



Lecture 10: Searching algorithm (Part. 1)

Algorithm

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Table of Contents

❖ Part 1

- Preliminaries

❖ Part 2

- Binary search tree

❖ Summary

Part 1

PRELIMINARIES

Preliminaries

❖ Record

- A unit space that contains **all information** about an object
 - e.g., Human record
 - Resident ID, name, address, phone number, etc.

❖ Field

- An element in a record that represents **each piece of information**
 - e.g., Resident ID in Human record

Preliminaries

❖ (Search) key

- A field that **uniquely** represents each record to avoid duplication
- The key may consist of one or more fields
 - e.g., Account ID

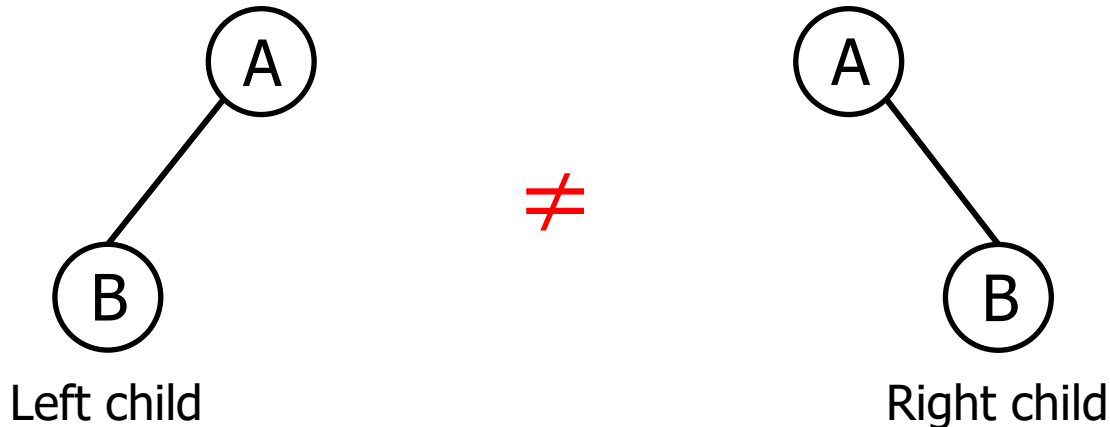
❖ Search tree

- A tree structure composed of nodes with keys following **specific rules**
- Allows identification of where a specific record is stored in the tree

Preliminaries

❖ Binary tree

- A tree structure where each node has a maximum of **two child nodes**
- If the positions of the children differ, it becomes a different tree

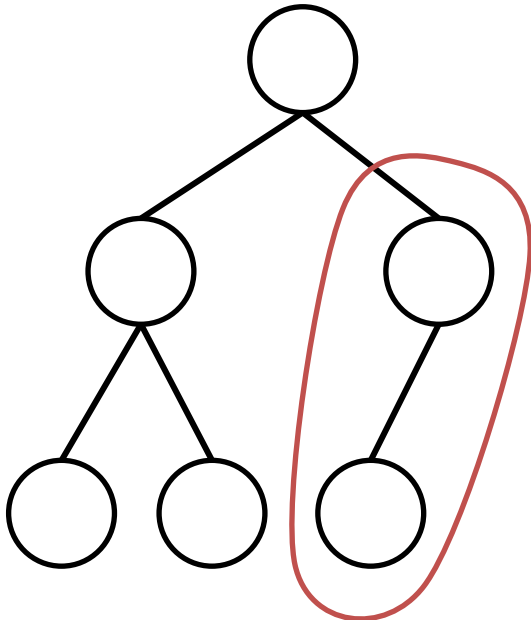


Preliminaries

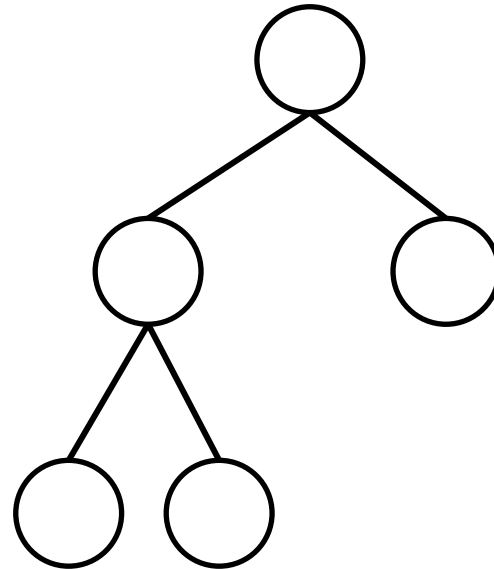
❖ Types of binary tree

1) Full binary tree

- A binary tree where every node has either **0 or 2** child nodes
 - Note that lead nodes are excluded



