

# Using Gaussian Process Emulators to Reduce Uncertainty in Sea Level Projections with Ice Sheet Models

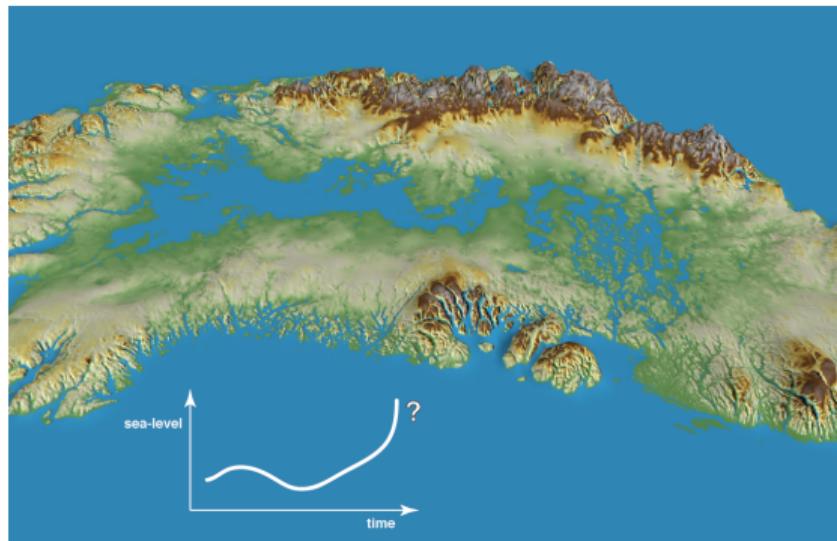
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AGU Fall Meeting 2019

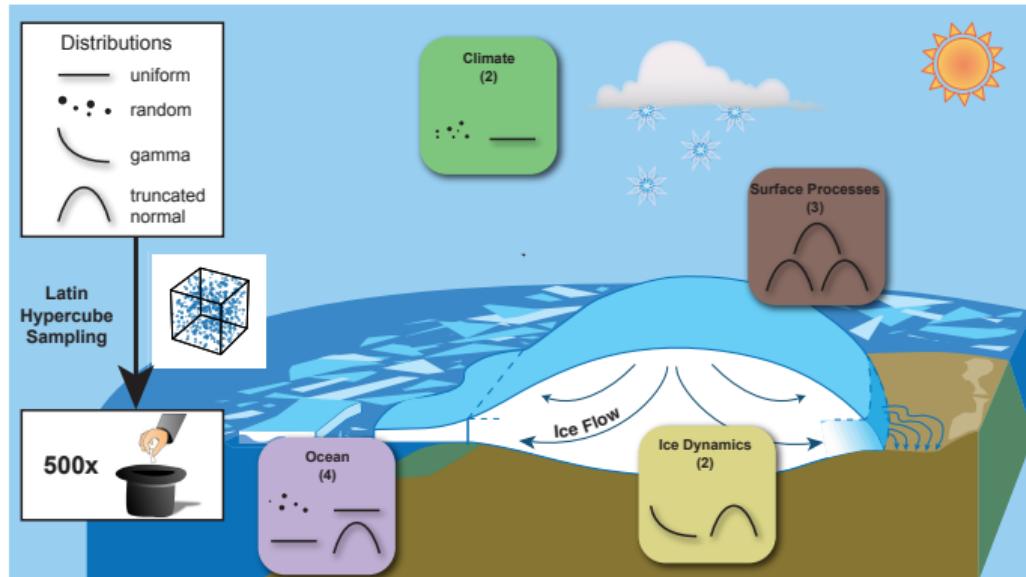
# Background

- ▶ Ice sheet melt rates are increasing with higher global temperatures
- ▶ Greenland ice sheet (GrIS) has 7.2 m sea level equivalent
- ▶ 5-33 cm sea level contribution by 2100 (Aschwanden *et al.* 2019)



