

Data and Computer Communications

CHAPTER 6

Error Detection and Correction

Types of Errors

➤ An error occurs when a bit is altered between transmission and reception

= bit error

- Binary 1 is transmitted and binary 0 is received
- Binary 0 is transmitted and binary 1 is received

Single bit errors

Isolated error that alters one bit but does not affect nearby bits

Can occur in the presence of white noise

Burst errors

가

Contiguous sequence of B bits in which the first and last bits and any number of intermediate bits are received in error

Can be caused by impulse noise or by fading in a mobile wireless environment

Effects of burst errors are greater at higher data rates

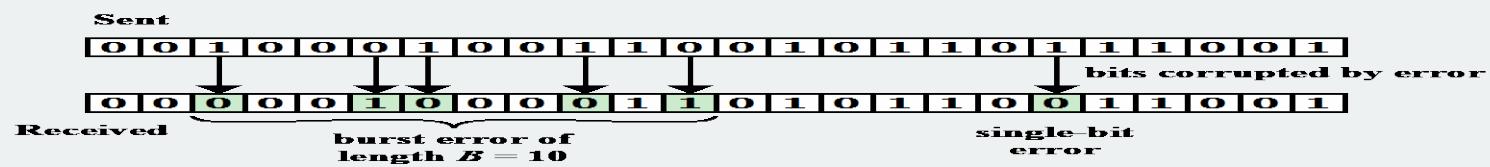
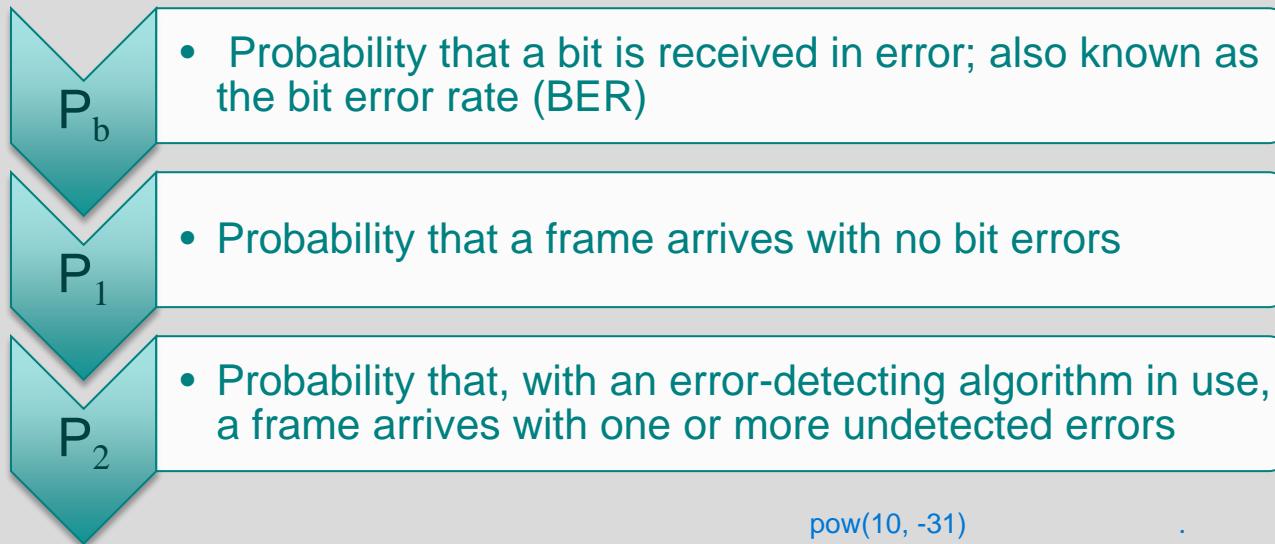


Figure 6.1 Burst and Single-Bit Errors

Error Detection

- Regardless of design you will have errors, resulting in the change of one or more bits in a transmitted frame
- Frames
 - Data transmitted as one or more contiguous sequences of bits