Binary tree



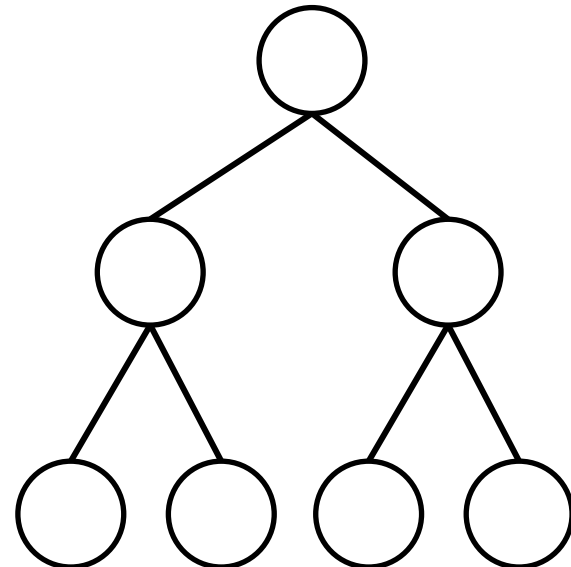
Full binary tree

Preliminaries

❖ Types of binary tree

2) Perfect binary tree

- A binary tree where every node has **2** child nodes
- All leaf nodes are at the **same level**
- Characteristics:
 - If the height is h , the total number of nodes is $2^{(h+1)} - 1$
 - The number of leaf nodes is 2^h



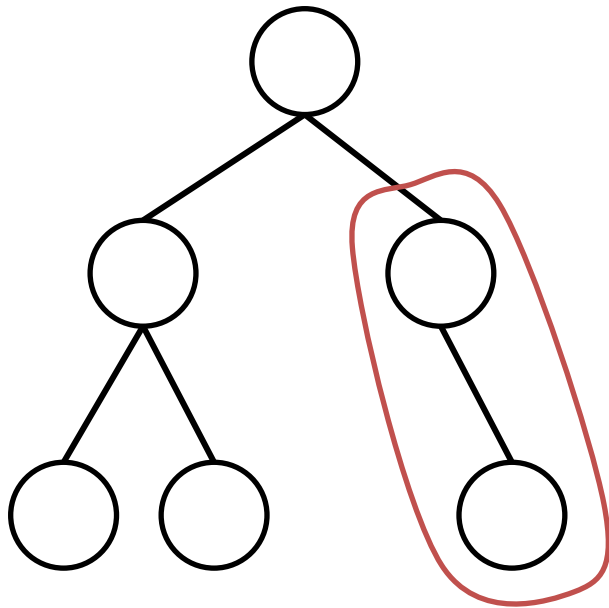
Perfect binary tree

Preliminaries

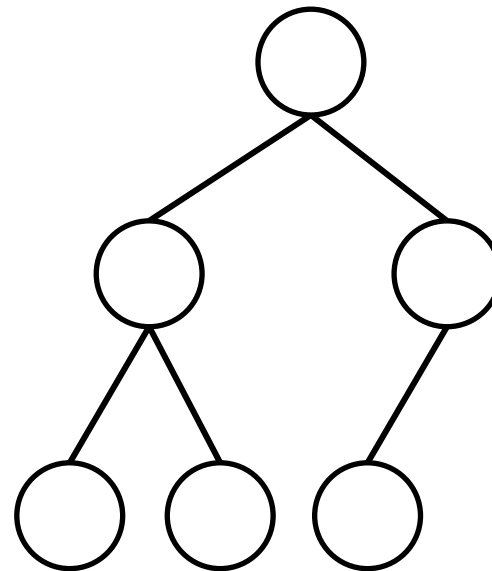
❖ Types of binary tree

3) Complete binary tree

- All nodes **must be filled** except for the last level
- All nodes are filled **from left to right**



Binary tree

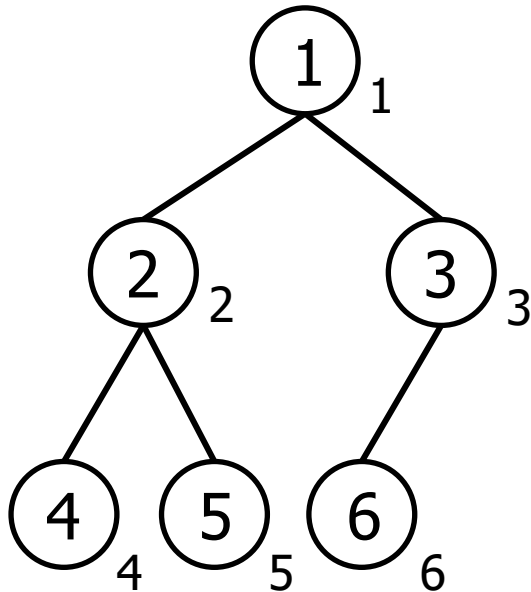


Complete binary tree

Preliminaries

❖ Characteristics of complete binary tree

- Can be represented as an 1-d array



Index	0	1	2	3	4	5	6
	-	1	2	3	4	5	6

- Left child of the i -th node: $(i * 2)$ -th node
- Right child of the i -th node: $(i * 2 + 1)$ -th node

