Formale Semantik 10. Montagues intensionale Logik

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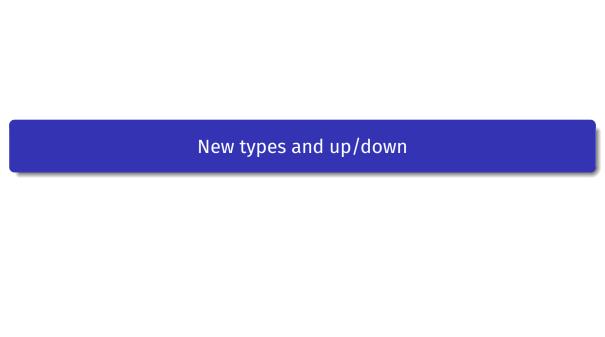
Stets aktuelle Fassungen: https://github.com/rsling/VL-Semantik

Inhalt

1 New types and up/down







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- again: individual concepts (variable function on indices) vs. names (constant)



• intension relative to models

$$\llbracket \alpha \rrbracket_{\mathbf{q}'}^{\mathcal{M},\mathbf{g}}$$

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$$\bullet \ \, \text{for a name } \textit{d} \colon \llbracket \textit{d} \rrbracket_{\not \varsigma}^{\mathcal{M},g} = \left[\begin{array}{ccc} \langle w_1,t_1 \rangle & \to & \textit{b} \\ \langle w_2,t_1 \rangle & \to & \textit{b} \\ \langle w_1,t_2 \rangle & \to & \textit{b} \\ \langle w_2,t_2 \rangle & \to & \textit{b} \\ \langle w_1,t_3 \rangle & \to & \textit{b} \\ \langle w_2,t_3 \rangle & \to & \textit{b} \end{array} \right]$$



• for an individual concept denoting expression *m*:

$$\llbracket \alpha \rrbracket_{q'}^{\mathcal{M},g}$$

• for an individual concept denoting expression *m*:

$$\bullet \ \llbracket m \rrbracket_{\varphi}^{\mathcal{M},g} = \left[\begin{array}{ccc} \langle w_1,t_1 \rangle & \to & a \\ \langle w_2,t_1 \rangle & \to & c \\ \langle w_1,t_2 \rangle & \to & b \\ \langle w_2,t_2 \rangle & \to & c \\ \langle w_1,t_3 \rangle & \to & c \\ \langle w_2,t_3 \rangle & \to & b \end{array} \right]$$



• for a one place predicate B:

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for a one place predicate B:

$$\bullet \hspace{0.1cm} \llbracket B \rrbracket^{\mathcal{M},g}_{\varsigma'} = \left[\begin{array}{ccc} \langle w_1,t_1 \rangle & \rightarrow & \{a,b\} \\ \langle w_2,t_1 \rangle & \rightarrow & \{b,c\} \\ \langle w_1,t_2 \rangle & \rightarrow & \{a,c\} \\ \langle w_2,t_2 \rangle & \rightarrow & \{a\} \\ \langle w_1,t_3 \rangle & \rightarrow & \{b,c\} \\ \langle w_2,t_3 \rangle & \rightarrow & \{a,b,c\} \end{array} \right]$$

• formula ϕ : $[\![\phi]\!]_{\sigma}^{\mathcal{M},g}$ is a function from indices to truth values

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$$\bullet \quad \llbracket \mathsf{B}(\mathsf{m}) \rrbracket_{\varphi}^{\mathcal{M},g} = \begin{bmatrix} \langle \mathsf{w}_1,\mathsf{t}_1 \rangle & \to & 1 \\ \langle \mathsf{w}_2,\mathsf{t}_1 \rangle & \to & 1 \\ \langle \mathsf{w}_1,\mathsf{t}_2 \rangle & \to & 0 \\ \langle \mathsf{w}_1,\mathsf{t}_2 \rangle & \to & 0 \\ \langle \mathsf{w}_2,\mathsf{t}_2 \rangle & \to & 0 \\ \langle \mathsf{w}_1,\mathsf{t}_3 \rangle & \to & 1 \\ \langle \mathsf{w}_2,\mathsf{t}_3 \rangle & \to & 1 \end{bmatrix}$$

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$$\bullet \quad \llbracket \mathcal{B}(m) \rrbracket_{\varphi}^{\mathcal{M},g} = \begin{bmatrix} \langle \mathbf{w}_1, \mathbf{t}_1 \rangle & \to & 1 \\ \langle \mathbf{w}_2, \mathbf{t}_1 \rangle & \to & 1 \\ \langle \mathbf{w}_1, \mathbf{t}_2 \rangle & \to & 0 \\ \langle \mathbf{w}_2, \mathbf{t}_2 \rangle & \to & 0 \\ \langle \mathbf{w}_1, \mathbf{t}_3 \rangle & \to & 1 \\ \langle \mathbf{w}_2, \mathbf{t}_3 \rangle & \to & 1 \end{bmatrix}$$

$$\bullet \quad \llbracket B(n) \rrbracket_{\varphi}^{\mathcal{M},g} = \begin{bmatrix} \langle \mathbf{w}_1, t_1 \rangle & \to & 0 \\ \langle \mathbf{w}_2, t_1 \rangle & \to & 1 \\ \langle \mathbf{w}_1, t_2 \rangle & \to & 1 \\ \langle \mathbf{w}_2, t_2 \rangle & \to & 0 \\ \langle \mathbf{w}_1, t_3 \rangle & \to & 1 \\ \langle \mathbf{w}_2, t_3 \rangle & \to & 1 \end{bmatrix}$$

ullet again, the proposition $[\![Bm]\!]_{arphi}^{\mathcal{M},g}$ is a set of indices $(\langle w_i,t_j \rangle)$

