



الجامعة السورية الخاصة
SYRIAN PRIVATE UNIVERSITY

المحاضرة التاسعة

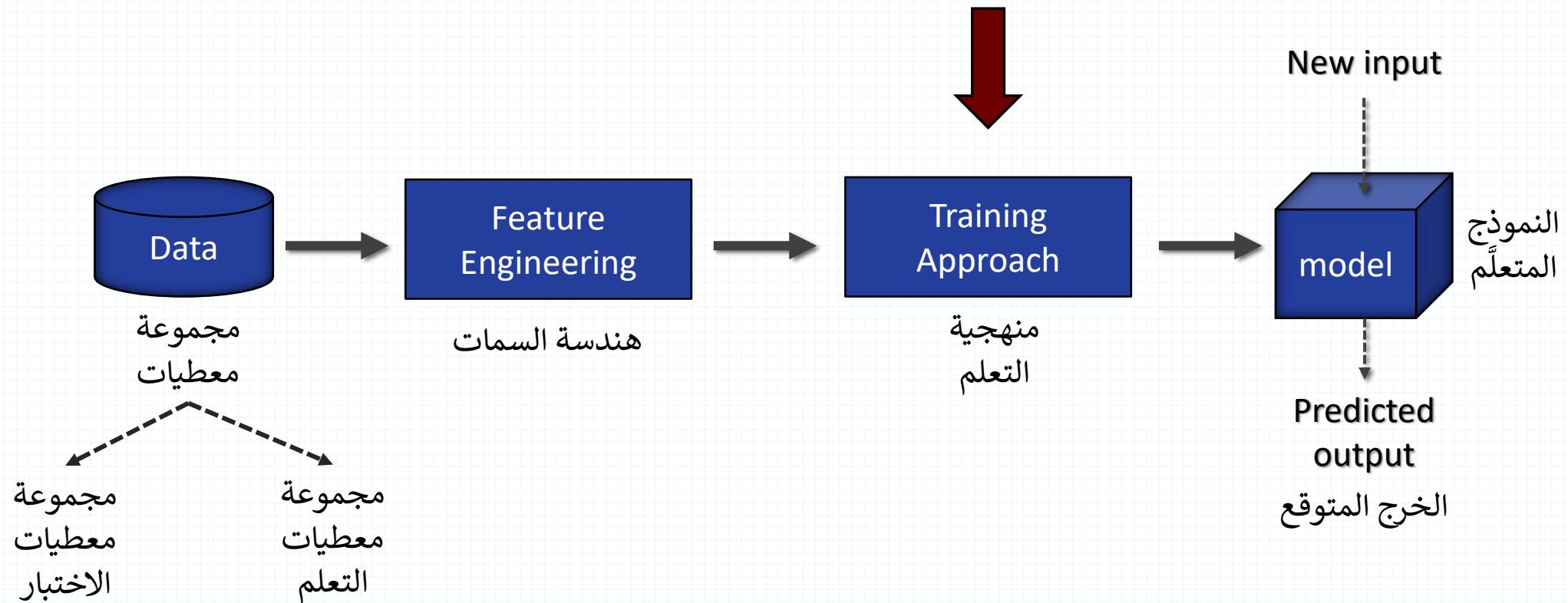
كلية الهندسة المعلوماتية

مقرر تعلم الآلة

Support Vector Machine (SVM) 2

د. رياض سنبل

ML Pipeline



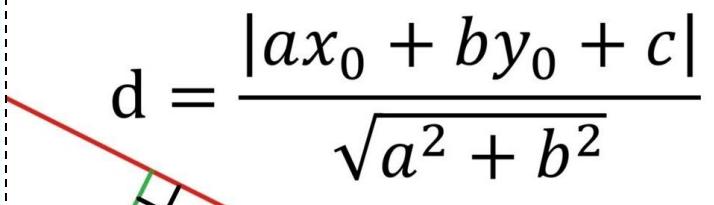
Intuition

- Our problem:

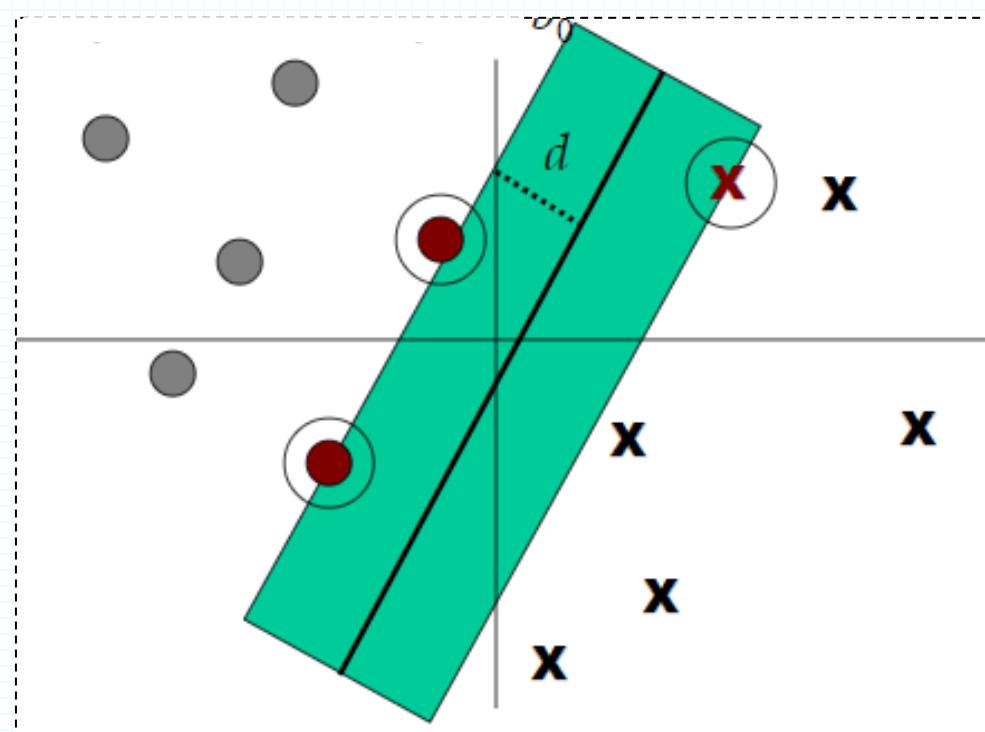
Maximizing the shortest distance to the closest positive or negative point.

The distance between a point (X_0, Y_0) and a line $aX + bY + c = 0$

$$d = \frac{|ax_0 + by_0 + c|}{\sqrt{a^2 + b^2}}$$

A diagram illustrating the formula. A red line represents a line in the plane. A green line segment, labeled 'd', is drawn perpendicular from a point on the red line to the red line itself, forming a right angle indicated by a square symbol.

d



So.. What is our optimization problem?

- Our problem:

Maximizing the shortest distance to the closest positive or negative point.

