



الجامعة السورية الخاصة
SYRIAN PRIVATE UNIVERSITY

المحاضرة التاسعة

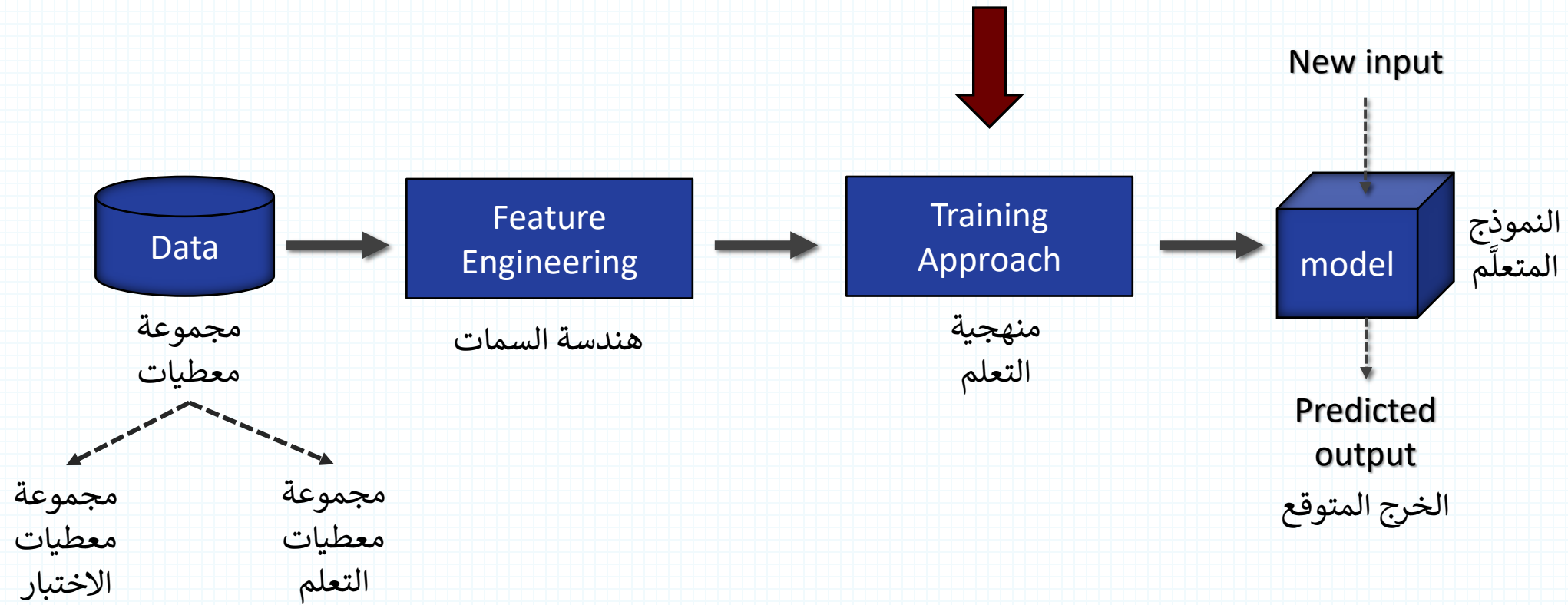
كلية الهندسة المعلوماتية

مقرر تعلم الآلة

Support Vector Machine (SVM) 2

د. رياض سنبل

ML Pipeline

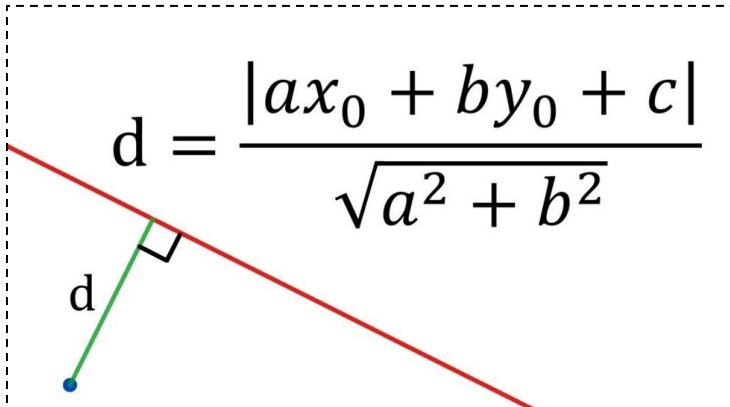


Intuition

- Our problem:

