+1/2}) \end{cases}$$

iii) Apply M–H procedure

---

<sup>6</sup>Hairer/Lubich/Wanner (2006)

<sup>7</sup>Girolami/Calderhead (2011)

i) Sample momenta (Ornstein-Uhlenbeck or direct sampling)

ii) Integrate Hamiltonian dynamics

⇒ Generalized Störmer–Verlet<sup>6</sup> (time-reversible, symplectic but implicit)

$$\begin{cases} p^{n+1/2} = p^n - \frac{\Delta t}{2} \nabla_q H(q^n, p^{n+1/2}) \\ q^{n+1} = q^n + \frac{\Delta t}{2} \left( \nabla_p H(q^n, p^{n+1/2}) + \nabla_p H(q^{n+1}, p^{n+1/2}) \right) \\ p^{n+1} = p^{n+1/2} - \frac{\Delta t}{2} \nabla_q H(q^{n+1}, p^{n+1/2}) \end{cases}$$

iii) Apply M–H procedure

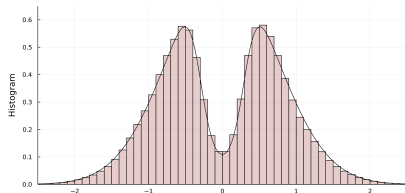
- (Effective) Rejection rates scale as  $\mathcal{O}(\Delta t^{3/2})$

---

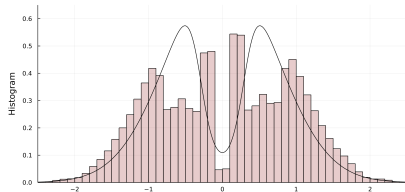
<sup>6</sup>Hairer/Lubich/Wanner (2006)

<sup>7</sup>Girolami/Calderhead (2011)

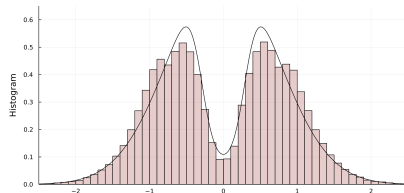
# Bias arising with standard RMHMC implementation



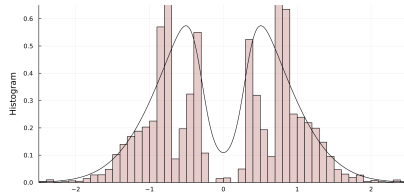
$\Delta t = 0.18$



$\Delta t = 0.86$

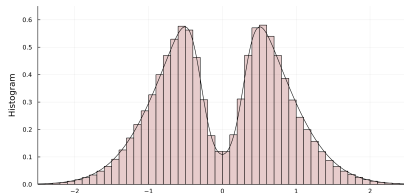


$\Delta t = 0.69$

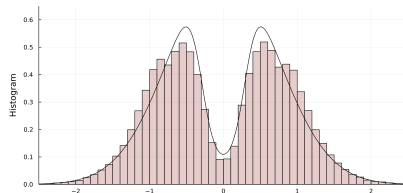


$\Delta t = 1.68$

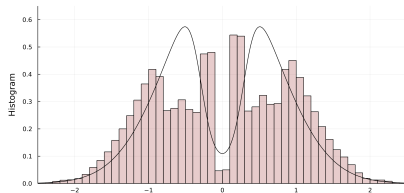
# Bias arising with standard RMHMC implementation



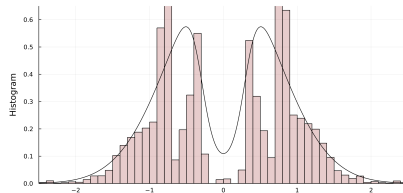
$\Delta t = 0.18$



$\Delta t = 0.69$



$\Delta t = 0.86$



$\Delta t = 1.68$

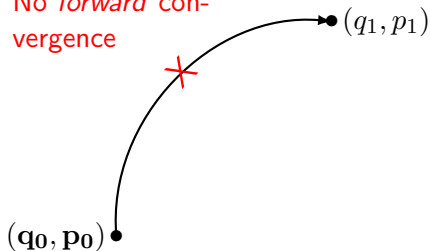
Implicit methods  $\Rightarrow$  convergence and numerical reversibility issues<sup>8</sup>

