

AP[®] Physics C 1985 Scoring Guidelines

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Mechanics		Distribution
Mech. 1. (a)	5 points	of points
11100011 11. (0)	$v_{0y} = (50 \text{ m/s}) \sin 37^\circ = (50 \text{ m/s}) (.60) = 30 \text{ m/s}$	l point .
	$y = y_0 + v_{0y}t + \frac{1}{2}at^2$	l point
	•	, pour
	$0 = (35 \text{ m}) + (30 \text{ m/s})t - \frac{1}{2} (10 \text{ m/s}^2)t^2$	2 points
	(1 point for $y = 0$, 1 point for correct substitutions on right-hand side)	
	For corretion solution, $t = 7 s$	1 point
*	Full credit was given for alternate equivalent solutions.	
(b)	3 points	٠.
•	$R = v_{0x}t$	l point
	$R = (50 \text{ m/s}) (\cos 37^\circ) (7 \text{ s})$ (i.e., for correct substitution)	
	For correct solution, $R = 280 \text{ m}$	l point
	5 points	
	$v_A = v_{0x} = 40 \text{ m/s}$	l point
	$v_{s} = v_{0} = 50 \text{ m/s}$	l point
	For v_C : For any mention of energy	l point
*	For conserving energy	l point
*	$\frac{1}{2} m v_C^2 = \frac{1}{2} m v_0^2 + mgh$	
•	$v_C = \sqrt{v_0^2 + 2gh}$	* *
# Y	$= \sqrt{(50 \text{ m/s})^2 + 2(10 \text{ m/s}^2)(35 \text{ m})} = \sqrt{3200 \text{ m}^2/\text{s}^2}$	
	$v_C = 56.6 \text{ m/s}$	1 point
•	Full credit was given for alternate equivalent solutions	. ,
	(e.g., if time of travel from point B to point C is	
	known from part (a), kinematic equations can be used)	• •
(d)	2 minte	
	2 points For any use of momentum or content of more	1 mains
	For any use of momentum or center of mass $x (10 \text{ kg}) = (30 \text{ m}) (6 \text{ kg})$	1 point
	x = 18 m	l point
	A CONTRACTOR OF THE PROPERTY O	•
Mech. 2. (a)		
known total	$f_s = \mu_s N$	l point
	$f_1 = mg \sin \sigma \text{ or } w \sin \sigma$	l point
	$N = mg \cos \theta \text{ or } w \cos \theta$	l point
2000 (12), 20 11 € \$ \$15 (14)	$\mu_s = \frac{f_s}{N} = \frac{mg \sin \theta}{mg \cos \theta} = \tan \theta$	2 points
· · · · · · · · · · · · · · · · · · ·	Alternate solution using $F = ma$: (A	lternate points)
	$N - mg \cos \theta = 0$	
	$f_s - mg \sin \theta = ma$	(1 point)
	$f_{i} = \mu_{i} N^{(f_{i})}$	(1 point)
	μ_{μ} mg cos θ – mg sin θ = ma	,
		26
	$\mu_{r} = \frac{mg \sin \theta + ma}{mg \cos \theta} = \tan \theta + \frac{a}{g \cos \theta}$	(1 point)
		(1 point)
e de la composición dela composición de la composición dela composición de la composición de la composición dela composición dela composición de la composic		/- F
•		

* * ...

Distribution of points

l point

2 points

2 points

1 point

l point

2 points

l point

(b) 5 points
$$\Delta E = \Delta K + \Delta U$$
The initial and final points are at the highest point on the incline and the point of full spring compression,

on the incline and the point of full spring compression, respectively.

$$\Delta K = 0$$

$$\Delta U = \Delta U_{\text{gravity}} + \Delta U_{\text{spring}}$$

$$\Delta U_{\text{spring}} = -\frac{1}{2}kx^2$$

$$\Delta E = mg(d+x)\sin\theta - \frac{1}{2}kx^2$$

 $\Delta U_{\text{gravity}} = mgh = mg(d + x) \sin \theta$

I point was deducted if the student did not write down the final expression for
$$\Delta E$$
.