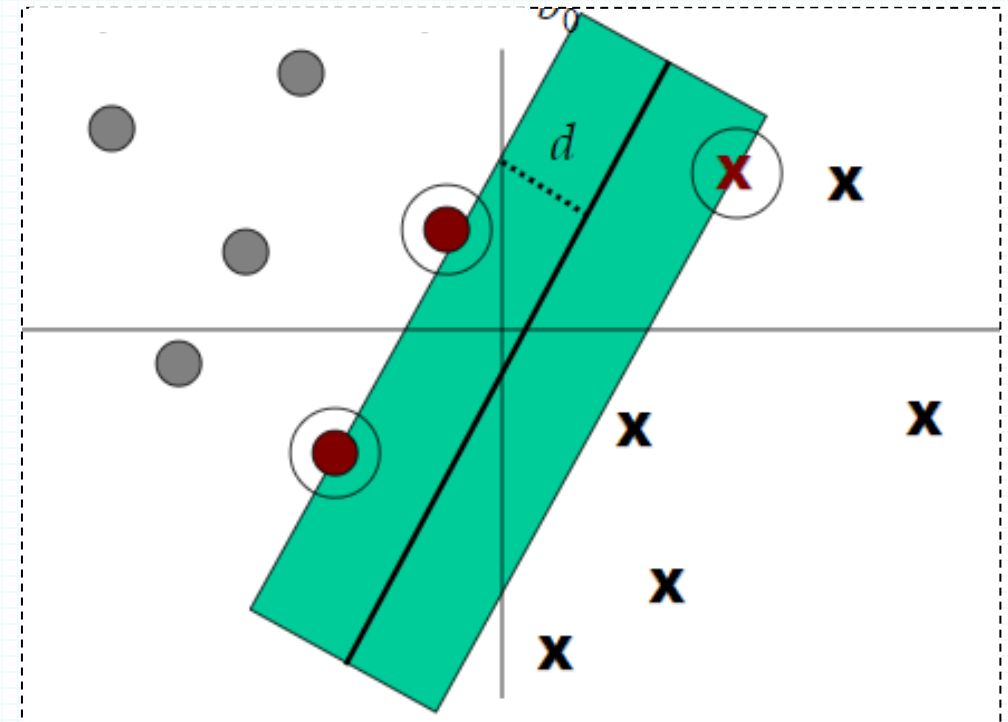
Maximizing the shortest distance to the closest positive or negative point.

The distance between a point (X_0, Y_0) and a line $aX + bY + c = 0$



A diagram showing a blue point and a red line. A green line segment of length d connects the point to the line at a right angle, indicated by a small square symbol.

$$d = \frac{|ax_0 + by_0 + c|}{\sqrt{a^2 + b^2}}$$



So.. What is our optimization problem?

- Our problem:

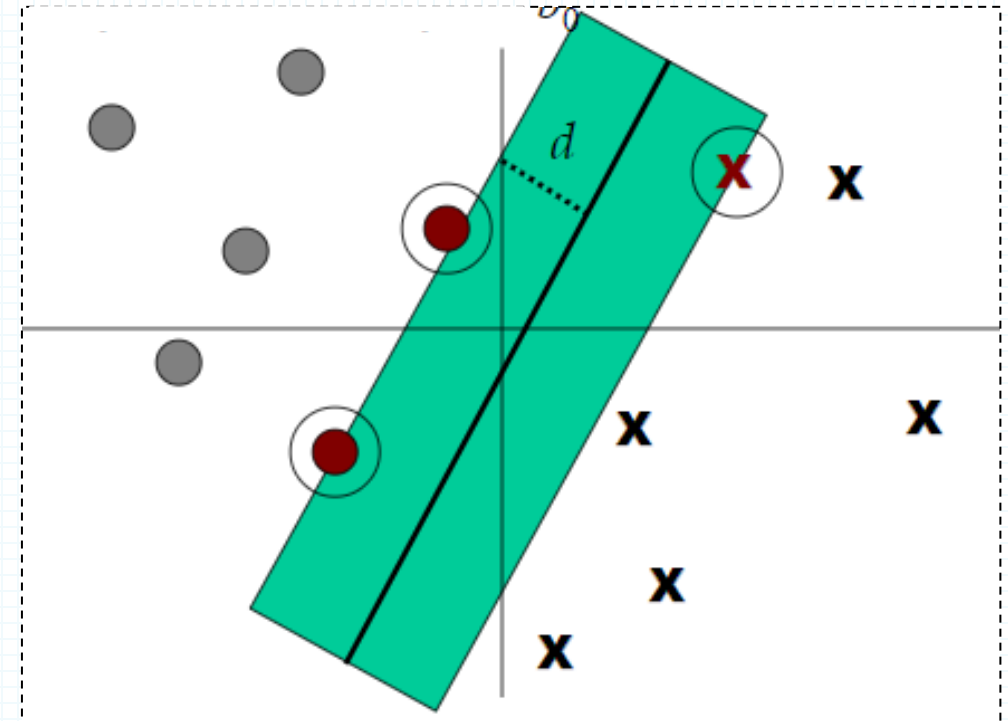
Maximizing the shortest distance to the closest positive or negative point.

In our case

the distance of a hyperplane equation:
 $w^T \Phi(x) + b = 0$ from a given point
vector $\Phi(x_0)$ can be easily written as :

$$d_H(\phi(x_0)) = \frac{|w^T(\phi(x_0)) + b|}{\|w\|_2}$$

$$\|w\|_2 =: \sqrt{w_1^2 + w_2^2 + w_3^2 + \dots w_n^2}$$



$$d = \frac{|ax_0 + by_0 + c|}{\sqrt{a^2 + b^2}}$$

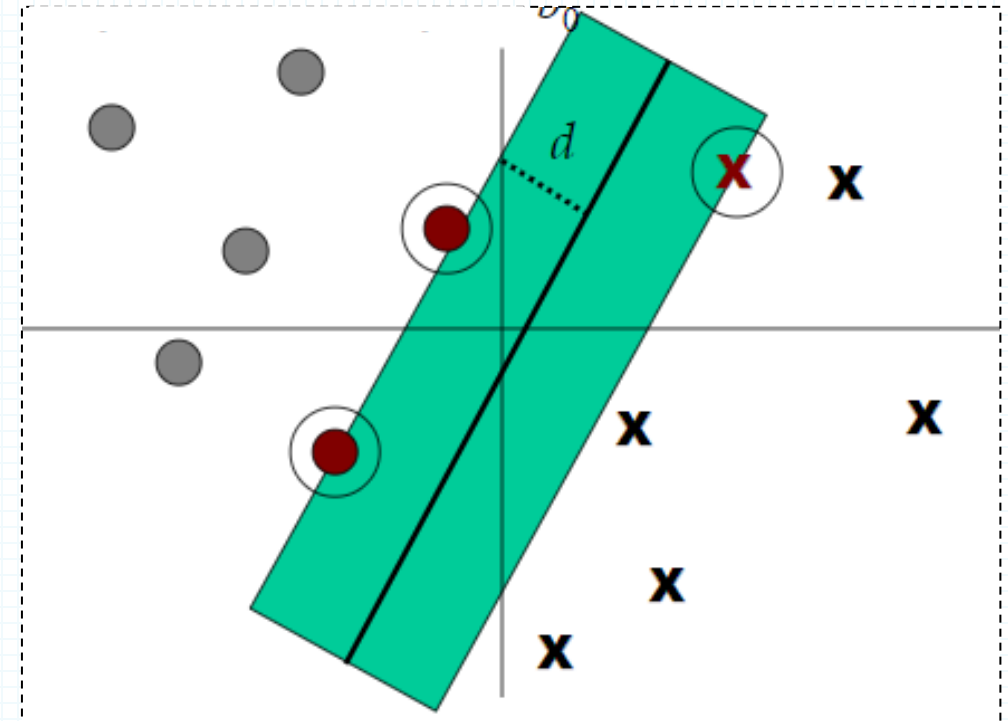
So.. What is our optimization problem?

