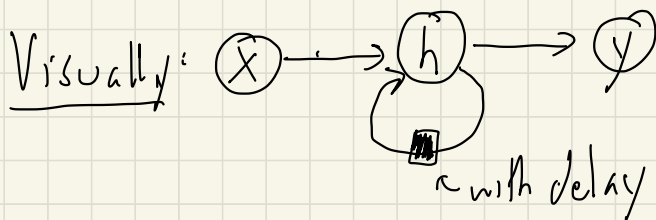


Typically: RNN has recurrence in the hidden layers

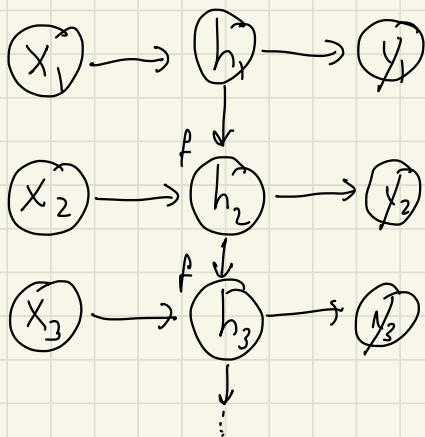
$$h_t = f(h_{t-1}, x_t, \beta)$$

↑ usually decomposed into an activation function with weights + bias

Goal: The RNN can remember a "summary" of the relevant aspects of the past



Unfolds as:



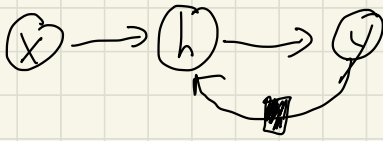
Initialize $h_0 = 0$

Often only run forward p steps so we still have a finite memory

Many possible recurrent structures exist

2 most common are:

- 1) recurrence between hidden nodes (displayed above)
- 2) recurrence from output at one time step to the hidden units at the next time step



Note: RNNs typically assume homoscedastic (iid) errors
There is recent research on heteroscedastic RNNs
Sometimes called Generalized Recurrent Neural Networks
(GRNNs)

Gated RNNs and Long Short-Term Memory (LSTM) Networks

Gating allows for dynamic control of the flow of past information to the current state at each time instant

ex: α -RNN

$$y_t = W_y \hat{h}_t + b_y$$

$$\hat{h}_t = g(U_h \tilde{h}_{t-1} + W_h x_t + b_h)$$

$$\tilde{h}_t = \alpha \hat{h}_t + (1-\alpha) \tilde{h}_{t-1} \leftarrow \text{smoothing}$$

If $\alpha = 1$: this is a typical (plain) RNN

If $\alpha \neq 1$: smooth the hidden layer to retain infinite memory
(even if we restart with hidden node at p steps in the past)

LSTM Networks

LSTM networks use "cells" that have an internal recurrence + outer recurrence

\nwarrow similar to (plain) RNN

\hookrightarrow use an additional "state" s_t which is used to remember the past

Mathematically: 3 Gates

Forget Gate

$$f_t = \sigma(U_f h_{t-1} + V_f x_t + b_f)$$

↑ hidden layer [the output of the LSTM]
sets value between 0 + 1

determines how much to remember / forget about
the current state

External Input Gate

$$g_t = \sigma(U_g h_{t-1} + V_g x_t + b_g)$$

The updated state is then constructed as:

$$s_t = \underbrace{f_t s_{t-1}}_{\text{amount to recall from prior state}} + \underbrace{g_t \sigma(U h_{t-1} + W x_t + b)}_{\text{"new" information for the state}}$$

amount to
recall from
prior state

"new" information for the state

Output Gate

$$h_t = \tanh(s_t) q_t$$

$$q_t = \sigma(U_o h_{t-1} + W_o x_t + b_o)$$

Extensions exist

ex: use s_{t-1} as an additional input to each gate

Visually

