

SM5083 - BASICS OF PROGRAMMING

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Abstract—This paper contains solution to problem no 5 of Examples III Section of Chapter III of Analytical Geometry by Hukum Chand. Links to Python codes are available below.

Download python codes at

<https://github.com/rsgirishkumar/SM5083/ASSIGNMENT2>

1 PROBLEM

The opposite vertices of a square are $\begin{pmatrix} 0 \\ -1 \end{pmatrix}, \begin{pmatrix} 0 \\ 3 \end{pmatrix}$. Find the equations of four sides.

2 SOLUTION

Let the given points are indicated as below

$$\mathbf{A} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}, \mathbf{C} = \begin{pmatrix} 0 \\ 3 \end{pmatrix}. \quad (2.0.1)$$

Let the unknown vertices are indicated as \mathbf{B}, \mathbf{D} . The step by step procedure involves

- 1) By doing affine transformation steps i.e Translation and Rotation of the given vertices \mathbf{A} and \mathbf{C} those provide \mathbf{A}' and \mathbf{C}' for the ease of solution
- 2) Find the diagonal \mathbf{AC} .
- 3) Find the norm of \mathbf{AC} .
- 4) Find the points \mathbf{B} and \mathbf{D} by using inspection method and reverse affine transformation.
- 5) Form the equations of lines using vertices.

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2.1 AFFINE TRANSFORMATION

Translation

$$\begin{aligned} \mathbf{A} &= \begin{pmatrix} 0 \\ -1 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \\ \mathbf{C} &= \begin{pmatrix} 0 \\ 3 \end{pmatrix} + \begin{pmatrix} 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 4 \end{pmatrix}. \end{aligned} \quad (2.1.1)$$

Rotation The rotation is by 45° clock wise. The rotation matrix is given by

$$\begin{aligned} &\begin{pmatrix} \cos(-45^\circ) & -\sin(-45^\circ) \\ \sin(-45^\circ) & \cos(-45^\circ) \end{pmatrix} \\ \Rightarrow \mathbf{A}' &= \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \\ \Rightarrow \mathbf{C}' &= \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 0 \\ 4 \end{pmatrix} = \begin{pmatrix} 2\sqrt{2} \\ 2\sqrt{2} \end{pmatrix}. \end{aligned} \quad (2.1.2)$$

Step-1: Diagonal $\mathbf{A}'\mathbf{C}'$

$$\mathbf{A}'\mathbf{C}' = \begin{pmatrix} 2\sqrt{2} - 0 \\ 2\sqrt{2} - 0 \end{pmatrix} = \begin{pmatrix} 2\sqrt{2} \\ 2\sqrt{2} \end{pmatrix} \quad (2.1.3)$$

The line equation of $\mathbf{A}'\mathbf{C}'$ is $x-y=0$ or simply $x=y$.

Step-2: Norm of $\mathbf{A}'\mathbf{C}'$

$$\|\mathbf{A}'\mathbf{C}'\| = \sqrt{(2\sqrt{2})^2 + (2\sqrt{2})^2} = 4 \quad (2.1.4)$$

Step-3: The angle between line $\mathbf{A}'\mathbf{B}'$ and $\mathbf{A}'\mathbf{C}'$ will be 45° . Hence, the line equation will be $y=0$. The angle between line $\mathbf{A}'\mathbf{D}'$ and $\mathbf{A}'\mathbf{C}'$ will be 45° . Hence, the line equation will be $x=0$.

Length of any side $s = \frac{\|\mathbf{A}'\mathbf{C}'\|}{\sqrt{2}} = 2\sqrt{2}$.

