

AP[®] Physics C 1978 Scoring Guidelines

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b) Partial credit:

3

$$L = \frac{n}{2} \lambda$$

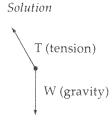
$$\lambda = \frac{2L}{n}$$

1978 C: Mech.-1

Distribution of Points

1

a) 3 points



Each force with correct direction

If no extraneous forces were shown 1

b) 7 points

T
$$\cos \theta = mg$$
 2
(1 point for any use of F = ma)

T $\sin \theta = ma$ 1
$$= m\omega^{2}r$$
 1
$$= m\omega^{2} (A + \ell \sin \theta)$$
 1

$$mg \tan \theta = m\omega^2 (A + \ell \sin \theta)$$

$$\omega = \sqrt{\frac{g \tan \theta}{A + \ell \sin \theta}}$$

Alternate:

$$\tan \theta = \frac{m\omega^2 r}{mg} = \frac{\omega^2 r}{g}$$

$$g \tan \theta = \omega^2 (A + \ell \sin \theta)$$
2

etc.

c) 5 points

$$W = \Delta E \text{ (or any mention of work-energy theorem)}$$
 1
$$\Delta E = \Delta K + \Delta U$$
 1
$$\Delta K = \frac{1}{2} \text{ mv}^2 \text{ per rider}$$
 1
$$\Delta U = \text{mg} \ell (1 - \cos \theta) \text{ per rider}$$
 1
$$W = 6 \left(\frac{1}{2} \text{ mv}^2 + \text{mg} \ell (1 - \cos \theta)\right)$$
 1

1978 C: Mech.-2

Solution a) 4 points	Distribution of Points
$L_{ m before\ collision}=L_{ m after\ collision}$	1
$L_{\rm before} = I\omega = (\frac{1}{3} M_1 \ell^2) \omega$	1
$L_{after} = \ell M_2 v$	1
$v = M_1 \ell \omega / 3M_2$	I

b) 3 points

Most common solution employed the concept of center of mass:

$$P_{\text{CM}} = M_1 \, v_{\text{CM}} = M_1 \, (\omega \ell/2) = P_{\text{system}} \label{eq:pcm} 3$$

Full credit also given for direct integration:

$$\begin{bmatrix} P = \int v \ dM, \ where \ dM = \rho \ dV = \rho A \ dr \\ and \ v = r\omega \ thus \\ P = \int_0^{\mathfrak{k}} r\omega \ \rho A \ dr = \omega \rho A \int_0^{\mathfrak{k}} r \ dr = \omega \rho A \ \ell^2/2 \\ Thus, since \ M_1 = \rho Al, \ P = \omega \ell M_1/2 \\ \end{bmatrix}$$

c) 2 points

$$P_{after} = M_2 v_{after}$$

where from part a, $v_{after} = M_1 \ell \omega / 3M_2$

2

3

- d) There is a net external force acting on the system at the pivot P. Hence, the linear momentum is *not* conserved.
- e) Since the net external force in the plane of rotation acts at the pivot P, the net torque about the pivot P is zero. Hence, angular momentum is conserved.

1978 C: Mech.-3

Solution a) 4 points	Distribution of Points
F = -kx	1
$x = L\theta (or \sin \theta)$	1
$F = -kL\theta$ Torque = FL (cos θ or 1)	1
Torque = $-kL^2\theta$ (or $\sin \theta \times \cos \theta$)	1

b) 4 points

Torque =
$$I\alpha$$
 2
$$I = 2mL^{2}$$
 2
$$\alpha = \frac{T}{I} = -\frac{k}{2m}\theta$$

c) 3 points

$$\alpha = \frac{d^2\theta}{dt^2}$$
Thus,
$$\frac{d^2\theta}{dt^2} = -\frac{k}{2m}\theta$$

d) 4 points

$$\theta = \theta_0 \cos \left(\sqrt{\frac{k}{2m}} t \right)$$

or any equivalent solutions with appropriate constants

1978 C: E & M-1

a) 4 points	Solution	Distribution of Points
From energy c	onsideration	
$\Delta PE = \Delta K$	E	
$eV_g = \frac{1}{2} n$	nv_e^2	3
$v_e = \sqrt{2eV}$	$\frac{V_{\rm g}/{\rm m}}{}$. 1

b) 5 points

Again from energy consideration

Total energy upon entering = total energy at y_{max}

$$^{1}/_{2} \text{ mv}_{e}^{2} = ^{1}/_{2} \text{ mv}_{e}^{2} \cos^{2} \theta + e \frac{V_{p}}{d} y_{max}$$
 3

Thus,
$$y_{max} = d \frac{V_g}{V_p} \sin^2 \theta$$
 2

(Full credit also given for alternate correct solution, e.g., using Newton's Laws or a modified work- Δ KE attack)

c) 3 points

The speed at impact is unchanged.

