

# **Catamaran/ARIFIC: Architecture Research in FPGAs in the Cloud**

**Tutorial at HPCA-29, Montreal**



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GitHub repo for this tutorial: [https://github.com/rsnikhil/Tutorial\\_at\\_HPCA-29](https://github.com/rsnikhil/Tutorial_at_HPCA-29)

# What is Catamaran/ARIFIC?

## The Architecture Researcher's Dilemma

- The Architecture Researcher is typically focused on a specific artifact:
  - CPU pipeline organization, branch predictor, cache organization, store buffers, instruction fusion, ..., reorder buffer, accelerator...
- But for credible impact, needs whole-system environment:
  - Reasonable SoC with devices (networking, block storage, UART)
  - Running actual apps, often under a real operating system
  - On FPGA
    - For microarchitecture credibility
    - To run programs of credible length

Creative work;  
occupies you full-time

Lots of boring boilerplate; man-years to construct; not portable, reusable or scalable (e.g., one-off, soon-obsolete FPGA board, unfixable on departure of key grad student), ...

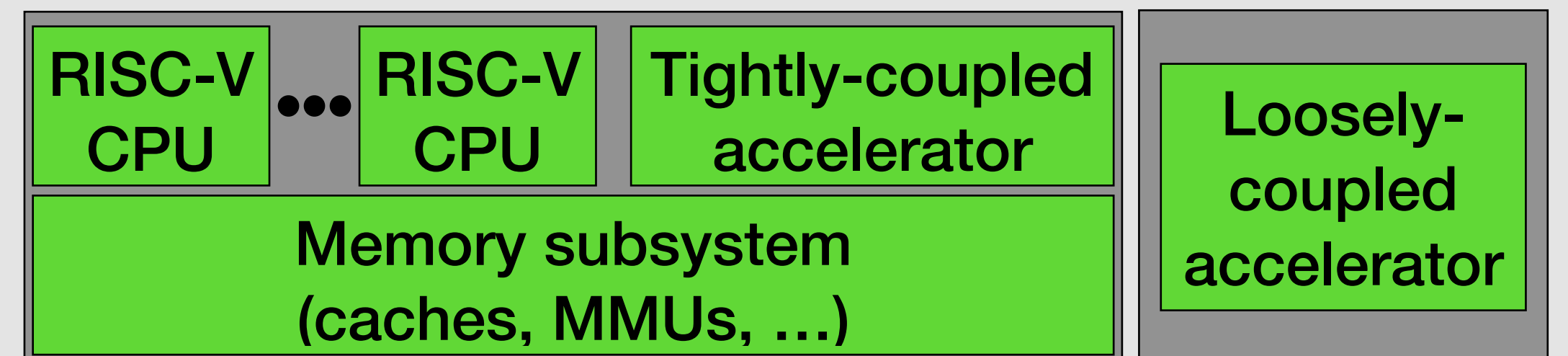
Beyond Qemu, GEM5, ...

# What is Catamaran/ARIFIC?

## Infrastructure so Architect can focus on their creative work

### Architecture Researcher's Focus

- CPU microarchitecture
- Memory systems (caches, MMUs, coherence, WMMs, ...)
- Accelerators



### Catamaran/ARIFIC

(infrastructure in the cloud)

Host computer running Linux

#### System Control:

- Load ELF/memhex (programs, data)
- into DDR
- Assert/Deassert Core's RESET
- Configure CPU
- Collect stats, traces

Console (to/from UART)

Disk-device support

Network-device support

GDB control of CPU on FPGA

PCIe connection

FPGA

UART (for console)

Disk-device support

Network-device support

Support for counters, traces, etc.

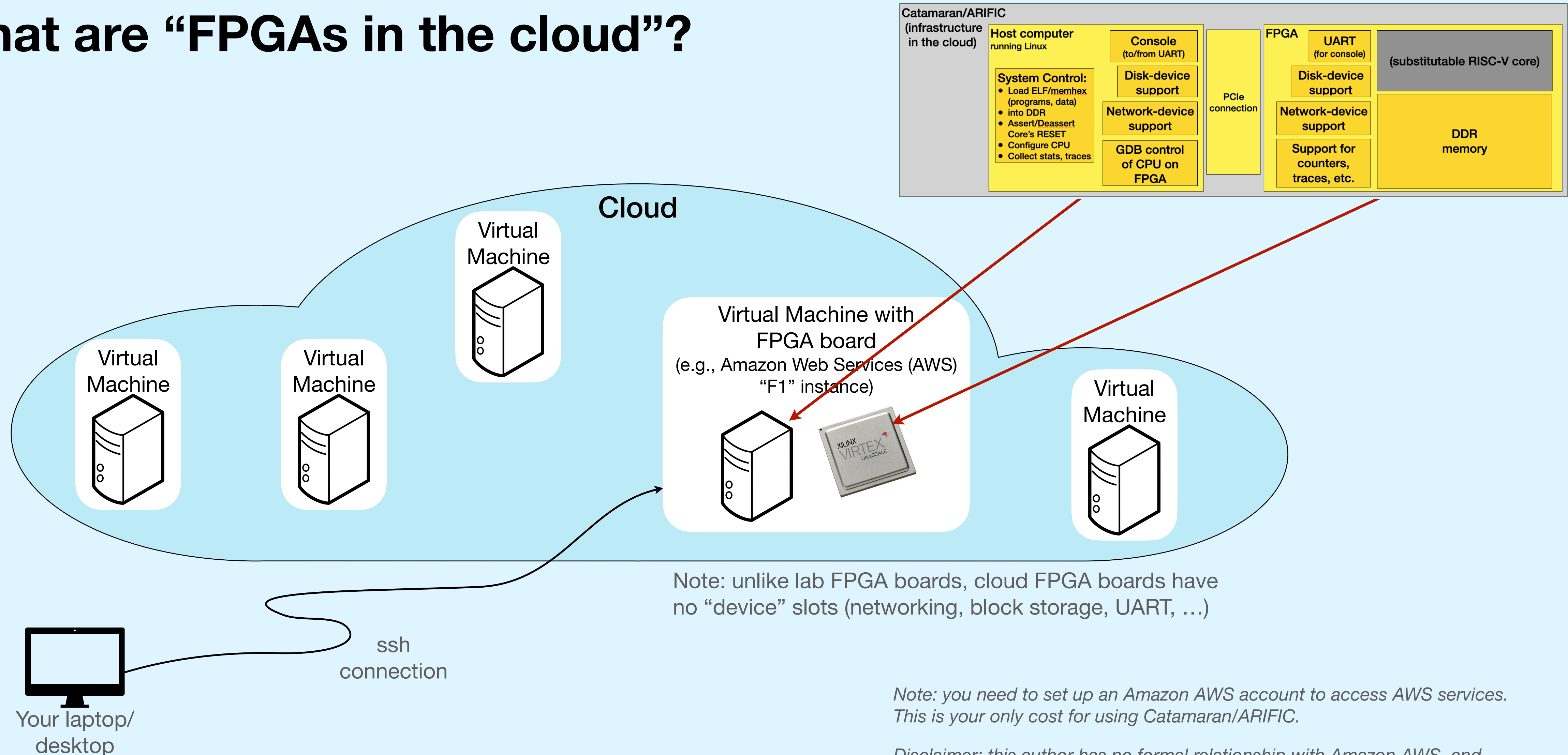
(substitutable RISC-V core)

DDR memory

Easily modifiable/  
substitutable

# What is Catamaran/ARIFIC?

## What are “FPGAs in the cloud”?





# Plan for this tutorial

## Walk through: how to substitute your own core, and run it

- Basics of Amazon AWS virtual machines
- Demo/description of what you can do with Catamaran/ARIFIC
  - Run ISA tests
  - Cross-compile and run bare-metal (no OS) C programs
  - Run Linux, with networking and block devices
  - Cross-compile and run C programs under Linux
- Demo/description of plugging in your own RISC-V Core<sup>1</sup>
  - Standard RTL-level interface for the core
  - Build a full-system simulation (using Verilator), and run it (can do on your local computer; does not need cloud)
  - Build a bitfile for AWS F1 FPGA, and run it
- Use GDB to control the RISC-V CPU on the FPGA

### <sup>1</sup> “Your own RISC-V Core”

#### Options:

- Your own new CPU design
- Modify available CPU (many open-source)
  - microarchitecture change
  - new instruction
  - new CSRs (e.g., counters)
- Modify/replace memory system (caches, MMUs, PMPs, PTWs, ...)
- Add tightly-coupled or loosely coupled accelerator
- ... or other research idea ...

# Goal for this tutorial

**By the end of this tutorial, you should feel confident you know:**

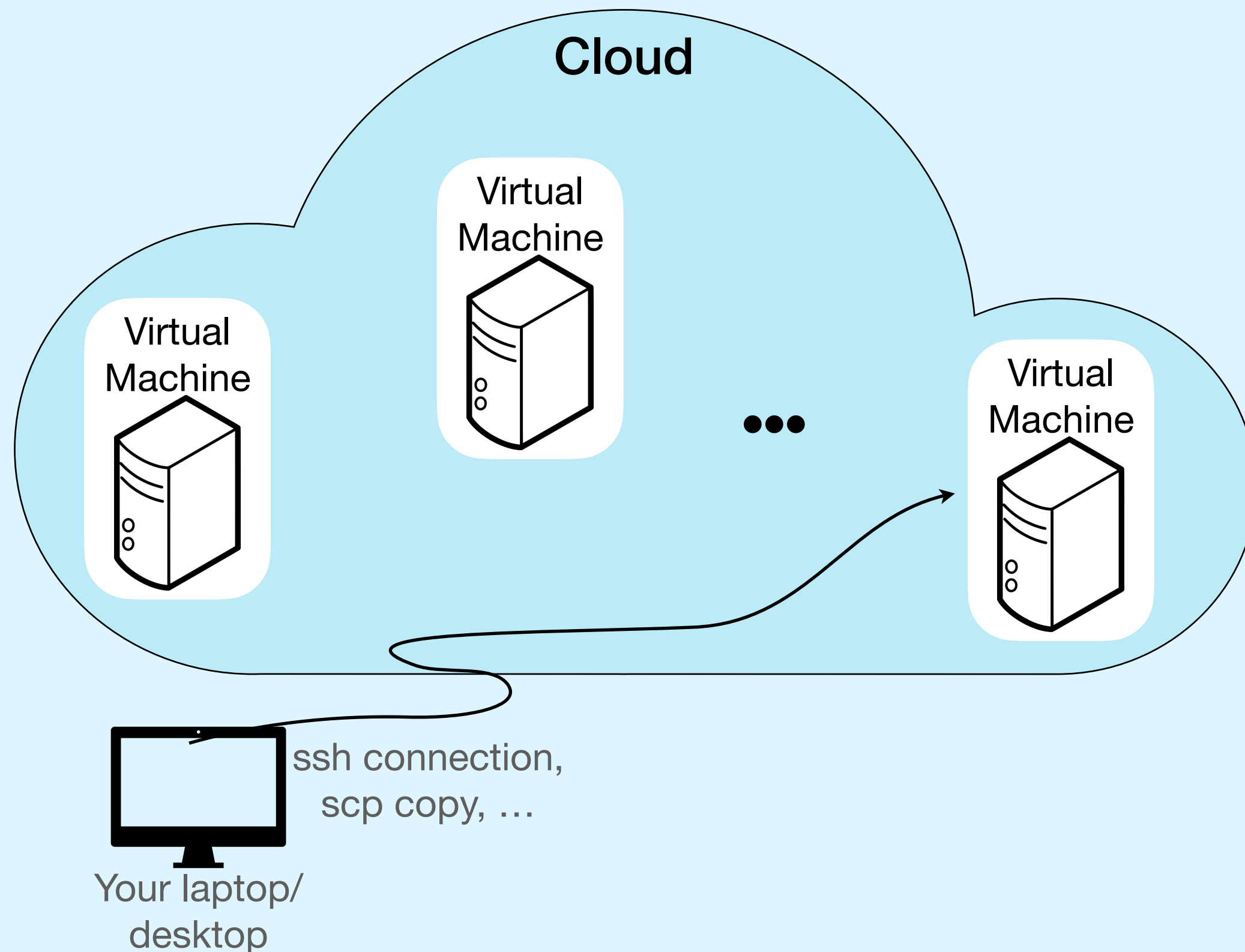
- How to open an AWS account and create AMIs (virtual machines) in which you can use Catamaran/ARIFIC
- How to download and install, into your AMIs, all the relevant software tools: AWS tools, RISC-V Gnu tools, Catamaran software and scripts
- How to replicate all the tutorial demos (compile and run ISA tests, compile and run bare-metal C programs, boot Linux, use networking and block device in Linux)
  - all using the pre-built AWS bitfiles (with Catamaran+Rocket and Catamaran+CVA6)
- How to substitute your own core in place of Rocket/CVA6, create a new bitfile, load it, debug it, run code on it, measure it.

# Basics of Amazon AWS

- *AMIs (virtual machines in the Amazon cloud)*
- Connecting to an AMI using “ssh”
- About AWS bitfiles; available Catamaran/ARIFIC bitfiles

# Basics of Amazon AWS

## AMIs (virtual machines in Amazon cloud)



Amazon terminology for a virtual machine in their cloud:

“AMI” = “Amazon Machine Instance”

We also just say “instance” for an AMI/virtual machine

With an Amazon AWS account, you can “create” one or more AMIs for yourself (see Appendix for info on how to create an AMI).

For Catamaran/ARIFIC we usually create two AMIs:

- For **building** FPGA bitfiles: choose the free “FPGA Developer AMI” from AWS Marketplace, which is CentOS + Xilinx tools (Vivado) and licenses + aws-fpga SDK and HDK, running on “m6i.2xlarge” instance type.
- For **running** Catamaran/ARIFIC on FPGA: choose the free basic standard Ubuntu 22.04 AMI from AWS Marketplace, running on an “f1.2xlarge” instance type. “f1” instances have FPGAs attached.

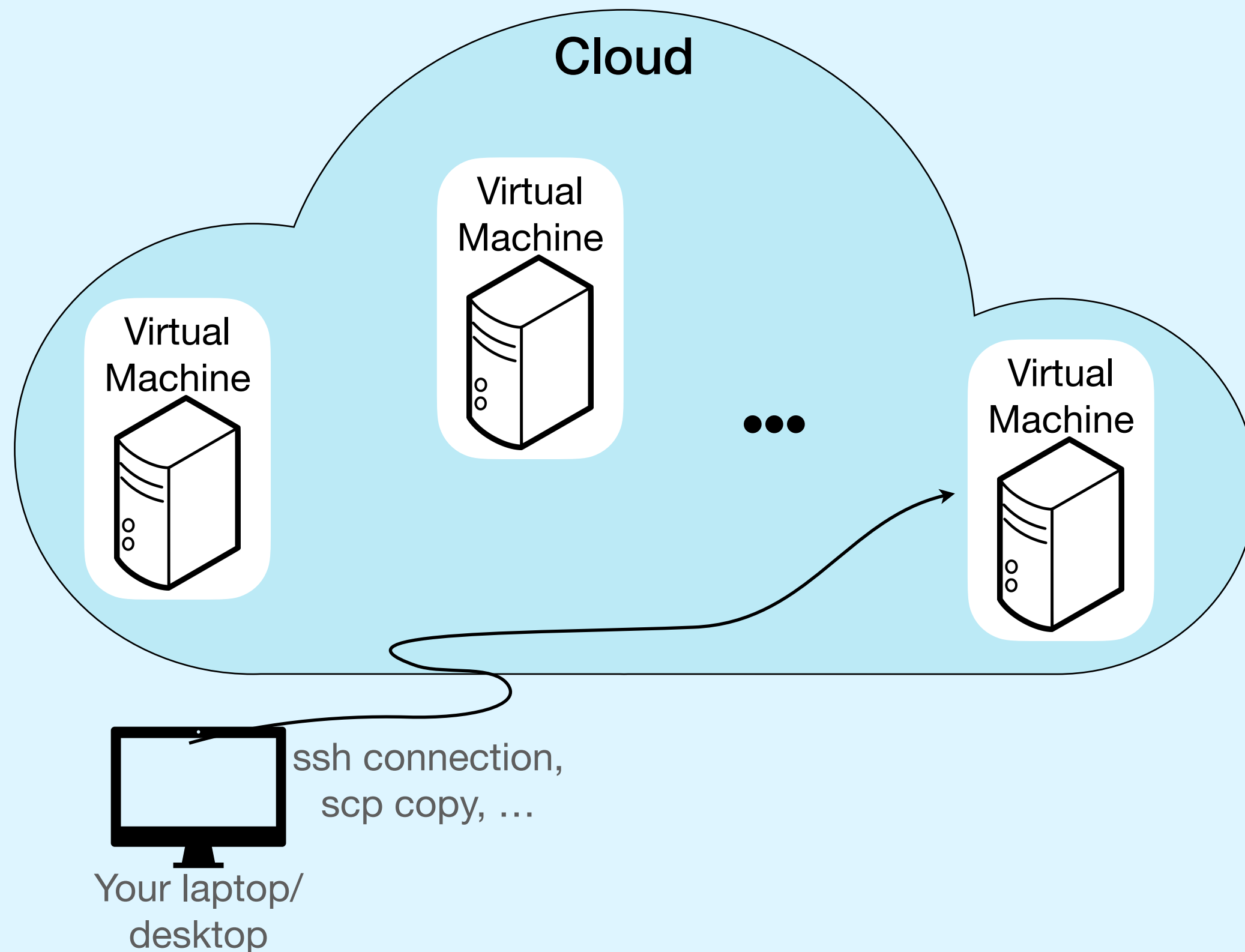
Costs:

- For using Catamaran/ARIFIC, your only costs are AWS costs (between you and Amazon)
- AWS charges vary by instance type. Charges for “f1” instances (with FPGA) are somewhat higher, hence our choice above of a cheaper instance for our “build” AMI, which does not need an attached FPGA.
- *Hint:* put your AMI into the “stopped” state when not in use, to save charges.



# Basics of Amazon AWS

## AMIs (virtual machines in Amazon cloud)



Please see Appendix for how to install:

- aws-fpga SDK and HDK
  - Needed to go from RTL to bitfiles
  - Needed for installing Xilinx XDMA driver for host-FPGA PCIe communication
- CLI (command-line interface)
  - Needed for loading bitfiles into FPGA, etc.

# Basics of Amazon AWS

- AMIs (virtual machines in the Amazon cloud)
- *DEMO: Connecting to an AMI using “ssh”*
- About AWS bitfiles; available Catamaran/ARIFIC bitfiles

# Basics of Amazon AWS

## Connecting to your AML with ssh (1/2)

In “EC2 Instances” dashboard ...