<sup>8</sup>Brofos/Lederman (2021)

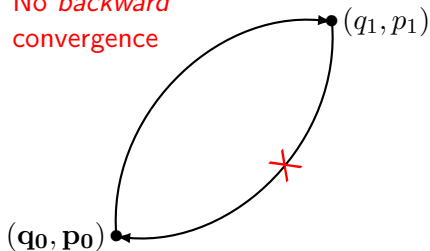


# RMHMC with enforced numerical reversibility<sup>9</sup>

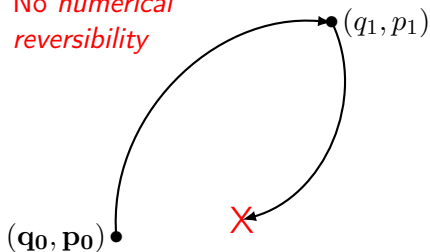
No *forward* convergence



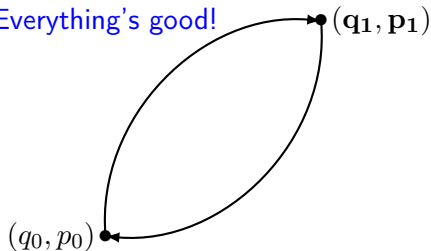
No *backward* convergence



No *numerical reversibility*



Everything's good!



<sup>9</sup>Zappa/Holmes-Cerfon/Goodman (2018)

# HMC: canonical measure preservation

## Theorem

HMC algorithm preserves the probability measure

$$\mu = \exp(-H(q, p)) / Z_\mu \, dq \, dp$$

## Proof

$$T_{\Delta t}((q, p), dq' dp') = r_{\Delta t} \delta_{\varphi_{\Delta t}(q, p)}(dq' dp') + (1 - r_{\Delta t}(q, p)) \delta_{(q, p)}(dq' dp')$$

If  $f: \mathbb{R}^d \rightarrow \mathbb{R}^d \rightarrow \mathbb{R}$  measurable & bounded,  $[x=(q, p), S(q, p)=(q, -p)]$

$$\begin{aligned} \int r_{\Delta t}(x) f(\varphi_{\Delta t}(x)) \mu(dx) &= \int r_{\Delta t}(\varphi_{\Delta t}^{-1}(y)) f(y) \frac{e^{-\beta[H \circ \varphi_{\Delta t}^{-1}](y)}}{Z_\mu} dy \\ [\|\nabla \varphi_{\Delta t}\| = 1] &= \int r_{\Delta t}((S \circ \varphi_{\Delta t})(z)) f(z) \frac{e^{-\beta[H \circ S \circ \varphi_{\Delta t}](z)}}{Z_\mu} dz \\ [S \circ \varphi_{\Delta t} \circ S = \varphi_{\Delta t}^{-1}] &= \int r_{\Delta t}(z) f(z) \mu(dz) \end{aligned}$$

# Our contribution

Define  $\psi_{\Delta t} = S \circ \varphi_{\Delta t}$  and

$$\psi_{\Delta t}^{\text{REV}} = \psi_{\Delta t} \mathbf{1}_{\mathcal{B}} + \text{id} \mathbf{1}_{\mathcal{B}^c}$$

where

$$\mathcal{B} = \{(q, p) \mid \psi_{\Delta t}^2(q, p) = (q, p)\}$$

## Proposition

$\psi_{\Delta t}^{\text{REV}}$  is a globally defined measure preserving involution. RMHMC algorithm performed with  $\psi_{\Delta t}^{\text{REV}}$  yields an unbiased estimator.