By inspection method, using length of a side, the vertices \mathbf{B}' and \mathbf{D}' can be found.

$$\begin{aligned} \mathbf{B}' &= \begin{pmatrix} 0 + 2\sqrt{2} \\ 0 \end{pmatrix} = \begin{pmatrix} 2\sqrt{2} \\ 0 \end{pmatrix} \\ \mathbf{D}' &= \begin{pmatrix} 0 \\ 0 + 2\sqrt{2} \end{pmatrix} = \begin{pmatrix} 0 \\ 2\sqrt{2} \end{pmatrix} \end{aligned} \quad (2.1.5)$$

Hence the vertices are

$$\mathbf{A}' = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \mathbf{B}' = \begin{pmatrix} 2\sqrt{2} \\ 0 \end{pmatrix}, \mathbf{C}' = \begin{pmatrix} 2\sqrt{2} \\ 2\sqrt{2} \end{pmatrix}, \mathbf{D}' = \begin{pmatrix} 0 \\ 2\sqrt{2} \end{pmatrix}. \quad (2.1.6)$$

2.2 REVERSE AFFINE TRANSFORMATION

Rotation The rotation is by 45° counter clock wise. The rotation matrix is given by

$$\begin{aligned} & \begin{pmatrix} \cos(45^\circ) & -\sin(45^\circ) \\ \sin(45^\circ) & \cos(45^\circ) \end{pmatrix} \\ \Rightarrow \mathbf{A}' &= \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \\ \Rightarrow \mathbf{B}' &= \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 2\sqrt{2} \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ 2 \end{pmatrix} \\ \Rightarrow \mathbf{C}' &= \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 2\sqrt{2} \\ 2\sqrt{2} \end{pmatrix} = \begin{pmatrix} 0 \\ 4 \end{pmatrix}. \\ \Rightarrow \mathbf{D}' &= \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 0 \\ 2\sqrt{2} \end{pmatrix} = \begin{pmatrix} -2 \\ 2 \end{pmatrix} \end{aligned} \quad (2.2.1)$$

Translation

$$\begin{aligned} \mathbf{A} &= \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \end{pmatrix} \\ \mathbf{B} &= \begin{pmatrix} 2 \\ 2 \end{pmatrix} + \begin{pmatrix} 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} \\ \mathbf{C} &= \begin{pmatrix} 0 \\ 4 \end{pmatrix} + \begin{pmatrix} 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 3 \end{pmatrix}. \\ \mathbf{D} &= \begin{pmatrix} -2 \\ 2 \end{pmatrix} + \begin{pmatrix} 0 \\ -1 \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \end{pmatrix} \end{aligned} \quad (2.2.2)$$

2.3 LINE EQUATIONS

Coordinates are

$$\mathbf{A} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}, \mathbf{B} = \begin{pmatrix} -2 \\ 1 \end{pmatrix}, \mathbf{C} = \begin{pmatrix} 0 \\ 3 \end{pmatrix}, \mathbf{D} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}. \quad (2.3.1)$$

When two coordinates $\begin{pmatrix} X_1 \\ Y_1 \end{pmatrix}, \begin{pmatrix} X_2 \\ Y_2 \end{pmatrix}$ are given, then the line equation is given by

$$\frac{(Y - Y_1)}{(Y_2 - Y_1)} = \frac{(X - X_1)}{(X_2 - X_1)} \quad (2.3.2)$$

and on comparison with the form $ax+by+c=0$,

$$\begin{aligned} a &= Y_2 - Y_1, \\ b &= X_1 - X_2, \\ c &= -(Y_2 - Y_1) * X_1 + ((X_2 - X_1) * Y_1) \end{aligned} \quad (2.3.3)$$

In Matrix form, $\mathbf{PT}_1 = \begin{pmatrix} X_1 \\ Y_1 \end{pmatrix}, \mathbf{PT}_2 = \begin{pmatrix} X_2 \\ Y_2 \end{pmatrix}$ and vector $\mathbf{DV}_1 = \mathbf{PT}_2 - \mathbf{PT}_1 = \begin{pmatrix} X_2 - X_1 \\ Y_2 - Y_1 \end{pmatrix}$ then,

$$\begin{aligned} a &= \mathbf{DV}_1[1], \\ b &= -\mathbf{DV}_1[0], \\ c &= (\mathbf{PT}_1[1] \quad -\mathbf{PT}_1[0]) (\mathbf{DV}_1.T) \end{aligned} \quad (2.3.4)$$