Use “Instance state” drop-down menu to start/stop selected instance

Select your instance

Make sure your AML is “Running”

aws

Services

Search

[Option+S]

EC2

New EC2 Experience

EC2 Dashboard

EC2 Global View

Events

Tags

Limits

Instances

Instances

Instance Types

Launch Templates

Spot Requests

Savings Plans

Reserved Instances

Dedicated Hosts

Scheduled Instances

Capacity Reservations

Images

Instances (1/2)

Find instance by attribute or tag (case-sensitive)

Catamaran

Clear filters

	Name	Instance ID	Instance state	Instance type	Status check	Alarm status	Availability Zone
<input type="checkbox"/>	Catamaran_Build	i-076651ea2ab3f3f46	Stopped	m6i.2xlarge	–	No alarms	us-east-1a
<input checked="" type="checkbox"/>	Catamaran_f1_Run	i-0b4c8df2758d2f0b9	Running	f1.2xlarge	2/2 checks passed	No alarms	us-east-1c

Instance: i-0b4c8df2758d2f0b9 (Catamaran\_f1\_Run)

Details

Security

Networking

Storage

Status checks

Monitoring

Tags

Instance summary

Instance ID

i-0b4c8df2758d2f0b9 (Catamaran\_f1\_Run)

IPv6 address

–

Public IPv4 address

54.173.149.133 | open address

Instance state

Running

Private IPv4 addresses

172.31.83.224

Public IPv4 DNS

ec2-54-173-149-133.compute-1.amazonaws.com | open address

Note the IPv4 DNS address for the instance.  
Hint: click to copy to clipboard

# Basics of Amazon AWS

## Connecting to your AML with ssh (2/2)

In a terminal on your laptop/desktop, connect to your AML:

```
$ ssh -i ~/.ssh/MyPrivateKey.pem ubuntu@ec2-54-173-149-133.compute-1.amazonaws.com
```

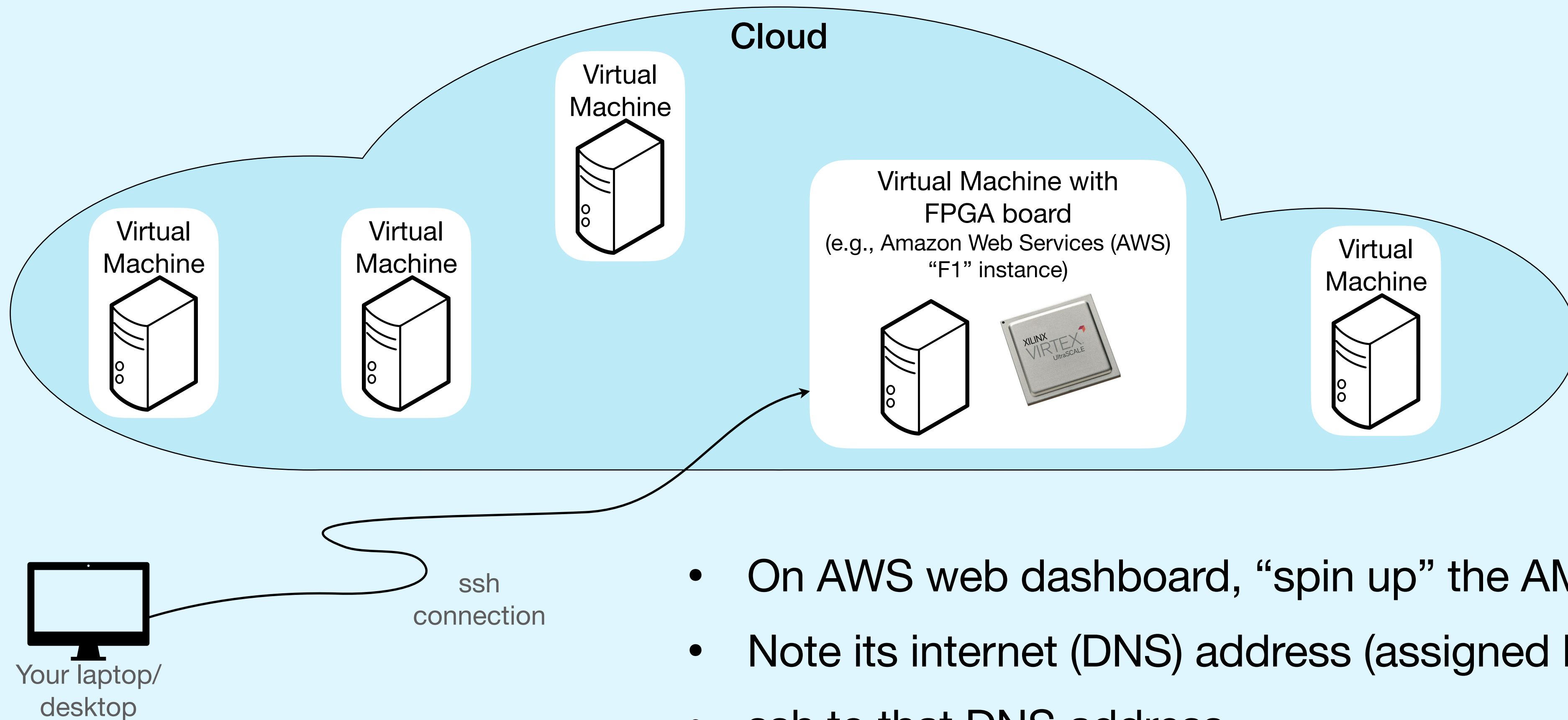
Note: you can copy files to and from your AML using “scp” (which is based on “ssh”)

```
$ scp -i ~/.ssh/MyPrivateKey.pem \  
    localfile \  
    ubuntu@ec2-54-173-149-133.compute-1.amazonaws.com:~/remotefile
```

```
$ scp -i ~/.ssh/MyPrivateKey.pem \  
    ubuntu@ec2-54-173-149-133.compute-1.amazonaws.com:~/remotefile \  
    localfile
```

# Basics of Amazon AWS

## DEMO: connect to your “run” AMI



- On AWS web dashboard, “spin up” the AMI into “running” state
- Note its internet (DNS) address (assigned by AWS during spin-up)
- ssh to that DNS address
- Tour of tutorial directory contents



# Basics of Amazon AWS

- AMIs (virtual machines in the Amazon cloud)
- DEMO: Connecting to an AMI using “ssh”
- *About AWS bitfiles; available Catamaran/ARIFIC bitfiles*

# Basics of Amazon AWS

## About AWS bitfiles

- Unlike “on-premises” FPGAs (on your lab bench/desktop), on AWS, FPGA bitfiles reside somewhere in the cloud (we have no direct access to the actual bitfile).
- Each bitfile has unique ids:
  - AFI (Amazon FPGA Image). These are unique within an AWS geographic region.
  - AGFI (...Global...). These are unique across all AWS geographic regions.
- See later section of this tutorial re. creating a bitfile and obtaining its AFI and AGFI
- AWS makes available software that, given an AGFI, will fetch the bitfile from somewhere in the cloud and load it into the FPGA in your instance.

*(The author is unclear why AWS has two IDs for a bitfile, the AFI and AGFI, instead of just the AGFI?)*

# Basics of Amazon AWS

Available pre-built bitfiles in Catamaran/ARIFIC  
(all based on open-source CPUs)

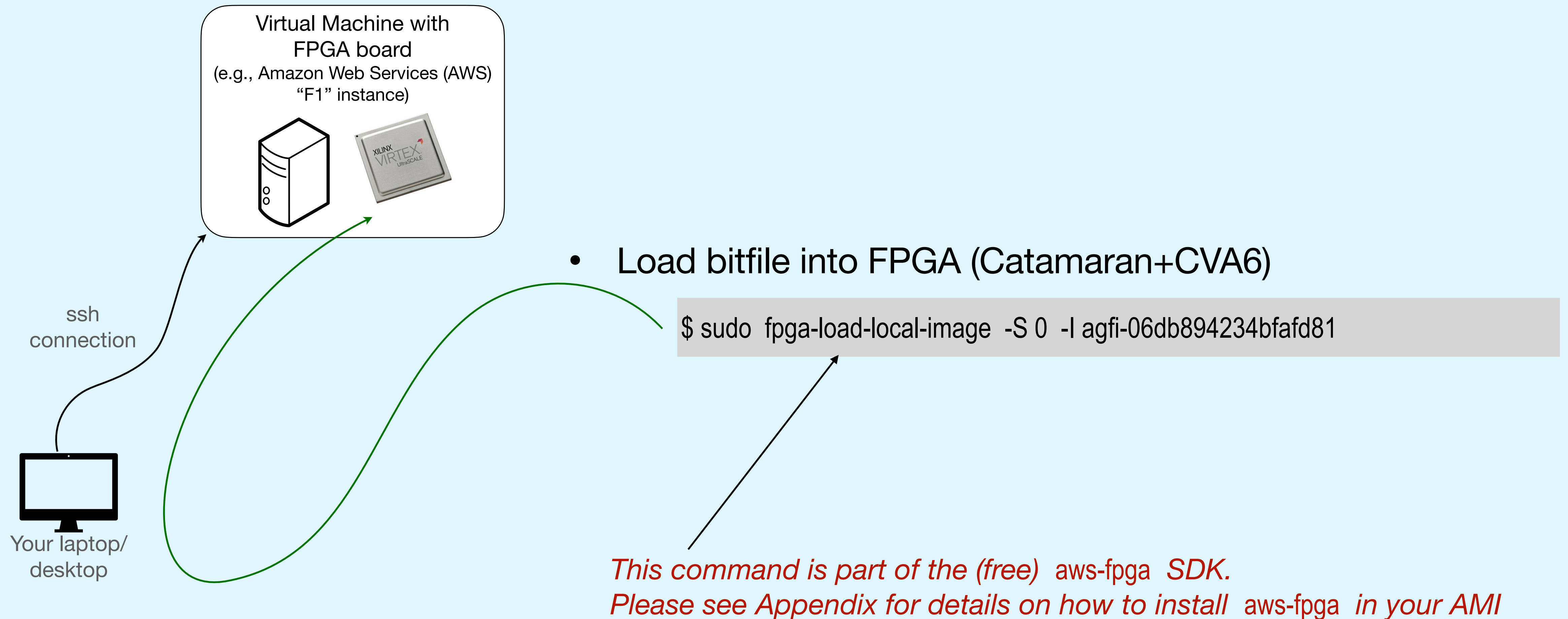
CPU	Original HDL	ISA	Runs bare-metal programs	Runs Linux
Berkeley/SiFive Rocket	Chisel	RV64GC MSU privilege levels Sv39 virtual memory	Yes	Yes
Bluespec Flute	BSV	RV64GC MSU privilege levels Sv39 virtual memory	Yes	Yes
OpenHardware Group CVA6 (a.k.a. ETH Zurich Ariane)	SystemVerilog	RV64GC MSU privilege levels Sv39 virtual memory	Yes	Yes (expected 3/2023)

*In this tutorial we'll show demos on Amazon AWS using Catamaran with Rocket and CVA6*

*Other low-hanging fruit: Berkeley/SiFive BOOM and MIT RISCY-000  
(both designs speculative, superscalar, out-of-order)*

# Basics of Amazon AWS

## DEMO: Loading an AWS bitfile into the FPGA



# What you can do with Catamaran/ARIFIC

- *DEMO: Cross-compile and run ISA tests*
- DEMO: Cross-compile C programs for bare-metal and Linux
- DEMO: Run C programs on bare-metal
- DEMO: Run Linux, with networking and block devices
- DEMO: Run C programs under Linux



# What you can do with Catamaran/ARIFIC

## Cross-compile and run ISA tests

### What are “ISA tests”?

- RVI (RISC-V International, <https://riscv.org>) provides a standard set of tests for the RISC-V Instruction Set Architecture (ISA)
  - <https://github.com/riscv-software-src/riscv-tests>
- Consists of a number of assembly-language program files; each one focuses on testing one particular RISC-V instruction (opcode)
  - 236 tests for RV64 IMAFDC + MSU privileges + Sv39 Virtual Memory
  - 173 tests for RV32 IMAFDC + MSU privileges + Sv32 Virtual Memory
- Each program contains a number of sub-tests (each self-checking)
- Each program ends by writing to a particular “tohost” MMIO address
  - 0, if all sub-tests succeed (pass)
  - N, if sub-test N failed

# What you can do with Catamaran/ARIFIC

## Cross-compile ISA tests

Please see Appendix for info on installing the (free) RISC-V GNU Toolchain (“gcc” and friends).

This tutorial repository contains, in the dir `ISA_Tests/`

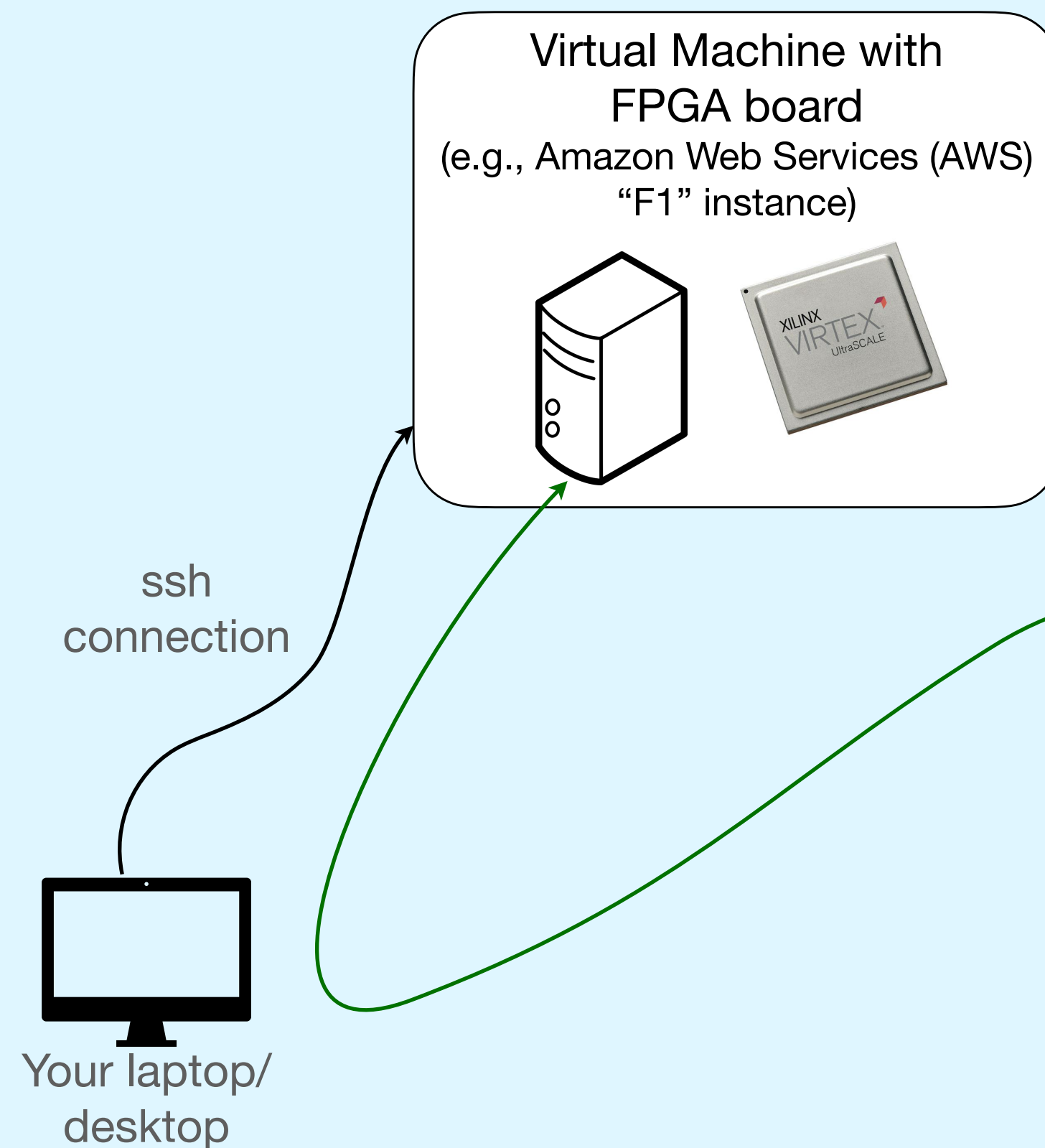
- A copy of the RISC-V ISA tests source code in `ISA_Tests/isa/` (see GitHub URL on previous slide)
- A Makefile and linker scripts to cross-compile the RISC-V ISA tests for RV64GC+MSU+Sv39
- Pre-built results of cross-compiling: set of RISC-V ELF files for the tests in `ISA_Tests/isa/elfs`

Note: our linker script sets

- Catamaran/ARIFIC program-start address = `0x_8000_0000`
- “tohost” MMIO address = `0x_6fff_0010`
- See `ISA_Tests/README.txt` for details

# What you can do with Catamaran/ARIFIC

## DEMO: cross-compile RISC-V ISA tests



### Prerequisites:

- your RISC-V Gnu Toolchain (including cross-compiler gcc) is installed
- you've defined RISC\_V environment variable to point at your toolchain installation directory
- you've added `${RISC_V}/bin` to your PATH environment variable.

```
$ cd ISA_Tests/isa  
$ make
```

It will produce 100s of ELF files with a naming convention like this:

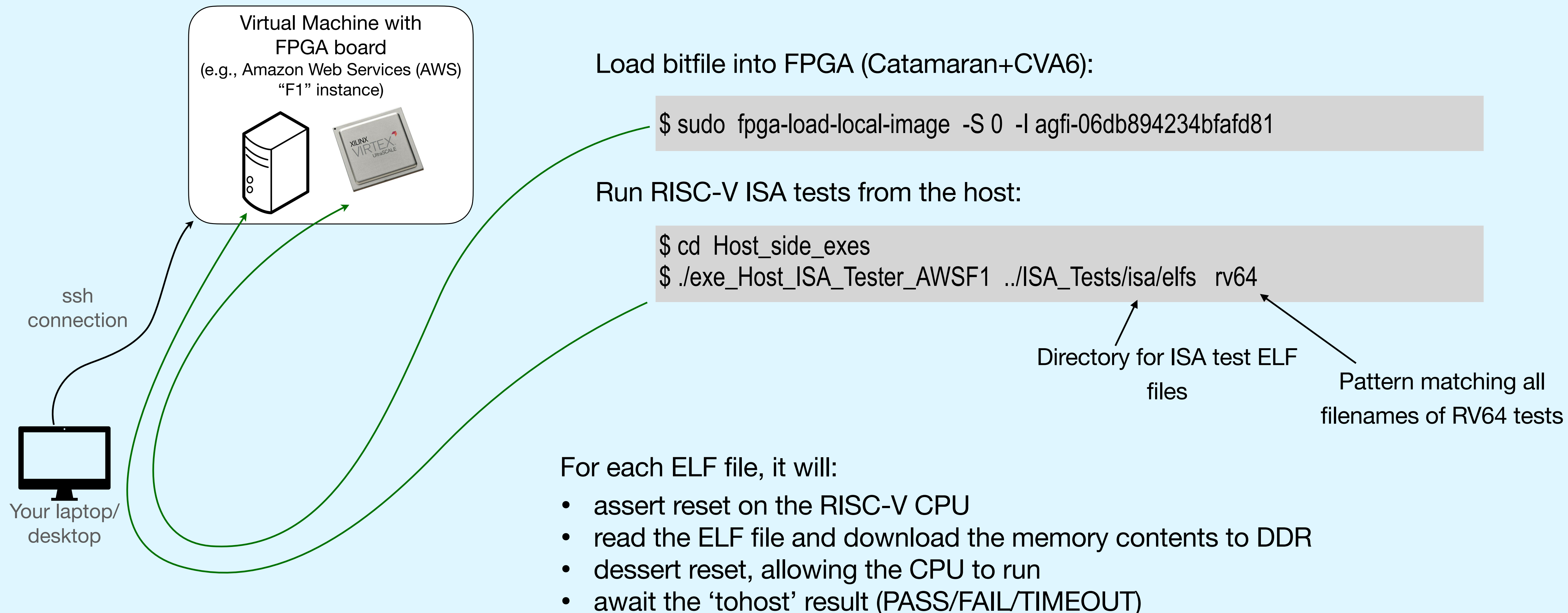
rv64ui-p-add	(user-level, integer, physical memory, 'add' opcode)
rv64ui-v-add	(..., virtual memory, ...)

as well as "object dump" (disassembly) files like this:

rv64ui-p-add.dump

# What you can do with Catamaran/ARIFIC

## DEMO: run RISC-V ISA tests



# What you can do with Catamaran/ARIFIC

- DEMO: Cross-compile and run ISA tests
- *DEMO: Cross-compile C programs for bare-metal and Linux*
- DEMO: Run C programs on bare-metal
- DEMO: Run Linux, with networking and block devices
- DEMO: Run C programs under Linux



# What you can do with Catamaran/ARIFIC

## Bare-metal (no OS) C programs and C programs under Linux

Bare-metal C program	C program under Linux
No system calls. E.g., “printf/putc/putchar”, “scanf/getc/getchar” are compiled to function calls to library code that directly interacts with a console device.	Has system calls for OS services. E.g., “printf/putc/putchar”, “scanf/getc/getchar” are compiled to system calls, and the OS interacts with a console device.
No “exit”; typically ends in an infinite idle loop.	Typically ends in an “exit” system call that reverts to the OS scheduling loop.