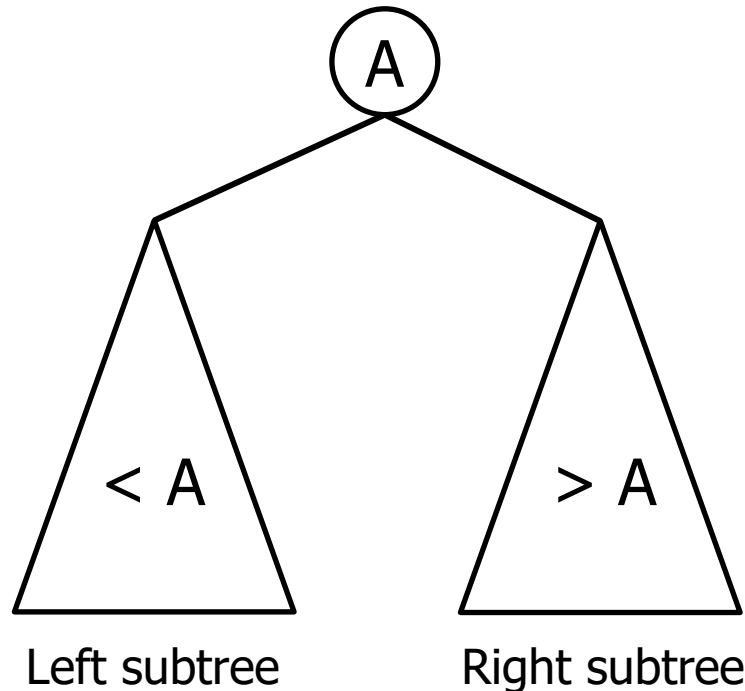
Part 2

BINARY SEARCH TREE

Binary Search Tree

❖ Definition

- A binary tree where each node has a unique key
- The key of any node is **greater than** the key of its **left child** node and **smaller than** the key of its **right child** node



Binary Search Tree

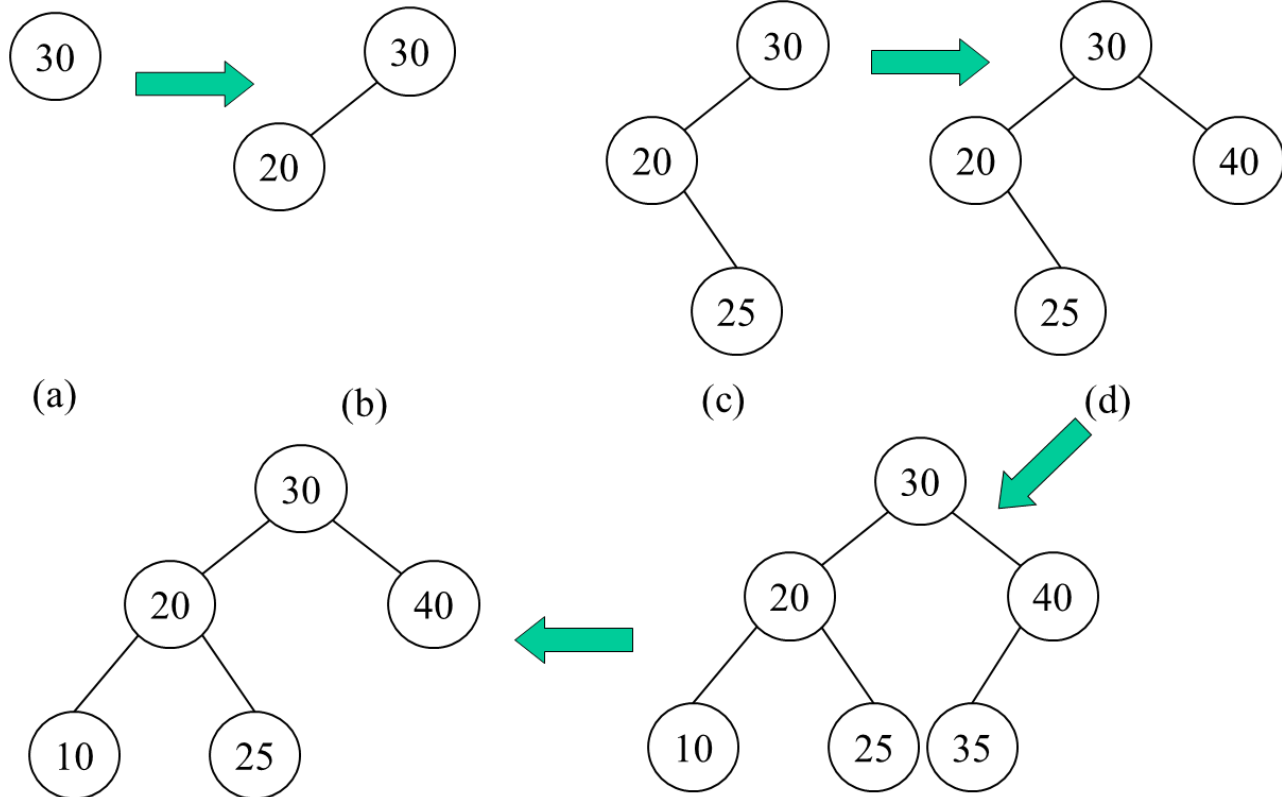
❖ Node insertion in a binary search tree

```
int tree[MAX_SIZE];  
void treeInsert(int x, int idx = 1){  
    if (idx = NIL)  
        tree[idx] = x;  
    if (x < tree[idx])  
        treeInsert(x, idx * 2);  
    else  
        treeInsert(x, idx * 2 + 1);  
}
```