2 points were awarded if the student tried to solve this part using frictional force and showed
$$\Delta E = f_k(d+x) \text{ or } \Delta E = \mu_k N(d+x) \text{ or } \Delta E = \mu_k mg \cos\theta (d+x)$$

$$\Delta E = f_k(d+x) \text{ or } \Delta E = \mu_k N(d+x) \text{ or } \Delta E = f_k(d+x)$$
(c) 5 points

$$f_k = \mu_k N$$

$$\mu_k N(d+x) = mg \sin \theta (d+x) - \frac{1}{2}kx^2$$
I point was deducted if the force of (d+x)

I point was deducted if the factor of
$$(d + x)$$
 was missing from left hand side.

$$N = mg \cos \theta$$

$$\mu_k = \frac{mg \sin \theta (d+x) - \frac{1}{2}kx^2}{mg \cos \theta (d+x)}$$

$$\mu_k = \tan \theta - \frac{kx^2}{2(d+x)mg \cos \theta}, \text{ or }$$

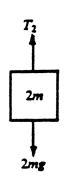
$$\mu_k = \mu_k - \frac{kx^2}{2(d+x)mg \cos \theta}$$

 $W_{\text{fric}} = \Delta E = f_k(d+x)$

Since
$$\mu_k < \mu_s$$
, the minus sign in the above expression is important. If the signs were interchanged in this expression, 1 point was deducted.

Mech. 3. (a) 4 points





For indicating tension vectors

1 point
For indicating weight vectors

1 point
For indicating different tensions on each block
1 point
For indicating different weights for each block
1 point
(The last 2 points were also awarded if such indications were made in the solution of subsequent parts.)

(b) 5 points

3

i. For applying
$$F = ma$$
 1 point
$$T_1 - mg = ma$$
 1 point
$$2mg - T_2 = 2ma$$
 1 point
The sign of the applemation is arbitrary in these

The sign of the acceleration is arbitrary in these two equations.

ii.
$$I\alpha = (T_2 - T_1)r$$
 2 points
1 point for torque = $I\alpha$
1 point for torque = $(T_2 - T_1)r$

(c) 3 points

For using the system of three equations obtained in part (b)

$$T_{1} = m(g + a)$$

$$T_{2} = 2m(g - a)$$

$$T_{2} = \frac{3}{2}mr^{2}\frac{a}{r} = (mg - 3ma)r$$

$$a = \frac{2}{9}g$$
 1 point

(d) 1 point

$$T_1 = m(g + a) = m(g + \frac{2}{9}g) = \frac{11}{9}mg$$
 1 point

Full credit was awarded for answer that was consistent with previous work.

Distribution of points

(e) 2 points

 $N = 7mg + T_1 + T_2$ or a clear indication that the normal force is different from the static weight

l point

$$T_2 = 2m\left(g - \frac{2}{9}g\right) = \frac{14}{9}mg$$

$$N = 7mg + \frac{11}{9}mg + \frac{14}{9}mg = \frac{88}{9}mg$$

1 point

Electricity and Magnetism

E&M 1. (a) 4 points

$$\int \vec{E} \cdot d\vec{A} = q/\epsilon_0 \text{ or } 4\pi kq$$

$$E(2\pi r L) = q/\epsilon_0 \text{ or } 4\pi kq$$

$$E = \frac{q}{2\pi \epsilon_0 r L} \text{ or } \frac{2kq}{r L}$$
2 points
1 point
1 point

(b) 5 points

$$V = -\int_{-\infty}^{\infty} \vec{E} \cdot \vec{dt}$$
 ($V = \int E dt$ was acceptable) 2 points

$$V = -\int_{a}^{b} \frac{q}{2\pi\epsilon_{0}L} \frac{dr}{r}$$
 1 point

$$V = -\frac{q}{2\pi\epsilon_0 L} [\ln r]_b^a$$
 1 point

$$V = \frac{q}{2\pi\epsilon_0 L} \ln\left(\frac{b}{a}\right) \text{ or } \frac{2kq}{L} \ln\left(\frac{b}{a}\right)$$
 1 point

No deduction was taken for reversal of limits of integration.