# What you can do with Catamaran/ARIFIC

## Two small example C programs in the repository

This tutorial repository contains

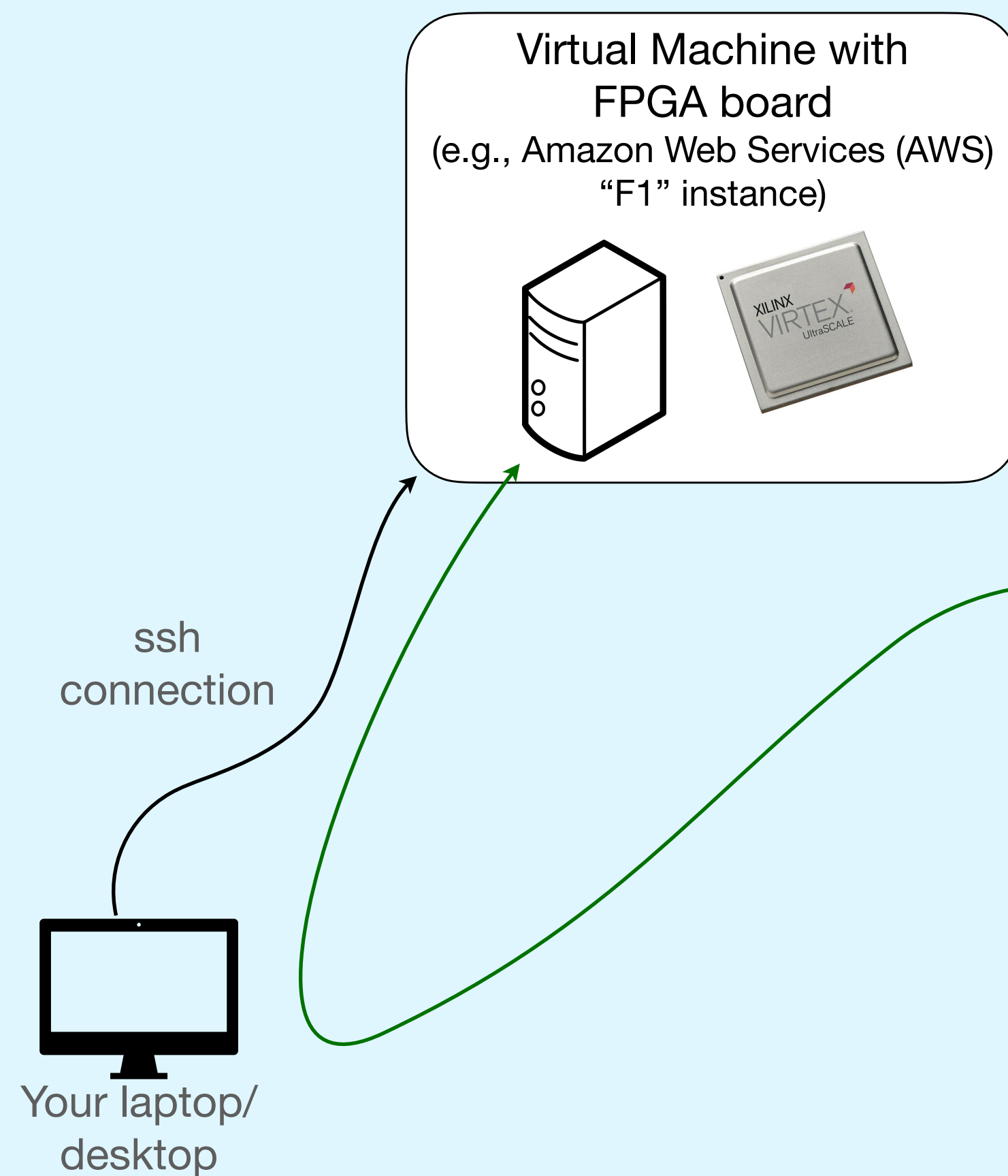
- Two small C programs: “Hello World!” and “cat” (echoes stdin to stdout)
- A Makefile and linker scripts to cross-compile the C programs for RV64GC
- Pre-built results of cross-compiling the examples: two RISC-V ELF files

Note: our linker script sets

- Catamaran/ARIFIC program-start address = 0x\_8000\_0000
- UART MMIO address = 0x\_6010\_0000

# What you can do with Catamaran/ARIFIC

## DEMO: Cross-compile C programs to run on “bare-metal” (no OS)



### Prerequisites:

- your RISC-V Gnu Toolchain (including cross-compiler gcc) is installed
- you’ve defined RISC\_V environment variable to point at your toolchain installation directory
- you’ve added `${RISC_V}/bin` to your PATH environment variable.

### Classical “Hello World!” program

```
$ cd C_Examples/hello  
$ make all_bare
```

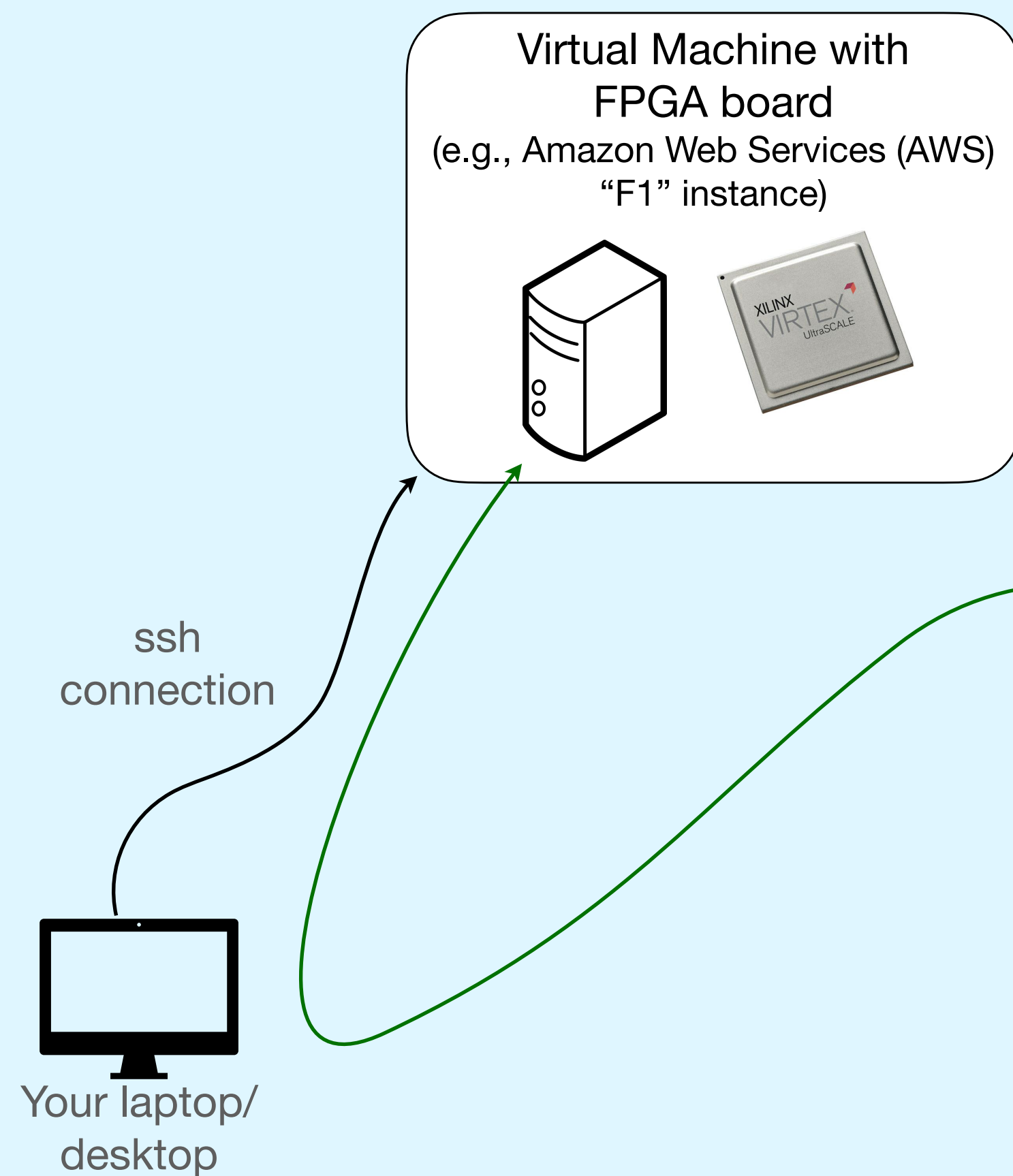
Creates: `hello.RV64.bare.elf` `hello.RV64.bare.map` `hello.RV64.bare.objdump`

### Program that just echoes stdin to stdout (UART-in to UART-out)

```
$ cd C_Examples/cat  
$ make all_bare
```

# What you can do with Catamaran/ARIFIC

## DEMO: Cross-compile C programs to run under Linux



### Prerequisites:

- your RISC-V Gnu Toolchain (including cross-compiler gcc) is installed
- you've defined RISC\_V environment variable to point at your toolchain installation directory
- you've added `${RISC_V}/bin` to your PATH environment variable.

### Classical "Hello World!" program

```
$ cd C_Examples/hello  
$ make all_linux
```

Creates: `hello.RV64.linux.elf` `hello.RV64.linux.map` `hello.RV64.linux.objdump`

### Program that just echoes stdin to stdout (UART-in to UART-out)

```
$ cd C_Examples/cat  
$ make all_linux
```

# What you can do with Catamaran/ARIFIC

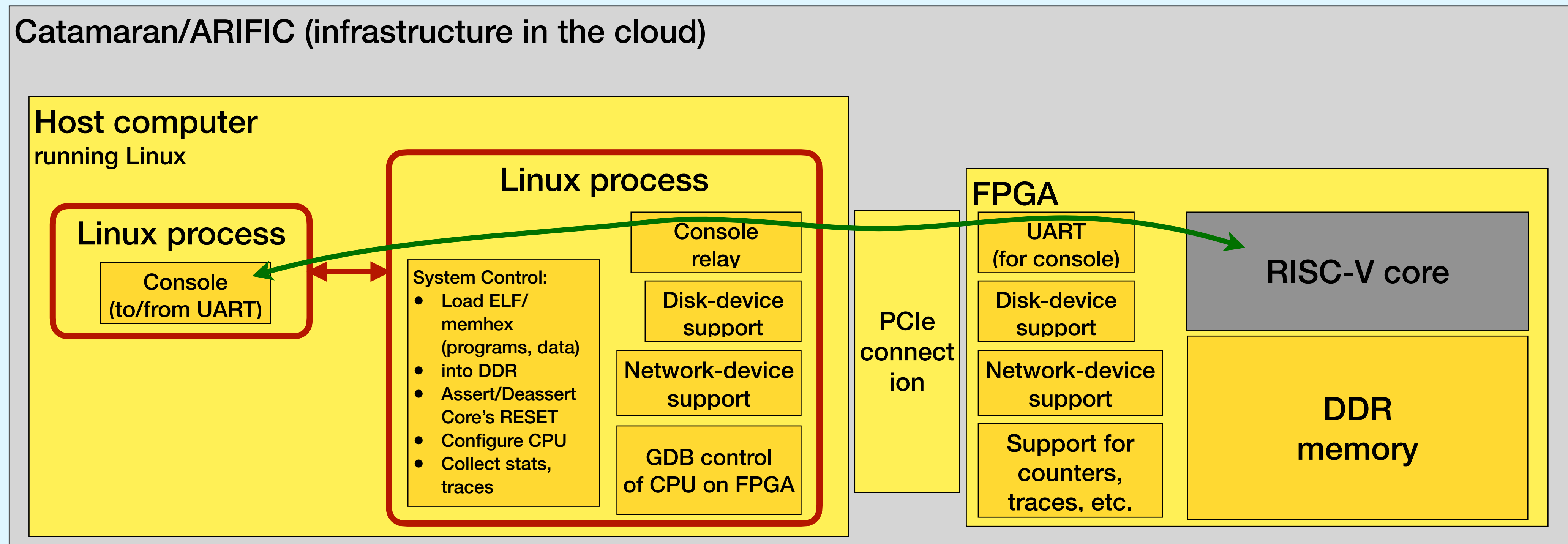
- DEMO: Cross-compile and run ISA tests
- DEMO: Cross-compile C programs for bare-metal and Linux
- *DEMO: Run C programs on bare-metal*
- DEMO: Run Linux, with networking and block devices
- DEMO: Run C programs under Linux



# What you can do with Catamaran/ARIFIC

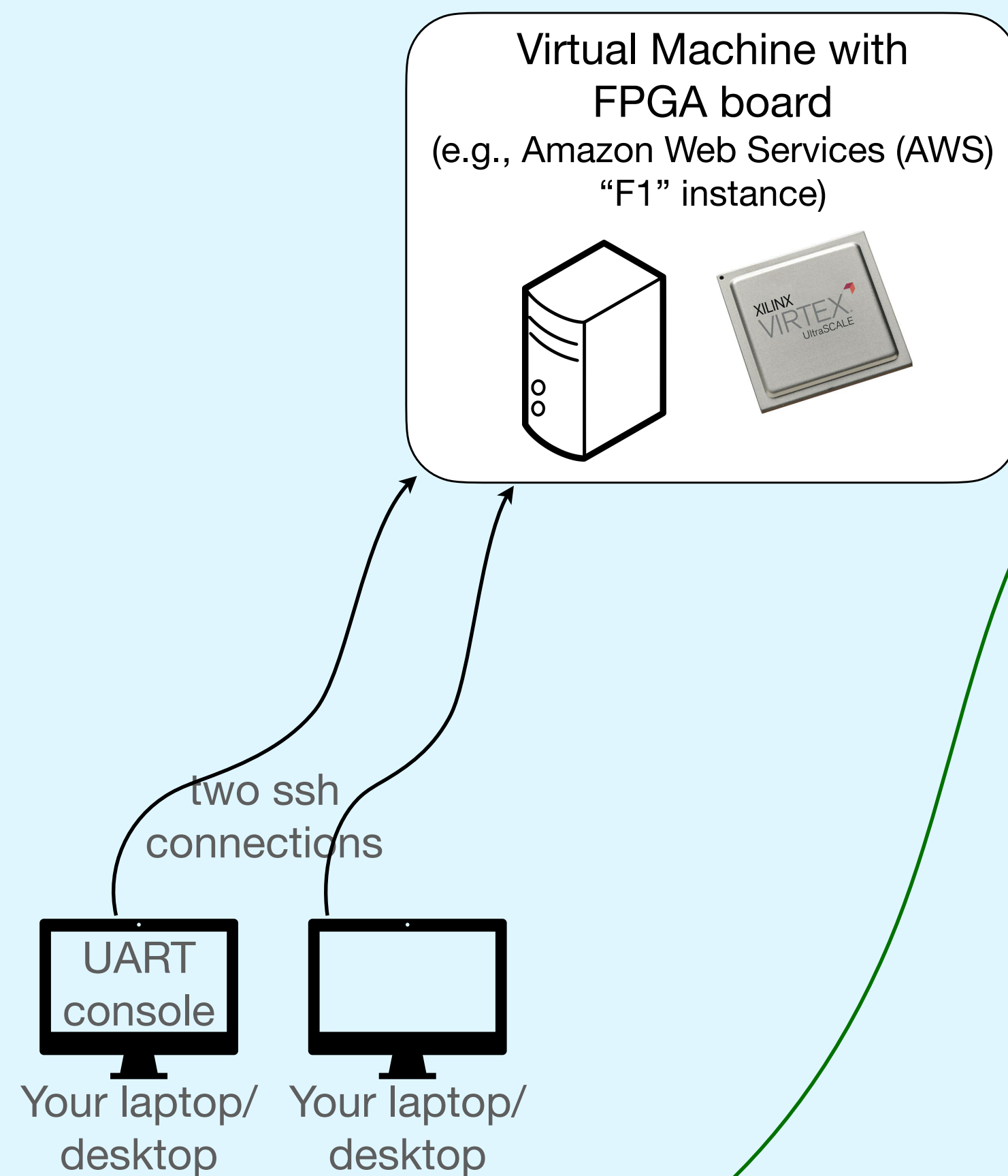
## For most programs we need a UART (console device for “printf”)

- Catamaran/ARIFIC contains a UART and connections to a terminal on the host computer



# What you can do with Catamaran/ARIFIC

## DEMO: Open a second terminal on the AMI for the UART process



Make 2nd ssh connection to AMI; start UART console

```
$ ssh -i ~/.ssh/MyPrivateKey.pem \
ubuntu@ec2-54-173-149-133.compute-1.amazonaws.com
```

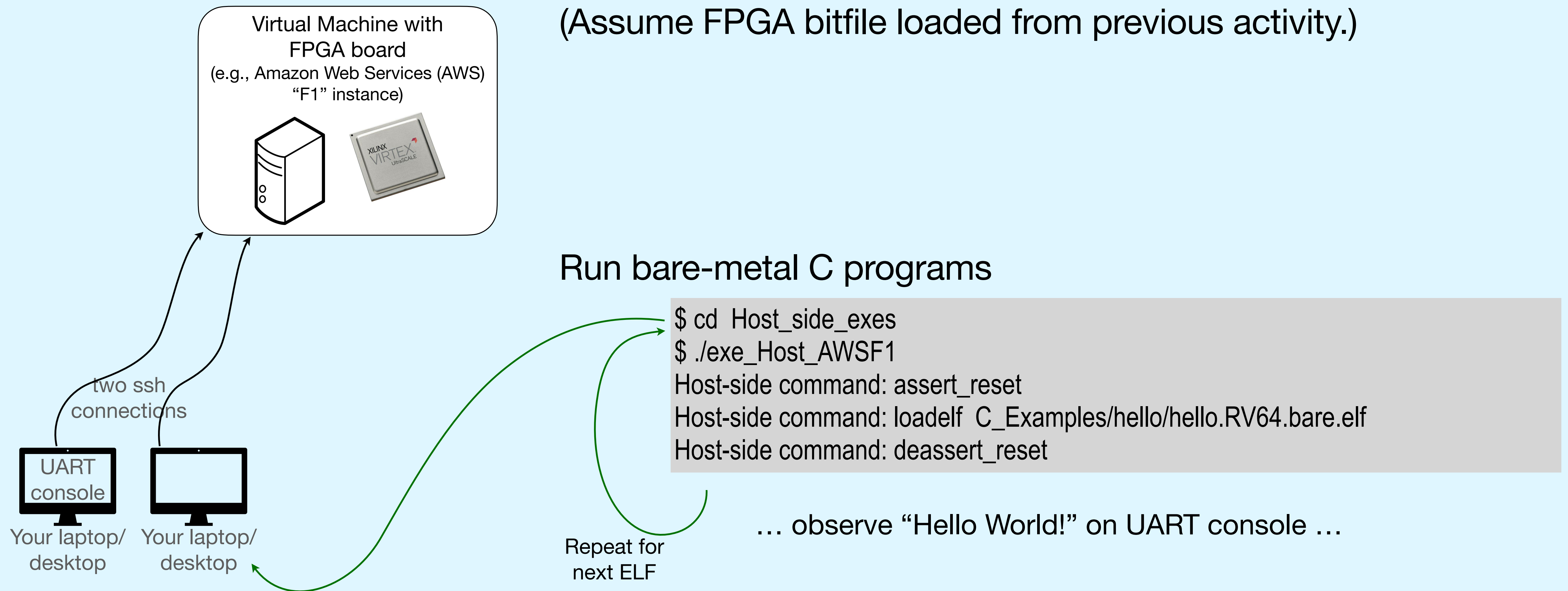
In the terminal, start the "UART\_Console" program

```
$ sudo UART_Console --log_UART.txt
```

```
--22:32:22--ip-172-31-83-224: ~/Git/Tutorial_at_HPCA-29/Host_side_exes
$ sudo ./UART_Console --log_UART.txt
ptyname_file filename = UART_ptynome_file
UART output logfile name = (null)
Awaiting file 'UART_ptynome_file' for reading pty name
█
```

