E & M Review

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1 Electrostatics

1.1 E Fields

1.1.1 Definitions

• Quantization of charge:

$$Q = Ne$$

• Coulomb's law:

$$F_E = \frac{kq_1q_2}{r^2} = \frac{1}{4\pi\epsilon_0} \frac{q_1q_2}{r^2}$$

• <u>Electric field</u>: region of space in which charged particle experiences electric force

$$E = \frac{F_E}{q}$$

1.1.2 E Field Derivations

• Finite line of charge:

$$E = \frac{kQ}{x_0(x_0 - L)}$$

• Above infinite line:

$$E = \frac{2k\lambda}{r}$$

• Above ring of charge:

$$E = \frac{kQZ}{(R^2 + Z^2)^{3/2}}$$

• At center of arc of charge:

$$E = \frac{2k\lambda\sin\theta}{R}$$

• Above disk of charge:

$$E = \frac{\sigma}{2\epsilon_0} \left[1 - \frac{Z}{(R^2 + Z^2)^{3/2}} \right]$$

• Above infinite sheet:

$$E = \frac{\sigma}{2\epsilon_0}$$

1.1.3 Electric Flux

• Gauss' Law:

$$\Phi_E = \oint \vec{E} \, \cdot \, d\vec{A} = \frac{q_{enc}}{\epsilon_0}$$

1.1.4 Gauss' Law E Derivations

• Point charge:

$$E = \frac{kQ}{r^2}$$

 \bullet Conducting sphere: same for hollow/solid;

$$E = \frac{kQ}{r^2}$$

- Insulated sphere:
 - <u>Hollow</u>:

$$E = \begin{cases} 0 & r < R \\ \frac{kQ}{r^2} & r > R \end{cases}$$

– Solid, uniform ρ :

$$E = \begin{cases} \frac{kQr}{R^3} & r < R \\ \frac{kQ}{r^2} & r > R \end{cases}$$

• <u>Infinite line</u>:

$$E = \frac{2k\lambda}{r}$$

• <u>Hollow infinite cylinder</u>: same for conducting/insulating;

$$E = \begin{cases} 0 & r < R \\ \frac{2k\lambda}{r} & r > R \end{cases}$$

- Solid infinite cylinder:
 - Conducting:

$$E = \begin{cases} 0 & r < R \\ \frac{2k\lambda}{r} & r > R \end{cases}$$

- Insulating:

$$E = \begin{cases} \frac{2k\lambda r}{R^2} & r < R\\ \frac{2k\lambda}{r} & r > R \end{cases}$$

• <u>Infinite sheet</u>:

$$E = \frac{\sigma}{2\epsilon_0}$$

• Parallel sheets:

$$E = \frac{\sigma}{\epsilon_0}$$

1.2 Electric Potential

1.2.1 Definitions

• Electric potential:

$$\Delta V = -\int_{-\infty}^{r} E \cdot dr$$

• <u>Work</u>:

$$W = -q \, \Delta V$$

• Point charge/generalization:

$$V = \frac{kQ}{r} = k \int \frac{dq}{r}$$

• Parallel plates:

$$V = -E \cdot s = Ed$$

1.2.2 V Derivations

• Above line of charge:

$$V = k\lambda \ln \left[\frac{L + (L^2 + d^2)^{1/2}}{d} \right]$$

• Ring of charge:

$$V = \frac{kQ}{(R^2 + x^2)^{1/2}}$$

• Disk of charge:

$$V = 2k\sigma\pi [(R^2 + x^2)^{1/2} - x]$$

1.2.3 V Derivations Using E

• Charged hollow sphere:

$$V = \begin{cases} \frac{kQ}{R} & r < R \\ \frac{kQ}{r} & r > R \end{cases}$$

• Charged solid insulating sphere, uniform ρ :

$$V = \begin{cases} \frac{3kQ}{2R} - \frac{kQr^2}{2R^3} & r < R\\ \frac{kQ}{r} & r > R \end{cases}$$