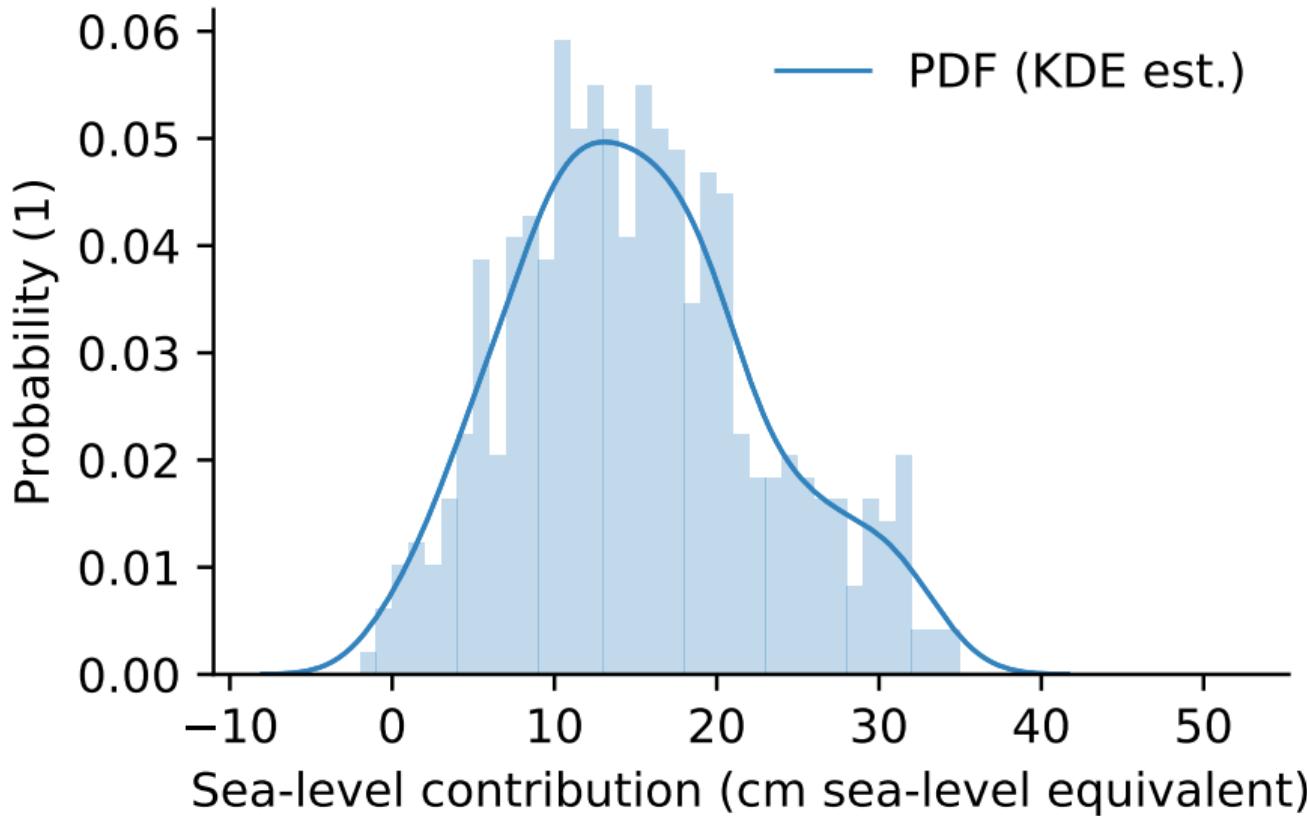
(RCP 8.5, Year 3000)

# Background



- ▶ Numerical models predict mass loss as function of geophysical parameters:  
 $y = f(\mathbf{x}), \mathbf{x} = x_1, x_2, x_3, \dots$
- ▶ Models have uncertainties (e.g. structural, parametric)
- ▶ Parametric: vary parameter values in simulation runs (“ensemble members”) of model