# What you can do with Catamaran/ARIFIC

## DEMO: run bare-metal C programs

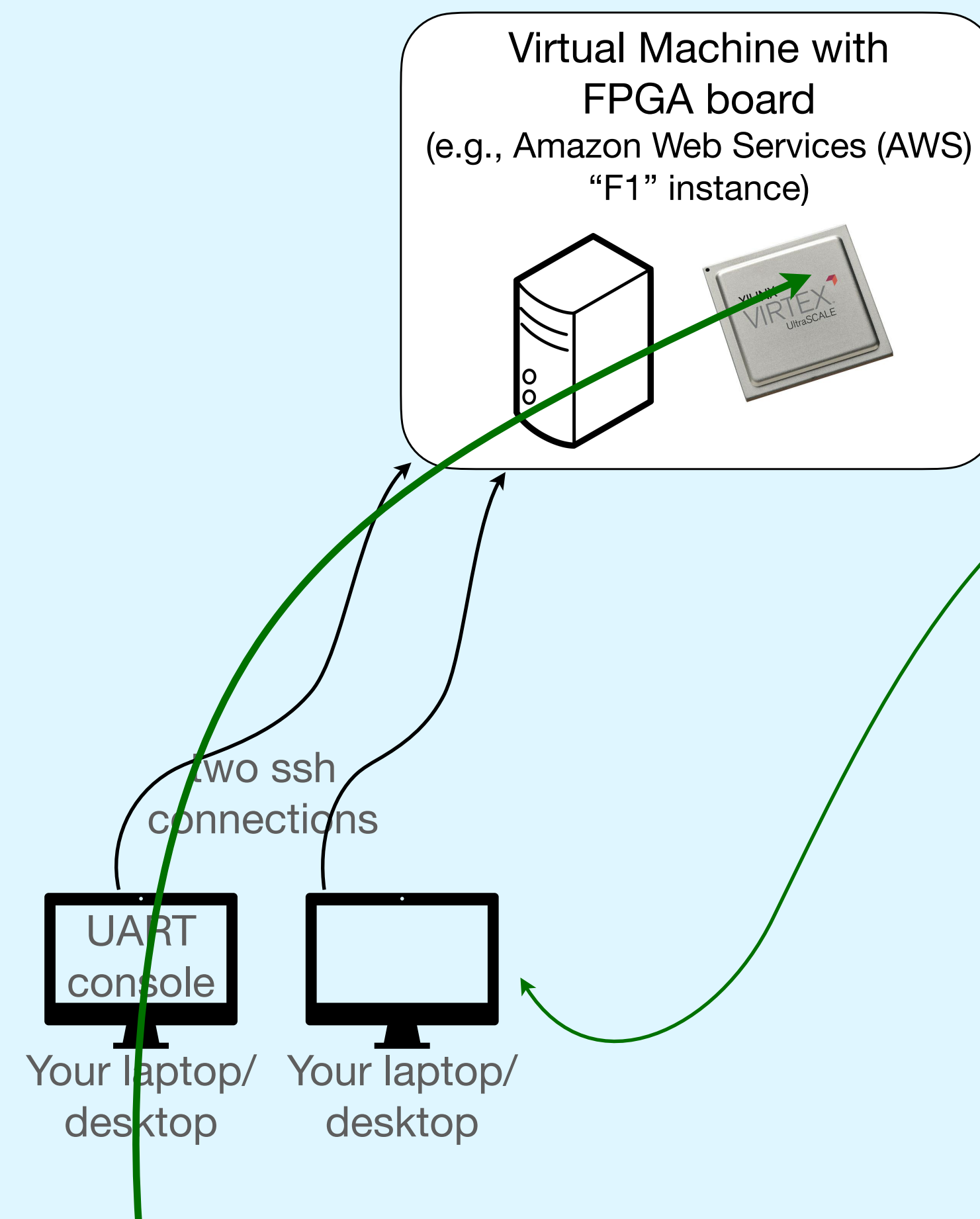


# What you can do with Catamaran/ARIFIC

- DEMO: Cross-compile and run ISA tests
- DEMO: Cross-compile C programs for bare-metal and Linux
- DEMO: Run C programs on bare-metal
- *DEMO: Run Linux, with networking and block devices*
- DEMO: Run C programs under Linux

# What you can do with Catamaran/ARIFIC

## DEMO: Run Linux



... interact with the Linux shell

Load bitfile into FPGA (Catamaran+Rocket):

```
$ sudo fpga-load-local-image -S 0 -l agfi-0e54cfdbc5e783a9b
```

Linux is just another ELF file, just like our bare-metal C programs

```
$ cd Host_side_exes
$ ./exe_Host_AWSF1
Host-side command: assert_reset
Host-side command: loadelf <path to Linux ELF>
Host-side command: deassert_reset
```

Observe console messages from OpenSBI boot loader,  
followed by console messages from Linux boot,  
finally the Linux shell prompt.  
Then, ...

*But note: without networking or block devices (disks), Linux is very limited*



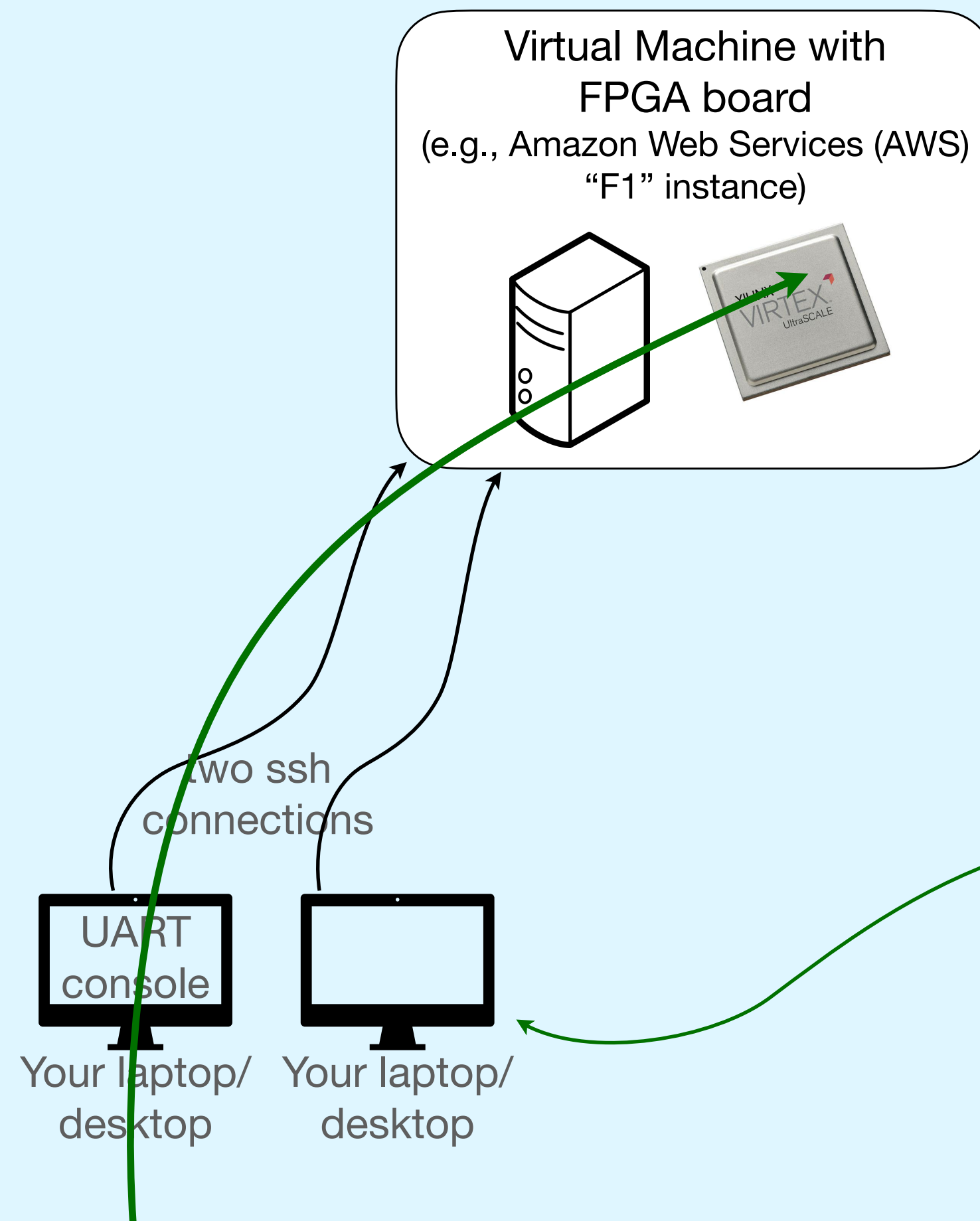
# What you can do with Catamaran/ARIFIC

## DEMO: Run Linux with a block device (1/2)

Create a file on the Ubuntu AMI host that will act as a block-device (disk) for Linux:

```
$ truncate --size=1G disk.img
```

This represents a 1 GiB “unformatted” disk; we will format it with a filesystem from inside Linux.



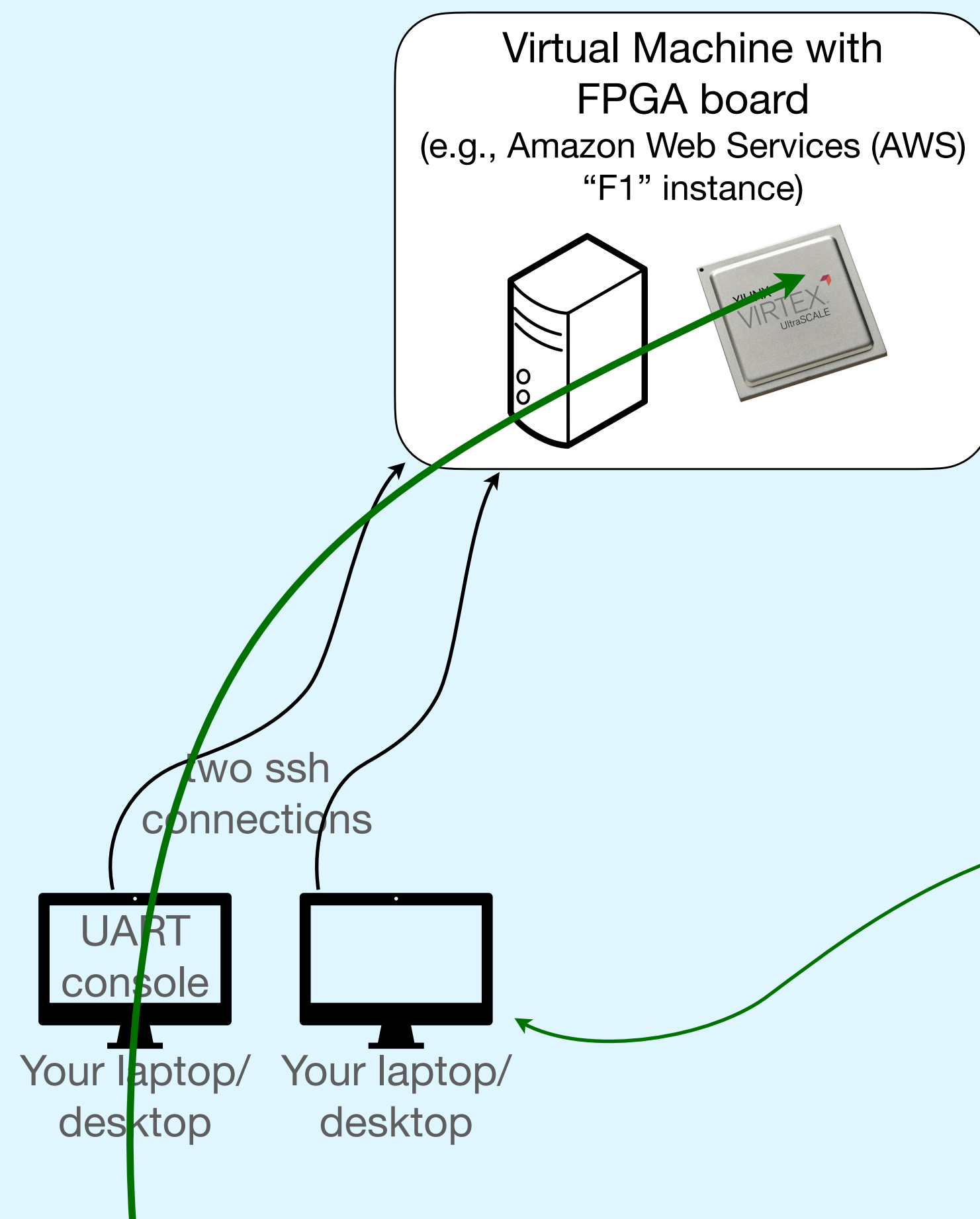
Boot Linux again on the FPGA, providing it these facilities:

```
$ sudo ./exe_Host_AWSF1. --elf ./Elfs/Linux.elf \  
--blockdev ./disk.img \  
--tundev tap0
```

... interact with the Linux shell and use block device (see next slide)

# What you can do with Catamaran/ARIFIC

## DEMO: Run Linux with block device (2/2)



After booting Linux, observe there is a block device:

```
# ls /dev/vda
```

Format it with a filesystem:

```
# mkfs.ext2 /dev/vda
```

Mount the filesystem:

```
# mount -t ext2 /dev/vda /mnt
```

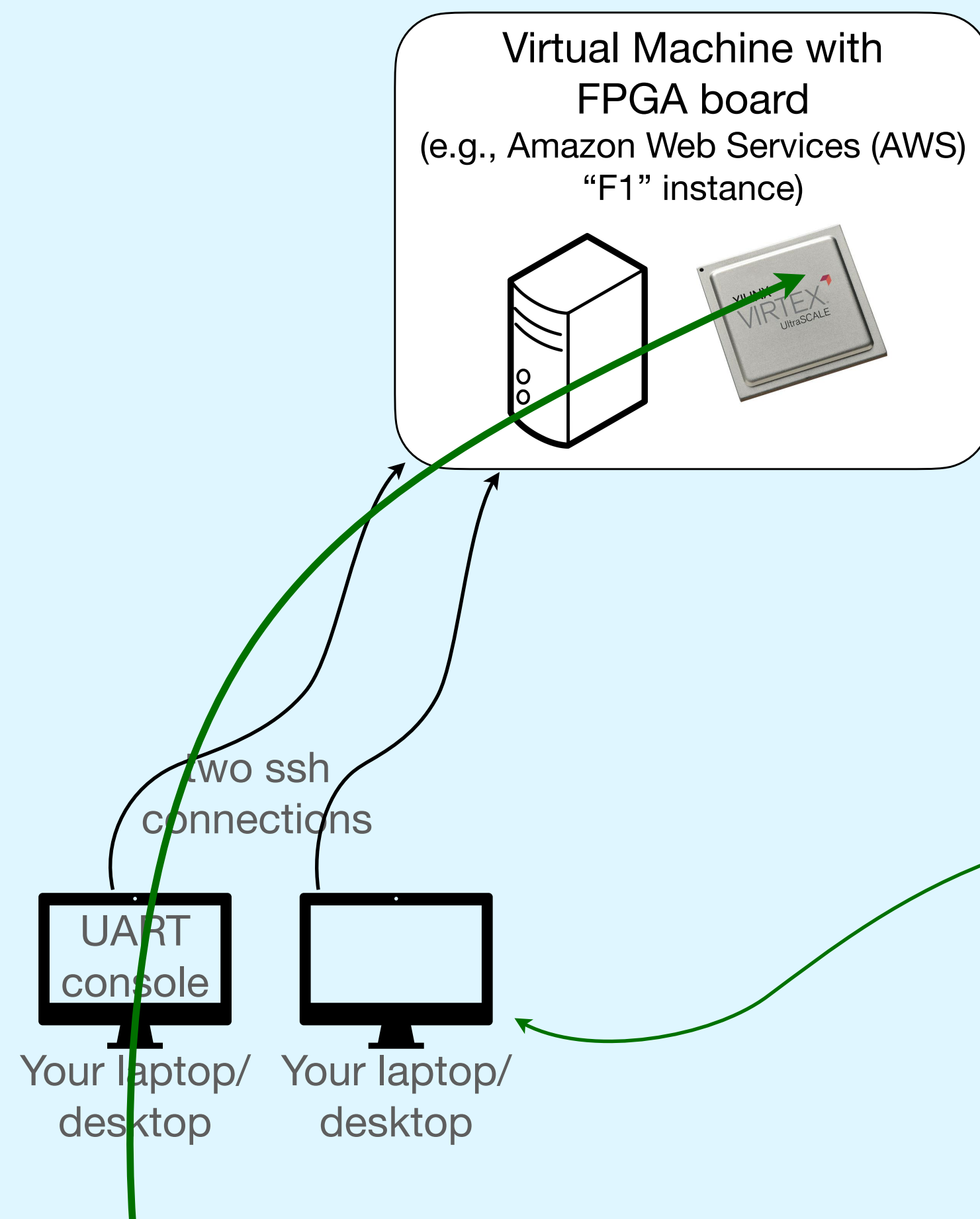
Interact with the filesystem

```
# ls ..  
# cat ...
```

... interact with the Linux shell and use block device

# What you can do with Catamaran/ARIFIC

## DEMO: Run Linux with a network and block device (1/2)



Execute the provided shell script "netinit.sh"

```
$ sudo ./netinit.sh
```

This sets up a TUN/TAP networking device on your Ubuntu AMI, through which Linux on the RISC-V will access the network.

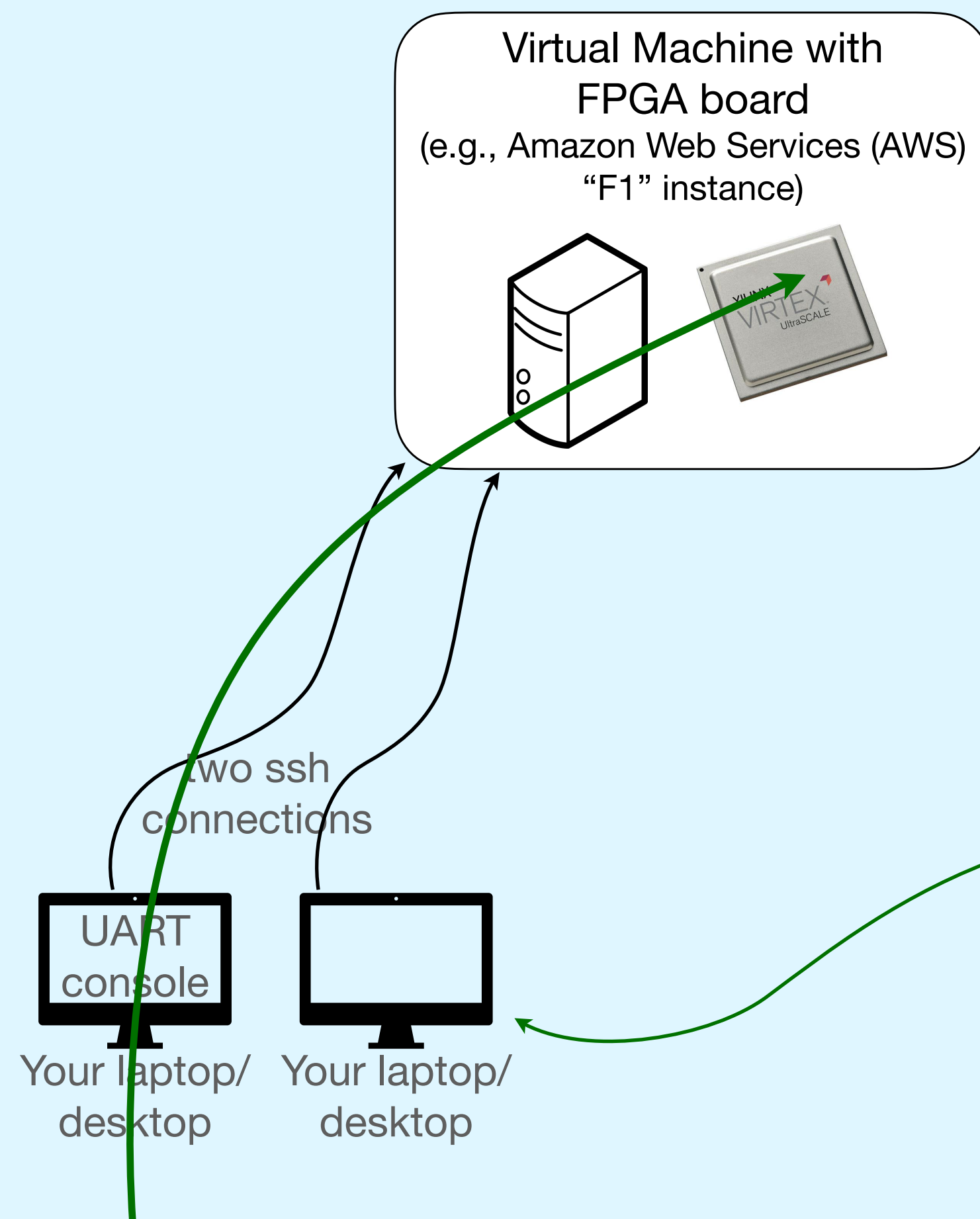
Boot Linux again on the FPGA, providing it these facilities:

```
$ sudo ./exe_Host_AWSF1. --elf ./Elfs/Linux.elf \  
--blockdev ./disk.img \  
--tundev tap0
```