By using the same, the line equation **AB** for points $\mathbf{A} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}, \mathbf{B} = \begin{pmatrix} -2 \\ 1 \end{pmatrix}$ is as follows:

$$\begin{aligned} \mathbf{AB} &= \begin{pmatrix} -2 \\ 2 \end{pmatrix} \\ a &= 2, \quad b = 2, \\ c &= (-1 \quad 0) \begin{pmatrix} -2 \\ 2 \end{pmatrix} = 2 \end{aligned} \quad (2.3.5)$$

Line equation for **AB**

$$\Rightarrow 2x + 2y + 2 = 0 \text{ or } x + y = -1. \quad (2.3.6)$$

In vector form

$$\Rightarrow \begin{pmatrix} 1 & 1 \end{pmatrix} \mathbf{X} = -1 \quad (2.3.7)$$

The line equation **BC** for points $\mathbf{B} = \begin{pmatrix} -2 \\ 1 \end{pmatrix}, \mathbf{C} = \begin{pmatrix} 0 \\ 3 \end{pmatrix}$ is as follows:

$$\begin{aligned} \mathbf{BC} &= \begin{pmatrix} 2 \\ 2 \end{pmatrix} \\ a &= 2, \quad b = -2, \\ c &= \begin{pmatrix} 1 & 2 \end{pmatrix} \begin{pmatrix} 2 \\ 2 \end{pmatrix} = 6 \end{aligned} \quad (2.3.8)$$

Line equation for **BC**

$$\Rightarrow 2x - 2y + 6 = 0 \text{ or } x - y = -3. \quad (2.3.9)$$

In vector form

$$\Rightarrow \begin{pmatrix} 1 & -1 \end{pmatrix} \mathbf{X} = -3 \quad (2.3.10)$$

The line equation **CD** for points $\mathbf{C} = \begin{pmatrix} 0 \\ 3 \end{pmatrix}$, $\mathbf{D} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ is as follows:

$$\begin{aligned} \mathbf{CD} &= \begin{pmatrix} 2 \\ -2 \end{pmatrix} \\ a &= -2, \quad b = -2, \\ c &= \begin{pmatrix} 3 & 0 \end{pmatrix} \begin{pmatrix} 2 \\ -2 \end{pmatrix} = 6 \end{aligned} \quad (2.3.11)$$

Line equation for **CD**

$$\Rightarrow -2x - 2y + 6 = 0 \text{ or } x + y = 3. \quad (2.3.12)$$

In vector form

$$\Rightarrow \begin{pmatrix} 1 & 1 \end{pmatrix} \mathbf{X} = 3 \quad (2.3.13)$$

The line equation **DA** for points $\mathbf{D} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$, $\mathbf{A} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$ is as follows:

$$\begin{aligned} \mathbf{DA} &= \begin{pmatrix} -2 \\ -2 \end{pmatrix} \\ a &= -2, \quad b = 2, \\ c &= \begin{pmatrix} 1 & -2 \end{pmatrix} \begin{pmatrix} -2 \\ -2 \end{pmatrix} = 2 \end{aligned} \quad (2.3.14)$$

Line equation for **DA**

$$\Rightarrow -2x + 2y + 2 = 0 \text{ or } x - y = 1. \quad (2.3.15)$$

In vector form

$$\Rightarrow \begin{pmatrix} 1 & -1 \end{pmatrix} \mathbf{X} = 1 \quad (2.3.16)$$

The plotted graph is shown as below.

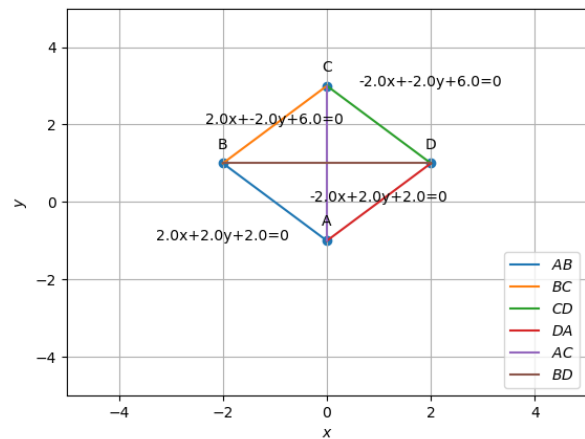


Fig. 5: Square ABCD