# Formale Semantik 10. Montagues intensionale Logik

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Folien in Überarbeitung. Englische Teile (ab Woche 8) sind noch von 2007!

Stets aktuelle Fassungen: https://github.com/rsling/VL-Semantik

## Inhalt





3 Examples



ullet  $[\![\phi]\!]^{\mathcal{M},\mathsf{w},i,g}$  and  $[\![\mathbf{P}]\!]^{\mathcal{M},\mathsf{w},i,g}$  don't truth conditionally determine  $[\![\mathbf{P}\phi]\!]^{\mathcal{M},\mathsf{w},i,g}$ 

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- again: individual concepts (variable function on indices) vs. names (constant)



• intension relative to models

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• for a name 
$$d$$
:  $\llbracket d 
bracket^{\mathcal{M},g}_{arphi} = egin{bmatrix} \langle w_1,t_1 
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angle & o & b \ \langle w_1,t_2 
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• for an individual concept denoting expression *m*:

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$$\bullet \hspace{0.1cm} \llbracket m \rrbracket^{\mathcal{M},g}_{\mathscr{C}} = \left[ \begin{array}{ccc} \langle w_1,t_1 \rangle & \rightarrow & a \\ \langle w_2,t_1 \rangle & \rightarrow & c \\ \langle w_1,t_2 \rangle & \rightarrow & b \\ \langle w_2,t_2 \rangle & \rightarrow & c \\ \langle w_1,t_3 \rangle & \rightarrow & c \\ \langle w_2,t_3 \rangle & \rightarrow & b \end{array} \right]$$



• for a one place predicate B:

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$$\bullet \ \llbracket \textit{B}(\textit{n}) \rrbracket_{\textit{c}'}^{\mathcal{M},\textit{g}} = \left[ \begin{array}{ccc} \langle \textit{w}_1,\textit{t}_1 \rangle & \rightarrow & 0 \\ \langle \textit{w}_2,\textit{t}_1 \rangle & \rightarrow & 1 \\ \langle \textit{w}_1,\textit{t}_2 \rangle & \rightarrow & 1 \\ \langle \textit{w}_2,\textit{t}_2 \rangle & \rightarrow & 0 \\ \langle \textit{w}_1,\textit{t}_3 \rangle & \rightarrow & 1 \\ \langle \textit{w}_2,\textit{t}_3 \rangle & \rightarrow & 1 \end{array} \right]$$

ullet again, the proposition  $[\![Bm]\!]_{arphi}^{\mathcal{M},g}$  is a set of indices  $(\langle w_i,t_j
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- $\bullet \ \llbracket \alpha \rrbracket_{q'}^{\mathcal{M},g}(\langle \mathbf{w}_i, \mathbf{t}_j \rangle) = \llbracket \alpha \rrbracket^{\mathcal{M},\mathbf{w}_i,\mathbf{t}_j,g}$

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- $\bullet \hspace{0.1cm} \llbracket \, \hat{}_{}^{} \! \mathsf{Bm} \rrbracket^{\mathcal{M}, \mathsf{w}, \mathsf{i}, \mathsf{g}} = \llbracket \mathsf{Bm} \rrbracket^{\mathcal{M}, \mathsf{g}}_{\mathit{q'}}$

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- $\alpha$  and  $\hat{\alpha}$  are just denoting expressions
- for an intension-denoting expression  $\alpha$ :  $\llbracket\check{\alpha}\rrbracket^{\mathcal{M},w,i,g} = \llbracket\alpha\rrbracket^{\mathcal{M},g}(\langle w,t\rangle)$

## Down-up and up-down

ullet observe:  $begin{bmatrix} \hat{a} \\ \hat{b} \end{bmatrix}^{\mathcal{M}, \mathsf{w}, \mathsf{i}, \mathsf{g}} = begin{bmatrix} \alpha \end{bmatrix}^{\mathcal{M}, \mathsf{w}, \mathsf{i}, \mathsf{g}} \ \text{for any } \langle \mathsf{w}, \mathsf{t} \rangle \end{pmatrix}$ 

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- can easily be the case for intension-denoting expressions

## Non-equality

$$\textbf{k' intension:} \ \llbracket k \rrbracket_{q'}^{\mathcal{M},g} = \left[ \begin{array}{cccc} \langle w_1,t_1 \rangle & \rightarrow & a \\ \langle w_1,t_2 \rangle & \rightarrow & a \\ \langle w_2,t_1 \rangle & \rightarrow & a \\ \langle w_2,t_1 \rangle & \rightarrow & a \\ \langle w_1,t_2 \rangle & \rightarrow & \langle w_1,t_2 \rangle & \rightarrow & a \\ \langle w_1,t_2 \rangle & \rightarrow & \langle w_1,t_2 \rangle & \rightarrow & a \\ \langle w_2,t_1 \rangle & \rightarrow & \langle w_2,t_1 \rangle & \rightarrow & c \\ \langle w_2,t_2 \rangle & \rightarrow & d \\ \langle w_1,t_2 \rangle & \rightarrow & d \\ \langle w_1,t_2 \rangle & \rightarrow & d \\ \langle w_2,t_1 \rangle & \rightarrow & a \\ \langle w_1,t_2 \rangle & \rightarrow & d \\ \langle w_2,t_1 \rangle & \rightarrow & a \\ \langle w_1,t_2 \rangle & \rightarrow & d \\ \langle w_2,t_1 \rangle & \rightarrow & a \\ \langle w_2,t_1 \rangle & \rightarrow & a \\ \langle w_2,t_2 \rangle & \rightarrow & a \\ \langle w_1,t_2 \rangle & \rightarrow & d \\ \langle w_2,t_1 \rangle & \rightarrow & a \\ \langle w_2,t_2 \rangle & \rightarrow & a \\ \langle w_2,t_2 \rangle & \rightarrow & b \\ \end{array} \right]$$