`pow(10, -31)`

- The probability that a frame arrives with no bit errors decreases when the probability of a single bit error increases
- The probability that a frame arrives with no bit errors decreases with increasing frame length
 - The longer the frame, the more bits it has and the higher the probability that one of these is in error

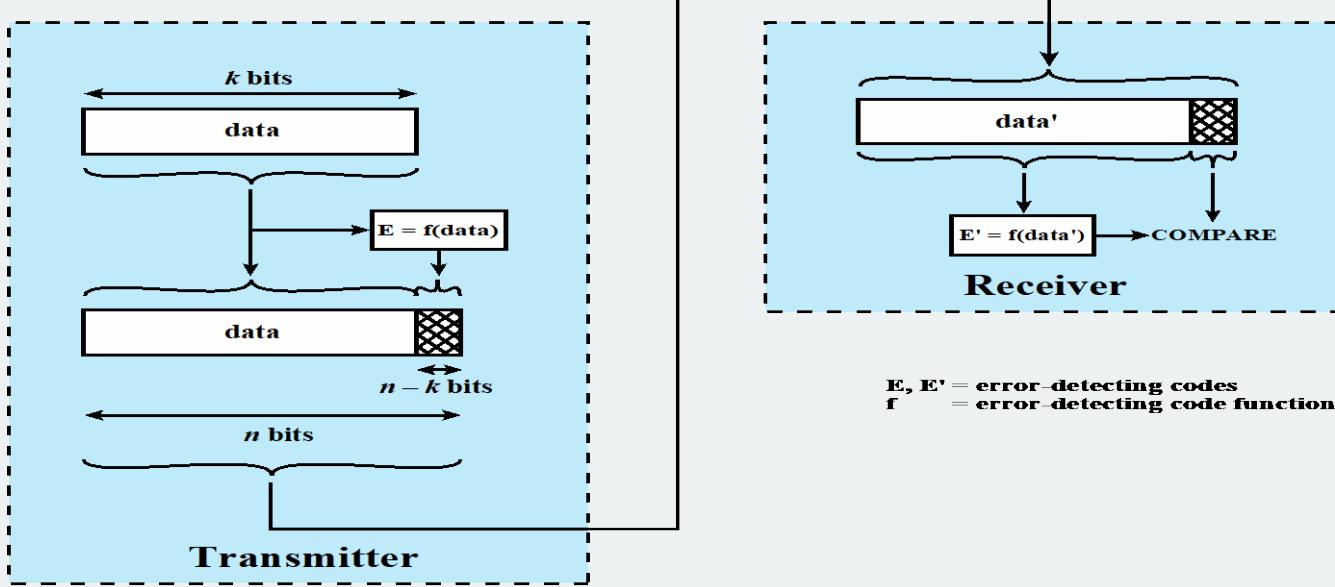


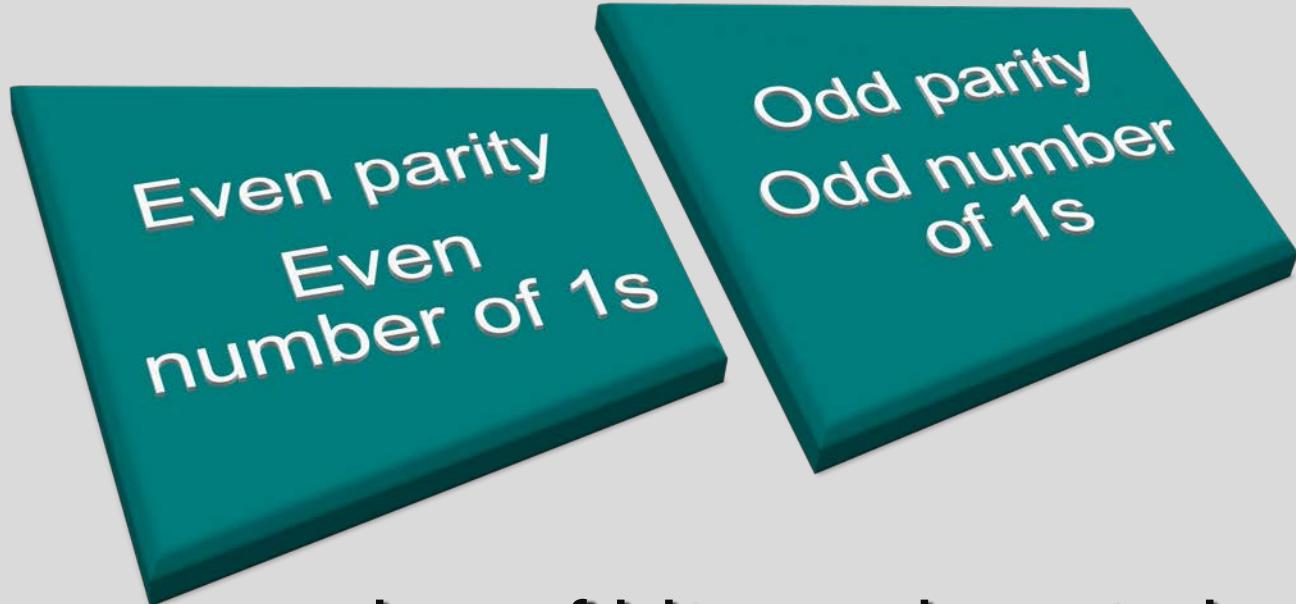
Figure 6.2 Error Detection Process

Parity Check

가

1bit

- The simplest error detecting scheme is to append a parity bit to the end of a block of data



- If any even number of bits are inverted due to error, an undetected error occurs

				row parity
$b_{1,1}$	\dots	$b_{1,j}$	r_1	
$b_{2,1}$	\dots	$b_{2,j}$	r_2	
		$b_{i,1}$	\dots	$b_{i,j}$
		c_1	\dots	c_j
				p

column parity

↓

(a) Parity calculation

0	1	1	1	0	1
0	1	1	1	0	1
0	1	0	0	0	1
0	1	0	1	1	1
0	0	0	1	1	0

(b) No errors

0	1	1	1	0	1
0	0	1	1	0	1
0	1	0	0	0	1
0	1	0	1	1	1
0	0	0	1	1	0

(c) Correctable single-bit error

0	1	1	1	1	1	0	1
0	0	1	1	0	1	1	0
0	0	1	1	0	0	1	1
0	0	0	0	0	0	0	0
1	0	1	1	1	1	1	0

(d) Uncorrectable error pattern

Figure 6.3 A Two-Dimensional Even Parity Scheme

The Internet Checksum