In our case

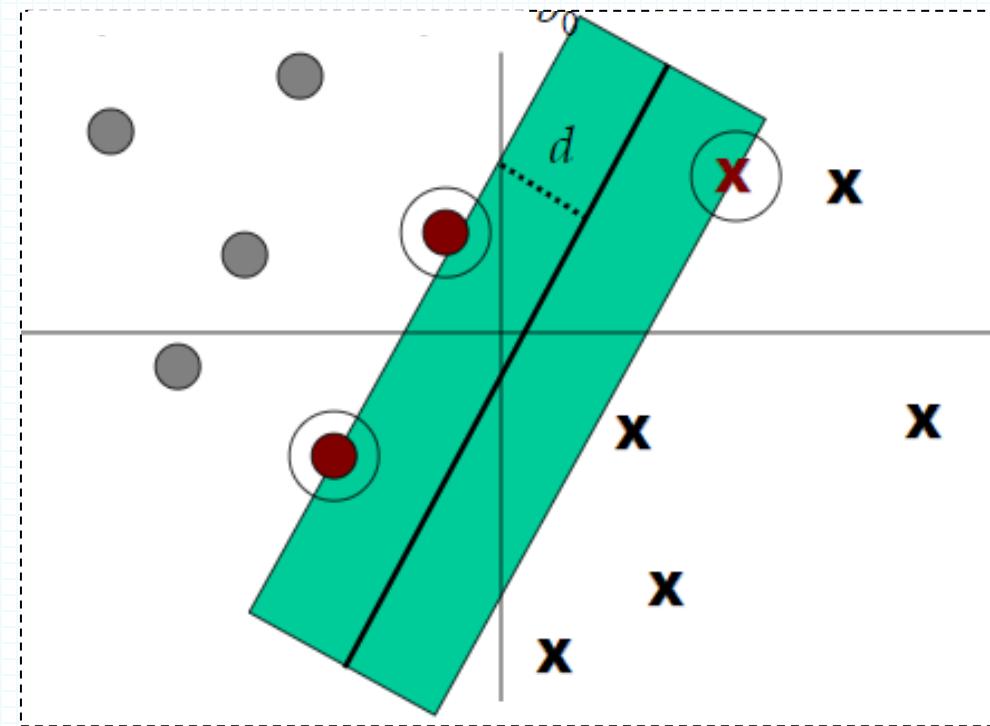
the distance of a hyperplane equation:

$w^T \Phi(x) + b = 0$ from a given point

vector $\Phi(x_0)$ can be easily written as :

$$d_H(\phi(x_0)) = \frac{|w^T(\phi(x_0)) + b|}{\|w\|_2}$$

$$\|w\|_2 = \sqrt{w_1^2 + w_2^2 + w_3^2 + \dots w_n^2}$$



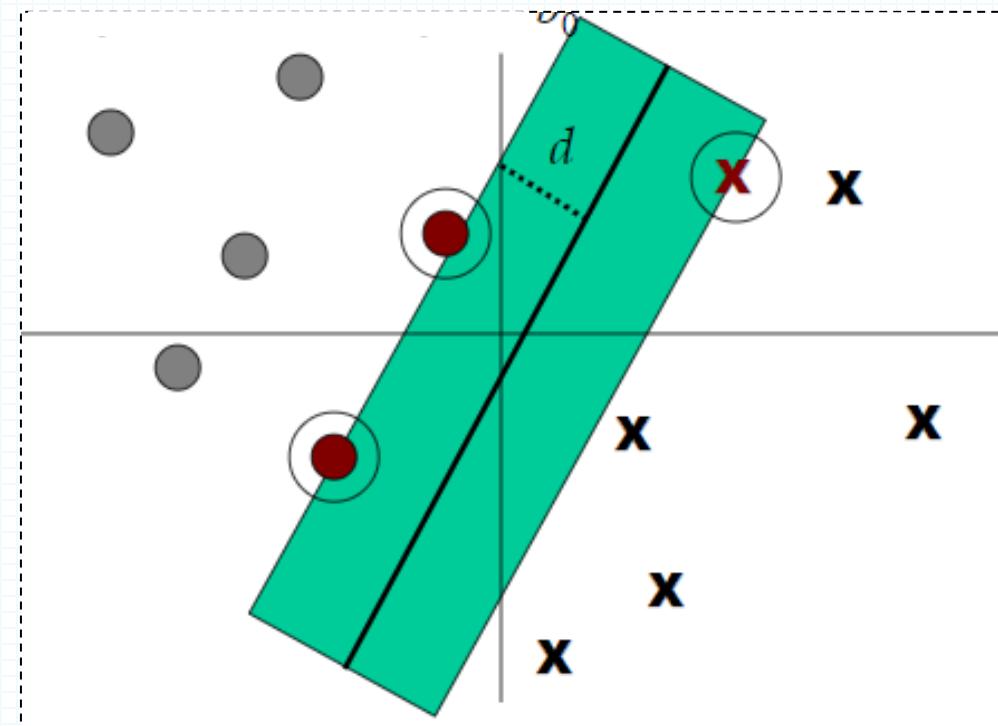
$$d = \frac{|ax_0 + by_0 + c|}{\sqrt{a^2 + b^2}}$$

So.. What is our optimization problem?

