GEOMLAB 2020

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1 Motivation

Motivated by the COVID-19 disease several outlets printed two-dimensional depictions of data which usually contained multidimensional datasets. These datasets usually compromise {infections, recoverd, death} rates with regard to the country and sometimes also the evolution over time.

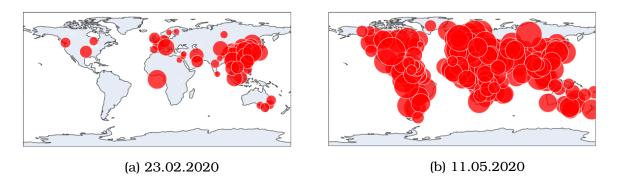


Figure 1: Comparison of a typical scatterplot depicting the *log* of confirmed cases as the radius.

In this lab we focus on depicting data in a meaningful way. Besides its quantitative nature this task has some qualitative properties. Similar to many solutions of problems in computational geometry, like deciding if a point is contained in a polygon or the construction of a convex hull for a set of points, the quality of the scatterplot is obvious to the human observer. Not so for a machine. While Fig. (1a) is highly informative for a human or potential policy maker, Fig. (1b) bears little information content. Despite this fact both figures result from the very same algorithm depicting data from the disease spread of COVID-19 during 2020 [Algo im Appendix].

To investigate the quantification of visual quality mainly Tufte in 1983 in *The visual display of quantitative information graphics press"* and Miller et al in *The Need For Metrics In Visual Information Analysis* provided fundamental work. Based on this, follow-up work and further considerations from visibility problems and sorting we develop a novel approach to visualize multidimensional data in a scatterplot which transports as much information content as possible.

2 Problem Statement and State of the Art

2.1 Problem statement and constraints

- 1. Represention and visibility of scatter plots with glyphs
- 2. Represention and visibility of multi-dimensional data in nested discs
- 3. Represention and visibility of pie charts glyphs
- 4. Represention and visibility of (one?) other type of glyphs

2.2 Previous work

1. See papers in Slack Channel

3 Methodology

3.1 Cost functions

- 1. Information content covered by the data,
- 2. information content of the data in the visualization,
- 3. information capacity of a visualization,
- 4. topological information content.

3.2 Selection of algorithms and complexity

- 1. Random inseration
- 2. Painter
- 3. MaxMinSumK/absolute Sum of visible circumference/hull
- 4. MaxMinSumK/weighted weighted such that big circles/glyphs not dominate
- 5. MaxMinSumK/relative Sum of relative circumference/hull
- 6. MaxMinMinK/absolute MaxMin of minimal visible circumference/hull of each circle/glyph
- 7. MaxMinMinK/relative

3.3 Optimalitaet fuer Pie Chart

Let D be a finite set and for $d \in D$ and $S \subseteq D$ the function $\phi(d,S) \mapsto \Re_{\geq 0}$ with the property, that for every $d \in D$ $S' \subseteq S => \phi(d,S') \geq \phi(d,S)$. Let the stacking-order $\pi : \{1,...,n\} \mapsto D$ be bijective.

Theorem 1. The algorithm

```
ALG(finite set D) {
   x := argmax_{d \in D} \phi(d, D \setminus {d})
   return [x, ALG(D \setminus {x})]
}
```

returns a stacking-order, which maximizes $min_{d \in D} \phi(d, \{d \in D | d' > d\})$.

Proof. Given an optimal stacking-order s and output of ALG s^* .

Roland: shouldn't it be 'minimizes'?

```
1. case: s = s^*. Done.
```

2. case: $s \neq s^*$. $s \neq s^*$ implies, that there is a lowest $k \in N$, such that $s(k) \neq s^*(k)$. Let $s(k) = d_k$ and $s^* = d_k^*$. Hence, $k^* = s^{-1}(s^*(k)) = s^{-1}(d_k^*)$ is the index of d_k^* with respect to s. It follows $k < k^*$.

We modify s such, that at point in time, we insert disc d_k^* and shift all others towards the end. Let this new stacking-order be s'.

Roland: What end, small or large end?

an order so it would be 'at position' as far as I see.

point in

'time'? It's

Comparing s and s', we find that s' selects all discs later. That means, that all ϕ -values are at least bigger.

Now d_k^* is chosen in s', as well as in s^* at position k. As d_k^* was chosen by s^* , d_k^* has to maxmize ϕ . Therefore, it is bigger or equal to d_k , as s and s^* are identical except at position k.

Roland: Argumentiere hier mit Position. Das macht mEn mehr Sinn. Warte auf Eure Kommentare.

Remark. ϕ may be the visible glyph boundary, the visible glyph boundary, the visible surface or the distance of..._

Roland: Proof stops.