※ NIL = nothing

Binary Search Tree

❖ Example of node insertion



Binary Search Tree

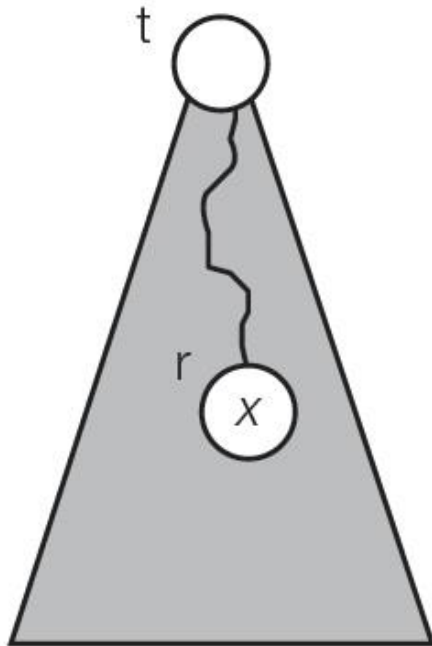
❖ Searching algorithm

```
int tree[MAX_SIZE];  
int treeSearch(int x, int idx = 1){  
    if (idx = NIL or tree[idx] = x)  
        return idx;  
    if (x < tree[idx])  
        return treeSearch(x, idx * 2);  
    else  
        return treeSearch(x, idx * 2 + 1);  
}
```

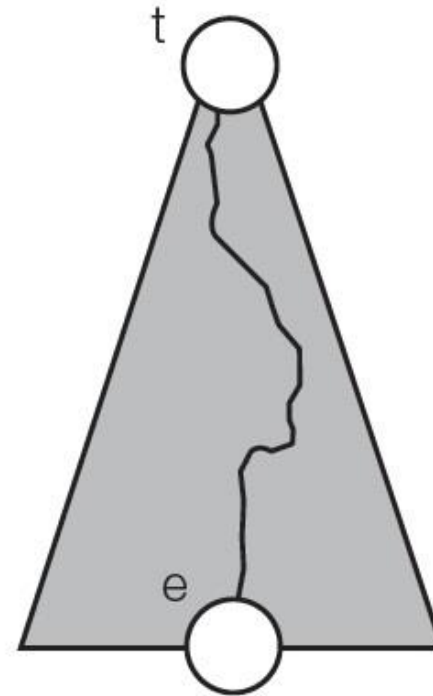
※ NIL = nothing

Binary Search Tree

- ❖ Algorithm analysis
 - Successful and unsuccessful searching



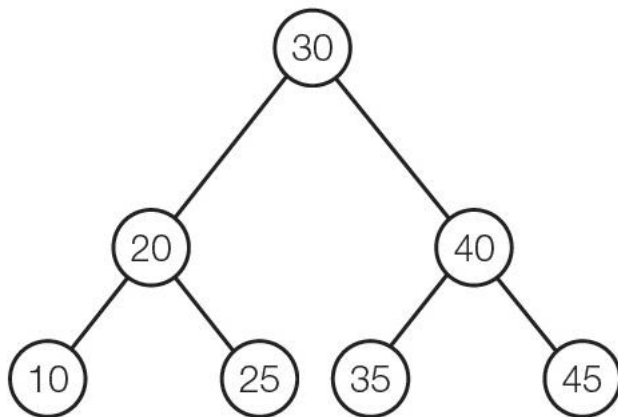
Successful searching



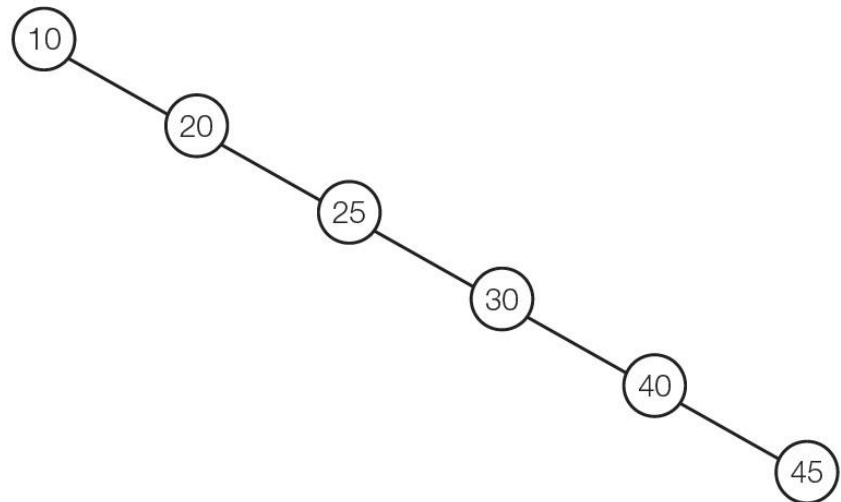
Unsuccessful searching

Binary Search Tree

- ❖ Time complexity of insertion and searching in a binary search tree
 - If the tree is balanced (best case): $O(\log n)$
 - If the tree is unbalanced (worst case): $O(n)$
 - Averagely $O(\log n)$



