Rohit Sengar, MASc

sengarr@uwindsor.ca
863984b1/

□ +1-226-759-5742

in http://www.linkedin.com/in/rohit-sengar-

Highlights

- Fast Learner
- Always Curious about learning new things
- Diverse Knowledge
- Highly Motivated and Work Enthusiastic
- Punctual and Smart Worker
- Good Communication Skills and Experienced in Team Lead

Employment History

Jan 2021 - May 2021

General Labour. Topline Farms

May 2021 - September 2021

- **General Labour**. Exkkor Manufacturing
- - **Research Assistant at BMS Lab**, University of Windsor.

July 2022- Dec 2022

- **Research Assistant at BMS Lab**, University of Windsor.
- Feb 2023 Oct 2023
- Systems Engineer at Stellantis (Fiat Chrysler Automobiles)
- Oct 2023 June 2024
- State Estimation Data Engineer at Stellantis(Fiat Chrysler Automobiles)

Education

Jan 2021 – May 2022

M.A.Sc., Electrical and Computer Engineering, University of Windsor.
Thesis title: Analysis and Improvement of Electrochemical Impedance Spectroscopy.

Sept 2015 - July 2019

B.E., Mechanical Engineering, Aligarh Muslim University. CGPA: 8.3/10.

Sept 2012 - July 2015

Diploma, Mechanical Engineering, Aligarh Muslim University. Percentage: 83/100.

Skills

Design and Simulation Softwares

■ IBM Rhapsody, AutoDesk 360, SOLIDWORKS, Ansys, Solid EDGE, NX Unigraphics

Manufacturing Skills

PCB Printing, Soldering, and 3D Printing (Ender 3 v2)

Software Skills

PLC Programming (Allen Bradley and Siemens), Proteus, Xlink, MatLab, Simulink and State Flow, Python, C, Latex, HDL, Mits Proby Arbin, Gamry Framework.

Hardware Skills

Aurdino, Raspberry Pi, ESP32

Technical Skills

Data Analysis, Data Collection, Experiment Design, Machine Learning, Mathematical Techniques for Estimation, Frequency Domain Analysis, Time Domain Analysis, Control Techniques

Communication Skills

CAN communication, LIN Communication, Ethernet communication and I2C

State Estimation Data Engineer Projects

- **Enhancement of 2RC model of Battery** Added Hysteresis Component on top of normal 2RC Model Implemented that in the Prototype and Production Software
- Handling bugs related to Battery Management System Software minor bugs which affect the estimation were captured using vehicle data and corrected
- Development of Model in Loop Environment for testing SOX estimation algorithm Matlab (Simulink) model was developed for estimating State of Charge, State of Health, State of Power in noise scenarios by injecting noise to the plant model

Systems Engineer Projects

■ Implementation of Secure Idle feature

Broke Down requirements to secure the vehicle whenever Power Panel is used

Select Speed Control feature

Implementation of Select Speed Control feature for low speed off-road functions

Limiting vehicle Speed When Power Frunk is left open

Identifying the Scenarios when Power Frunk is open or popped up

Generation of CAN Signals to identify both conditions

Limiting the Speed when both scenarios are open

Radio based Park and Neutral gear shifting of Vehicle

Taking inputs from Radio for Park and Neutral Conditions

Generating Control Strategies to use inputs from vehicle when Gear Shifter is faulted

Control Projects

Control System of Tesla for the study of regenerative braking (Jan 2021 - April 2021)

Used a PID controller to account for acceleration and braking

Used a simple and effective braking control strategy to switch between regenerative and friction braking Made a Simulink-Simscape model

Compared the energy and range (with or without regenerative braking)

Optimised Control system of 2 gear transmission for effective torque-speed performance (May 2021

- September 2021)

Study the effect of Single and 2 gear transmission system

Optimization of transmission system based on acceleration, grading and top speed constraints using Genetic Algorithm

Comparison of Optimized and Non-Optimized Gear Ratios

Control System Design for Antilock Braking System (Jan 2022 - April 2022)

Designed an LQR controller for braking of vehicle

Compared LQR controller with rule based controller

Design Projeccts

Design and Fabrication of Autonomous Underwater Vehicle for SAUVC 2018

Designed an Autonomous Underwater Vehicle (AUV) in SOLIDWORKS

Fabricated two custom battery packs with 22.2 V and 9.9 Ah power.

Leak proofing of AUV such that all electronics doesn't get damaged.

Programming of thrusters, IMU, Pressure Sensor using Raspberry Pi

Designing and fabricating PCBs using iron-printing and ferric chloride technique

Tested the Vehicle at controlled performance tests in swimming pool

Remotely Operated Underwater Vehicle

Fabricated a Remotely Operated Underwater Vehicle for demonstration purposes in order to gather funds for SAUVC competetion

Used two thrusters and programmed using Aurdino.

Projects (continued)

Design and Simulation of Underwater Torpedoes

Used hit and try methods to design and simulate the torpedo in ansys fluent

Power Electronics Projects

Development of battery charger using PI control of Tapped-inductor Cuk converter (24V 4 Amp) (September 2022-Dec 2022)

Used the equations of Tapped-inductor bi-directional Cuk converter to write its transfer function Designing a PI controller to have current and voltage control

Programming the charging logic in simulink and converting it to HDL.

Designing and testing of Circuit in Proteus followed by printing PCB and soldering of components.

Diploma

Remotely Operated Underwater Vehicle with Rotatable Thrusters

Fabricated our own thrusters using brushless motor and CPU fans Controlled the thrusters and servo motors using Servo Testers Make a full control board of 2 thrusters and two servo motors for multiple motions

Projects for fun

- Piano in Matlab operated using keyboard
- Python app for managing details of Multiple Projects
- HDL code generation of SOC Estimation in batteries using Matlab and Simulink

Research Publications

Journal Articles

- M. Abaspour R. Sengar, P. K. B. S. B. B. (2022). Robust approach to battery equivalent circuit model parameter extraction using electrochemical impedance spectroscopy. *IEEE -TMECH (Under Review)*.
- R. Sengar, S. S., B. Balasingam. (2022). Battery parameter analysis through electrochemical impedance spectroscopy at different state of charge levels. MDPI-JLPEA (Under Review).

Patents Publications

- 6 PIN UNDERWATER ELECTRICAL CONNECTOR. (2018, September 14) 201811027144 A.
- A LOW COST AUTONOMOUS UNDERWATER VEHICLE (AUV) HAVING FIVE DEGREES OF FREEDOM AND MINIMUM OF TWO THRUSTERS. (2018, September 14) 201911014948 A.
- 3 CLUTCH CUM ACCELERATOR. (2018, September 7) 201811027149 A.

Achievements

Won People's Choice Award in SAUVC 2018

Most Proud Of

Founding Member of MTS AUV ZHCET Club (https://www.mtsauvzhcet.com/)