... interact with the Linux shell and use network and block device (see next slide)

# What you can do with Catamaran/ARIFIC

## DEMO: Run Linux with networking and block device (2/2)



After booting Linux, mount the block device:

```
# mount -t ext2 /dev/vda /mnt
```

Observe this network-setup shell script:

```
# cat /mnt/net.sh
ip a add 192.168.3.2/24 dev eth0
ip link set eth0 up
ip route add 0.0.0.0/0 via 192.168.3.1
echo "nameserver 9.9.9.9" > /etc/resolv.conf
```

Execute it:

```
# /mnt/net.sh
```

Use 'ssh' to log in to a remote machine, 'scp' to copy files, etc.:

```
# ssh user@remote.machine.org
# scp localfile user@remonte.machine.org:~/remotefile
# scp user@remonte.machine.org:~/remotefile localfile
```

... interact with the Linux shell and use network and block device

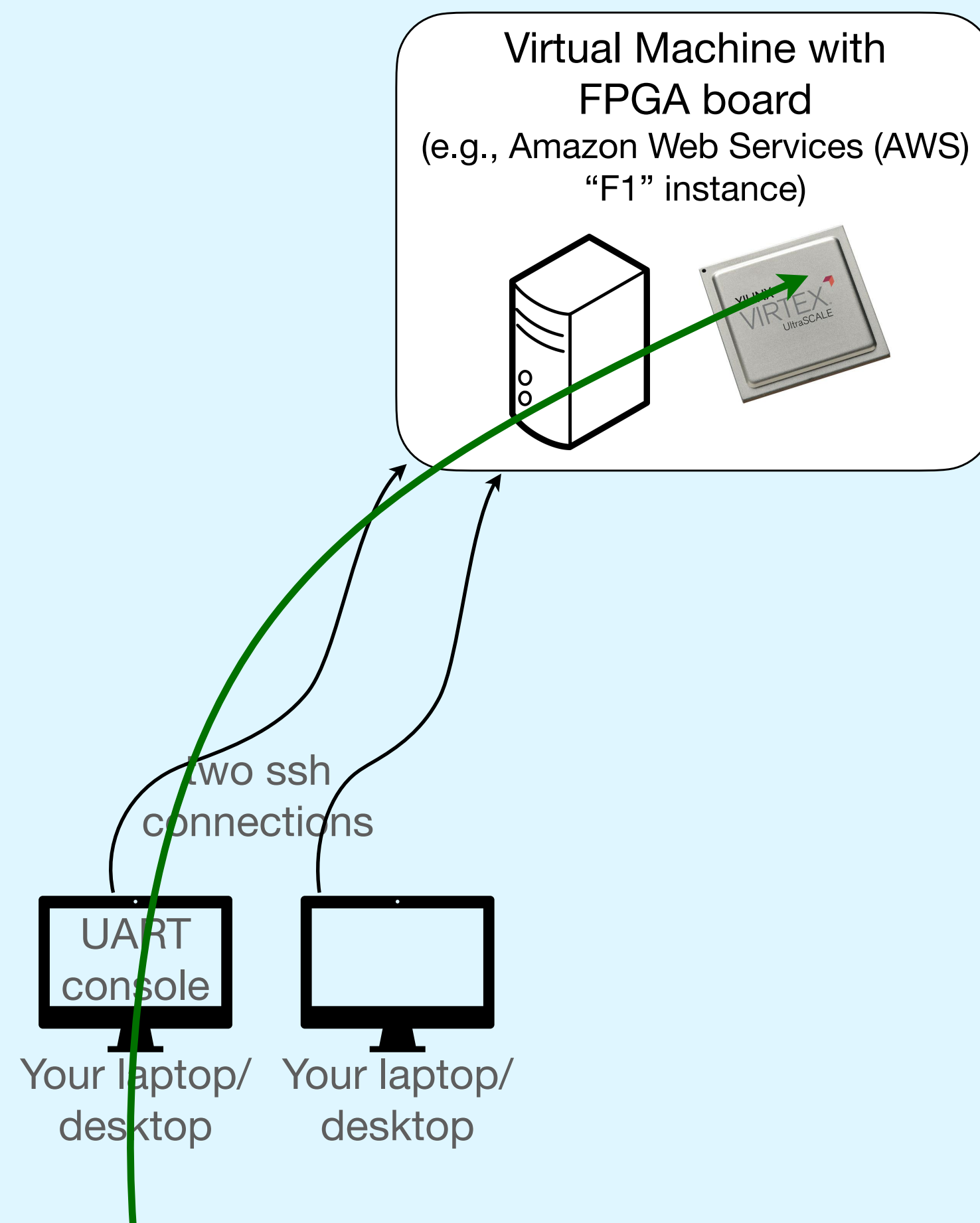
# What you can do with Catamaran/ARIFIC

- DEMO: Cross-compile and run ISA tests
- DEMO: Cross-compile C programs for bare-metal and Linux
- DEMO: Run C programs on bare-metal
- DEMO: Run Linux, with networking and block devices
- *DEMO: Run C programs under Linux*



# What you can do with Catamaran/ARIFIC

## DEMO: Run C programs under Linux



At the Linux shell running on the RISC-V CPU, use 'scp' to copy the ELF files we created earlier for 'hello' and 'cat' for running under Linux:

```
# ls /mnt/  
... hello.RV64.linux.elf ...  
... cat.RV64.linux.elf ...
```

Execute them:

```
# /mnt/hello.RV64.linux.elf  
Hello, World!  
# /mnt/cat.RV64.linux.elf  
... echo chars typed on the keyboard to the screen ...
```

... interact with the Linux shell, run C programs under Linux

# What you can do with Catamaran/ARIFIC

- DEMO: Cross-compile and run ISA tests
- DEMO: Cross-compile C programs for bare-metal and Linux
- DEMO: Run C programs on bare-metal
- DEMO: Run Linux, with networking and block devices
- DEMO: Run C programs under Linux
- *Collecting measurement data*

# What you can do with Catamaran/ARIFIC

## Collecting measurement data

“Hardware Performance Monitor” counters: The RISC-V Privileged ISA Spec defines 29 64-bit performance counters that can be read/written as CSRs (Control/Status Registers). The functionality of these counters (what events they count) is left up to each platform (each core).

During, and at the end of an experiment, code can record hpmcounter values to memory. The Host-Side Hub’s interactive prompt has a command to dump a DDR memory region to a file.

*Note: the AWS F1 FPGA board has 64 GiB of DDR memory.*

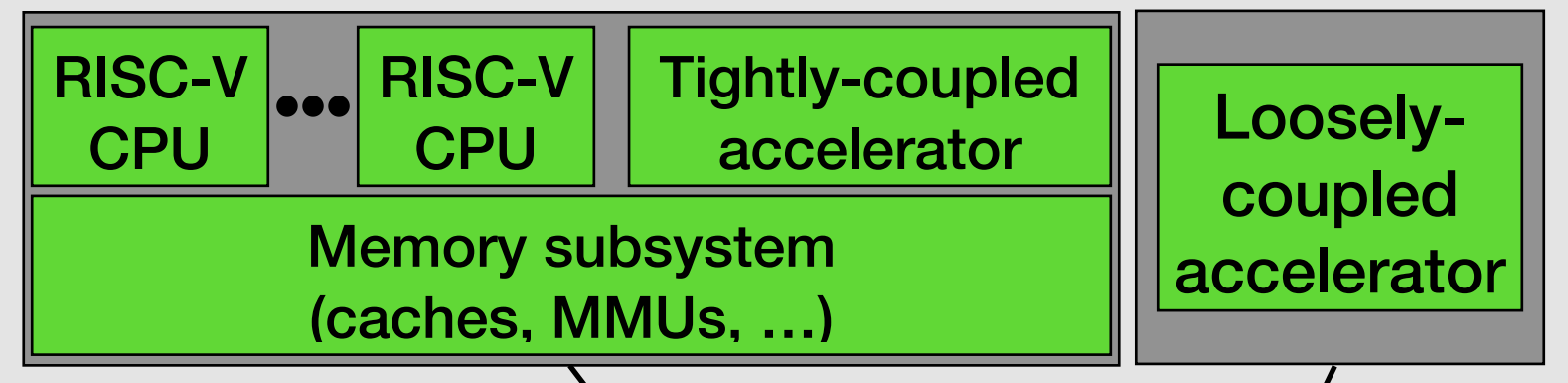
# Plug in your own RISC-V Core

- The Catamaran/ARIFIC Core Interface (RTL)
- DEMO: Build and run a whole-system simulation executable
- DEMO: Build an FPGA bitfile for Amazon AWS

# Plug in your own RISC-V core: goals

## Architecture Researcher's Focus

- CPU microarchitecture
- Memory systems (caches, MMUs, coherence, WMMs, ...)
- Accelerators



## Catamaran/ARIFIC (infrastructure in the cloud)

### Host computer running Linux

#### System Control:

- Load ELF/memhex (programs, data) into DDR
- Assert/Deassert Core's RESET
- Configure CPU
- Collect stats, traces

Console  
(to/from UART)

Disk-device  
support

Network-device  
support

GDB control  
of CPU on FPGA

PCIe  
connection

### FPGA

UART  
(for console)

Disk-device  
support

Network-device  
support

Support for  
counters,  
traces, etc.

(substitutable RISC-V  
core)

DDR  
memory

Assume you've created your own core<sup>1</sup>

1. Build a whole-system simulation executable of the FPGA-side, with your core substituted in place of the demo cores
2. Build the FPGA bitfile of the FPGA-side, with your core substituted in place of the demo cores, and run on AWS

### <sup>1</sup> "Your own RISC-V Core"

#### Options:

- Your own new CPU design
- Modify available CPU (many open-source)
  - microarchitecture change
  - new instruction
  - new CSRs (e.g., counters)
- Modify/replace memory system (caches, MMUs, PMPs, PTWs, ...)
- Add tightly-coupled or loosely coupled accelerator
- ... or other research idea ...

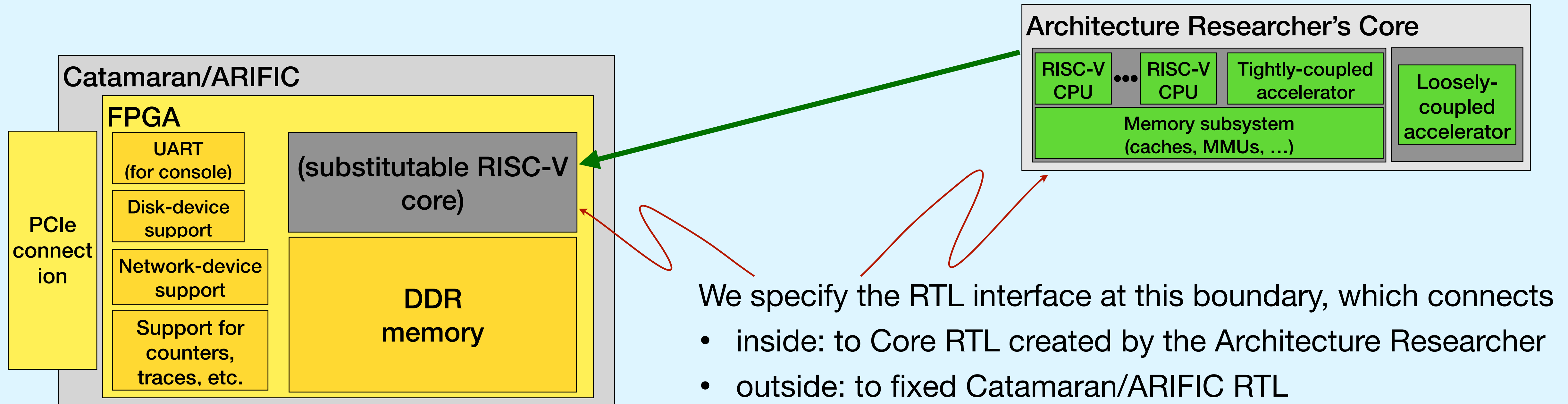


# Plug in your own RISC-V Core

- *The Catamaran/ARIFIC Core Interface (RTL)*
- DEMO: Build and run a whole-system simulation executable
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# Plug in your own RISC-V core

## The Catamaran/ARIFIC Core Interface (RTL)



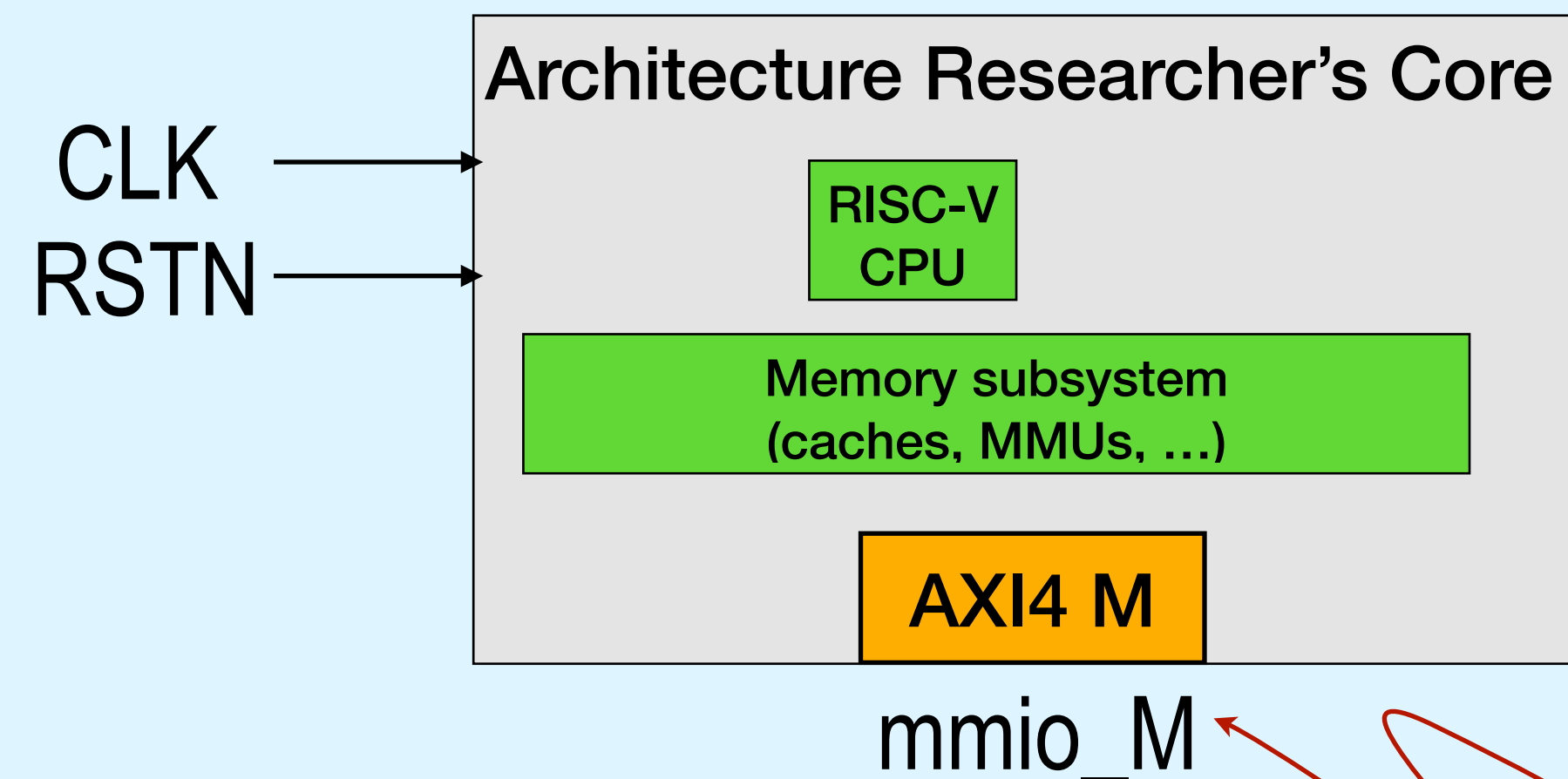
Please see this file in the tutorial repository: `Catamaran_Core_Interface/mkAWSteria_Core_EMPTY.v` which contains a template “empty” core module with the required RTL inputs and outputs. The Architecture Researcher substitutes their core for the module body, connects inputs/outputs.

# Plug in your own RISC-V core

## The Catamaran/ARIFIC Core Interface (RTL)

DEMO: View actual interface RTL in tutorial repository: `Catamaran_Core_Interface/mkAWSteria_Core_EMPTY.v`

*Minimal core*



CPU can be RV32 or RV64,  
from small (“embedded, IoT”)  
to large (“application”, “server”).

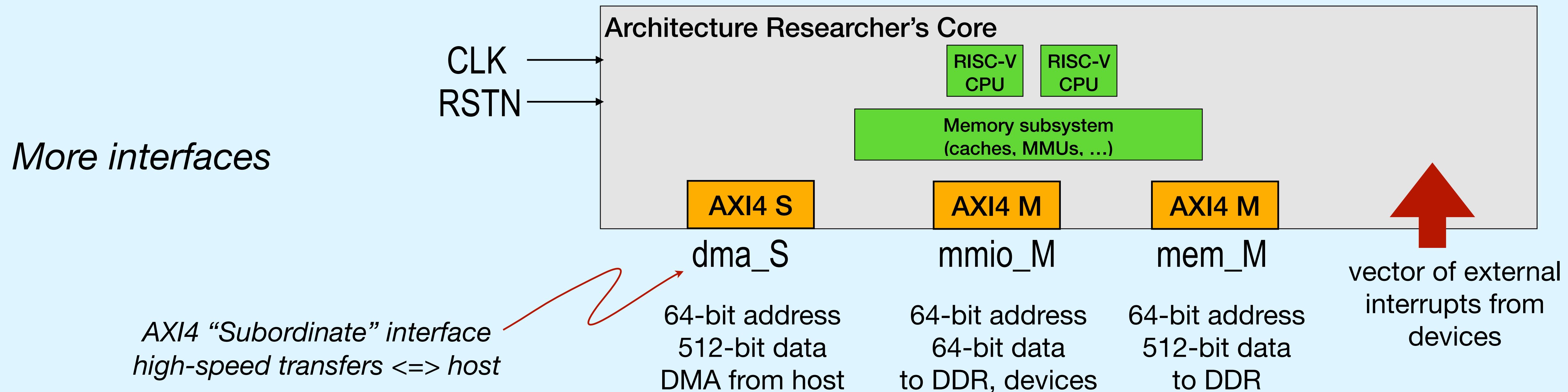
AXI4 “Manager” interface  
64-bit address, 64-bit data,  
connects to DDR memory,  
UART, other devices

CLK can connect to one of six available clocks provided by Catamaran/ARIFIC, ranging from about 15 MHz to 250 MHz, depending on the speed/timing requirements of the core.