Balanced tree



Unbalanced tree

Binary Search Tree

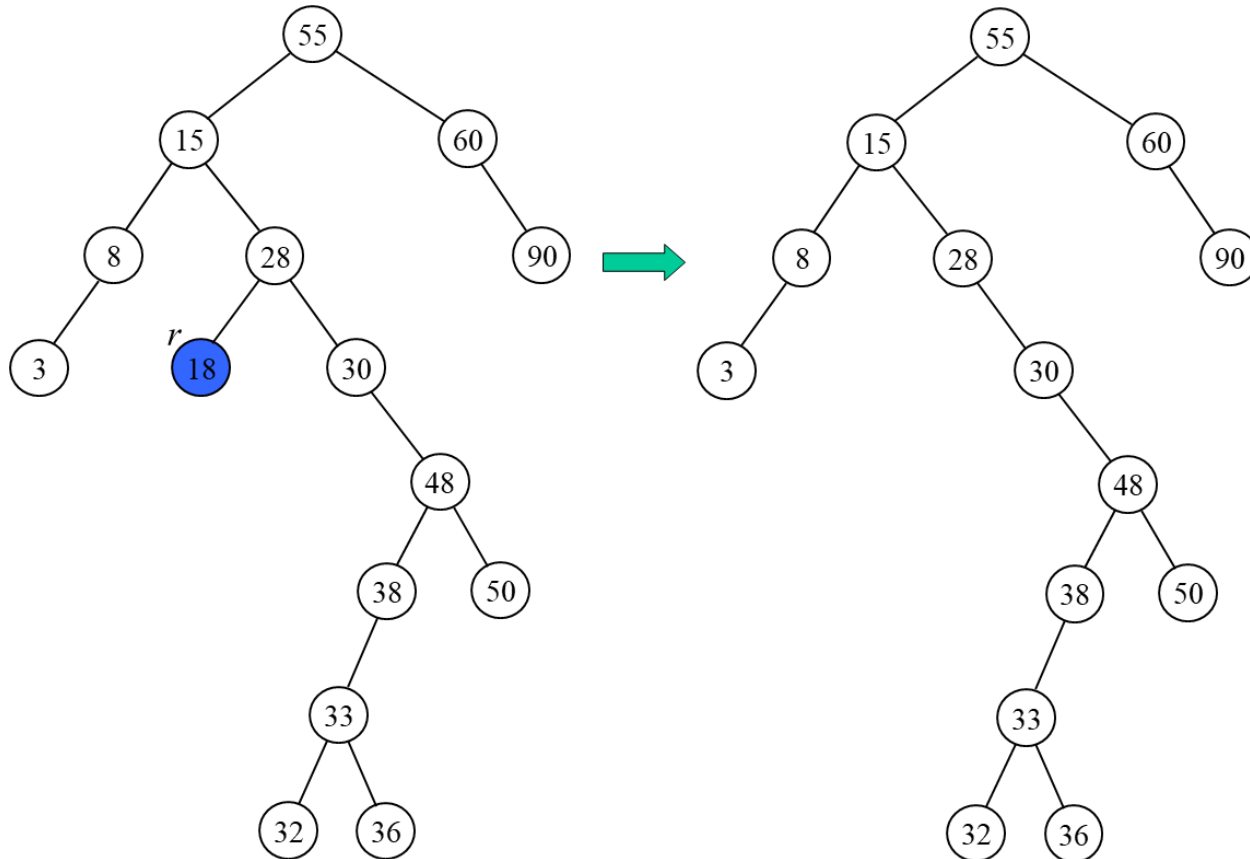
- ❖ Node deletion in a binary search tree
 - Handled differently depending on following three cases:
 - Case 1: if the target has 0 child node (= leaf node)
 - Case 2: if the target has 1 child node
 - Case 3: if the target has 2 child nodes

```
int tree[MAX_SIZE];  
void treeDelete(int x, int idx = 1){  
    int target = treeSearch(x, idx)  
    if (tree[target * 2] = NIL and tree[target * 2 + 1] = NIL)  
        remove the target node  
    else if (tree[target * 2] != NIL and tree[target * 2 + 1] != NIL)  
        swap the target node with the minimum node of its right subtree,  
        then delete  
    else  
        directly connect the target node's parent to its child  
}
```

