

Vector: A C++ Class for 3D Vector Algebra Reference Sheet

Operation	Mathematical Notation	Computer Code
Definition	Let \mathbf{v} be an unspecified vector.	Vector \mathbf{v} ;
	Let \mathbf{a} be the cartesian vector $(1, 2, 3)$.	Vector $\mathbf{a}(1., 2., 3.)$; <i>or</i> Vector $\mathbf{a}(1., 2., 3., \text{CART})$;
	Let \mathbf{b} be the polar vector (r, θ, ϕ) . ^a	Vector $\mathbf{b}(r, \text{th}, \text{ph}, \text{POLAR})$;
Input vector \mathbf{a}	n/a	<code>cin >> a;</code>
Output vector \mathbf{a}	n/a	<code>cout << a;</code>
Cartesian representation	Let $\mathbf{a} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$.	Vector $\mathbf{a}(x, y, z)$; <i>or</i> Vector $\mathbf{a}(x, y, z, \text{CART})$;
Polar representation	$\mathbf{a} = (r, \theta, \phi)$ ^a	Vector $\mathbf{a}(r, \text{th}, \text{ph}, \text{POLAR})$;
Assign one vector to another	Let $\mathbf{b} = \mathbf{a}$ <i>or</i> $\mathbf{b} \leftarrow \mathbf{a}$	<code>b = a;</code> <i>or</i> <code>b(a);</code>
Components of vector \mathbf{a}	a_x, a_y, a_z	<code>a.x(), a.y(), a.z()</code> <i>or</i> <code>x(a), y(a), z(a)</code> <i>or</i> <code>a[X], a[Y], a[Z]</code>
	r, θ, ϕ	<code>a.r(), a.theta(), a.phi()</code> <i>or</i> <code>r(a), theta(a), phi(a)</code>
Vector addition	$\mathbf{c} = \mathbf{a} + \mathbf{b}$	<code>c = a + b;</code>
Addition assignment	$\mathbf{b} \leftarrow \mathbf{b} + \mathbf{a}$	<code>b += a;</code>
Vector subtraction	$\mathbf{c} = \mathbf{a} - \mathbf{b}$	<code>c = a - b;</code>
Subtraction assignment	$\mathbf{b} \leftarrow \mathbf{b} - \mathbf{a}$	<code>b -= a;</code>
Multiplication by a scalar s	$\mathbf{b} = s\mathbf{a}$ <i>or</i> $\mathbf{b} = \mathbf{a}s$	<code>b = s * a;</code> <i>or</i> <code>b = a * s;</code>
Multiplication assignment	$\mathbf{a} \leftarrow s\mathbf{a}$ <i>or</i> $\mathbf{a} \leftarrow \mathbf{a}s$	<code>a *= s;</code>
Dot (scalar) product	$c = \mathbf{a} \cdot \mathbf{b}$	<code>c = a * b;</code>
Cross (vector) product	$\mathbf{c} = \mathbf{a} \times \mathbf{b}$	<code>c = a ^ b;</code>
Negative of a vector	$-\mathbf{a}$	<code>-a;</code>
Magnitude of a vector	$ \mathbf{a} $	<code>a.r();</code> <i>or</i> <code>a.mag();</code> <i>or</i> <code>mag(a);</code> <i>or</i> <code>scalar(a);</code>
Angle between two vectors	$\theta = \cos^{-1} \left(\frac{\mathbf{a} \cdot \mathbf{b}}{ \mathbf{a} \mathbf{b} } \right)$	<code>angle(a, b);</code>
Unit vector	$\mathbf{u} = \frac{\mathbf{v}}{ \mathbf{v} }$	Vector <code>u = v.unit();</code> <i>or</i> Vector <code>u = unit(v);</code> <i>or</i> Vector <code>u = v.normalize();</code> <i>or</i> Vector <code>u = normalize(v);</code>
Perpendicular vector	$(r, \theta - \pi/2, \phi)$	<code>a.perp();</code> <i>or</i> <code>perp(a);</code>
Projection of \mathbf{a} along \mathbf{b}	$\left(\mathbf{a} \cdot \frac{\mathbf{b}}{ \mathbf{b} } \right) \frac{\mathbf{b}}{ \mathbf{b} }$	<code>proj(a, b);</code> <i>or</i> <code>a.proj(b);</code>
Rotate vector \mathbf{a} about the axial vector \mathbf{b} through the angle α	$\mathbf{a} + \mathbf{b} \times \mathbf{a} \sin \alpha + \mathbf{b} \times (\mathbf{b} \times \mathbf{a})(1 - \cos \alpha)$	<code>a.rotate(b, alpha);</code> <i>or</i> <code>a.rot(b, alpha);</code>
Check for equality	Is it true that $\mathbf{a} = \mathbf{b}$?	<code>a == b;</code>
Check for inequality	Is it true that $\mathbf{a} \neq \mathbf{b}$?	<code>a != b;</code>

^a θ is the polar angle measured from the z -axis and ϕ is the azimuthal angle measured from the x -axis to the plane that contains the vector and the z -axis. The angles θ and ϕ are in radians; use `rad(deg)` to convert degrees to radians and `deg(rad)` to convert radians to degrees.