2 Circuits

2.1 Capacitance

2.1.1 Definitions

• Capacitance:

$$C = \frac{\epsilon_0 A}{d} = \frac{Q}{V} = \kappa C_0$$

• Energy: $E = \frac{1}{2}CV^2 = \frac{Q^2}{2C} = \frac{1}{2}QV$

2.1.2 CQVE Circuits

- <u>Series</u>:
 - $-C_{tot} < any C$

$$\frac{1}{C_{tot}} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3} + \dots$$

- Q same
- -V adds up
- <u>Parallel</u>:
 - $-C_{tot} > \text{any } C$

$$C_{tot} = C_1 + C_2 + C_3 + \dots$$

- V same
- -Q adds up

2.1.3 C Derivations

• Parallel plate:

$$C = \frac{\epsilon_0 A}{d}$$

• Cylindrical:

$$C = \frac{2\pi\epsilon_0 L}{\ln(\frac{r_o}{r_i})}$$

• Spherical shells:

$$C = 4\pi\epsilon_0 \frac{r_o r_i}{r_o - r_i}$$

• Isolated sphere:

$$C = 4\pi\epsilon_0 r_i$$

2.1.4 Dielectrics

$$E = \frac{E_0}{\kappa} \iff \int E \cdot dA = \frac{q_{enc}}{\kappa \epsilon_0}$$

2.2 VIRP Circuits

$$I = \frac{dQ}{dt} = n \, q \, v_d \, A$$

2.2.1 Kirchhoff's Rules

- 1. Loop Rule: $\Sigma V_{gains} = \Sigma V_{drops}$
 - Battery voltage = sum of voltages in loop connected to battery
- 2. Junction Rule: $\Sigma I_{in} = \Sigma I_{out}$
 - Current that enters junction must split between paths

2.2.2 Resistors

- Ohm's Law: $V = \varepsilon = IR$; $R = \frac{\rho l}{A}$
- Power: $P = IV = I^2R = \frac{V^2}{R}$
- Series:
 - $-R_{tot} > \text{any } R$

$$R_{tot} = R_1 + R_2 + R_3 + \dots$$

- I same
- V adds up
- <u>Parallel</u>:
 - $-R_{tot} < any R$

$$\frac{1}{R_{tot}} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \dots$$

- V same
- I adds up

2.2.3 *RC* Circuits

$$\tau = RC$$

1. Charging:

$$q = \varepsilon C \left(1 - e^{-t/\tau} \right)$$

$$I = I_{MAX} e^{-t/RC}$$

$$V_R = I_{MAX} R e^{-t/RC}$$

$$V_C = \varepsilon \left(1 - e^{-t/RC} \right)$$

2. Discharging:

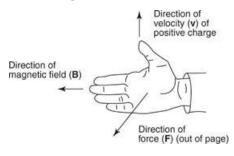
$$q = Q e^{-t/RC}$$

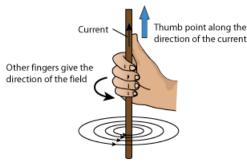
$$I_R = -I_{MAX} e^{-t/RC}$$

$$I_C = \frac{Q}{C} e^{-t/RC}$$

3 Magnetism

3.1 Right Hand Rule





Right Hand Grip Rule

3.2 Magnetic Force

- Charged particle: $\vec{F}_B = q (\vec{v} \times \vec{B})$
- Current-carrying wire: $\vec{F}_B = L(\vec{I} \times \vec{B})$
- Use right hand rule to determine direction; F_B , v, and B all mutually perpendicular

