

1 Formulation: Part I

Optimization equation

$$\min \sum_{k \in N} \sum_{i \in I} (\alpha \ln Q_i(k) + c(k) P_{0i}(k)) \quad (1)$$

$$\ln Q_i(k) = \ln(B) - \frac{E_A}{RT_i(k)} + z \ln \frac{W_{h,i}(k)}{V_i(k)} \quad \forall k \in 1..N, i \in 1..I \quad (2)$$

$$W_{h,i}(k+1) = W_{h,i}(k) + |p_{b,i}(k)| \Delta t \quad \forall k \in 1..N, i \in 1..I \quad (3)$$

$$E_i(k+1) = E_i(k) - p_{b,i}(k) \Delta t \quad \forall k \in 1..N, \forall i \in 1..I \quad (4)$$

$$P_{0i}(k) = d(k) - p_{b,i}(k) \quad \forall k \in 1..N, \forall i \in 1..I \quad (5)$$

$$\sum_{i \in I} P_{0i}(k) \leq G(k) \quad \forall k \in 1..N, \forall i \in 1..I \quad (6)$$

$$E_{\min} \leq E_i(k) \leq E_{\max} \quad \forall k \in 1..N, i \in 1..I \quad (7)$$

$$0 \leq W_{h,i}(k) \leq W_{h,\max} \quad \forall k \in 1..N, i \in 1..I \quad (8)$$

$$-P_{\text{batt}, \max} \leq p_{b,i}(k) \leq P_{\text{batt}, \max} \quad \forall k \in 1..N, i \in 1..I \quad (9)$$

2 Temperature dynamics

$$\rho C V_B \dot{T}_i(k) = h A_s (T_i(k) - T_\infty) + R_B \left(\frac{p_{b,i}(k)}{V_i(k)} \right)^2 \quad \forall k \in 1..N, i \in 1..I \quad (10)$$

$$T_i(k) + \dot{T}_i(k) \Delta t = T_i(k+1) \quad \forall k \in 1..N, i \in 1..I \quad (11)$$

$$T_{\min} \leq T_i(k) \leq T_{\max} \quad \forall k \in 1..N, i \in 1..I \quad (12)$$

$$V_i(k) = V_{oc,i}(k) - I_i(k) R_B \quad \forall k \in 1..N, i \in 1..I \quad (13)$$

$$Q_{\text{cap}, i}(k) = Q_{\max} (1 - Q_i(k)) \quad \forall k \in 1..N, i \in 1..I \quad (14)$$

$$0 \leq I_i(k) \leq I_{\max} \quad \forall k \in 1..N, i \in 1..I \quad (15)$$

3 DP Formulation

Let $V(k)$ represent the cumulative capacity fade and power generation from time step k to total time N . We define control variables $I_i(k)$ as $u_k \forall i$ and state variables $T_i(k)$ as $x_k \forall i$:

$$V_k(x_k) = \min_{u_k, x_k} \left\{ \sum_{i \in I} \left(\alpha \cdot Q_i(k) + c(k) \cdot (d_i(k) - u_i(k)) \right) + V(k+1) \right\} \quad \forall k \in 1..N \quad (16)$$

We finally establish the boundary condition:

$$V(N+1) = 0$$