

| Grade                    |                | Excellent<br>(100%)  | Competent<br>(60%)   | Developing<br>(0%)   |
|--------------------------|----------------|--|--|--|
| Presentation<br>75 pts   | _____/75       | <ul style="list-style-type: none"> <li>• Complete discussion of robot design</li> <li>• Expected performance has been quantified, in terms of speed, and accuracy</li> </ul> | <ul style="list-style-type: none"> <li>• Incomplete discussion of design</li> <li>• Quantification of expected performance not convincing</li> </ul> | <ul style="list-style-type: none"> <li>• No discussion of design</li> <li>• No quantification of expected performance</li> </ul> |
| Team Documents<br>75 pts | _____/20       | <ul style="list-style-type: none"> <li>• Reflection Logs Completed</li> </ul>  | <ul style="list-style-type: none"> <li>• One team member has not completed reflection log</li> </ul>   | <ul style="list-style-type: none"> <li>• Multiple team members have not completed reflection log</li> </ul>                      |
|                          | _____/35       | <ul style="list-style-type: none"> <li>• Team agenda and minutes are completed and show team problems and progress</li> </ul>  | <ul style="list-style-type: none"> <li>• Team agenda and minutes partially completed</li> </ul>  | <ul style="list-style-type: none"> <li>• Team agenda and minutes mostly incomplete</li> </ul>                                    |
|                          | _____/20       | <ul style="list-style-type: none"> <li>• All team members have completed CATME</li> </ul>  | <ul style="list-style-type: none"> <li>• One team member has not completed CATME</li> </ul>  | <ul style="list-style-type: none"> <li>• Multiple team members have not completed CATME</li> </ul>                               |
|                          | Total:_____/75 |  |  |  |
| Total Doc: ____/150      |                |  |  |  |

**Performance**  
100 pts

Detect: \_\_\_\_\_  
Sense: \_\_\_\_\_  
Move: \_\_\_\_\_  
Total (max 100) \_\_\_\_\_/100

- Failures to detect the beacon: \_\_\_\_\_
- Reported angle: \_\_\_\_\_  
Actual angle: \_\_\_\_\_  
Error : \_\_\_\_\_
- Maximum distance from goal point: \_\_\_\_\_

- Total failures to detect a beacon: \_\_\_\_\_
- Average error in reported angle: \_\_\_\_\_
- Average distance error: \_\_\_\_\_

- Detect: Best team: \_\_\_\_\_
- Sense: Best team: \_\_\_\_\_
- Move: Best team: \_\_\_\_\_