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- from the extension at all indices, compute the intension
- $\llbracket \alpha \rrbracket_{\alpha'}^{\mathcal{M},g}(\langle \mathbf{w}_i, \mathbf{t}_j \rangle) = \llbracket \alpha \rrbracket^{\mathcal{M},\mathbf{w}_i,\mathbf{t}_j,g}$

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- $\bullet \ \llbracket u \rrbracket^{\mathcal{M},g}_{q'}(\langle w_i,t_j \rangle) = g(u)$

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- alternatively: introduce rules which access an expression's extension/intension as appropriate

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- α and $\hat{\alpha}$ are just denoting expressions
- $\bullet \ \ \text{for an intension-denoting expression} \ \alpha \textbf{:} \ \big[\![\check{\ } \alpha]\!]^{\mathcal{M}, \mathbf{w}, i, g} = \big[\![\alpha]\!]^{\mathcal{M}, g} (\langle \mathbf{w}, \mathbf{t} \rangle)$

Down-up and up-down

ullet observe: $[\![\hat{\ } lpha]\!]^{\mathcal{M}, \mathbf{w}, i, g} = [\![lpha]\!]^{\mathcal{M}, \mathbf{w}, i, g}$ for any $\langle \mathbf{w}, \mathbf{t}
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- but not always: $\llbracket \tilde{\alpha} \rrbracket^{\mathcal{M},w,i,g} = \llbracket \alpha \rrbracket^{\mathcal{M},w,i,g}$ for any $\langle w,t \rangle$
- can easily be the case for intension-denoting expressions

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• \emph{k}' extension (e.g., at $\langle \emph{w}_1, \emph{t}_2 \rangle$): $\llbracket \emph{k} \rrbracket_{\emph{c}'}^{\mathcal{M}, \emph{g}} (\langle \emph{w}_1, \emph{t}_2 \rangle) =$

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- $\bullet \quad \text{however: } \llbracket {}^{\sim} k \rrbracket^{\mathcal{M}, w_1, t_2, g} = \left[\begin{array}{ccc} \langle w_1, t_1 \rangle & \rightarrow & a \\ \langle w_1, t_2 \rangle & \rightarrow & b \\ \langle w_2, t_1 \rangle & \rightarrow & d \\ \langle w_2, t_2 \rangle & \rightarrow & b \end{array} \right]$
- since: $[\![k]\!] \mathcal{M}, w_1, t_1, g = a$ $[\![k]\!] \mathcal{M}, w_1, t_2, g = b$ $[\![k]\!] \mathcal{M}, w_2, t_1, g = d$ $[\![k]\!] \mathcal{M}, w_2, t_2, g = b$



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- if $\alpha, \beta \in ME_a$ then $\alpha = \beta \in ME_t$

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	type	variables	constants
	е	<i>x</i> , <i>y</i> , <i>z</i>	a, b, c
	$\langle s, \pmb{e} angle$	x, y, z	_
	$\langle oldsymbol{e}, oldsymbol{t} angle$	<i>X</i> , <i>Y</i>	walk′, A, B
•	$\langle\langle s, \pmb{e} \rangle, \pmb{t} \rangle$	Q	rise′, change′
	$\langle s, \langle e, t \rangle \rangle$	P	_
	$\langle oldsymbol{e}, oldsymbol{e} angle$	P	Sq
	$\langle e, \langle e, t \rangle \rangle$	R	Gr, K
	$\langle e, \langle e, e \rangle \rangle$	_	Plus

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- instead of: F(expression)(index)=extemsion

Some interpretations

• $[\![\lambda u\alpha]\!]^{\mathcal{M},w,i,g}$, $u \in Var_b$, $\alpha \in ME_a$ is a function h with domain D_b s.t. $x \in D_b$, $h(x) = [\![\alpha]\!]^{\mathcal{M},w,t,g'}$ with g' exactly like g except g'(u) = x

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- $\llbracket \hat{\alpha} \rrbracket^{\mathcal{M},w,i,g}$ is a function h from $W \times T$ to denotations of α 's type s.t. at every $\langle w',t' \rangle \in W \times T \llbracket \alpha \rrbracket^{\mathcal{M},w',t',g} = h(\langle w',t' \rangle) = \llbracket \hat{\alpha} \rrbracket^{\mathcal{M},w,i,g}(\langle w',t' \rangle)$

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- from relations $\langle e, \langle e, t \rangle \rangle$ to relations-in-intensions $\langle s, \langle e, \langle e, t \rangle \rangle \rangle$

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- useful thing: We never talk about indices!
- since often $\check{\ }\alpha(\beta)$ is needed for $\alpha\in \mathit{ME}_{\langle \mathsf{s},\langle e,\mathsf{t}\rangle\rangle}$ and $\beta\in \mathit{ME}_e$, abbr. $\alpha\{\beta\}$

Examples

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- we could give $\Box \phi$ as $\mathbf{Nec}(\hat{\ }\phi)$

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- So, for any individual x $h(\langle w, t \rangle)(k)(x) = 1$ iff $k(\langle w, t' \rangle)(x) = 1$ for some t' < t.

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Literatur I

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