# Our contribution

Define  $\psi_{\Delta t} = S \circ \varphi_{\Delta t}$  and

$$\psi_{\Delta t}^{\text{REV}} = \psi_{\Delta t} \mathbf{1}_{\mathcal{B}} + \text{id} \mathbf{1}_{\mathcal{B}^c}$$

where

$$\mathcal{B} = \{(q, p) \mid \psi_{\Delta t}^2(q, p) = (q, p)\}$$

## Proposition

$\psi_{\Delta t}^{\text{REV}}$  is a globally defined measure preserving involution. RMHMC algorithm performed with  $\psi_{\Delta t}^{\text{REV}}$  yields an unbiased estimator.

Show that  $\mathcal{B}$  is measurable (even open)

# Our contribution

Define  $\psi_{\Delta t} = S \circ \varphi_{\Delta t}$  and

$$\psi_{\Delta t}^{\text{REV}} = \psi_{\Delta t} \mathbf{1}_{\mathcal{B}} + \text{id} \mathbf{1}_{\mathcal{B}^c}$$

where

$$\mathcal{B} = \{(q, p) \mid \psi_{\Delta t}^2(q, p) = (q, p)\}$$

## Proposition

$\psi_{\Delta t}^{\text{REV}}$  is a globally defined measure preserving involution. RMHMC algorithm performed with  $\psi_{\Delta t}^{\text{REV}}$  yields an unbiased estimator.

Show that  $\mathcal{B}$  is measurable (even open)

- Whole space is a topological manifold, hence locally path connected

# Our contribution

Define  $\psi_{\Delta t} = S \circ \varphi_{\Delta t}$  and

$$\psi_{\Delta t}^{\text{REV}} = \psi_{\Delta t} \mathbf{1}_{\mathcal{B}} + \text{id} \mathbf{1}_{\mathcal{B}^c}$$

where

$$\mathcal{B} = \{(q, p) \mid \psi_{\Delta t}^2(q, p) = (q, p)\}$$

## Proposition

$\psi_{\Delta t}^{\text{REV}}$  is a globally defined measure preserving involution. RMHMC algorithm performed with  $\psi_{\Delta t}^{\text{REV}}$  yields an unbiased estimator.

Show that  $\mathcal{B}$  is measurable (even open)

- Whole space is a topological manifold, hence locally path connected
- Show that each path connected component of  $\mathcal{B}$  is open

# Our contribution

Define  $\psi_{\Delta t} = S \circ \varphi_{\Delta t}$  and

$$\psi_{\Delta t}^{\text{REV}} = \psi_{\Delta t} \mathbf{1}_{\mathcal{B}} + \text{id} \mathbf{1}_{\mathcal{B}^c}$$

where

$$\mathcal{B} = \{(q, p) \mid \psi_{\Delta t}^2(q, p) = (q, p)\}$$

## Proposition

$\psi_{\Delta t}^{\text{REV}}$  is a globally defined measure preserving involution. RMHMC algorithm performed with  $\psi_{\Delta t}^{\text{REV}}$  yields an unbiased estimator.

Show that  $\mathcal{B}$  is measurable (even open)

- Whole space is a topological manifold, hence locally path connected
- Show that each path connected component of  $\mathcal{B}$  is open
- Then  $\varphi_{\Delta t}^{\text{REV}}$  is a  $\mathcal{C}^1$ -measure preserving local diffeomorphism on  $\mathcal{B}$

# Our contribution

Define  $\psi_{\Delta t} = S \circ \varphi_{\Delta t}$  and

$$\psi_{\Delta t}^{\text{REV}} = \psi_{\Delta t} \mathbf{1}_{\mathcal{B}} + \text{id} \mathbf{1}_{\mathcal{B}^c}$$