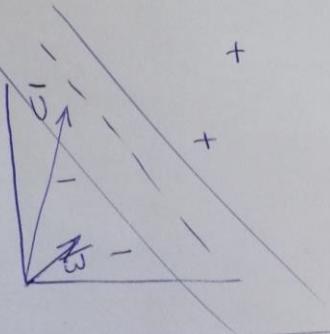
- Our problem:

Maximizing the shortest distance
to the closest positive or negative
point.

$$w^* = \arg \max_w [\min_n d_H(\phi(x_n))]$$



Note that W represents all parameters
i.e. w and b



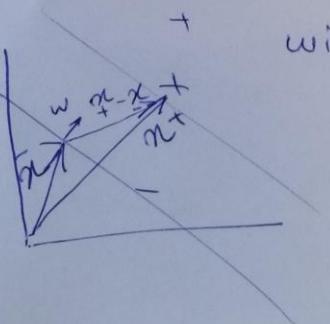
$$\bar{w} \cdot \bar{x} \geq c \text{ for } N^+$$

$$\bar{w} \cdot \bar{x} + b \geq \phi$$

$$\bar{w} \cdot \bar{x}_+ + b \geq 1$$

$$w \cdot x_- + b \leq -1$$

constraint $y_i = +1$ for + samples
 -1 for - samples
 $y_i(\bar{w} \cdot \bar{x}_i + b) \geq 1$ for all points
 $\circledast y_i(\bar{w} \cdot \bar{x}_i + b) = 1$ for support vector



$$\text{width} = (\bar{x}_+ - \bar{x}_-) \cdot \frac{\bar{w}}{\|w\|}$$

support vector

$$= (\bar{x}_+ \bar{w} - \bar{x}_- \bar{w}) \frac{1}{\|w\|}$$

from (*)

$$x_+ \rightarrow \bar{w} \cdot \bar{x}_+ + b = 1 \rightarrow \bar{w} \cdot \bar{x}_+ = 1 - b$$

$$x_- \rightarrow \bar{w} \cdot \bar{x}_- + b = -1 \rightarrow -\bar{w} \cdot \bar{x}_- = 1 + b$$

∴

$$\text{width} = \frac{2}{\|w\|}$$

Goal

Maximize width

$$\frac{2}{\|w\|}$$

Minimize $\|w\|$

Goal

Minimize $\frac{1}{2} \|w\|^2$

true only if
 the constraint is satisfied

use Lagrange Multiplier

$$L = \frac{1}{2} \|\bar{w}\|^2 - \sum \alpha_i [y_i(\bar{w} \cdot \bar{x}_i + b) - 1]$$

Simplified Objective

$$w^*, b^* = \arg \min_{w,b} \frac{1}{2} \|w\|^2, \quad s.t. \quad y_n(w^T(\phi(x_n)) + b) \geq 1 \quad \forall n$$

How to find the optimum w and b ?