Binary Search Tree

❖ Node deletion in a binary search tree

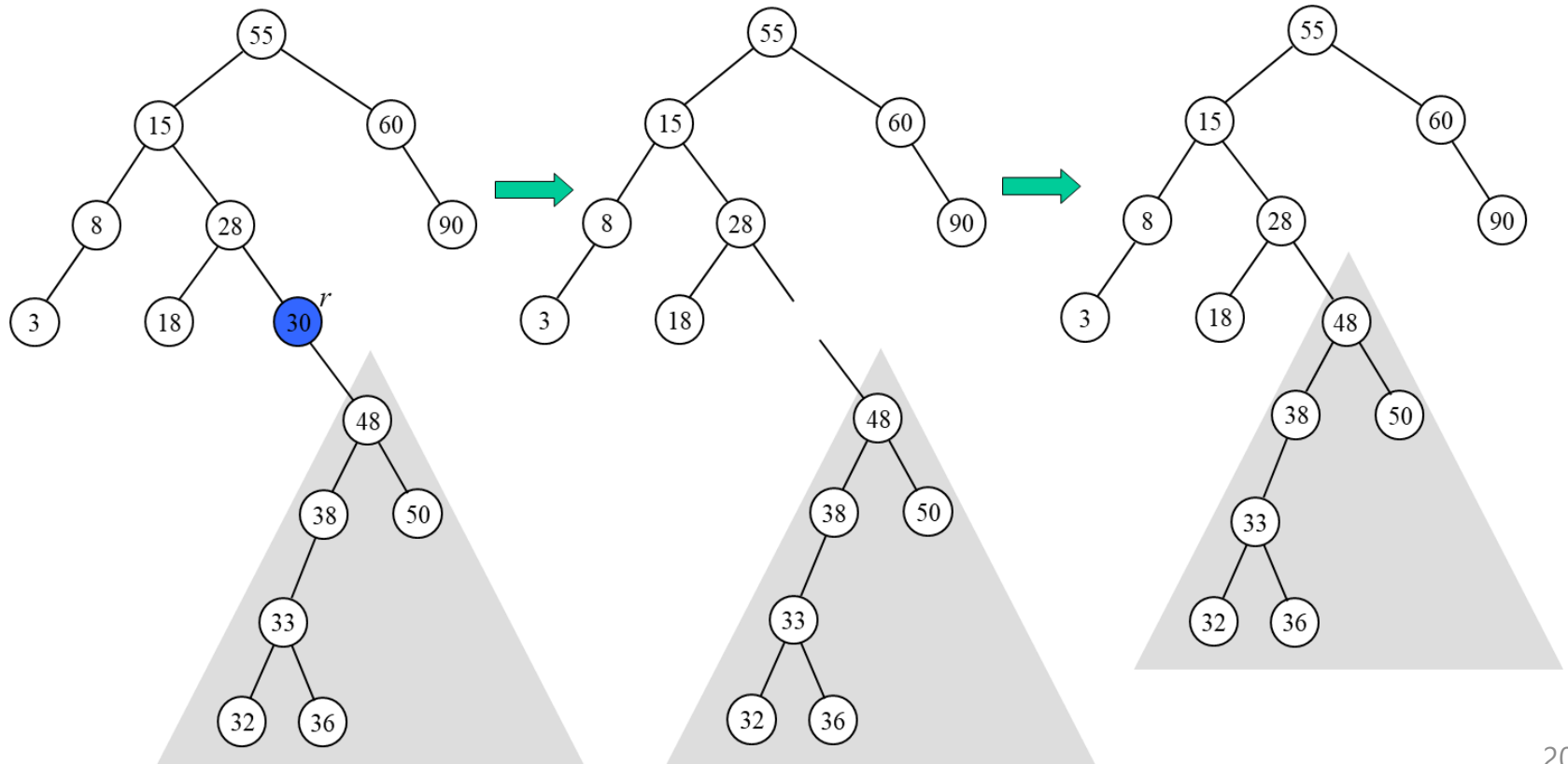
- Handled differently depending on following three cases:
 - Case 1: if the target has 0 child node (= leaf node)



Binary Search Tree

❖ Node deletion in a binary search tree

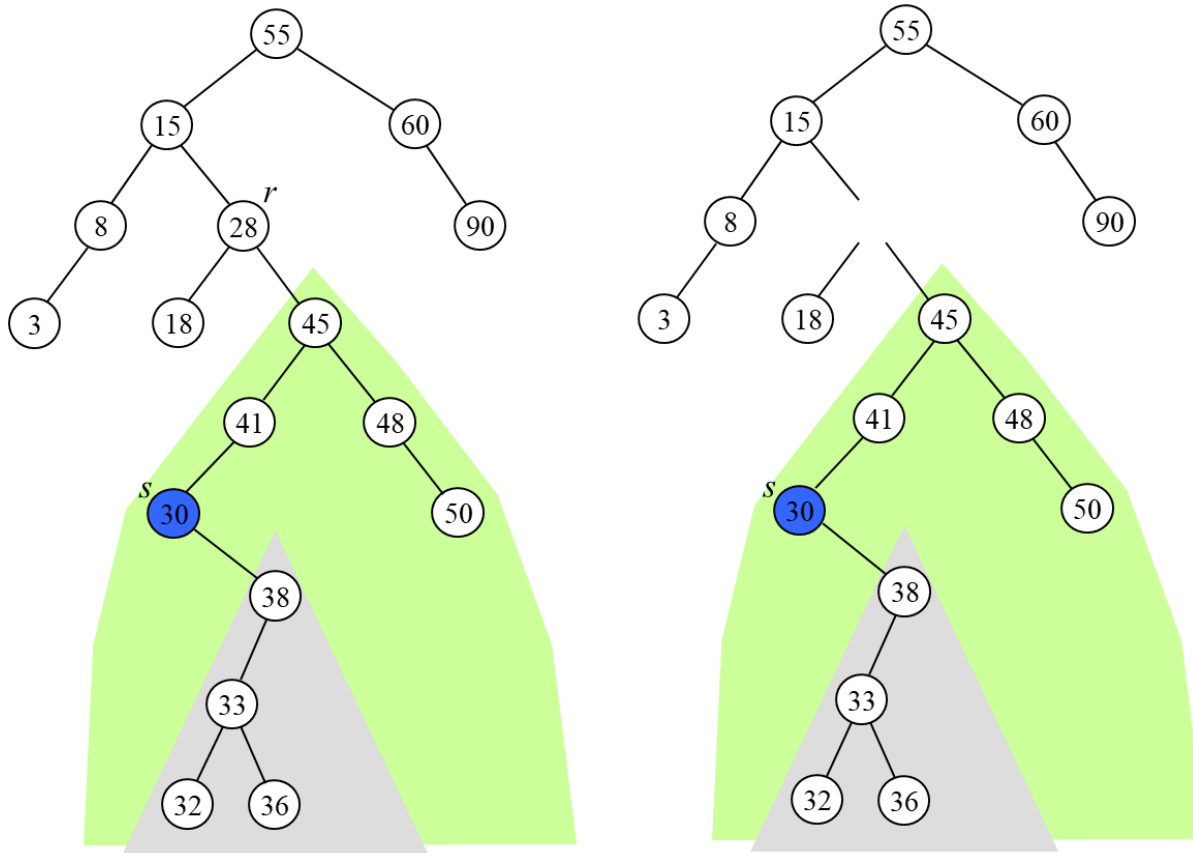
- Handled differently depending on following three cases:
 - Case 2: if the target has 1 child node