(c) 3 points

$$C_0 = \frac{q}{V}$$
 2 points
$$C_0 = \frac{2\pi\epsilon_0 L}{\ln(b/a)} \text{ or } \frac{L}{2k \ln(b/a)}$$
 1 point

1 point was deducted if the value of C_0 was negative, as would be the case if the expression contained $\ln (a/b)$.

(d) 3 points

1

$$C = C_1 + C_2$$
 or the capacitors are parallel 1 point
$$C_1 = k \frac{1}{3} C_0 = \frac{2}{3} C_0$$
 1 point
$$C_2 = \frac{2}{3} C_0$$
 1 point
$$C = \frac{4}{3} C_0$$

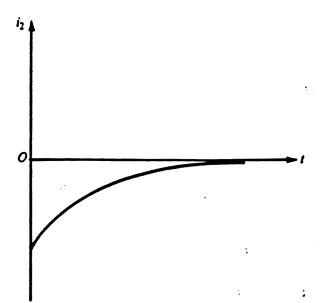
Full credit was awarded for correct final answer, regardless of the method used by the student.

1968 Physics C Solutions	
	Distribution of points
E&M 2. (a) 3 points $V = iR$ or equivalent (may appear here or in part (c)). For correct substitutions, $V = 3000 \text{ V}$ and $R = 5 \times 10^5 \Omega$. For correct answer, $i_1 = .006 \text{ A}$	l point l point l point
(b) 3 points	
0	;
For starting curve at the origin For showing V_2 asymptotic to a positive final value For showing V_2 monotonically increasing and exponential	l point l point l point
(c) 2 points $i_1 = i_2 \text{ or } \frac{V}{R} = \frac{3000 \text{ V}}{15 \times 10^5 \Omega} \text{ or a statement indicating the series nature of the circuit in this situation}$ For correct answer, $i_2 = .002 \text{ A}$	1 point
(d) 2 points $Q = CV \text{ and/or } V = 2000 \text{ V}$ For correct answer, $Q = .01 \text{ C}$	í point l point
(e) 2 points $U = \frac{1}{2}QV \text{ or equivalent}$	l point

l point

For correct answer, U = 10 J

(f) 3 points



Distribution of points

For non-zero initial value For showing i2 asymptotic to zero

For showing i_2 monotonically approaching the final value and exponential.

1 point

1 point

1 point

1 point was deducted if parts (a) and (c) were both correct but no work was shown.

I point was awarded if at least one graph showed an exponential form and no other points were available.

E&M 3. (a) 5 points

$$\mathcal{E} = -\frac{d\Phi}{dt} \text{ (negative sign not required)}$$

$$\Phi = BA$$
2 points
1 point

$$\frac{d\Phi}{dt} = \frac{dB}{dt}A$$

$$\frac{\partial}{\partial t} = \frac{\partial}{\partial t} A$$

$$A = \pi r^2$$
 1 point

$$\mathcal{E} = \frac{dB}{dt} \pi r^2 = (60 \text{ T/s})\pi (.5 \text{ m})^2 = 15\pi \text{ V} = 47 \text{ V}$$

1 point

1 point

1 point

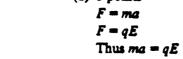
(b) 4 points

For showing
$$\vec{E}$$
 directed to the left at point P on diagram 1 point $E = Ed$ 1 point $d = 2\pi r$ 1 point $E = \frac{E}{d} = \frac{E}{2\pi r} = \frac{47 \text{ V}}{2\pi (.5 \text{ m})} = 15 \text{ V/m}$ 1 point

(c) 3 points
$$F = \frac{mv^2}{r}$$
1 point

$$F = qvB$$
Thus $\frac{mv^2}{r} = qvB$

$$v = \frac{qrB}{m} = \frac{(1.6 \times 10^{-19} \text{ C})(.5 \text{ m})(10^{-4} \text{ T})}{9.11 \times 10^{-31} \text{ kg}} = 8.8 \cdot 10^6 \text{ m/s}$$
 1 point



Thus
$$ma = qE$$

$$a = \frac{qE}{m} = \frac{(1.6 \times 10^{-19} \text{ C})(15 \text{ V/m})}{9.11 \times 10^{-31} \text{ kg}} = 2.6 \times 10^{12} \text{ m/s}^2$$

I point was awarded for merely stating that $a = \frac{dv}{dt}$

1 point