3.3 Biot-Savart

• Currents:

$$dB = \frac{\mu_0}{4\pi} \frac{I \, d\ell \, \sin \theta}{r^2}$$

• Point charges:

$$dB = \frac{\mu_0}{4\pi} \frac{q \, v \, \sin \theta}{r^2}$$

3.3.1 Biot-Savart Derivations

• Above finite wire:

$$B = \frac{\mu_0 I}{4\pi} \left(\sin \theta_R - \sin \theta_L \right)$$

• Above infinite wire:

$$B = \frac{\mu_0 I}{2\pi r}$$

• Above loop of wire:

$$B = \frac{\mu_0 I R^2}{2(R^2 + Z^2)^{3/2}}$$

3.4 Ampere's Law

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_0 \, I_{enc}$$

3.4.1 Ampere's Law Derivations

• Infinite cylinder:

$$B = \begin{cases} \frac{\mu_0 I r}{2\pi R^2} & r < R \\ \frac{\mu_0 I}{2\pi r} & r > R \end{cases}$$

• <u>Solenoid</u>:

$$B = \mu_0 \, NI$$

• Toroid:

$$B = \frac{\mu_0 NI}{2\pi r}$$

3.5 No Magnetic Monopoles

$$\oint \vec{B} \, \cdot \, d\vec{A} = 0$$

3.6 Faraday's Law

$$\varepsilon = -\frac{d\Phi_B}{dt} = -\frac{d}{dt}\int B\,\cdot\,dA = -N\,\frac{d\Phi_B}{dt} \ \ \text{if N turns}$$

$$\varepsilon = \oint \vec{E}\,\cdot\,d\vec{\ell}$$

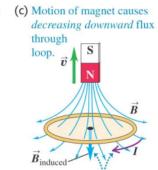
3.7 Magnetic Flux

 \bullet Lenz's Law: induced B and I act to oppose change

• Equation: $\Phi = \int \vec{B} \cdot d\vec{A}$

(a) Motion of magnet causes increasing downward flux through loop.

(b) Motion of magnet causes decreasing upward flux through loop.



(d) Motion of magnet causes increasing upward flux through loop.

3.8 Transformers

$$\frac{I_P}{I_S} = \frac{V_S}{V_P} = \frac{N_S}{N_P}$$

3.9 Motional EMF: Moving Rod

$$\varepsilon = B\ell v$$

3.10 Inductance

3.10.1 Definitions

• Inductance:

$$L = \frac{N\Phi_B}{I}$$

• Solenoid:

$$L = \mu_0 N^2 A \ell$$

• Toroid: H = toroid height, a, b are inner and outer radii

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$$L = \frac{\mu_0 N^2 H \ln(b/a)}{2\pi}$$

3.10.2 Circuits

• Self-Inductance/Back EMF:

$$\varepsilon_B = -L \, \frac{dI}{dt}$$

• Energy: $U = \frac{1}{2}LI^2$

3.10.3 LR Circuits

1. Rise of current: $\tau = L/R$

$$I = \frac{\varepsilon}{R} \left(1 - e^{-\frac{R}{L}t} \right) = I_{MAX} \left(1 - e^{-t/\tau} \right)$$

2. Decay of current:

$$I = I_{MAX} e^{-t/\tau}$$

3.10.4 LC Circuits

$$\frac{dI}{dt} + \frac{Q}{LC} = 0 \implies \frac{d^2Q}{dt^2} + \frac{Q}{LC} = 0$$

 $\omega^2 = \frac{1}{LC} \implies \text{ general solution with } \sin \omega t \text{ or } \cos \omega t$

4 Maxwell's Equations, Integral Form

<u>Gauss' Law for Electricity</u>: $\oint \vec{E} \cdot d\vec{A} = \frac{q_{enc}}{\epsilon_0} = \frac{1}{\epsilon_0} \int \rho \, dV$

Gauss' Law for Magnetism: $\oint \vec{B} \, \cdot \, d\vec{A} = 0$

<u>Faraday's Law</u>: $\oint \vec{E} \, \cdot \, d\vec{\ell} = -\frac{d\Phi_B}{dt} = -\frac{d}{dt} \, \int \vec{B} \, \cdot \, d\vec{A}$

<u>Ampere's Law*</u>: $\oint \vec{B} \cdot d\vec{\ell} = \mu_0 I_{enc}$