where

$$\mathcal{B} = \{(q, p) \mid \psi_{\Delta t}^2(q, p) = (q, p)\}$$

## Proposition

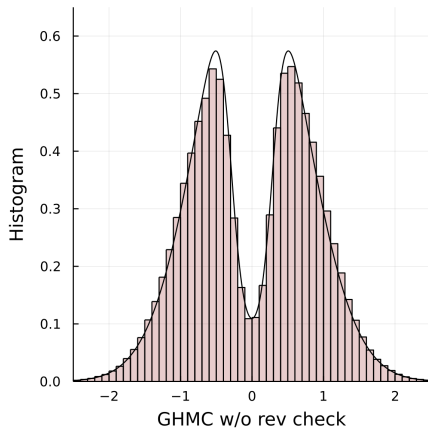
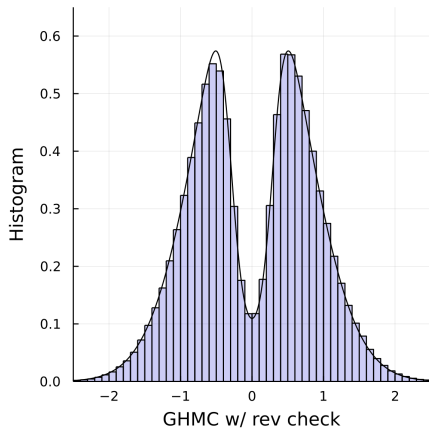
$\psi_{\Delta t}^{\text{REV}}$  is a globally defined measure preserving involution. RMHMC algorithm performed with  $\psi_{\Delta t}^{\text{REV}}$  yields an unbiased estimator.

Show that  $\mathcal{B}$  is measurable (even open)

- Whole space is a topological manifold, hence locally path connected
- Show that each path connected component of  $\mathcal{B}$  is open
- Then  $\varphi_{\Delta t}^{\text{REV}}$  is a  $\mathcal{C}^1$ -measure preserving local diffeomorphism on  $\mathcal{B}$
- Coming from its definition on  $\mathcal{B}^c$ , it is a involution

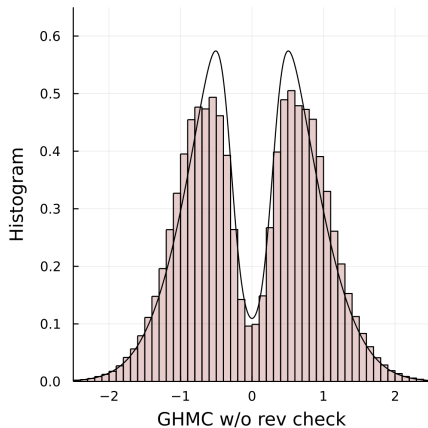
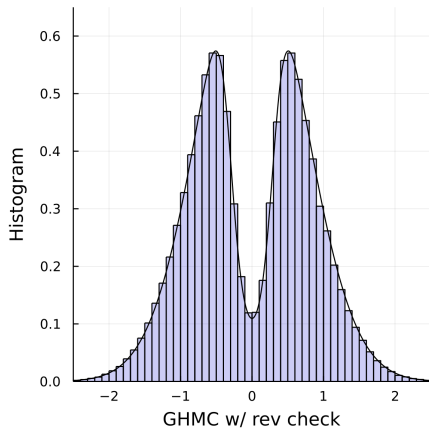


# Unbiased sampling with corrected RMHMC



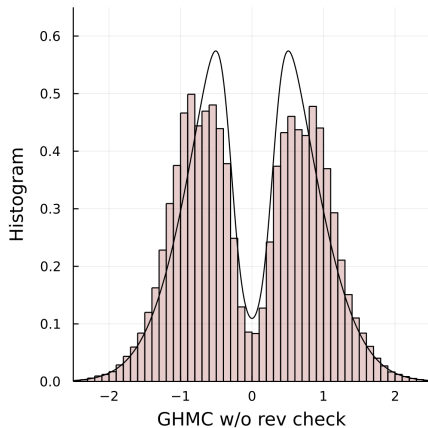
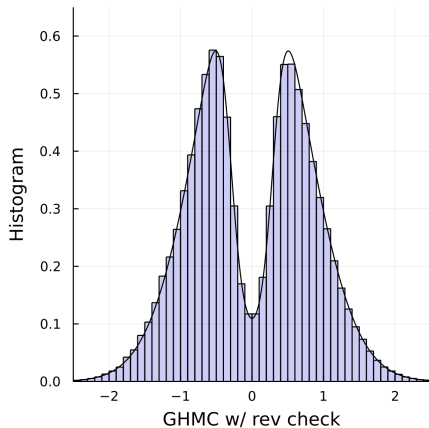
Sampling results with  $\Delta t = 0.28$ . Left histogram: reversibility checks.