# Estimates of GrIS Sea Level Contribution



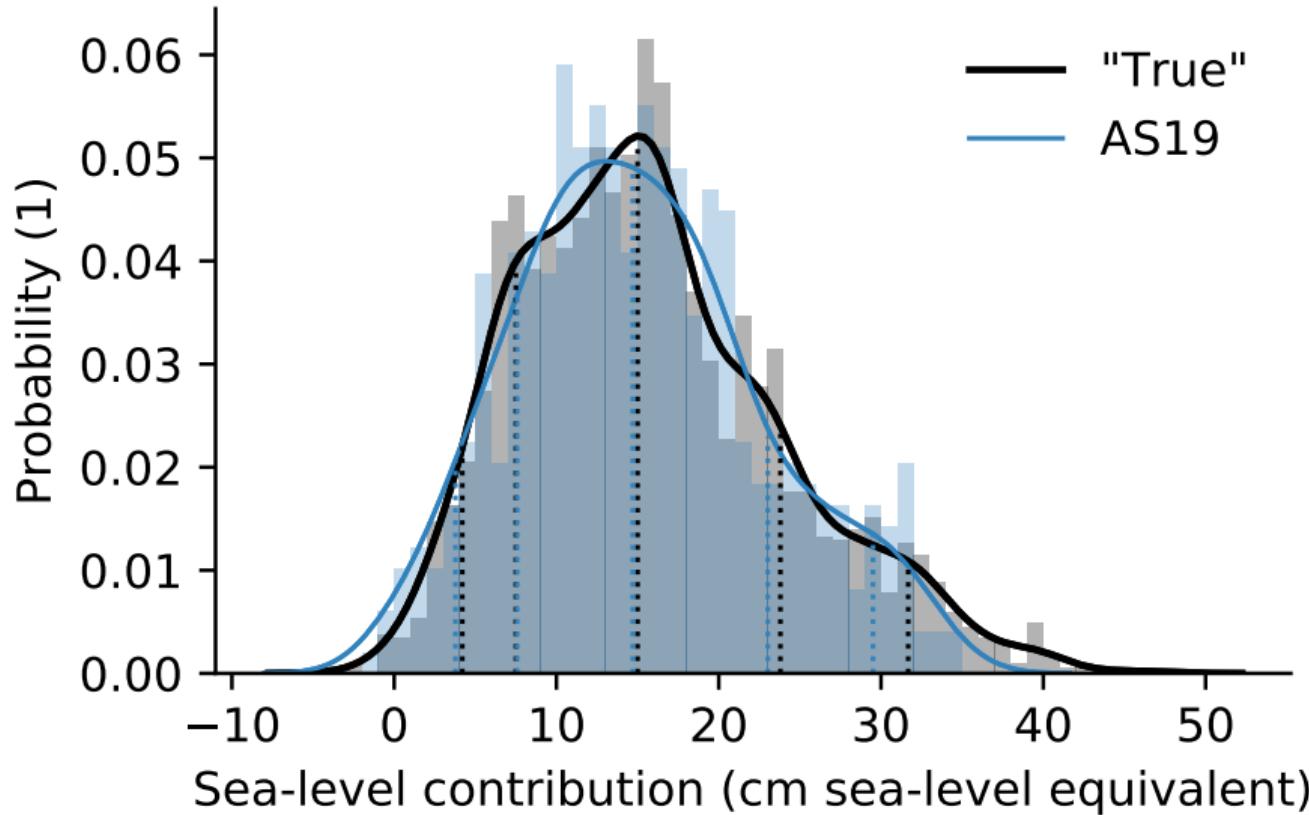
RCP 4.5, Year  
2100 from  
Aschwanden  
*et al.* 2019

11 critically  
important  
parameters in  
Parallel Ice  
Sheet Model  
(PISM)