- Error detecting code used in many Internet standard protocols, including IP, TCP, and UDP
- Ones-complement operation
 - Replace 0 digits with 1 digits and 1 digits with 0 digits
- Ones-complement addition
 - The two numbers are treated as unsigned binary integers and added
 - If there is a carry out of the leftmost bit, add 1 to the sum (end-around carry)

Partial sum	0 0 0 1 F2 0 3 F2 0 4
Partial sum	F2 0 4 F4 F5 <u>1E 6 F9</u>
Carry	E 6 F9 1 E 6 FA
Partial sum	E 6 FA F6 F7 <u>1 DDF1</u>
Carry	DDF1 1 DDF2
Ones complement of the result	220D

(a) Checksum calculation by sender

Partial sum	0 0 0 1 F2 0 3 F2 0 4
Partial sum	F4 F5 <u>1E 6 F9</u>
Carry	E 6 F9 1 E 6 FA
Partial sum	E 6 FA F6 F7 <u>1 DDF1</u>
Carry	DDF1 1 DDF2
Partial sum	DDF2 220D <u>FFFF</u>

(b) Checksum verification by receiver

Figure 6.4 Example of Internet Checksum

Cyclic Redundancy Check (CRC)

- One of the most common and powerful error-detecting codes
- Given a k bit block of bits, the transmitter generates an $(n - k)$ bit frame check sequence (FCS) which is exactly divisible by some predetermined number
- Receiver divides the incoming frame by that number
 - If there is no remainder, assume there is no error

