

# Nova Watchdog Timer (Dusky-Petrel Extension)

This document defines the **Watchdog Timer** peripheral for Dusky-Petrel. The watchdog provides a safety mechanism for detecting stalled or unresponsive software. If the timer expires, it performs a configured action (interrupt, halt, reset, or none). The watchdog begins life *inactive* and only counts when explicitly armed. To keep the watchdog happy, the guest software may periodically **pet** it—reloading the timeout and reassuring it that the system is still healthy.

## Configuration (Host Side)

```
[devices.watchdog]
enabled = false           ; default: inactive until armed by guest or monitor
device_code = 0014       ; configurable Nova I/O channel
timeout_ms = 5000        ; default timeout
repeat = false           ; one-shot by default
action = "interrupt"     ; interrupt | halt | reset | none
```

## Registers and Flags (Guest View)

```
Register A – Timeout (milliseconds)
DOA → write new timeout value (low 16 bits)
DIA → read current configured timeout

Register B – Control / Mode
bit 0: ENABLE      (1 = watchdog may run when armed)
bit 1: REPEAT      (1 = periodic / repeating)
bits 2-3: ACTION   (0=none, 1=interrupt, 2=halt, 3=reset)
bit 4: PET         (1 = reload timer and keep the dog happy)
bit 5: CLEAR_FIRED (1 = clear FIRED/DONE state)

Register C – Status (read-only)
bit 0: FIRED      (1 if watchdog expired and not yet cleared)
bit 1: ACTIVE     (1 if currently counting)
bit 2: REPEAT     (mirror of control)
bits 3-4: ACTION  (mirror of control)
```

## Busy / Done Semantics

```
BUSY = 1 while the watchdog is armed and counting.
BUSY = 0 when disabled or expired.
DONE = 1 when the watchdog has fired (expired) and not yet cleared.
DONE is cleared by CLEAR_FIRED or device Clear signal.
```

```
Skip behavior:
SKPBN → skip while BUSY=1 (timer running)
SKPBZ → skip when BUSY=0
SKPDN → skip once DONE=1 (expired)
SKPDZ → skip while not yet expired
```

## Signals (NIO Start / Clear / Pulse)

```
Start → arm the watchdog if ENABLE=1 and timeout_ms>0.
Clear → disarm and clear BUSY/DONE/FIRED.
Pulse → optional: force an immediate fire event.
```

## Internal Behavior (Summary)

- \* The watchdog is inactive on reset (ENABLE=0, ACTIVE=0, FIRED=0).
- \* Arming reloads the countdown and sets BUSY=1, ACTIVE=1.
- \* When the deadline passes, the watchdog FIRES:
  - BUSY=0, DONE=1, FIRED=1
  - Perform configured ACTION (interrupt / halt / reset / none)
- \* If REPEAT=1 and ENABLE=1, it automatically re■arms after firing.

## Petting the Watchdog

To reassure the watchdog that the system is still healthy, the guest periodically <b>pets</b> it by writ

Example:

```
LDA    0, #0b00010101    ; ENABLE=1, REPEAT=0/1 as configured, PET=1
DOA    WDT B              ; pet the watchdog – resets the countdown
```

## Example (Nova Assembly)

```
; Configure 5■second watchdog and pet it in the main loop
LDA     0, #5000          ; timeout in ms
DOA     WDT A
LDA     0, #0b00001101    ; ENABLE=1, ACTION=reset, PET=1 (arm + first pet)
DOA     WDT B

MAIN:
; ... do useful work ...
LDA     0, #0b00010001    ; PET=1, ENABLE=1 (same mode)
DOA     WDT B             ; pet to keep the dog happy
JMP     MAIN
```

## Compatibility Notes

- \* The watchdog device is simulator■specific and disabled by default.
- \* Legacy Nova programs run unchanged unless they access the watchdog channel.
- \* Behavior is deterministic and suitable for interrupt■driven systems.