```
CiA301CommPort
      portFileDescriptor id
    - port

    usesockets

    - send_msg
     input
    - readBuffer

    readInbox

    + CiA301CommPort()
    + CiA301CommPort()
+ ReadSDO()
    + ReadSDO()
    + ReadNMT()
      WriteNMT()
      WritePDO()
    + FlushBuffer()
    + FlushBuffer()
      WriteSDO()
      WritePDO4()
    + ReadErrorNMT()
      ReadPDO()
      data4x8to32()
     CanOpenToCanBus()
     - CanBusToCanOpen()
    - DataToInt()
- SendMessage()
      SendCanMessage()
      WaitForReadMessage()
      ReadCobId()
    read_timeout()
      GetMsg()
      SetCanOpenMsg()
                 Δ
          CiA402Device

    comm

    currentPosition

port
- reduction_ratio_
                  motor

    encoder_resolution

    SampSL

current_limit
- Scaling_Factors_Velocity
- Scaling_Factors_Position
- Scaling_Factors_Acceleration
 CiA402Device()
+ CiA402Device()
+ CiA402Device()
+ CiA402Device()
+ CiA402Device()
+ CheckStatus()
+ PrintStatus()
+ SwitchOn()
+ SwitchOff()
+ QuickStop()
+ GetPosition()
+ GetVelocity()
+ SetCommunications()
+ CheckError()
 OperationMode()
+ Setup_Velocity_Mode
+ Setup_Torque_Mode()
                    Mode()
+ SetTorque()
+ ForceSwitchOff()
+ SetPosition()
+ SetupPositionMode()
+ SetPositionRECURSIVE_test()
 SetTarget_
              VELOCITY
+
 PROPORCIONAL()
_
+ Reset()
+ StartNode()
+ SetVelocity()
+ SetEnc
           res()
+ SetRed_Mot()
+ SetSampling_period()
  Scaling()

    Init()
```