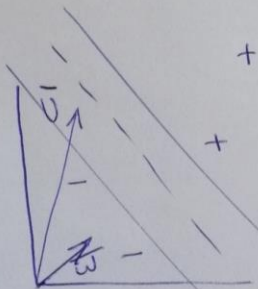
- Our problem:

Maximizing the shortest distance
to the closest positive or negative
point.

$$w^* = \arg_w \max [\min_n d_H(\phi(x_n))]$$

Note that W represents all parameters
i.e. w and b





$$\bar{w} \cdot \bar{U} \geq C \quad \text{the } N^+$$

$$\bar{w} \cdot \bar{U} + b \geq \phi$$

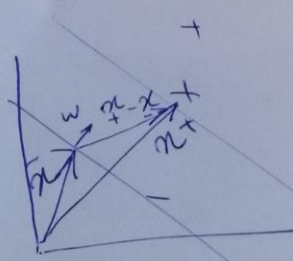
$$\bar{w} x_+^* + b \geq 1$$

$$w x_- + b \leq -1$$

constraint $y_i = +1$ for + samples
 -1 for - samples

$$(y_i (\bar{w} \cdot \bar{x}_i + b) \geq 1) \quad \text{for all points}$$

$$(*) \quad y_i (\bar{w} \cdot \bar{x}_i + b) = 1 \quad \text{for support vector}$$



$$\text{width} = (\bar{x}_+ - \bar{x}_-) \cdot \frac{\bar{w}}{\|\bar{w}\|}$$

support vector

$$= (\bar{x}_+ \bar{w} - \bar{x}_- \bar{w}) \frac{1}{\|\bar{w}\|}$$

from (*)

$$x_+ \rightarrow \bar{w} x_+ + b = 1 \rightarrow \bar{w} x_+ = 1 - b$$

$$x_- \rightarrow \bar{w} x_- + b = -1 \rightarrow -\bar{w} x_- = 1 + b$$

\Downarrow

$$\text{width} = \frac{2}{\|\bar{w}\|}$$

Goal Maximize $\frac{2}{\|\bar{w}\|}$

\Downarrow

Minimize $\|\bar{w}\|$

\Downarrow

Goal Minimize $\frac{1}{2} \|\bar{w}\|^2$

true only if the constraint is satisfied

\Downarrow

use Lagrange Multiplier

$$L = \frac{1}{2} \|\bar{w}\|^2 - \sum \alpha_i [y_i (\bar{w} \cdot \bar{x}_i + b) - 1]$$

Simplified Objective

$$w^*, b^* = \arg \underset{w, b}{\text{Min}} \frac{1}{2} \|w\|^2, \quad \text{s.t.} \quad y_n (w^T (\phi(x_n)) + b) \geq 1 \quad \forall n$$

How to find the optimum w and b ?