Binary Search Tree

❖ Node deletion in a binary search tree

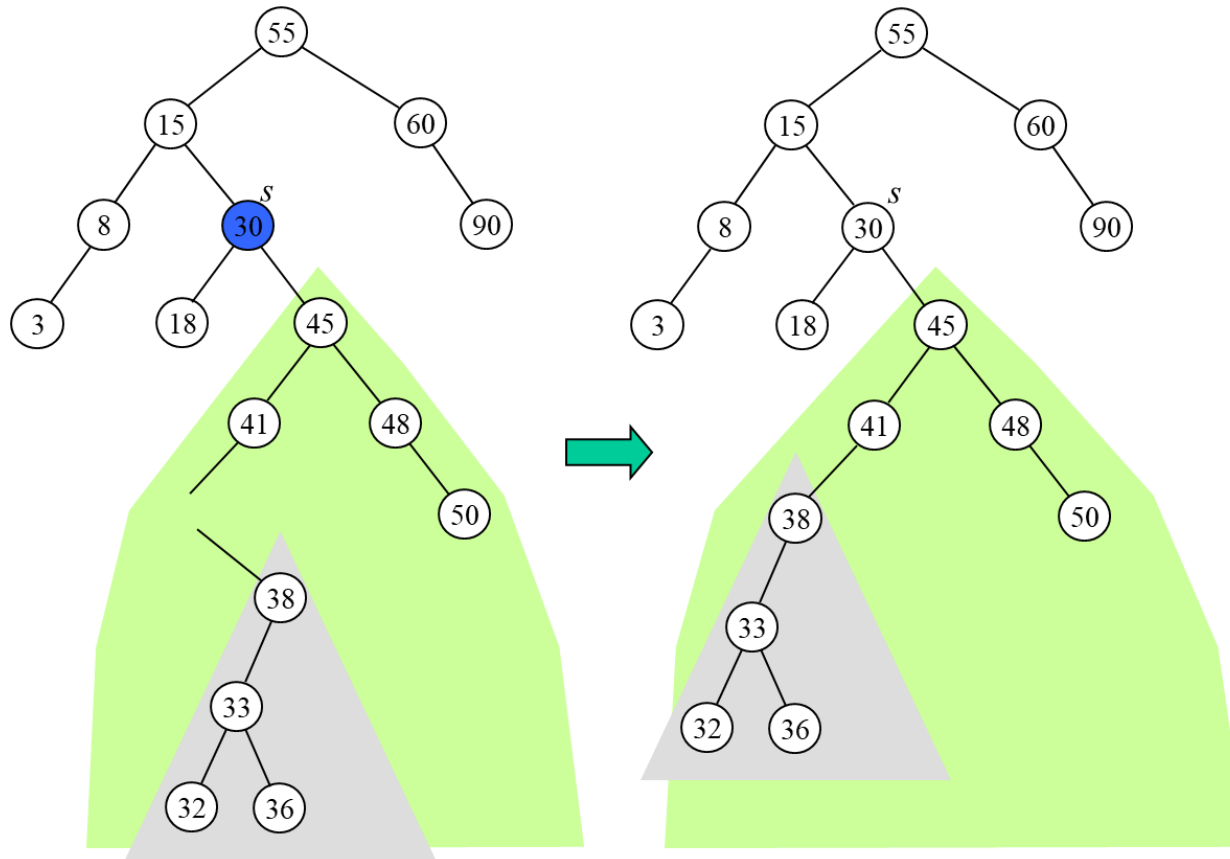
- Handled differently depending on following three cases:
 - Case 3: if the target has 2 child nodes



Binary Search Tree

❖ Node deletion in a binary search tree

- Handled differently depending on following three cases:
 - Case 3: if the target has 2 child nodes (cont'd)