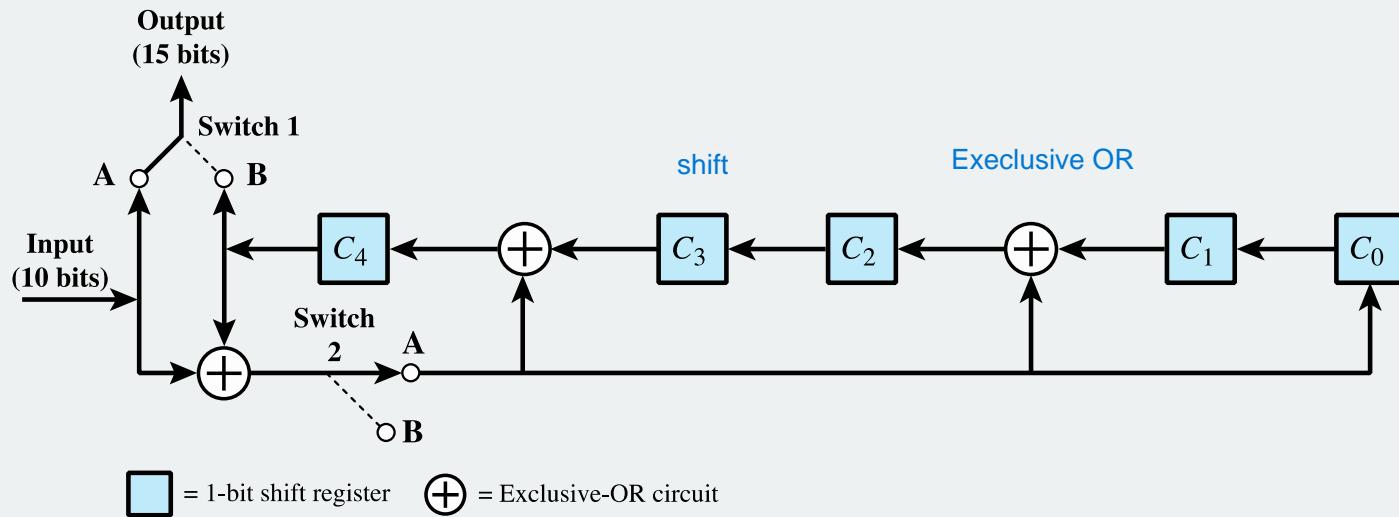
CRC Process

- Modulo 2 arithmetic
 - Uses binary addition with no carries
- Polynomials
 - Express all values as polynomials in a dummy variable X , with binary coefficients
 - Coefficients correspond to the bits in the binary number
- Digital logic
 - Dividing circuit consisting of XOR gates and a shift register
 - Shift register is a string of 1-bit storage devices
 - Each device has an output line, which indicates the value currently stored, and an input line
 - At discrete time instants, known as clock times, the value in the storage device is replaced by the value indicated by its input line
 - The entire register is clocked simultaneously, causing a 1-bit shift along the entire register

generate polynomial

$$\begin{array}{r} \text{= 1 1 0 1 0 1} \\ P(X) \rightarrow X^5 + X^4 + X^2 + 1 \end{array} \left/ \begin{array}{r} X^9 + X^8 + X^6 + X^4 + X^2 + X \\ X^{14} \quad \quad \quad X^{12} \quad \quad \quad X^8 + X^7 + \quad \quad X^5 \\ \hline X^{14} + X^{13} + \quad \quad X^{11} + \quad \quad X^9 \\ \hline X^{13} + X^{12} + X^{11} + \quad \quad X^9 + X^8 \\ \hline X^{13} + X^{12} + \quad \quad X^{10} + \quad \quad X^8 \\ \hline X^{11} + X^{10} + X^9 + \quad \quad \quad X^7 \\ \hline X^{11} + X^{10} + \quad \quad X^8 + \quad \quad X^6 \\ \hline X^9 + X^8 + X^7 + X^6 + X^5 \\ \hline X^9 + X^8 + \quad \quad X^6 + \quad \quad X^4 \\ \hline X^7 + \quad \quad X^5 + X^4 \\ \hline X^7 + X^6 + \quad \quad X^4 + \quad \quad X^2 \\ \hline X^6 + X^5 + \quad \quad X^3 + \quad \quad X \\ \hline X^3 + X^2 + X \end{array} \right. \begin{array}{l} \leftarrow Q(X) \\ \leftarrow X^5 D(X) \\ \leftarrow R(X) \end{array}$$