SVM Optimization

$$w^*, b^* = \arg \min_{w, b} \frac{1}{2} \|w\|^2, \quad \text{s.t.} \quad y_n (w^T (\phi(x_n)) + b) \geq 1 \quad \forall n$$

Solved by Lagrange multiplier method:

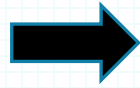
$$L(w, b, \alpha) = \frac{1}{2} \|w\|^2 - \sum_n \alpha_n [y_n (w^T (\phi(x_n)) + b) - 1]$$

where α is the Lagrange multiplier

The optimization problem can be solved by setting **derivatives** of *Lagrangian* to 0

SVM Optimization

$$L(w, b, \alpha) = \frac{1}{2} \|w\|^2 - \sum_n \alpha_n [y_n (w^T (\phi(x_n)) + b) - 1]$$


$$\left\{ \begin{array}{l} \frac{\partial L}{\partial w} = w - \sum_n \alpha_n y_n \phi(x_n) = 0 \Rightarrow w = \sum_n \alpha_n y_n \phi(x_n) \\ \frac{\partial L}{\partial b} = \sum_n \alpha_n y_n = 0 \Rightarrow \sum_n \alpha_n y_n = 0 \end{array} \right.$$

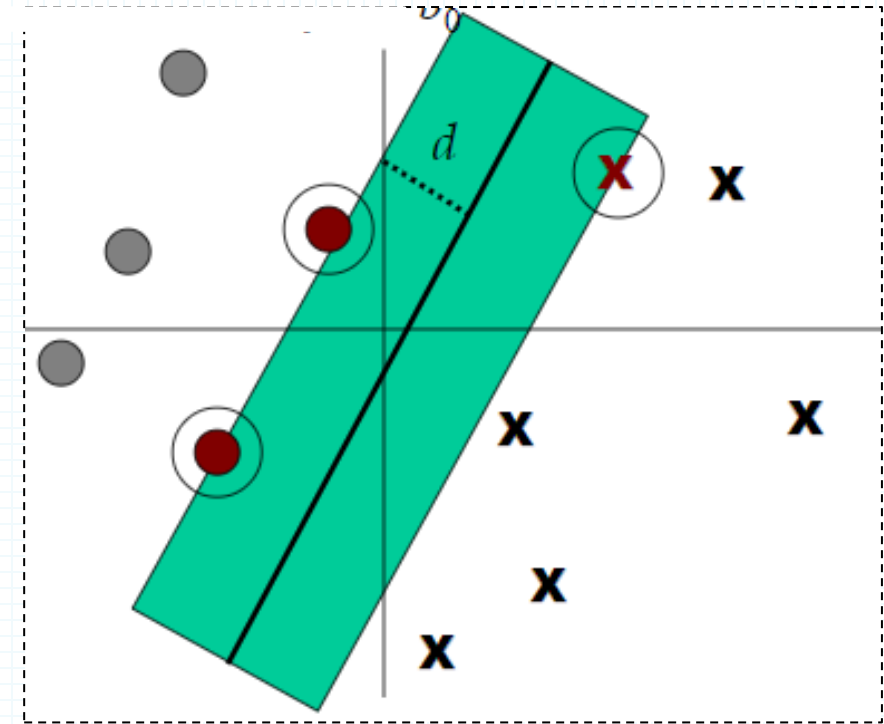
SVM Optimization

$$L = \sum_n \alpha_n + \frac{1}{2} \sum_{n,m} \alpha_n \alpha_m y_n y_m \phi^T(x_m) \phi(x_n)$$

The Boundary:

$$Y = w^T(\phi(x)) + b = \sum_n \alpha_n y_n \phi^T(x_n) \phi(x)$$

Only depend on
inner products



SVM Optimization

$$w^*, b^* = \arg \min_{w, b} \frac{1}{2} \|w\|^2, \quad \text{s.t.} \quad y_n (w^T (\phi(x_n)) + b) \geq 1 \quad \forall n$$

$$Y = w^T (\phi(x)) + b = \sum_n \alpha_n y_n \phi^T(x_n) \phi(x)$$

The decision rule in SVMs only depends on the **dot product with support vectors**

several important implications

Computational efficiency
Memory efficiency
Robustness to noise and outliers