# Plug in your own RISC-V core

## The Catamaran/ARIFIC Core Interface (RTL)

DEMO: View actual interface RTL in tutorial repository: `Catamaran_Core_Interface/mkAWSteria_Core_EMPTY.v`

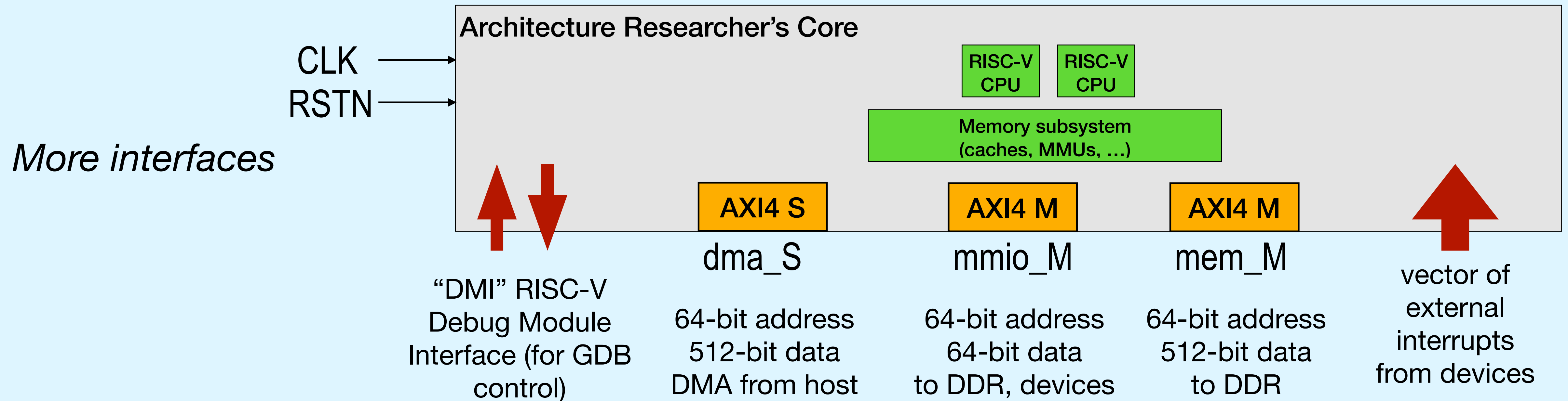


- In some cores, mem\_M transfers entire cache lines at the back-end of an L2 cache
- In some cores, dma\_S connects to a cache-coherent port in the memory subsystem

# Plug in your own RISC-V core

## The Catamaran/ARIFIC Core Interface (RTL)

DEMO: View actual interface RTL in tutorial repository: `Catamaran_Core_Interface/mkAWSteria_Core_EMPTY.v`

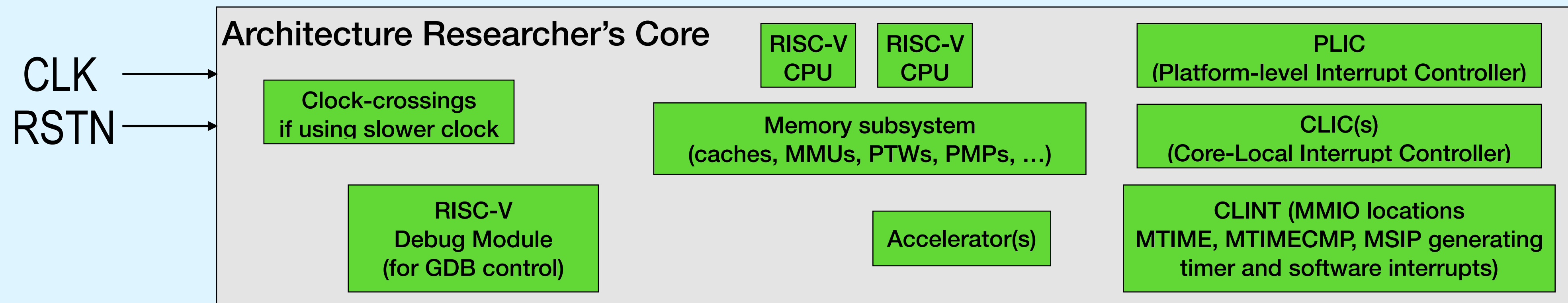




# Plug in your own RISC-V core

## The Catamaran/ARIFIC Core Interface (RTL)

Typical modules found in more complete and complex cores



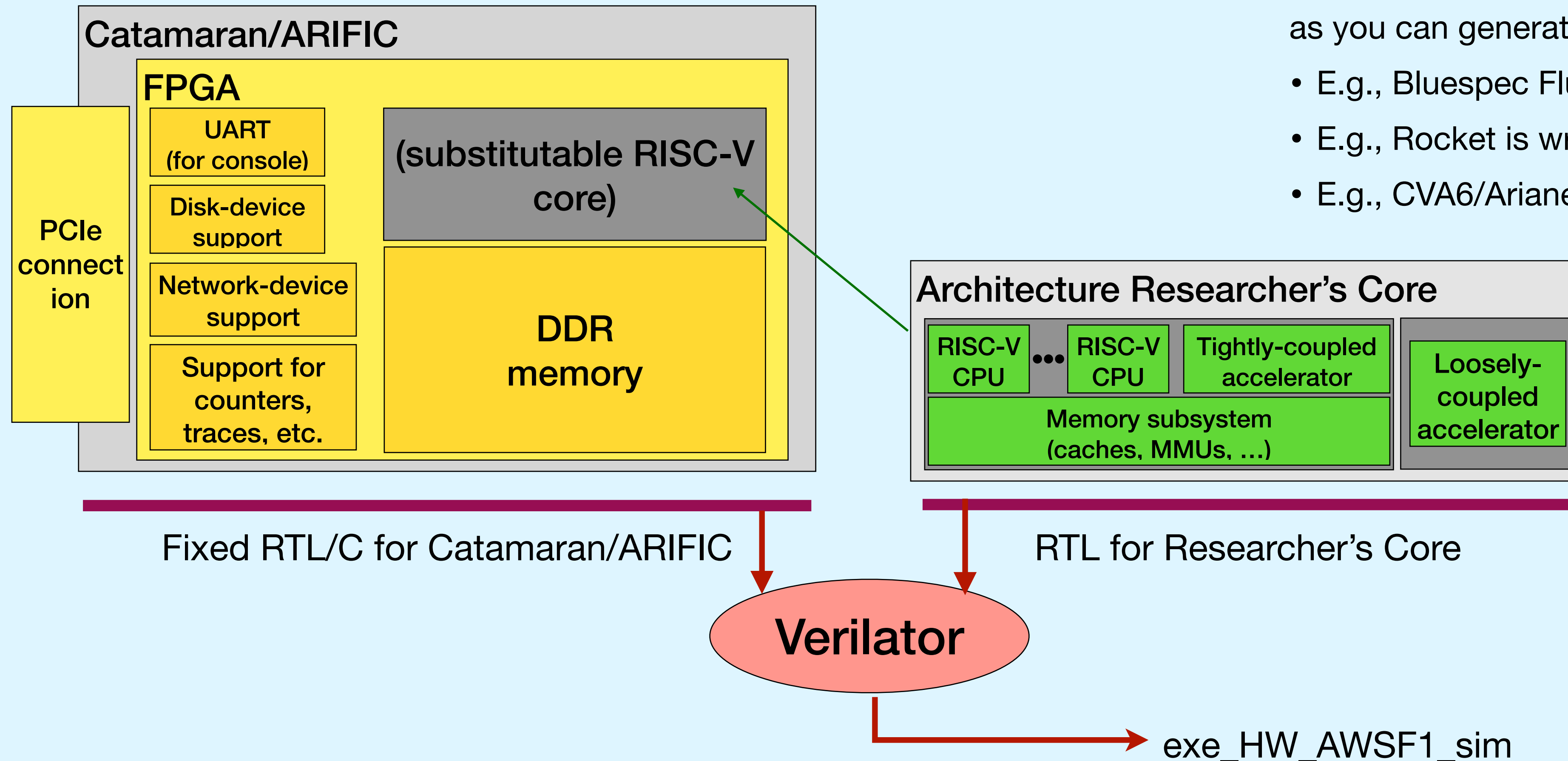
- Catamaran provides 6 clocks at various steps from 250MHz down to about 15 MHz
- All these components are available open-source from many projects; architecture researcher can focus on the subject module(s) of interest.

# Plug in your own RISC-V Core

- The Catamaran/ARIFIC Core Interface (RTL)
- *DEMO: Build and run a whole-system simulation executable*
- DEMO: Build an FPGA bitfile for Amazon AWS

# Plug in your own RISC-V core

## Build a whole-system simulation executable



Researcher's core can be written in any HDL, as long as you can generate RTL for it.

- E.g., Bluespec Flute is written in BSV
- E.g., Rocket is written in Chisel
- E.g., CVA6/Ariane is written in SystemVerilog

# Plug in your own RISC-V core

## DEMO: Build a whole-system simulation executable

This tutorial repository contains

- Fixed RTL for Catamaran/ARIFIC
- Makefile for using Verilator to create a whole-system simulation executable
  - Note: Verilator is a free, open-source tool for creating RTL simulators
  - For installation, please see: <https://verilator.org/guide/latest/install.html>

Build\_HW/

Catamaran\_C/

Catamaran\_RTL/

Core\_CVA6\_Wrapper\_RTL/

bsc\_lib\_RTL/

<https://github.com/openhwgroup/cva6.git>

Fixed RTL/C for Catamaran/ARIFIC

RTL from OpenHardware Group CVA6 (Ariane) RISC-V Core repository

**Verilator**

`$ cd Build_HW; make exe_HW_AWSF1_sim`

Note: does not need Amazon AWS;  
can be built on your laptop/desktop.

exe\_HW\_AWSF1\_sim

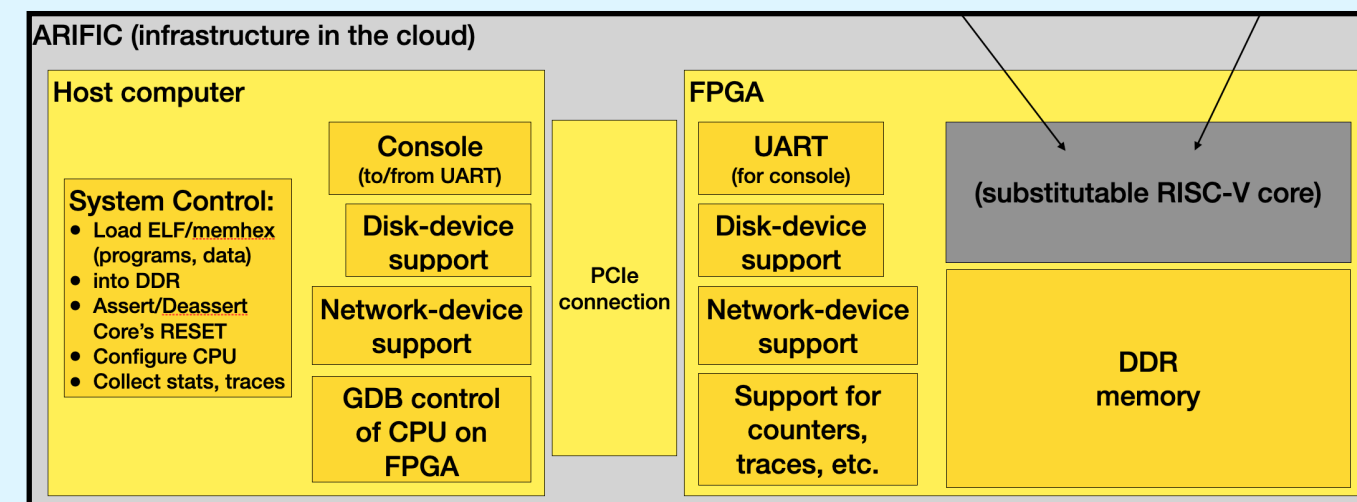


# Plug in your own RISC-V core

## DEMO: Run a whole-system simulation executable

exe\_Host\_ISA\_Tester\_AWSF1\_sim

```
Catamaran_simulation_Host
[$ ./exe_Host_ISA_Tester_AWSF1_sim ../ISA_Tests/isa/elfs rv64ui-p-add]
Directory for ELF files: ../ISA_Tests/isa/elfs
File-selection pattern: rv64ui-p-add
tcp_client_open: connecting to '127.0.0.1' port 30000
tcp_client_open: connected
INFO: DRM check
INFO: DRM: telling HW-side to disallow execution
INFO: DRM: telling HW-side to allow execution
INFO: DRM: Waiting for HW-side to confirm allow-execution
... confirmed after 1 polls
-----
Asserting reset (stops CPU)
-----
Loading ELF file into RISC-V memory:
../ISA_Tests/isa/elfs/rv64ui-p-addi
ELF load complete
Transfer rate: 3351648 bytes/sec (1220 bytes in 364000 nsecs)
Readback check
Readback check complete
Deasserting reset (CPU starts running)
Asserting reset (stops CPU)
Test PASS
So far: 1 test files, 1 PASS, 0 FAIL, 0 TIMEOUT
-----
```



exe\_HW\_AWSF1\_sim

```
Catamaran_simulation_HW
--13:05:30--Airedale: ~/Git/Tutorial_at_HPCA-29/Build_HW
[$ ./exe_HW_AWSF1_sim]
=====
Bluespec Catamaran simulation v2.2
Copyright (c) 2020-2023 Bluespec, Inc. All Rights Reserved.
=====
INFO: Listening for connection from host-side on TCP port 30000
INFO: Accepted connection from host-side on TCP port 30000
Host_Control_Status: Assert Core Reset
Host_Control_Status: Deassert Core Reset
Host_Control_Status: Assert Core Reset
Host_Control_Status: Deassert Core Reset
Host_Control_Status: Assert Core Reset
Host_Control_Status: Deassert Core Reset
Host_Control_Status: Assert Core Reset
Host_Control_Status: Deassert Core Reset
Host_Control_Status: Assert Core Reset
Host_Control_Status: Deassert Core Reset
Connection closed by remote host (in c_host_recv2())
--13:10:44--Airedale: ~/Git/Tutorial_at_HPCA-29/Build_HW
$
```

Instead of PCIe, connect with TCP/IP

Does not need Amazon AWS;  
can run on your laptop/desktop

- Simulation is, of course, much slower than running on FPGA Simulation (Linux boot can take a day or more)
- But simulation can print RTL \$displays, dump VCD waveforms, etc.
- So: simulation is good for running/debugging with small RISC-V programs

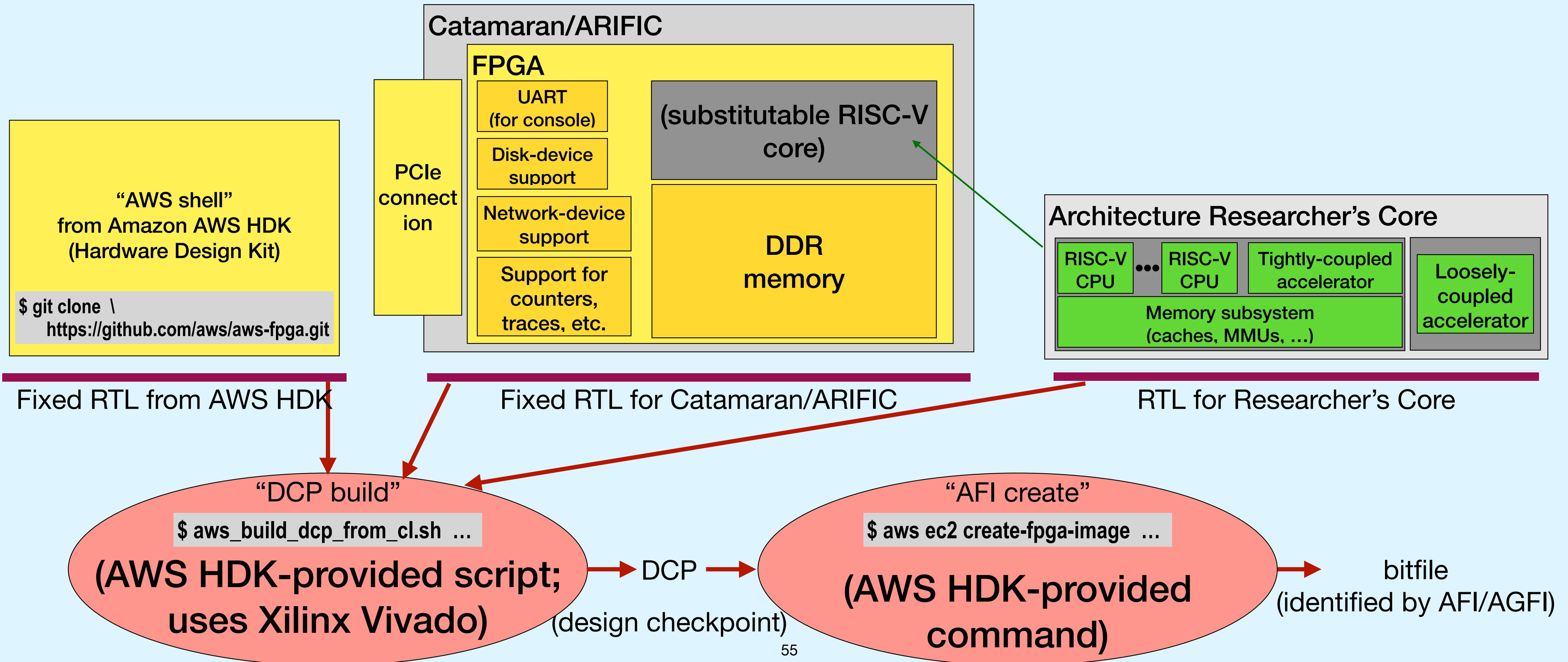


# Plug in your own RISC-V Core

- The Catamaran/ARIFIC Core Interface (RTL)
- DEMO: Build and run a whole-system simulation executable
- *DEMO: Build an FPGA bitfile for Amazon AWS*

# Plug in your own RISC-V core

## Building an FPGA bitfile for Amazon AWS



# Plug in your own RISC-V core

## DEMO: Building an FPGA bitfile for Amazon AWS

### General Caveat

- The flow described here and the files currently in the tutorial repository are somewhat specialized for building CVA6/Ariane RV64GC\_MSU\_Sv39 as the RISC-V Core in Catamaran.
- For a different core (and therefore different core RTL)
  - Various Vivado Tcl scripts have to be modified accordingly
  - Other adjustments may be needed to select a different clock speed
  - Other adjustments may be needed to incorporate a RISC-V Debug Module, which must sit outside the “reset domain” of the core
- We expect to simplify some of these adjustments in the weeks/months after the tutorial

# Plug in your own RISC-V core

## DEMO: Building an FPGA bitfile for Amazon AWS

“DCP build” step (this example is for the CVA6/Ariane core)

- Prepare a directory that is ready for the AWS HDK flow:

```
$ cd Build_HW  
$ make for_aws
```

- Creates a directory “AWS\_CL\_Catamaran/” which is initialized from “AWS\_CL\_Catamaran\_wo\_Core.tar.gz”, i.e., fixed RTL for Catamaran
- Then, copies the core’s RTL from your clone of <https://github.com/openhwgroup/cva6.git> (in the Makefile, “CVA6\_REPO\_DIR=...” should be edited to point at this clone)
- Finally, tars up this directory into “AWS\_CL\_Catamaran\_for\_AWS\_HDK.tar.gz”

- Copy this tar file to your “build AMI”, where you have Vivado tools and the AWS aws-fpga HDK+SDK installed, and untar it.

- Launch the DCP build:

```
$ cd AWS_CL_Catamaran  
$ ./aws_build_dcp_from_cl.sh -ignore_memory_requirement -clock_recipe_a A1
```

- This will launch a background process to perform Vivado synthesis resulting in a DCP (Design Checkpoint)
- The “clock\_recipe” argument here sets the core’s clock frequency to 125MHz
- The Vivado log is saved in a file with a timestamped filename, like this: “23\_02\_21-012910.vivado.log”. You should monitor this file to check that Vivado has not exited due to some error.
- This step takes ~ 2.5 hours for CVA6 RV64 GC SMU Sv39.