# Unbiased sampling with corrected RMHMC



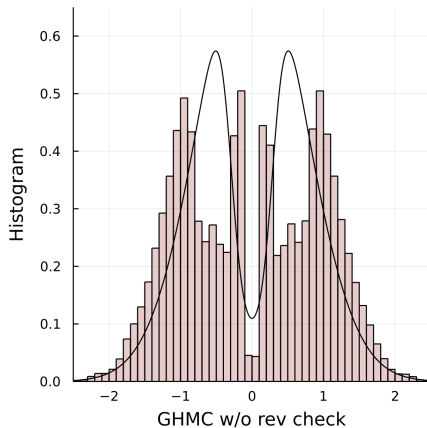
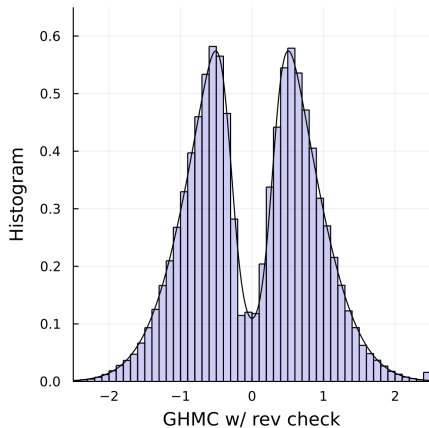
Sampling results with  $\Delta t = 0.44$ .

# Unbiased sampling with corrected RMHMC



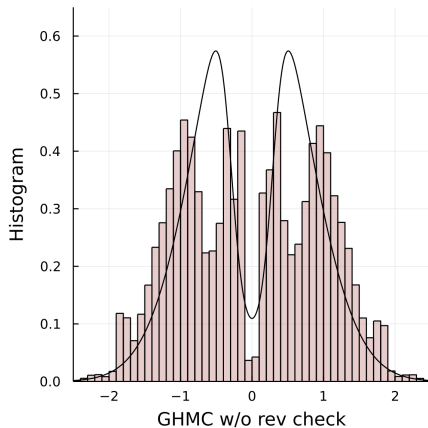
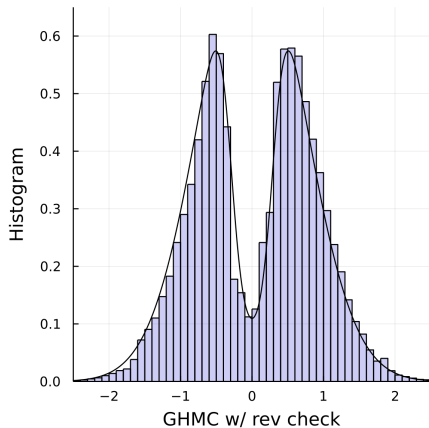
Sampling results with  $\Delta t = 0.69$ .

# Unbiased sampling with corrected RMHMC



Sampling results with  $\Delta t = 0.86$ .

# Unbiased sampling with corrected RMHMC



Sampling results with  $\Delta t = 1.08$ .

# Conclusion and perspectives

## Conclusions

- Overdamped Langevin with position dependent diffusion can dramatically **accelerate convergence**
- Care is required in numerical integration

# Conclusion and perspectives

## Conclusions

- Overdamped Langevin with position dependent diffusion can dramatically **accelerate convergence**
- Care is required in numerical integration

## Perspectives

- Higher dimension case: **use free energy  $F$** , reaction coordinate  $\xi$

$$D(q) \propto e^{\beta F(\xi(q))}$$

- Extension to **non-equilibrium** systems,  $F$  non-gradient force

$$dq_t^\eta = (D(q_t) [-\nabla V(q_t^\eta) + \eta F(q_t^\eta)] + \beta^{-1} \operatorname{div} D(q_t^\eta)) dt + \sqrt{2\beta^{-1} D(q_t^\eta)} dW_t$$

Thank you !