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$$\llbracket k \rrbracket^{\mathcal{M}, w_1, t_2, g} = \begin{bmatrix} \langle w_1, t_1 \rangle & \rightarrow & a \\ \langle w_1, t_2 \rangle & \rightarrow & b \\ \langle w_2, t_1 \rangle & \rightarrow & c \\ \langle w_2, t_2 \rangle & \rightarrow & d \end{bmatrix}$$

## Non-equality

• k' extension (e.g., at  $\langle w_1,t_2
angle$ ):  $\llbracket k
rbracket{M}_{g'}^{\mathcal{M},g}(\langle w_1,t_2
angle)=0$ 

- $\bullet \quad \text{however: } \llbracket {}^{\sim} k \rrbracket {}^{\mathcal{M}, w_1, t_2, g} = \left[ \begin{array}{ccc} \langle w_1, t_1 \rangle & \rightarrow & a \\ \langle w_1, t_2 \rangle & \rightarrow & b \\ \langle w_2, t_1 \rangle & \rightarrow & d \\ \langle w_2, t_2 \rangle & \rightarrow & b \end{array} \right]$
- since:  $[\![ \ ^{\!} k ]\!]^{\mathcal{M}, w_1, t_1, g} = a$   $[\![ \ ^{\!} k ]\!]^{\mathcal{M}, w_1, t_2, g} = b$   $[\![ \ ^{\!} k ]\!]^{\mathcal{M}, w_2, t_1, g} = d$  $[\![ \ ^{\!} k ]\!]^{\mathcal{M}, w_2, t_2, g} = b$



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- if  $\alpha, \beta \in ME_a$  then  $\alpha = \beta \in ME_t$

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|   | type   | variables                      | constants      |
|---|--|--------------------------------|----------------|
|   | е  | <i>x</i> , <i>y</i> , <i>z</i> | a, b, c        |
|   | $\langle s, \pmb{e}  angle$  | x, y, z                        | _              |
|   | $\langle e,t \rangle$  | <i>X</i> , <i>Y</i>            | walk′, A, B    |
| • | $\langle\langle s, \pmb{e} \rangle, \pmb{t} \rangle$   | Q                              | rise', change' |
|   | $\langle s, \langle e, t \rangle \rangle$  | P                              | _              |
|   | $\langle oldsymbol{e}, oldsymbol{e}  angle$  | P                              | Sq             |
|   | $\langle oldsymbol{e}, \langle oldsymbol{e}, \langle oldsymbol{e}, oldsymbol{t}  angle  angle$ | R                              | Gr, K          |
|   | $\langle e, \langle e, e \rangle \rangle$  | _                              | Plus           |

•  $\langle A, W, T, <, F \rangle$ 

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- instead of: F(expression)(index)=extemsion

## Some interpretations

•  $[\![\lambda u\alpha]\!]^{\mathcal{M},w,i,g}$ ,  $u \in Var_b$ ,  $\alpha \in ME_a$  is a function h with domain  $D_b$  s.t.  $x \in D_b$ ,  $h(x) = [\![\alpha]\!]^{\mathcal{M},w,t,g'}$  with g' exactly like g except g'(u) = x

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- $\llbracket \hat{\alpha} \rrbracket^{\mathcal{M},w,i,g}$  is a function h from  $W \times T$  to denotations of  $\alpha$ 's type s.t. at every  $\langle w',t' \rangle \in W \times T \llbracket \alpha \rrbracket^{\mathcal{M},w',t',g} = h(\langle w',t' \rangle) = \llbracket \hat{\alpha} \rrbracket^{\mathcal{M},w,i,g}(\langle w',t' \rangle)$

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  - $ightharpoonup \langle s, \langle \langle s, t \rangle, t \rangle \rangle$  properties of propositions
- from relations  $\langle e, \langle e, t \rangle \rangle$  to relations-in-intensions  $\langle s, \langle e, \langle e, t \rangle \rangle \rangle$

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- useful thing: We never talk about indices!
- since often  $\check{\ }\alpha(\beta)$  is needed for  $\alpha\in \mathit{ME}_{\langle \mathbf{s},\langle \mathbf{e},\mathbf{t}\rangle\rangle}$  and  $\beta\in \mathit{ME}_{\mathbf{e}}$ , abbr.  $\alpha\{\beta\}$

# Examples

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- we could give  $\Box \phi$  as  $\mathbf{Nec}(\hat{\ }\phi)$

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- So, for any individual  $x h(\langle w, t \rangle)(k)(x) = 1$  iff  $h(\langle w, t' \rangle)(x) = 1$  for some t' < t.

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- $\lambda$  conversion is restricted in IL!

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- $\mathbf{Bel}(j, \mathbf{F} \exists x [R(x) \land W(x)])$

# Literatur I

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