Sistemas de controle II Controle digital

$$\left(\begin{array}{c} \mathbb{R}(S+1) \left(\mathbb{R}_{2} \mathbb{C}_{2} \mathbb{S} + 1 \right) \\ \mathbb{S} + 2 \longrightarrow \mathbb{Z} \left(\begin{array}{c} \mathbb{Q} \\ \mathbb{Z} \end{array} + 1 \right) \end{aligned}$$

 $RC = \frac{1}{2}$

C=1/2/2 = 10/2

Equivalentes por mapeamento

Equivalentes por segurador

Específicações no plano Z

Controle PID digital

Diagramas de blocos de sistemas digitais

Thoremado valor final (Z)

No dominio s

Z= LST

No discusto.

Pare: y = utr)

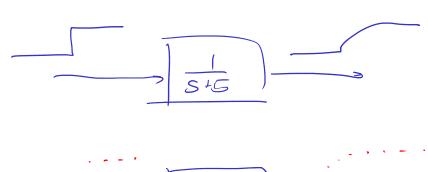
$$\mathbb{L}[\infty]^2 \lim_{Z \to 1} \frac{Z}{Z} = 1$$

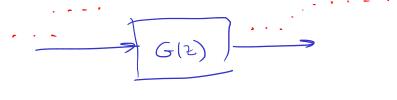
$$\frac{2}{2-1} \qquad \qquad \frac{2}{(2-0,5)} \qquad \qquad \frac{2}{2} \qquad \qquad \frac{2}{2-1} \qquad \qquad \frac{2}{2} \qquad \qquad \frac{2}{2-1} \qquad \qquad \frac{2}{2} \qquad \qquad \frac{2}$$

Ganho DC de un sistema:

Discreto. Analó sico Trustim G(2) G(s) periodo de and some Equivalente disnetes: Tustin U Mapeamento V 20 H Para cala polo/zuro calque um polo on zero correspondente Z $=) \hat{G}(z) = ?$ $G(s) = \frac{1}{s+5}$ T= 0, 1

≈ 0,6065





Jonalar os ganhas DC.

$$G(0) = \hat{G}(1)$$

$$\frac{1}{0+5} = \frac{1}{1-0,6065}$$

$$k = \frac{1-0,6065}{5} \approx 0,0787$$

$$\hat{G}(z) = \frac{0.6787}{2 - 0.6065}$$

$$E_{\times}$$
: $G(s) = \frac{10(8+1)}{5(8+3)}$ $T = 0, 1$

$$\widehat{G}(8) = \frac{k(2-n)}{(2-b)(2-c)} \qquad (2+1)$$

$$2 = e^{5T}$$

$$A = e^{-1.0,1} = e^{-0,1} = 0.905$$

$$b = e^{-0,1.0} = 1$$

$$C = e^{-0,1.3} = e^{-0,2} = 0.741$$

$$\widehat{G}(2) = \frac{k(2-0.705)}{(2-0.741)}$$

$$Ganlo Sist. + 1.10 1 = 0.005$$

$$= 8 \cdot \frac{S+1}{S(S+3)} \Big|_{S=0} = \frac{1}{3}$$

$$Ganlo DC do discuto:$$

$$\begin{array}{ccc}
(-2 - 1) & C(2) &= (2 - 1) & K(2 - 0,905) \\
2 - 3 & (2 - 1) & C(2) &= (2 - 1) & K(2 - 0,905) \\
&= K(1 - 0,905) \\
&= (2 - 1) & (2 - 0,905)
\end{array}$$

$$\frac{k(1-8,905)}{1-0,741} = \frac{1}{3} = 0 (2 \approx 9,909)$$

$$\hat{G}(2) = \frac{0,909(2-9,905)}{(2-1)(2-9,741)}$$