Figure 6.5 Example of Polynomial Division



(a) Shift-register implementation

	C_4	C_3	C_2	C_1	C_0	$C_4 \approx C_3 \approx I$	$C_4 \approx C_1 \approx I$	$C_4 \approx I$	$I = \text{input}$	
Initial	0	0	0	0	0	1	1	1	1	
Step 1	1	0	1	0	1	1	1	1	0	
Step 2	1	1	1	1	1	1	1	0	1	
Step 3	1	1	1	1	0	0	0	1	0	
Step 4	0	1	0	0	1	1	0	0	0	
Step 5	1	0	0	1	0	1	0	1	0	
Step 6	1	0	0	0	1	0	0	0	1	
Step 7	0	0	0	1	0	1	0	1	1	
Step 8	1	0	0	0	1	1	1	1	0	
Step 9	1	0	1	1	1	0	1	0	1	
Step 10	0	1	1	1	0					

A curly brace on the right side of the table is labeled 'Message to be sent', indicating the sequence of bits from Step 1 to Step 9 as the output message.

(b) Example with input of 1010001101

Figure 6.6 Circuit with Shift Registers for Dividing by the Polynomial $X^5 + X^4 + X^2 + 1$

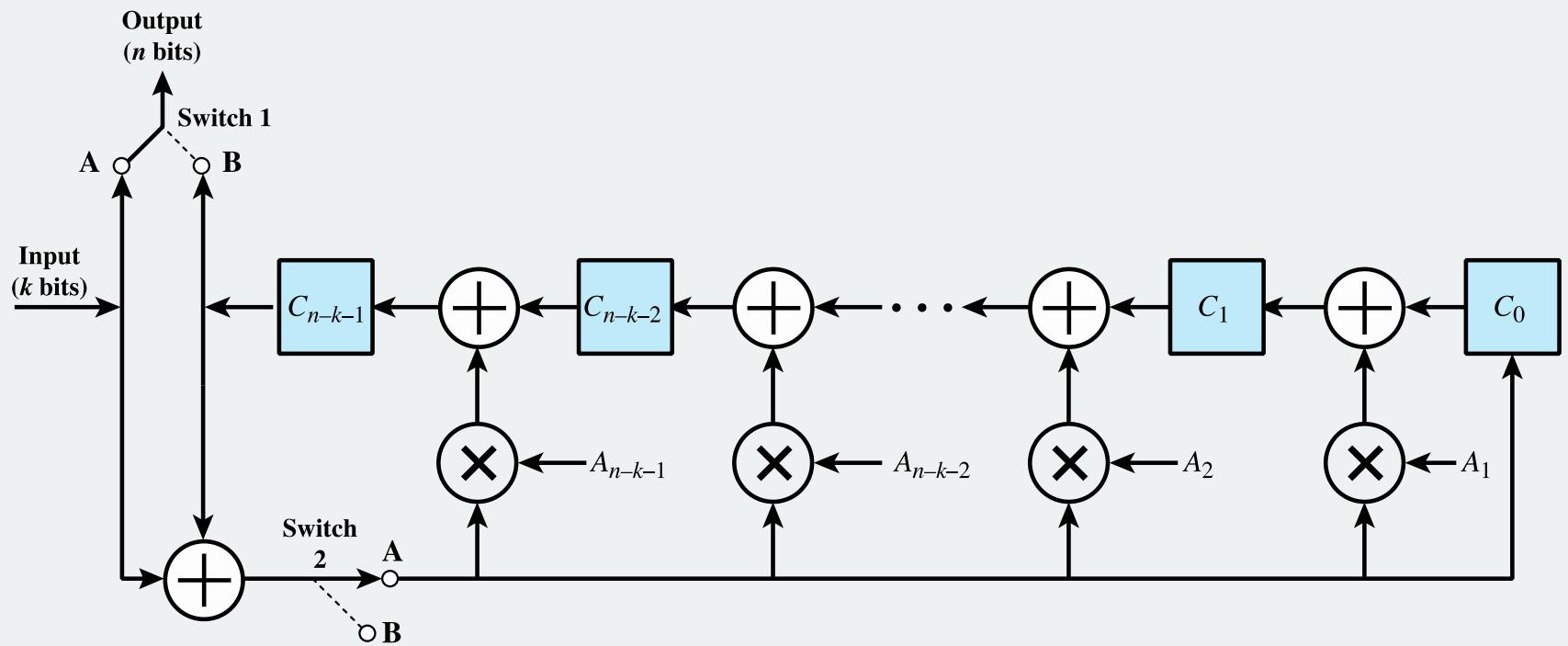


Figure 6.7 General CRC Architecture to Implement Divisor