- 1. Rotation
- 2. Physics/Heuristics based approaches

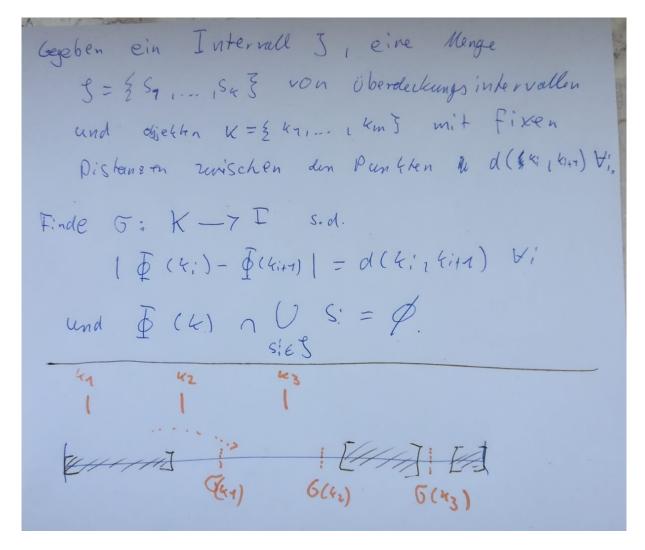
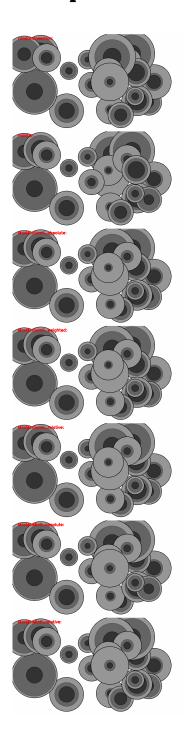
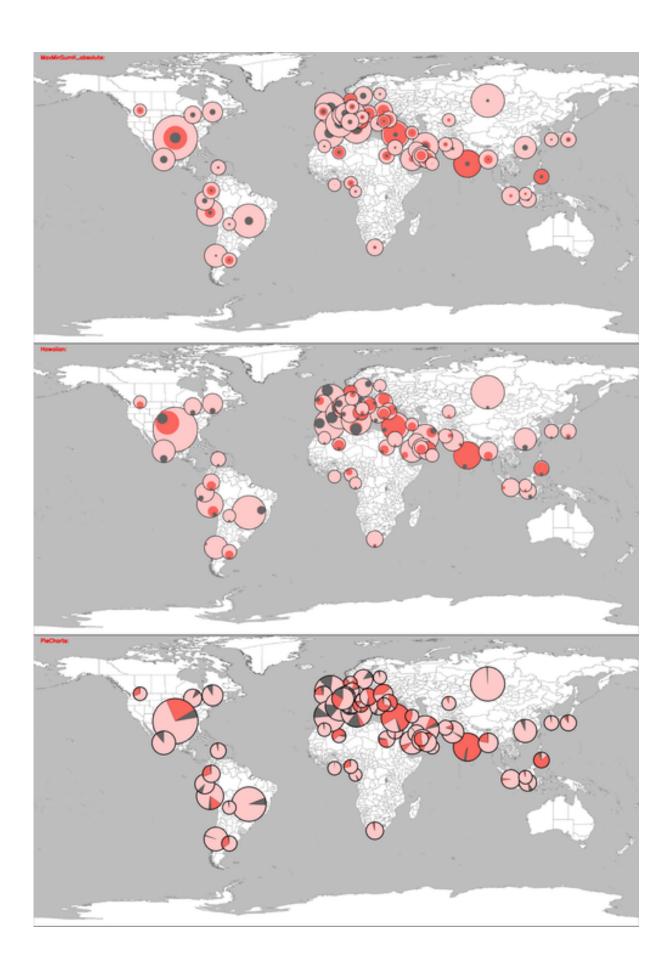
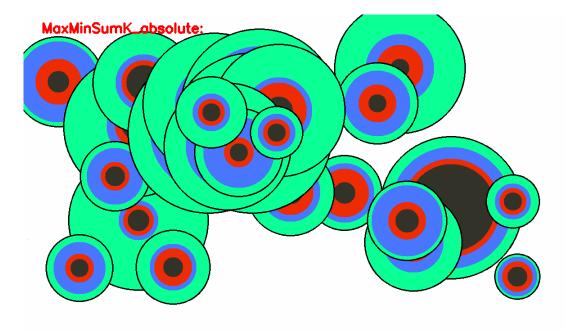


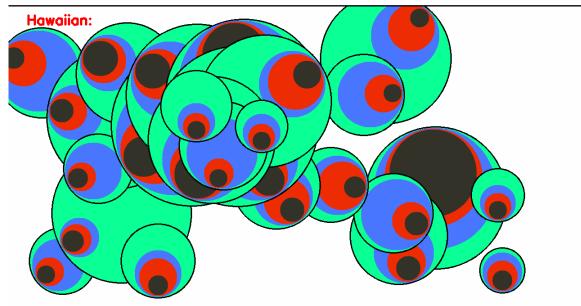
Figure 2: Trennlinienproblem

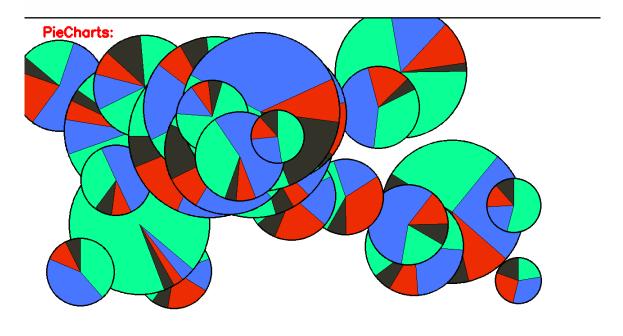
4 Experimental validation











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