- When Vivado has finished, you should examine some files to check that it succeeded:

- “build/scripts/<timestamp>.vivado.log” for any errors encountered by Vivado
- “build/reports/<timestamp>.timing\_summary\_route\_design.rpt” to check that synthesis met the timing target

*See AWS HDK documentation for more info on clock recipes, email-notification of synthesis completion, etc.*



# Plug in your own RISC-V core

## DEMO: Building an FPGA bitfile for Amazon AWS

### “AFI create” step: Launching the AFI-build

- A successful “DCP build” step produces a design checkpoint file: “build/checkpoints/to\_aws/23\_02\_21-012910.Developer\_CL.tar”
- Create an S3 bucket (if you have not already done so before):

```
$ aws s3 mb s3://rsnbucket1/Catamaran/
```

- “S3” is Amazon AWS’ name for their “storage in the cloud” service
- “bucket” is Amazon AWS’ name for “top-level directory”

- Upload your design checkpoint file to your S3 bucket:

```
$ aws s3 cp <path>/<timestamp>.Developer_CL.tar s3://rsnbucket1/Catamaran/
```

- Launch the AFI build

```
$ aws ec2 create-fpga-image --region us-east-1 \  
--name "Catamaran_CVA6_RV64GC_MSU_Sv39_Boot_ROM_125MHz" \  
--description "Catamaran CVA6 RV64GC MSU Sv39 Boot ROM_125MHz" \  
--input-storage-location Bucket=rsnbucket1,Key=Catamaran/<timestamp>.Developer_CL.tar \  
--logs-storage-location Bucket=rsnbucket1,Key=Catamaran
```

*See AWS HDK documentation for more info*

- This will immediately print out the AFI and AGFI allocated for this new bitfile:

```
{  
  "FpgalImageId": "afi-0a3fa15056f3de4d7",  
  "FpgalImageGlobalId": "agfi-0ab786417c04b7031"  
}
```

*IMPORTANT: please note these down immediately! You have no other way to refer to your bitfile other than these IDs!*



# Plug in your own RISC-V core

## DEMO: Building an FPGA bitfile for Amazon AWS

### “AFI create” step: Checking on your AFI build

- The following command prints info about an AFI:

```
$ aws ec2 describe-fpga-images --fpga-image-ids "afi-0a3fa15056f3de4d7"
```

- This will print out something like this:

AFI build time ~ 55 minutes.  
Seems independent of  
complexity of user’s design  
(just stitches together user’s  
DCP with AWS boilerplate)

The AFI is now ready for use  
(load into FPGA, ...)

```
{
  "FpgaImages": [
    {
      "UpdateTime": "2023-02-21T16:28:22.000Z",
      "Name": "Catamaran_CVA6_RV64GC_MSU_Sv39_Boot_ROM_125MHz",
      "Tags": [],
      "Pcild": {
        "SubsystemVendorId": "0xfedc",
        "VendorId": "0x1d0f",
        "DeviceId": "0xf001",
        "SubsystemId": "0x1d51"
      },
      "DataRetentionSupport": true,
      "FpgaImageGlobalId": "agfi-0ab786417c04b7031",
      "Public": false,
      "State": {
        "Code": "available"
      },
      "ShellVersion": "0x04261818",
      "OwnerId": "071524437452",
      "FpgaImageId": "afi-0a3fa15056f3de4d7",
      "CreateTime": "2023-02-21T15:32:09.000Z",
      "Description": "Catamaran CVA6 RV64GC MSU Sv39 Boot ROM_125MHz"
    }
  ]
}
```

Finish time of AFI build

“pending” at start of AFI build;  
“available” at finish of AFI build

Start time of AFI build

*See AWS HDK documentation for more info*

**Use GDB to control the RISC-V  
CPU on the FPGA**

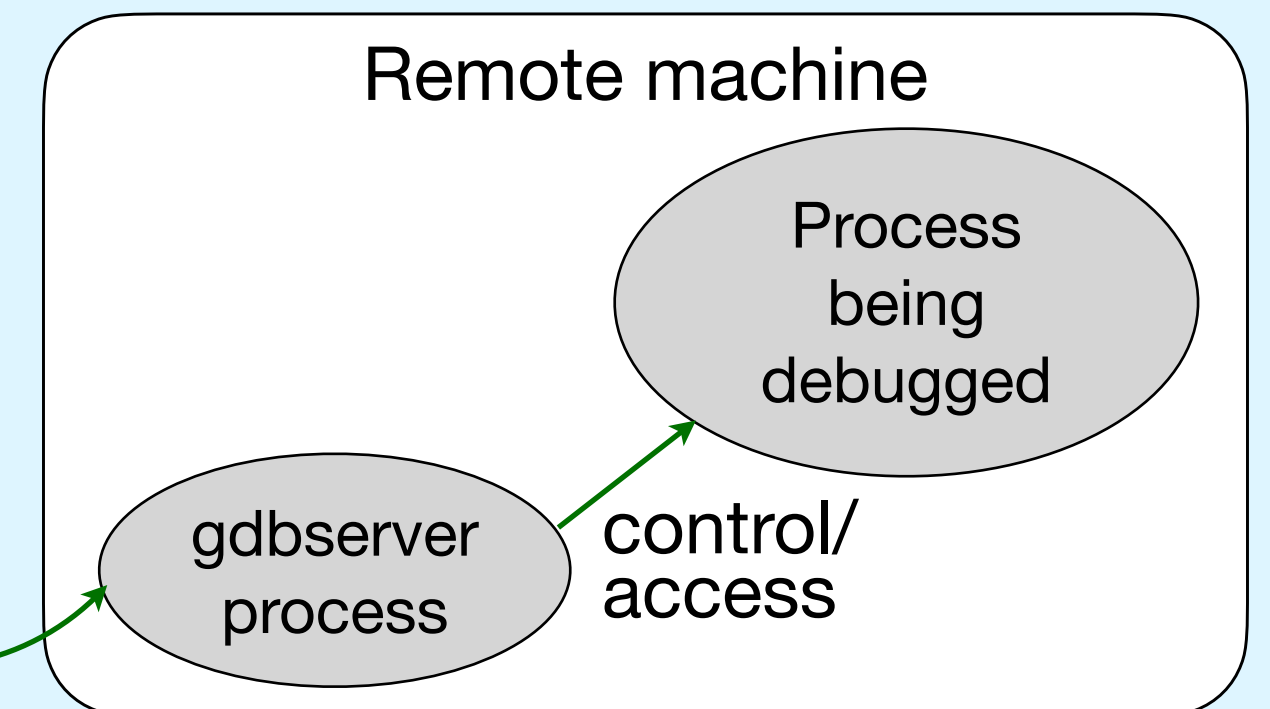
# GDB control of RISC-V CPU on FPGA

## Traditional vs. hardware remote GDB

Traditional “remote debugging”  
is done entirely with software:

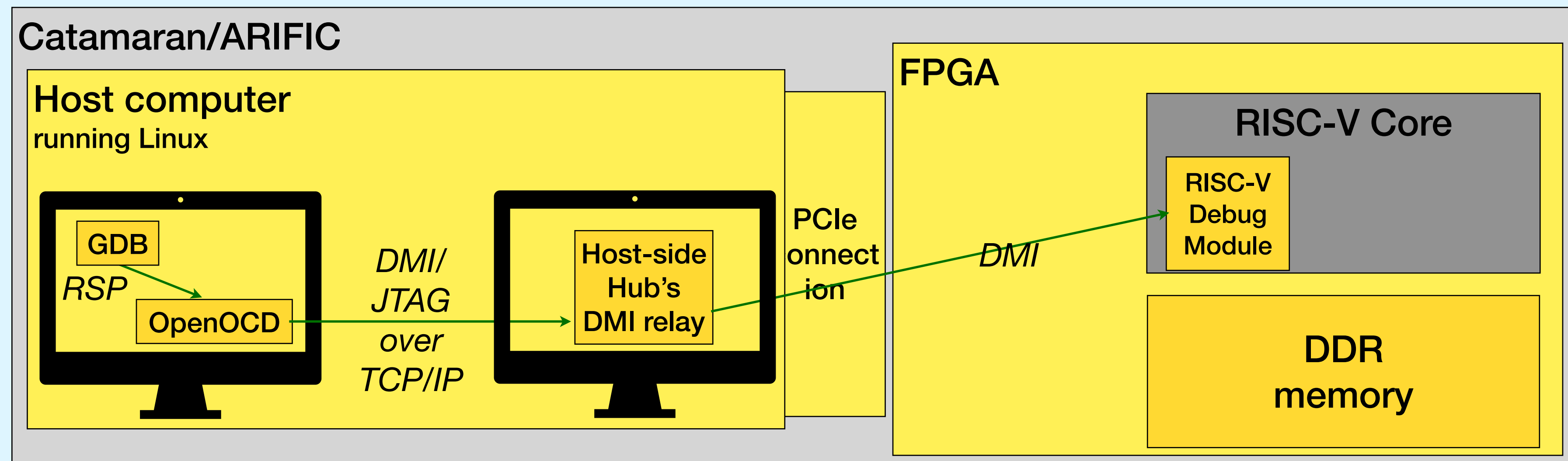


*RSP (“remote serial protocol”)  
transported over TCP/IP, USB, ...*



This assumes that the hardware (remote machine) is reliable (e.g., to run gdbserver);  
this may not be true for the architecture researcher.

On Catamaran:



# GDB control of RISC-V CPU on FPGA

## Connecting GDB

- When you start the Host-side Hub, provide a TCP/IP port number for GDB to connect:

```
$ exe_Host_AWSF1 --debugport 5555
```

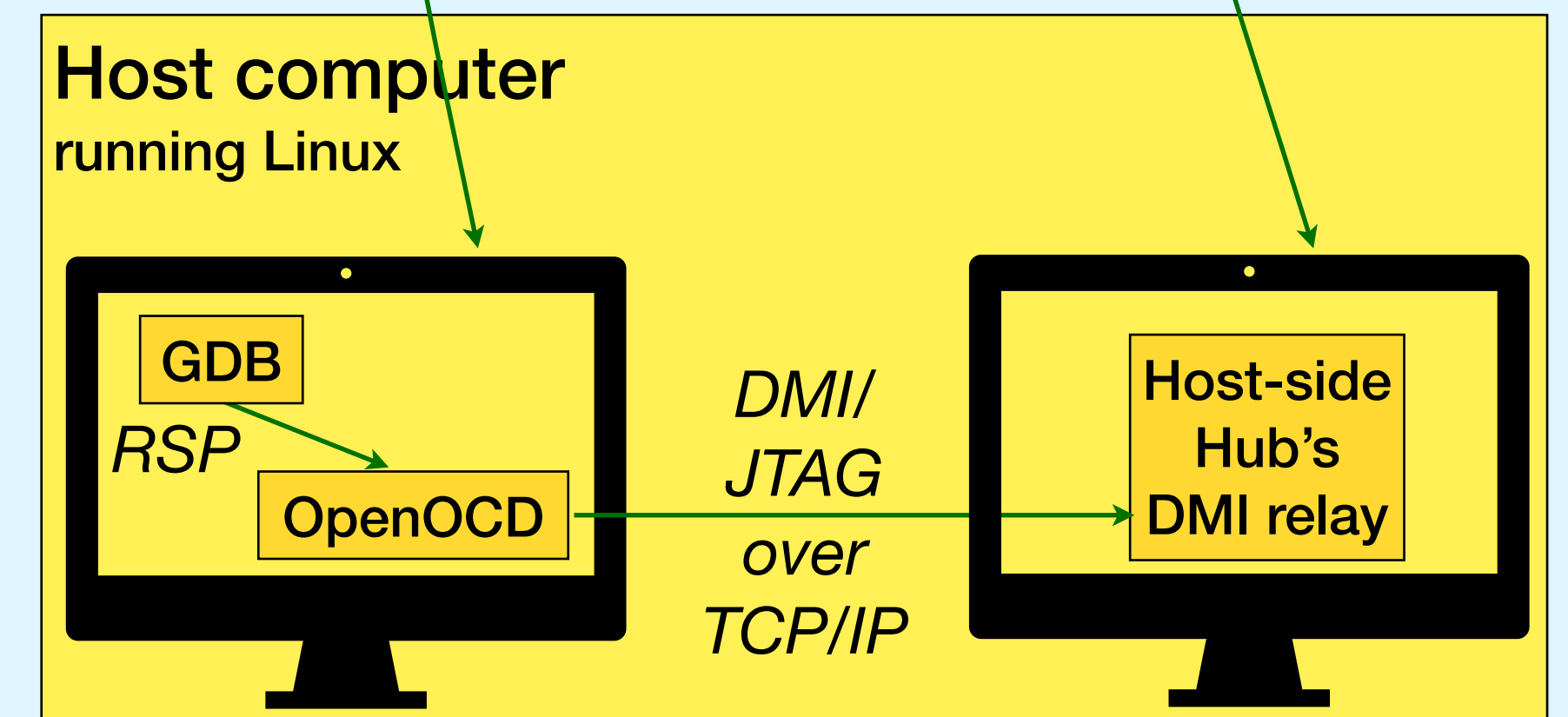
- In another terminal window, start GDB with the provided script, which will start GDB and OpenOCD and make the connections, and pause at the usual GDB prompt:

```
$ riscv64-unknown-elf-gdb --silent --command init_64.gdb
...
(gdb)
```

Please peruse the supplied gdb and OpenOCD scripts for more details of how the connections are established, etc.

- At the (gdb) prompt, use GDB commands as usual:  
load ELF,  
start, stop, continue, step, step, break,  
read/write registers and CSRs and memory, ...

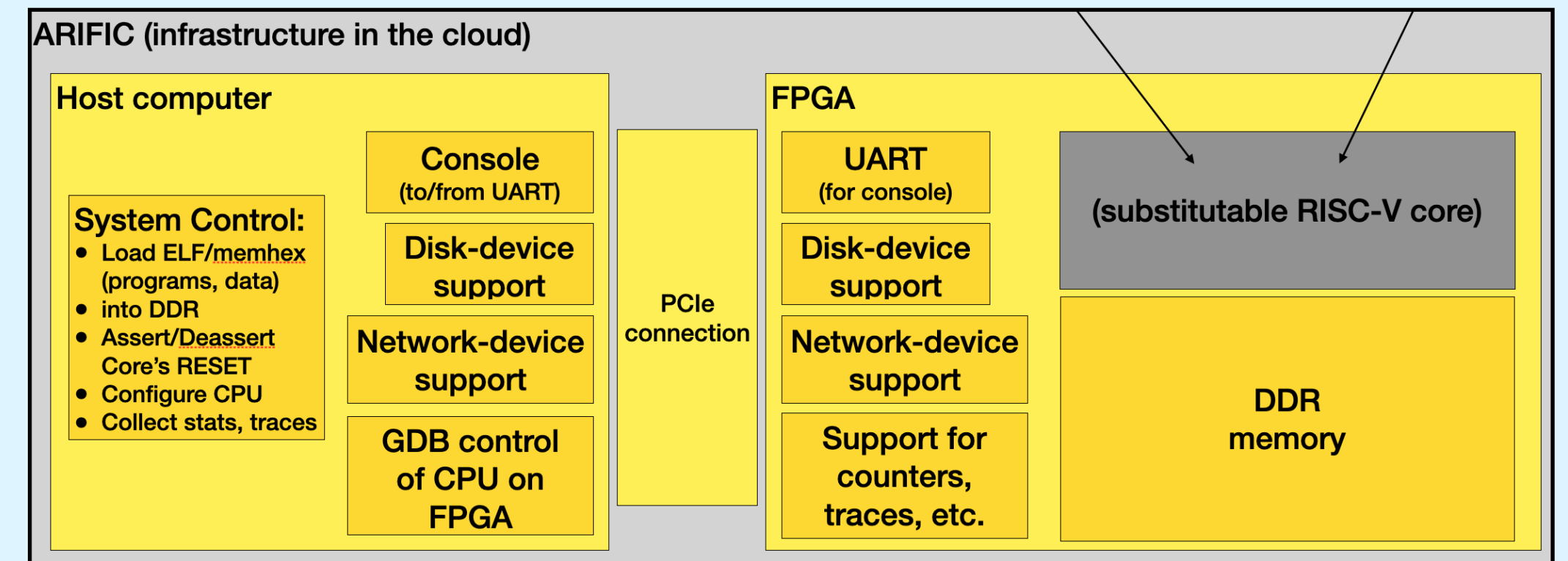
*Hint: Loading an ELF from GDB can be slow; you can still use the "loadelf" command at the Host-side Hub prompt to load an ELF, much faster.*



# Summary and Conclusion



# Summary of tutorial



- Catamaran/ARIFIC provides the large and complex infrastructure that frees the Architecture Researcher to focus on their creative work: research into the CPU microarchitectures, memory systems, accelerators, etc.
- In this tutorial we showed the capabilities immediately enabled by Catmaran/ARIFIC:
  - Run on FPGA on Amazon AWS virtual machines
  - Run ISA tests
  - Run bare-metal C programs with console I/O
  - Run Linux and C programs-under-Linux with console I/O, networking and “disk” devices
  - GDB-debug bare-metal programs
  - Dump memory data (e.g., performance data collected during program execution)

# End of Tutorial Slides

Appendix with reference material follows

Thank you all for attending!

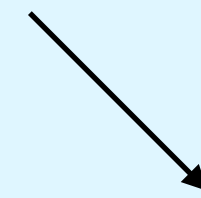
GitHub repo for this tutorial: <https://github.com/rsnikhil/Tutorial> at HPCA-29

# Appendix: Reference Material

- *Open an account on Amazon AWS*
- Create an AMI (or two) for Catamaran/ARIFIC
- Install Catamaran software and scripts
- Address map
- Install the RISC-V Gnu Toolchain (gcc, as, ld, gdb, ...)
- Install aws-fpga HDK and SDK
- Install the “aws” CLI (command-line interface)
- Install XDMA driver for Host-FPGA PCIe communication

# Open an account on Amazon AWS

- At: <https://aws.amazon.com>



The screenshot shows the AWS sign-in page. At the top is the AWS logo. Below it is the 'Sign in' heading. There are two main options: 'Root user' (selected with a radio button) and 'IAM user'. The 'Root user' option has a description: 'Account owner that performs tasks requiring unrestricted access. [Learn more](#)'. The 'IAM user' option has a description: 'User within an account that performs daily tasks. [Learn more](#)'. Below these is a text input field for 'Root user email address' with the placeholder 'username@example.com'. A blue 'Next' button is below the email field. At the bottom, there is a checkbox for 'New to AWS?' and a 'Create a new AWS account' button. Annotations include an arrow from the 'Sign In to the Console' button on the homepage to the 'Sign in' heading, and two arrows from the 'First time' and 'Subsequently' labels pointing to the 'Create a new AWS account' button.

First time

Subsequently

Amazon runs cloud farms in many parts of the world; you may be asked to select a region “near” you.  
E.g., I use: ‘us-east-1 (N.Virginia)’  
*Caution:* select a region that has support instances with FPGAs