# Research Question

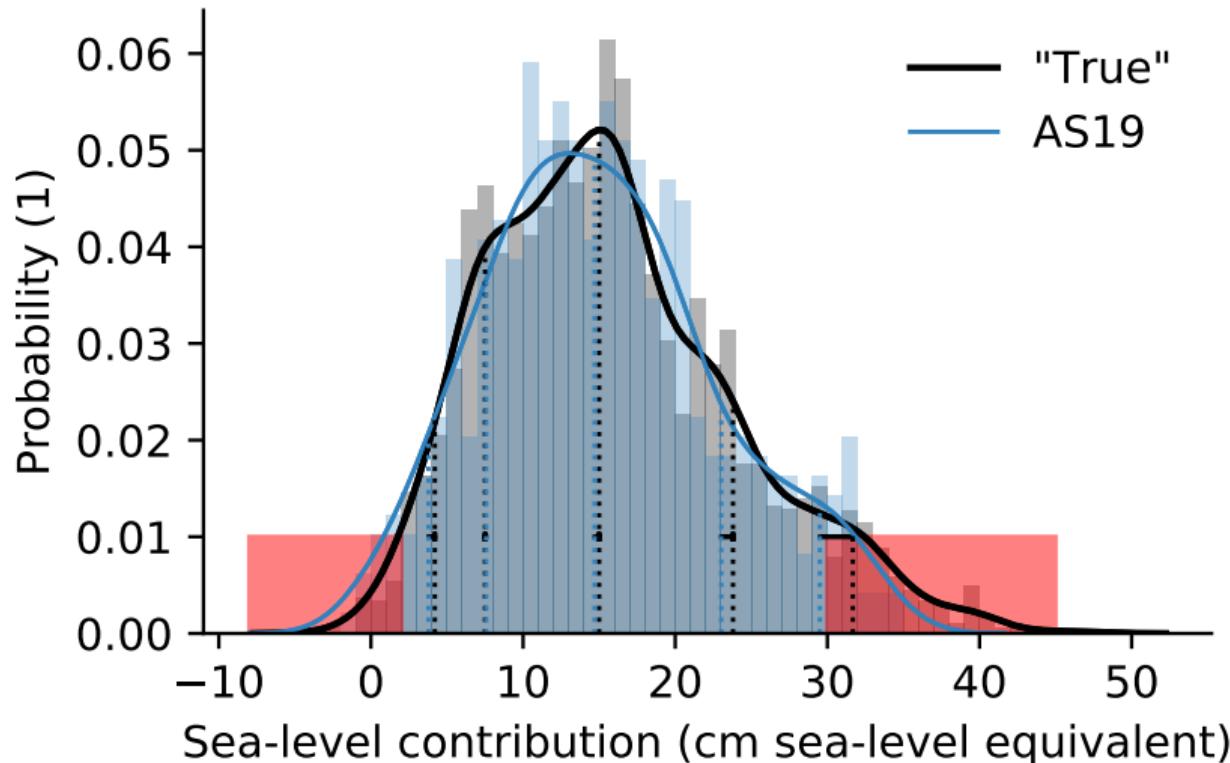
How well does the 500-member (“AS19”) ensemble characterize the “true” (or complete) probability density function (PDF)?

# Validation Ensemble (RCP 4.5, Year 2100)



“True”  
4,000-member  
ensemble  
close to  
complete PDF

# Validation Ensemble (RCP 4.5, Year 2100)

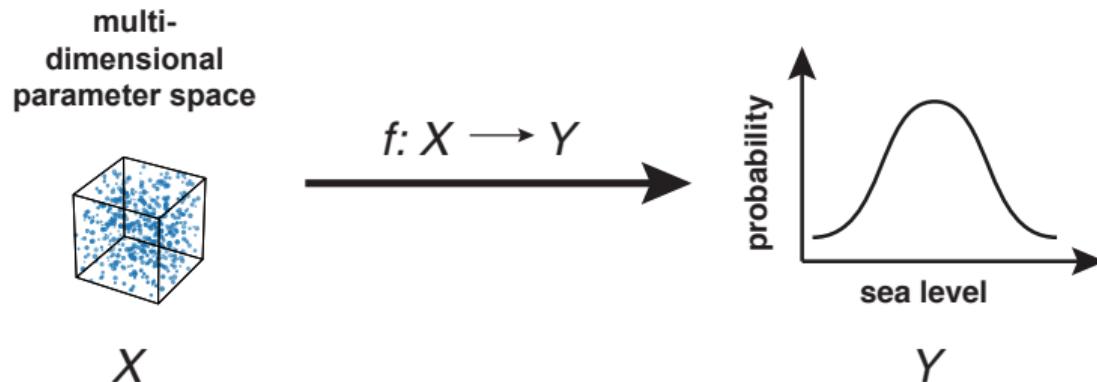


Problem: Infeasible supercomputing time, underestimates tails of "True" PDF

**Need:**  
**Computationally efficient approximation that captures uncertainty**

# Solution: Gaussian Process (GP) Emulators

- ▶ Following Edwards *et al.* 2019
- ▶ Trained on 500 members, predictions with 4,000 members
- ▶ **Benefits: computationally cheaper, provides uncertainty estimates of predictions**