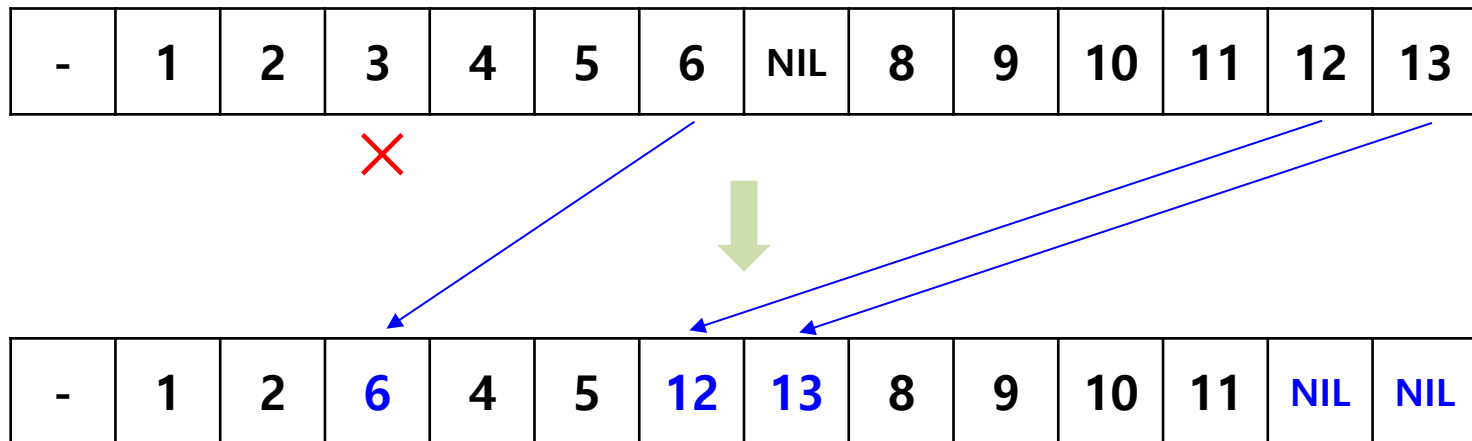


Binary Search Tree

❖ Node deletion in a binary search tree

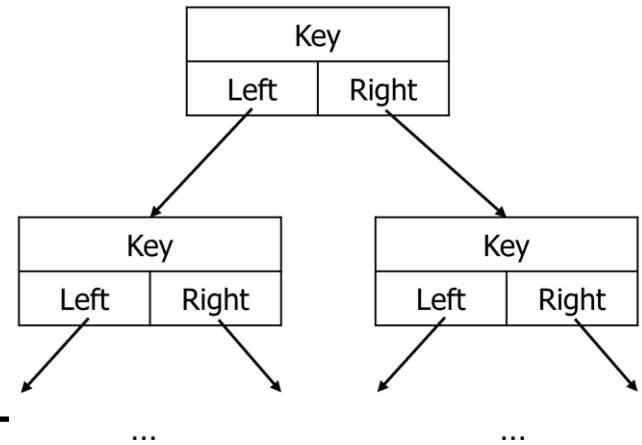
▪ Issues with 1-d array

- As the height of the binary tree increases, the space complexity of the array grows exponentially
- Due to node deletion, elements in the array must be shifted



Binary Search Tree

- ❖ Node deletion in a binary search tree
 - Linked list-based binary search tree
 - Can mitigate issues with 1-d arrays
 - However, it requires cost for linking



```
typedef struct Node {  
    int key;  
    struct Node* left;  
    struct Node* right;  
} Node;  
  
Node* createNode(int x){  
    Node* newNode = (Node*)malloc(sizeof(Node));  
    newNode -> key = x;  
    newNode -> left = NULL;  
    newNode -> right = NULL;  
    return newNode;  
}
```


Binary Search Tree

- ❖ Node deletion in a binary search tree
 - Linked list-based binary search tree (cont'd)

```
Node* treeInsert(Node* root, int x){  
    if (root = NULL){  
        return createNode(x);  
    }  
    if (x < root -> key)  
        root -> left = treeInsert(root -> left, x);  
    else if (x > root -> key)  
        root -> right = treeInsert(root -> right, x);  
    return root;  
}
```

Binary Search Tree

- ❖ Node deletion in a binary search tree
 - Linked list-based binary search tree (cont'd)

```
Node* treeSearch(Node* root, int x){  
    if (root = NULL and root -> key = x){  
        return root;  
    }  
    if (x < root -> key)  
        treeSearch(root -> left, x);  
    else  
        treeSearch(root -> right, x);  
}
```

Binary Search Tree

❖ Node deletion in a binary search tree

▪ Linked list-based binary search tree (cont'd)

```
Node* treeDelete(Node* root, int x){
    if (root == NULL){
        return root;
    }
    if (x < root->key)
        root->left = treeDelete(root->left, x);
    else if (x > root->key)
        root->right = treeDelete(root->right, x);
    else {
        if (root->left == NULL and root->right == NULL){
            free(root);
            return NULL;
        } else if (root->left == NULL){
            Node* temp = root->right;
            free(root);
            return temp;
        } else if (root->right == NULL){
            Node* temp = root->left;
            free(root);
            return temp;
        } else {
            Node* temp = findMinNode(root->right);
            root->key = temp->key;
            root->right = treeDelete(root->right, temp->key);
        }
    }
    return root;
}
```

```
Node* findMinNode(Node* root){
    while (root->left != NULL)
        root = root->left;
    return root;
}
```

Time complexity for node deletion
Balanced: $O(\log n)$
Unbalanced: $O(n)$

Summary

❖ Preliminaries

- Record
- Field
- Key
- Search tree
- Binary tree

❖ Binary search tree

- Searching
- Insertion
- Deletion

Questions?

SEE YOU NEXT TIME!