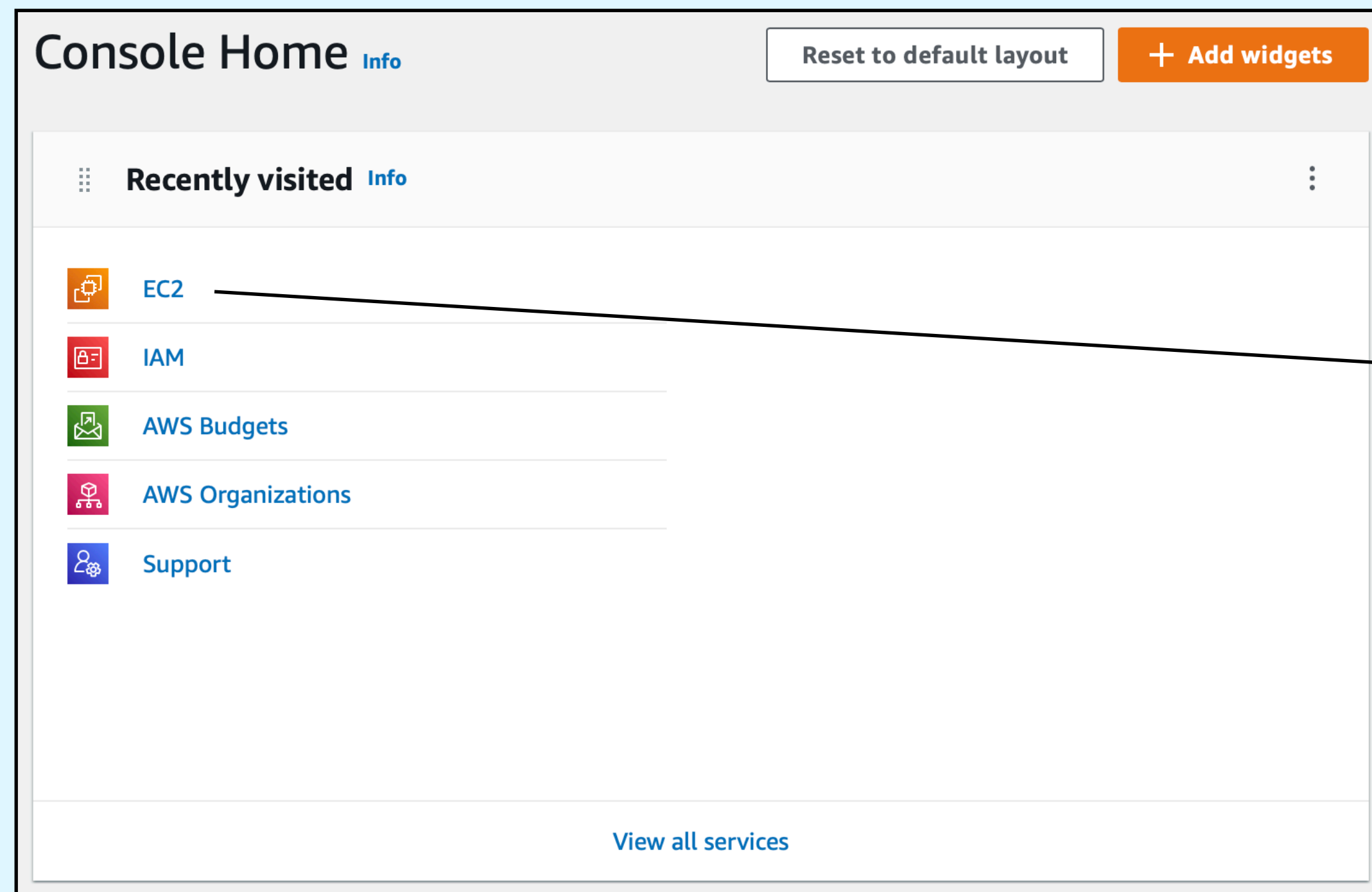
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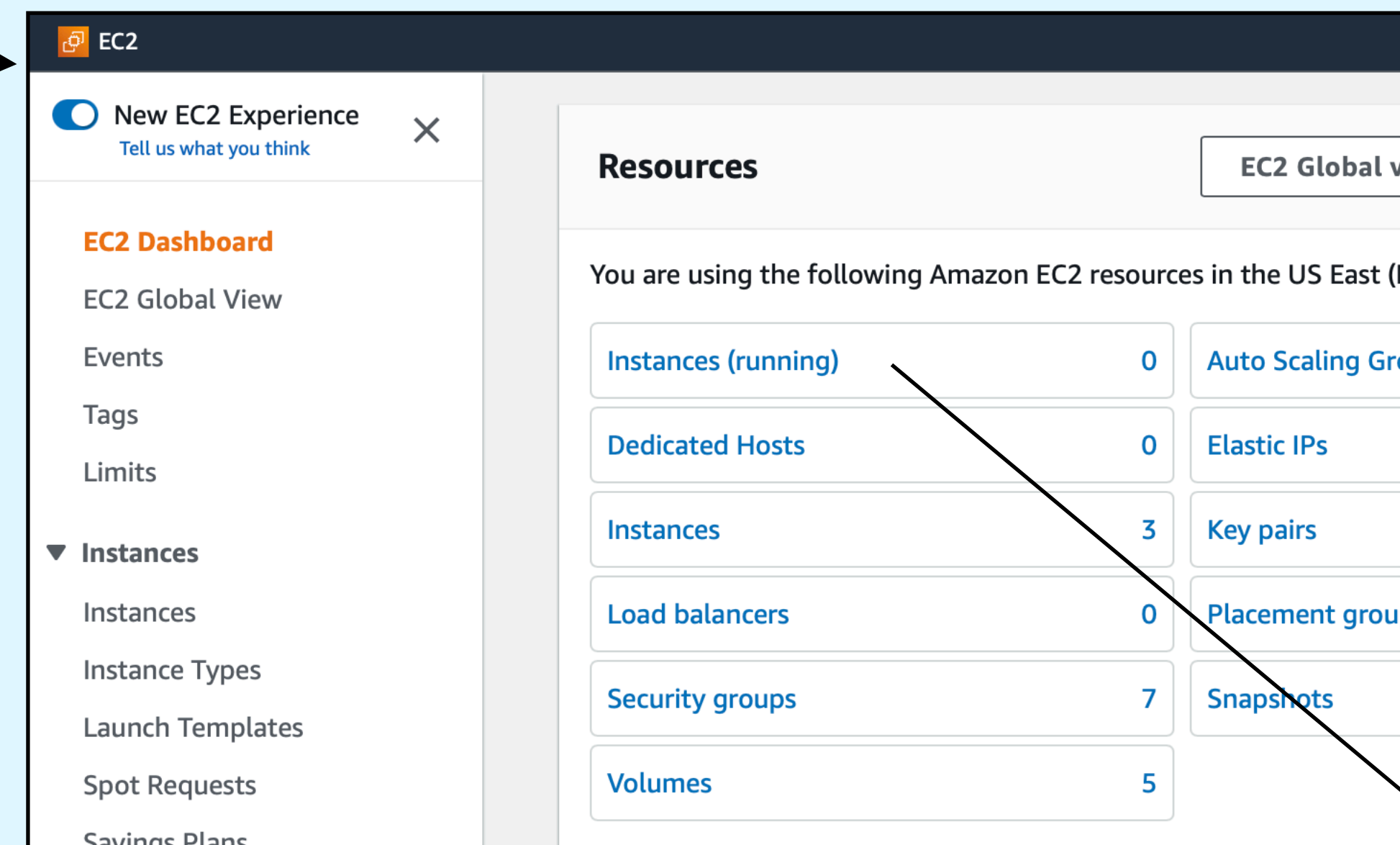


# Create an AMI (or two) for Catamaran/ARIFIC

## Navigate to your EC2 Instances dashboard



AWS offers a gazillion services; we want “EC2” (Elastic Computing), which are virtual machines in the cloud.



Then, move on to the “Instances” dashboard  
 (“instances” = AWS terminology for your virtual machines)

# Create an AMI (or two) for Catamaran/ARIFIC

## The EC2 “instances” dashboard

The screenshot displays the AWS Management Console's EC2 Instances page. At the top, there's a navigation bar with the AWS logo, 'Services' menu, a search bar, and account details (N. Virginia, rsnikhil). Below this, the 'EC2' service is selected. The main content area shows the 'Instances (3)' section. On the left, a sidebar lists navigation options: 'New EC2 Experience', 'EC2 Dashboard', 'EC2 Global View', 'Events', 'Tags', 'Limits', and 'Instances'. The 'Instances' section is expanded, showing a list of three instances. Each instance row includes a checkbox for selection, the instance name, ID, state (all 'Stopped'), type, status check, alarm status, and availability zone. The 'Launch instances' button is prominently displayed in orange. A green arrow points to this button from the text 'Create new instances from here:'. Another green arrow points to the instance list from the text 'Your existing instances are listed here. These persist across your AWS logins, until you delete them.' A third green arrow points to the 'Instance state' dropdown menu from the text 'The “Instance type” determines:'. A fourth green arrow points to the 'Select an instance' button at the bottom of the instance list from the text 'Select one or more instances here'.

<input type="checkbox"/>	Name	Instance ID	Instance state	Instance type	Status check	Alarm status	Availability Zone
<input type="checkbox"/>	RSN_AFI_Build2	i-076651ea2ab3f3f46	Stopped	m6i.2xlarge	–	No alarms	us-east-1a
<input type="checkbox"/>	RSN_AFI_Run	i-0f049486cb2592f76	Stopped	f1.2xlarge	–	No alarms	us-east-1c
<input type="checkbox"/>	RSN_AWSteria	i-0b4c8df2758d2f0b9	Stopped	f1.2xlarge	–	No alarms	us-east-1c

Create new instances from here:

Your existing instances are listed here. These persist across your AWS logins, until you delete them.

Select one or more instances here

These instances are all currently “Stopped” (like “sleep” on a laptop; saves AWS charges when not being actively used)

- Selected instances can be put into the “Running” state by selecting “Start instance” in the “Instance state” drop-down menu at top (like emerging from “sleep” on a laptop).

The “Instance type” determines:

- Host CPU type (x86, ARM, ...)
- Sizing (# of virtual cores, memory, ...)
- “f1.\*” types are the only ones with FPGAs attached.
- *Note:* AWS charges vary with instance type
- *Warning:* “f1” instances typically have higher AWS charges.
- *Hint:* you can do FPGA builds on an instance without an FPGA (cheaper), such as the first one shown above.

# Create an AMI (or two) for Catamaran/ARIFIC

## Create one or two AMIs?

The “Instance type” determines, for your AMI:

- Host CPU type (x86, ARM, ...)
- Sizing (# of virtual cores, memory, ...)

*Note:* “f1.\*” types are the *only* ones with FPGAs attached.

*Note:* AWS charges vary with instance type, and “f1” instances are typically more expensive.

*Hint* (for lower AWS charges): Create two AMIs:

- A “build” AMI of type “m6i.2xlarge” for building bitfiles for Catamaran/ARIFIC
  - Use the free AWS “FPGA Developer AMI” for this, which comes preloaded with Vivado, Vivado licenses, etc. (all free). The supplied OS is CentOS Linux.
- A “run” AMI of type “f1.2xlarge” for running Catamaran/ARIFIC with FPGA
  - You can choose an AMI with OS of your choice (we typically choose latest Ubuntu)

*Note: when you build a bitfile on the “build” AMI, it'll reside in the cloud named by an AGFI (unique id), which you can access from the “run” AMI*



# “Create” your virtual machine (“instance”)

When you select “Launch Instances” to create a new instance, it will take you through a series of steps (“Launch Instances Wizard”).

Here are some notes on the various steps:

- “Name and tags”: choose a name for your instance (e.g., on our slides: “RSN\_AFI\_Build2”, “RSN\_AFI\_run”, “RSN\_AWSteria”)
- Application and OS Images (Amazon Machine Image)
  - Choose one of the AMIs from the 1000s available in the search box
  - For Catamaran/ARIFIC bitfile building, we recommend the latest AWS “FPGA Developers AMI”
  - For Catamaran/ARIFIC running on FPGA, we recommend an AMI with the latest Ubuntu (22.04 LTS at time of writing), x86 (not ARM!), 64-bit
- “Select and Instance Type”
  - The menu shows 100s of possibilities, x86 and ARM, etc.
  - For Catamaran/ARIFIC bitfile building, we recommend “m6i.2xlarge” (e.g., see “Instance type” on previous slide)
  - For Catamaran/ARIFIC running on FPGA, this *must* be an “f1” instance; we recommend “f1.2xlarge” (e.g., see “Instance type” on our slides)
- “Create your Key Pair”
  - When one connects to an AMI (with “ssh”), for security reasons Amazon does not support password-based login authentication, only crypto-key based authentication.
  - This menu item creates a key pair for you, a public key and private key.
  - The prompts will ask you to copy the private key, and save it on your laptop/desktop in a file `~/.ssh/MyPrivateKey.pem` and set its protection to 0x400
  - Note: once you’ve created a key pair, you can reuse it for new instances; it will show you your existing key pairs and you can select one, instead of creating a new one.
- “Network Settings”: Leave unchanged. In particular, “Auto-assign public IP” = “Enable” and “Allow SSH traffic from Anywhere”
- “Configure Storage”: Leave unchanged, e.g., 8 GiB (these can be updated later, if needed)
- “Advanced Details”: Leave unchanged
- Finally, select “Launch Instance” on the “Summary” panel which floats on the right during the wizard.
  - (but see caveat on next slide)

# “Create” your virtual machine (“instance”)

*Caveat:* After selecting “Launch Instance” at the end of the AMI-creation wizard, you may encounter an error message like this:

You have requested more vCPU capacity than your current vCPU limit of 0 allows for the instance bucket that the specified instance type belongs to. Please visit <http://aws.amazon.com/contact-us/ec2-request> to request an adjustment to this limit.

If you get this message, please visit the contact-us link shown, click on “Support” and lodge a request to increase your “vCPU quota” to 8, which is required for the f1.2xlarge instance type. Try to include a few sentences explaining your need for an f1.2xlarge instance type.

You will get an almost instant response saying:

This specific limit increase request requires further internal review before approval ...

These requests are processed by humans, so it may take a few hours before you receive an email indicating that your request has been approved, after which you can proceed.



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# Install Catamaran Software and Scripts

## What are Catamaran software and scripts?

Executable	Description
exe_Host_AWSF1	Full host-side for running arbitrary ELF on Catamaran on FPGA supporting connections to UART console, GDB/OpenOCD, with network and block-storage device support, etc.
exe_Host_AWSF1_sim	Version of above for running with a hardware simulation instead of FPGA
exe_Host_ISA_Tester_AWSF1	Host-side to run a series of ISA tests on Catamaran on FPGA
exe_Host_ISA_Tester_AWSF1_sim	Version of above for running with a hardware simulation instead of FPGA
netinit.sh	Host-side script to prepare TUN/TAP network device before booting Linux on FPGA
???	ELF file containing OpenSBI bootloader + minimal Linux

# Install Catamaran Software and Scripts

## Installation

Bluespec, Inc. has made these available using the usual “apt” package-installation mechanism (Debian, Ubuntu).

- This command will download Bluespec, Inc.’s public key for authenticating the “apt” step:

```
$ curl -sS https://s3.wasabisys.com/bluespec/downloads/apt/bluespec.asc | sudo tee /etc/apt/trusted.gpg.d/bluespec.asc
```

- This command will inform your “apt” installer about where to go for the download:

```
$ curl -sS https://s3.wasabisys.com/bluespec/downloads/apt/ubuntu/bluespec-jammy.sources | \
sudo tee /etc/apt/sources.list.d/bluespec-jammy.sources
```

- Finally, this command will download and install the toolchains:

```
$ sudo apt install bluespec-catamaran-common
```

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# Install Catamaran Software and Scripts

## Address map for Catamaran

If you create your own software to run on the RISC-V core in Catamaran, or rebuild your own Linux, you will need some or all of the following address information (typically used in your “ld” linker script).

Device	Start address	Size	MMIO/Mem	Location in system
Boot ROM	0001_0000	0001_0000	MMIO	Core
CLINT	0200_0000	0001_0000	MMIO	Core
PLIC	0C00_0000	0400_0000	MMIO	Core
Host access	4000_0000	0000_4000	MMIO	Catamaran system
UART	6010_0000	0000_1000	MMIO	Catamaran system
MSI	6020_0000	0000_0004	MMIO	Catamaran system
SRAM	7000_0000	0040_0000	MMIO	Catamaran system
DDR	8000_0000	8000_0000	Mem	Catamaran system



# Install Catamaran Software and Scripts

## Address map for Catamaran: core device details

*These devices are in the substitutable Catamaran Core, and are “the same” in the provided cores (Rocket, CVA6, Flute). Other cores may omit them, have different functionality, or different address maps.*

Boot ROM: Typically contains the “device tree” for Linux and some initial instructions that call the Linux boot loader (e.g., OpenSBI) passing it the address of the device tree.

CLINT: Contains standard memory-mapped locations (see RISC-V Privileged ISA Specification for details).

- MSIP: offset 0, size 8 bytes: inter-hart software interrupts
- MTIME: offset 0xBFF8, size 8 bytes: real-time counter
- MTIMECMP: offset 0x4000, size 8 bytes: real-time compare, generating a timer interrupt

PLIC: Platform-level Interrupt Controller

- Please see “SiFive U54-MC Core Complex Manual v1p0”, <https://static.dev.sifive.com/U54-MC-RVCoreIP.pdf> for functional details and internal address-map details.

# Install Catamaran Software and Scripts

## Address map for Catamaran: Catamaran system device details

*These devices are in the fixed Catamaran System.*

*Addresses can be changed by regenerating the Catamaran System RTL.*

Host Access: loads/stores to these locations are handled remotely by the x86 host. We use these for:

- “Virtio” device locations (networking device, block device, entropy device)
- “tohost” location used by ISA tests

UART: this is hardware that emulates an NS16550 UART. Please see documentation widely available on the Web for internal register addresses and functionality.

MSI: “Message Sequenced Interrupts”: we use these typically for interrupts delivered by “Virtio devices” emulated on the host-side.

SRAM: Just a region of SRAM in MMIO (uncached) space.

DDR: This is main memory for the RISC-V CPU, which can be cached. Has high-speed path (512-bit AXI4 with bursts) to/from the CPU.

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# Install the RISC-V Gnu Toolchain

## What is the “RISC-V Gun Toolchain”?

- The familiar tools: *gcc/g++* (compilers), *as* (assembler), *ld* (linker), *gdb* (debugger), *objdump* (disassembler), ...
- These are needed for compiling C, C++ and RISC-V Assembly Language programs into ELF binaries to be loaded and run on a RISC-V CPU.
- We install “cross-compilers” that run under Ubuntu, but generate RISC-V machine code.

In the next two slides we describe two options:

- Simply download and install pre-built toolchains (pre-built by Bluespec, Inc.)
  - This is good enough for use for Catamaran
- Some tips on how you can build your own toolchain from sources
  - If you want to do something more sophisticate, customized, ...

# Install the RISC-V Gnu Toolchain

## Download and install pre-built toolchains

Bluespec, Inc. has pre-built certain configurations of the RISC-V Gnu Toolchain, and made them available using the usual “apt” package-installation mechanism (Debian, Ubuntu).

- This command will download Bluespec, Inc.’s public key for authenticating the “apt” step:

```
$ curl -sS https://s3.wasabisys.com/bluespec/downloads/apt/bluespec.asc | sudo tee /etc/apt/trusted.gpg.d/bluespec.asc
```

- This command will inform your “apt” installer about where to go for the download:

```
$ curl -sS https://s3.wasabisys.com/bluespec/downloads/apt/ubuntu/bluespec-jammy.sources | \
sudo tee /etc/apt/sources.list.d/bluespec-jammy.sources
```

- Finally, this command will download and install the toolchains:

```
$ sudo apt install bluespec-riscvtoolchain-medany
```



# Install the RISC-V Gnu Toolchain

- By “RISC-V Gnu Toolchain” we mean the familiar tools: *gcc*, *as*, *ld*, *gdb*, *objdump*, ...
- These are needed for compiling C, C++ and RISC-V Assembly Language programs into ELF binaries to be loaded and run on a RISC-V CPU.
- We install “cross-compilers” that run under Ubuntu, but generate RISC-V machine code.

Full details may be found at this URL; please follow the installation directions there.

```
https://github.com/riscv/riscv-gnu-toolchain
```

Hint: in the “configure” step, specify “medany” and “multilib”:

```
$ ./configure --prefix=<path_to_installation_dir> --with-cmodel=medany --enable-multilib
```

- <path...> should be a full absolute path (do not use ~ for your home directory).
- “newlib” is for the compiler for bare-metal C RV32 and RV64 programs (no system calls)
- “multilib” produces a compiler that can produce both RV32 and RV64 code, even though it is named *riscv64-unknown-elf-gcc*

Before using the cross-compiler, export the following environment variables:

```
$ export RISCVC=<path_to_installation_dir>  
$ export PATH=${RISCVC}/bin:${PATH}
```

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# Install aws-fpga HDK and SDK

“aws-fpga” is a free HDK (Hardware Development Kit) + SDK (Software Development Kit)

- The HDK is needed for creating AWS bitfiles for the FPGA
- The SDK is needed for creating host-side software that communicates with the FPGA
- It also contains the Xilinx XDMA Linux driver for the host-side to communicate with the FPGA over the PCIe connection

Git-clone it into your AMI from here:

```
$ git clone https://github.com/aws/aws-fpga.git
```

Each time you connect to your AMI, please do:

```
$ cd aws-fpga  
$ source hdk_setup.sh  
$ source sdk_setup.sh
```

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# Install the “aws” CLI (command-line interface)

The “aws” CLI is a software tool provided free by AWS.

- Is used for all kinds of AWS activities, including creating/listing/populating S3 buckets (storage in the cloud), describing AFIs (FPGA images), ... For example:

```
$ aws ec2 describe-fpga-images --fpga-image-ids $(AFI_ID)
```

When logged in to your AMI, install the CLI using the package manager for your AMI's OS:

```
$ sudo apt-get install awscli      # Ubuntu or Debian  
$ sudo yum install awscli         # CentOS, ...
```

Detailed information about AWS CLI:

<https://aws.amazon.com/cli/>



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- Install aws-fpga HDK and SDK
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- *Install XDMA driver for Host-FPGA PCIe communication*

# Install XDMA driver for Host-FPGA PCIe communication

The XDMA driver is a Linux kernel driver for the host to communicate with the FPGA over the high-speed PCIe bus. The driver is included in the “aws-fpga” HDK + SDK.

Git-clone the aws-fpga HDK+SDK into your AMI from here:

```
$ git clone https://github.com/aws/aws-fpga.git
```

Compile the driver (creates file “xdmi.ko”):

```
$ cd aws-fpga/sdk/linux_kernel_drivers/xdma
$ make
...
$ ls xdma.ko
```

Install the driver into the AMI's running Linux kernel:

```
$ sudo make install
```

Check that XDMA is installed and running:

```
$ lsmod | grep xdma
xdma          94208  0

$ ls /dev/xdma*
... will show many devices with the xdma prefix ...
```

# END

GitHub repo for this tutorial: <https://github.com/rsnikhil/Tutorial> at HPCA-29