 $(1 + A_1X + A_2X^2 + \dots + A_{n-k-1}X^{n-k-1} + X^{n-k})$

Forward Error Correction

= Channel Coding

- Correction of detected errors usually requires data blocks to be retransmitted
- Not appropriate for wireless applications:
 - The bit error rate (BER) on a wireless link can be quite high, which would result in a large number of retransmissions
 - Propagation delay is very long compared to the transmission time of a single frame
- Need to correct errors on basis of bits received

Codeword

- On the transmission end each k -bit block of data is mapped into an n -bit block ($n > k$) using a forward error correction (FEC) encoder

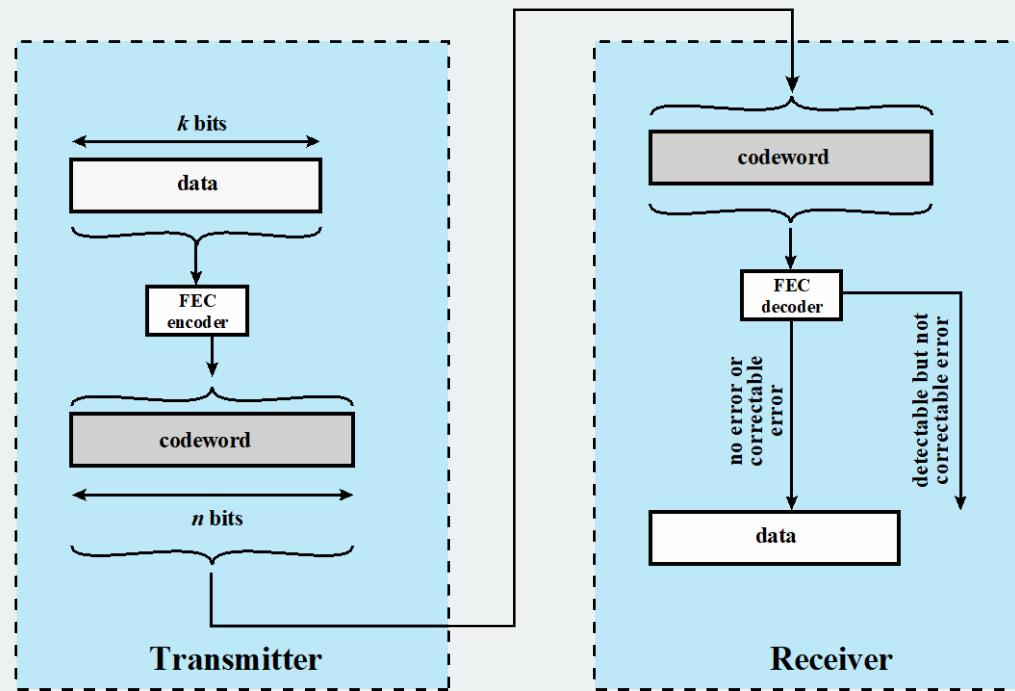


Figure 6.8 Error Correction Process

Block Code Principles

➤ Hamming distance

- $d(v_1, v_2)$ between two n -bit binary sequences v_1 and v_2 is the number of bits in which v_1 and v_2 disagree