\*Assume PISM is validated

# Gaussian Process

- ▶ Infinite set of random variables
  - ▶ Subset has joint multivariate normal distribution

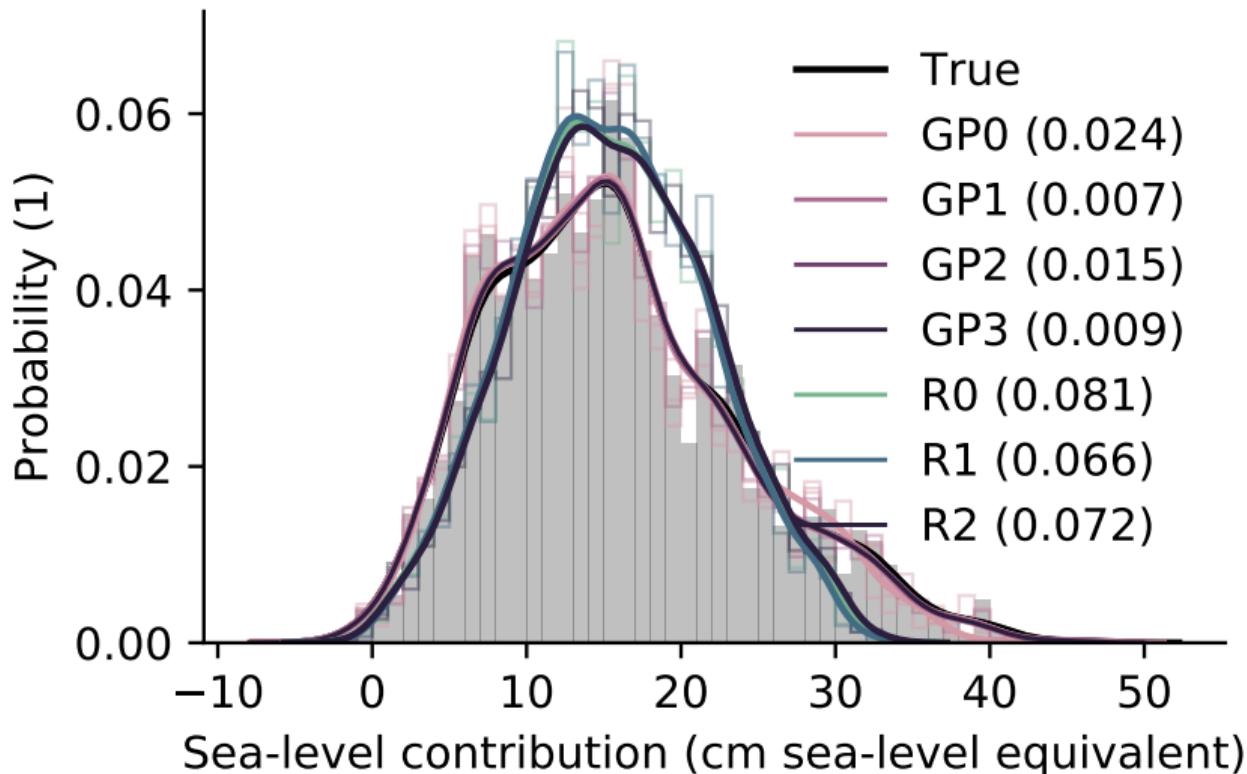
Specified by mean function  $m(\mathbf{x})$  and covariance function  $K(\mathbf{x}, \mathbf{x}_i)$

$$f(\mathbf{x}) \sim \mathcal{N}(m(\mathbf{x}), K(\mathbf{x}, \mathbf{x}_i))$$

where  $\mathbf{x}$  is a finite collection of sample points

- ▶ Mean function: expected values of  $f(\mathbf{x})$
- ▶ Covariance function: outputs of highly correlated inputs are close together