SVM Optimization

$$w^*, b^* = \arg \min_{w,b} \frac{1}{2} \|w\|^2, \quad s.t. \quad y_n(w^T(\phi(x_n)) + b) \geq 1 \quad \forall n$$

Solved by Lagrange multiplier method:

$$L(w, b, \alpha) = \frac{1}{2} \|w\|^2 - \sum_n \alpha_n [y_n(w^T(\phi(x_n)) + b) - 1]$$

where α is the Lagrange multiplier

The optimization problem can be solved by setting **derivatives** of *Lagrangian* to 0

SVM Optimization

$$L(w, b, \alpha) = \frac{1}{2} \|w\|^2 - \sum_n \alpha_n [y_n (w^T(\phi(x_n)) + b) - 1]$$

$$\begin{cases} \frac{\partial L}{\partial w} = w - \sum_n \alpha_n y_n \phi(x_n) = 0 \Rightarrow w = \sum_n \alpha_n y_n \phi(x_n) \\ \frac{\partial L}{\partial b} = \sum_n \alpha_n y_n = 0 \Rightarrow \sum_n \alpha_n y_n = 0 \end{cases}$$

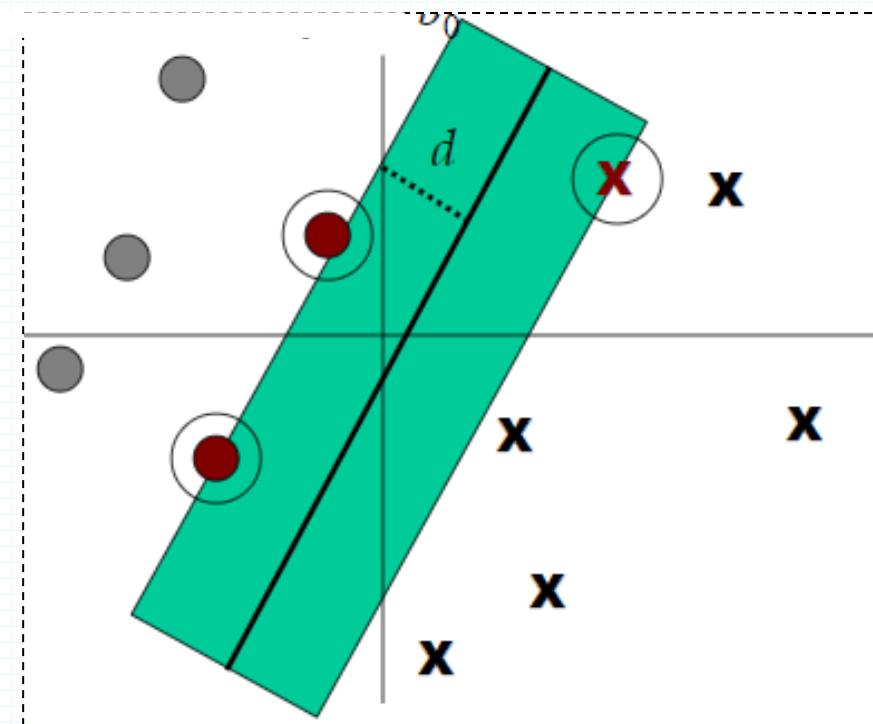
SVM Optimization

$$L = \sum_n \alpha_n + \frac{1}{2} \sum_{n,m} \alpha_n \alpha_m y_n y_m \phi^T(x_m) \phi(x_n)$$

The Boundary:

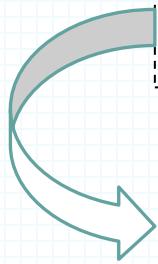
$$Y = w^T(\phi(x)) + b = \sum_n \alpha_n y_n \phi^T(x_n) \phi(x)$$

Only depend on
inner products



SVM Optimization

$$w^*, b^* = \arg \min_{w,b} \frac{1}{2} \|w\|^2, \text{ s.t. } y_n (w^T(\phi(x_n)) + b) \geq 1 \quad \forall n$$



$$Y = w^T(\phi(x)) + b = \sum_n \alpha_n y_n \phi^T(x_n) \phi(x)$$

The decision rule in SVMs only depends on the **dot product with support vectors**

several important implications

- Computational efficiency
- Memory efficiency
- Robustness to noise and outliers