➤ Redundancy of the code

- The ratio of redundant bits to data bits $(n-k)/k$

➤ Code rate

- The ratio of data bits to total bits k/n
- Is a measure of how much additional bandwidth is required to carry data at the same data rate as without the code

Block Code Principles

- **Block code example (k = 2, n=5)**
 - Data : 00, 01, 10, 11
 - Codeword : 00000, 00111, 11001, 11110
- **Hamming distance (d) = 3**
- **Correction :** $\left\lfloor \frac{d-1}{2} \right\rfloor$
- **Detection :** $d - 1$

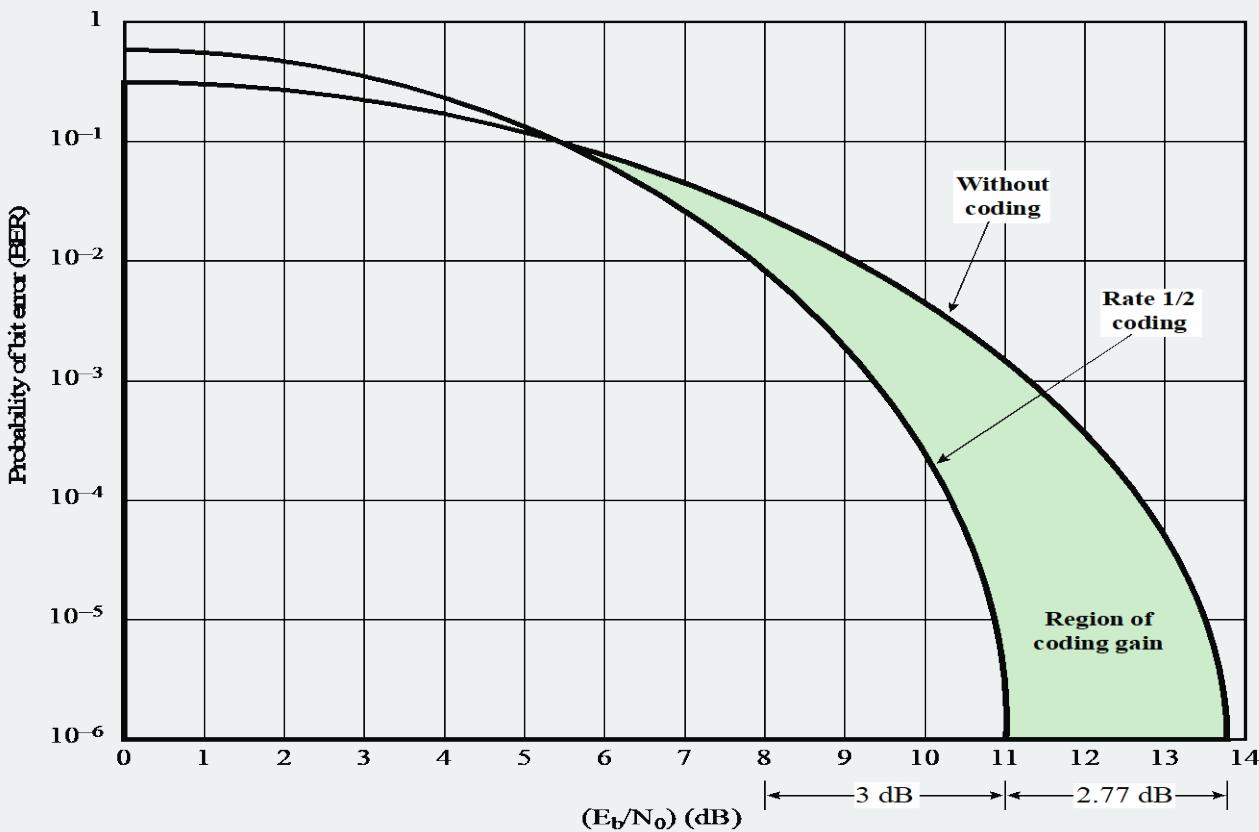


Figure 6.9 How Coding Improves System Performance