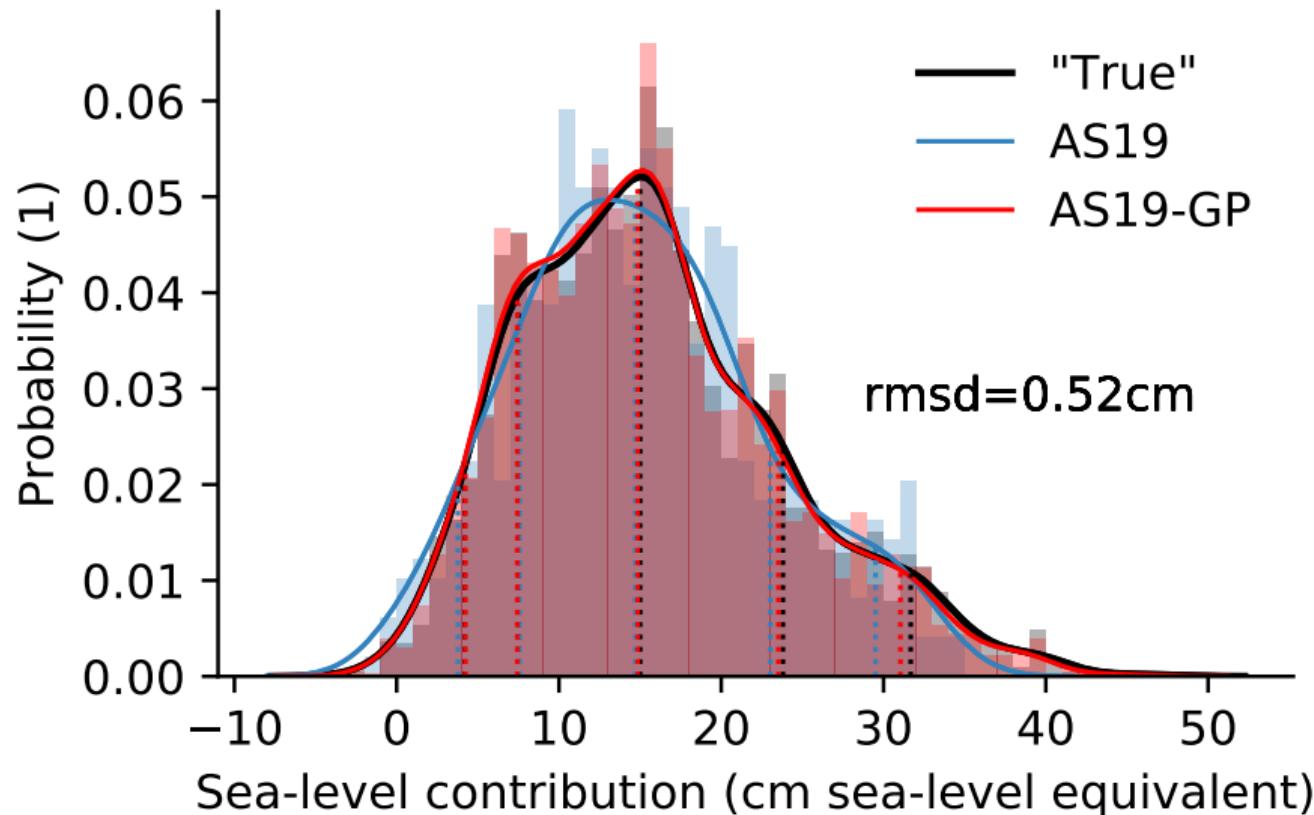
# Emulators vs. Fixed-Parameter Linear Models



Kullback-Leibler divergence - information lost in approximation of “True” PDF

Emulators outperform other regression methods (R0-R2)

# GP1 Emulator vs. Numerical Model



# Conclusion

- ▶ Numerical models are computationally expensive to run and do not capture complete probability distribution well
- ▶ Emulators enhance value of numerical models and decrease uncertainty in sea level projections
- ▶ Lots of other applications for emulators!

# References

- ▶ Aschwanden, A., Fahnestock, M. A., Truffer, M., Brinkerhoff, D. J., Hock, R., Khroulev, C., Mottram, R., & Khan, S. A. (2019). Contribution of the Greenland Ice Sheet to sea level over the next millennium. *Sci. Adv.* **5**(6).
- ▶ Edwards, T. L., Brandon, M. A., Durand, G., Edwards, N. R., Golledge, N. R., Holden, P. B., Nias, I. J., Payne, A. J., Ritz, C., & Wernecke, A. (2019). Revisiting Antarctic ice loss due to marine ice-cliff instability. *Nature* **566**:58-64.

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