1

The magnetic force is always at 90° to the displacement (velocity) and thus does no work.

2

Hence, the speed depends only on height y.

d) 3 points



2

Along the old path, the magnetic force on an electron always has a downward component; thus y_{max} is lower and the time of flight shorter. Further, since the magnetic force has a positive component in the x direction during the first half and a negative component during the second half, the range is shorter because the time of flight is shorter.

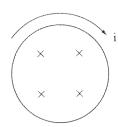
1

1978 C: E & M-2



Distribution of Points

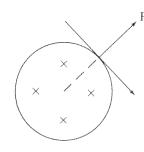
a) 3 points



Since the magnetic flux through the loop is decreasing, Lenz's Law states that the flux associated with the induced current will be increasing through the loop. Hence, a clockwise current.

2 James J.

b) 3 points



Expand

1

At every point the force is outward

$$F_G = \overrightarrow{il} \times \overrightarrow{B}$$

2

c) 4 points

$$Q = \int_0^\infty I \, dt = \int_0^\infty \frac{V}{R} \, dt$$

$$V = -\frac{d\theta}{dt} = -A \frac{dB}{dt} = \alpha A B_0 e^{-\alpha t}$$

1

$$V = -\frac{d\theta}{dt} = -A \frac{dB}{dt} = \alpha A B_0 e^{-\alpha}$$

2

Thus, Q =
$$\frac{\alpha B_0 A}{R} \int_0^\infty e^{-\alpha t} dt = \frac{A B_0}{R}$$

The same

d) 5 points

$$\begin{split} H &= \int_0^\infty I^2 R \ dt = \int_0^\infty \frac{V^2}{R} \ dt \\ From \ c) \ V &= \alpha A B_0 e^{-\alpha t} \\ Thus, \ H &= \frac{A^2 \alpha^2 B_0^2}{R} \int_0^\infty e^{-2\alpha t} \ dt \\ or \\ H &= A^2 B_0^2 \alpha / 2 R \end{split} \label{eq:Hamiltonian}$$

1978 C: E & M-3

Solution	Distribution of Points
a) 3 points	,
$\int \vec{E} \cdot d\vec{s} = Q/\epsilon_0$	1
$\int \vec{E} \cdot d\vec{s} = E_0 \cdot \text{area of sphere}$	1
$Q = \epsilon_0 \cdot E_0 \cdot 4\pi a^2$, personal programme (p. 1971).
(Only 1 point was awarded if Gauss's Law was not t	ised.)

b) 3 points

$$E = E_0 \, a^2/r^2$$

$$1/r^2 \, dependence \qquad \qquad 1$$

$$E = E_0 \, when \, r = a \qquad \qquad 1$$
 Expression in terms of E_0 a and r $\qquad \qquad 1$

No work was required, but partial credit was awarded when some correct work was shown.

c) 3 points

$$V = E_0 a^2 \left(\frac{1}{a} - \frac{1}{b} \right)$$

No work was required.

1 point off for wrong sign

1 point off for not expressing answer in terms of E_0 , a, and b

d) 3 points

$$U = \frac{1}{2} \, QV \text{ or } U = \frac{1}{2} \, CV^2 \text{ and } C = Q/V$$
 1
Substitution for Q or V from above 1
Answer expressed in terms of E₀, a, and b 1
$$U = \frac{1}{2} \, \epsilon_0 \, E_0 4\pi a^2 \cdot E_0 a^2 \left(\frac{1}{a} - \frac{1}{b}\right) = 2\pi \epsilon_0 E_0^2 \left(a^3 - \frac{a^4}{b}\right)$$

e) 3 points

dU/da = 0 1

Correct differentiation 1

Correct algebra and answer 1 $3a^2 - \frac{4a^3}{b} = 0 \implies a = \frac{3}{4}b$

1