

08/05/23

2 marks  
Q. comp Q.Electrostatics

$$e - ve \quad - 1.602 \times 10^{-19} C \quad \text{Mass} - 9.1 \times 10^{-31} \text{kg}$$

$$p + ve \quad - +1.602 \times 10^{-19} \quad 1.672 \times 10^{-27} \text{kg}$$

$$n - 0 \quad - \cancel{1.672 \times 10^{-27}} \text{ k. O} \quad 1.674 \times 10^{-27} \text{ kg.}$$

$$C = \frac{1(0) \times 1}{4\pi \epsilon_0} = 9 \times 10^9 \text{ Nm}^2/\text{C}^2$$

$$\epsilon_0 \approx \text{permittivity of free space} = 8.85 \times 10^{-12} \text{ C}^2/\text{Nm}^2$$

Coulomb's law of inverse square law:

The electrostatic force of interaction b/w 2 point charges is directly proportional to the product of their charges and inversely proportional to the square of the distance b/w them.  $\propto$  along the line joining the centres of charges.

Explanation:

Consider 2 point charges  $q_1$  &  $q_2$  separated by a distance of small  $r$  as shown in fig. Let 'F' be the force of interaction b/w them. Then

$$F \propto q_1 q_2 \rightarrow ①$$

$$F \propto \frac{1}{r^2} \rightarrow ②$$

From eq. ① & ② we have

$$F \propto q_1 q_2 \rightarrow ③$$

(or)

$$F = C \frac{q_1 q_2}{r^2} \rightarrow ④$$

where 'C' is columbs constant

In S.I unit  
 $C = \frac{1}{4\pi\epsilon_0} = 9 \times 10^9 \text{ Nm}^2/\text{C}^2$

where  $\epsilon_0 = \text{permittivity of free space} = 8.85 \times 10^{-12} \text{ C}^2/\text{Nm}$

$q_1, q_2$  charges are in free space.

$$\text{Derivation from eq. ④} \quad F = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r^2} \rightarrow \text{free space}$$

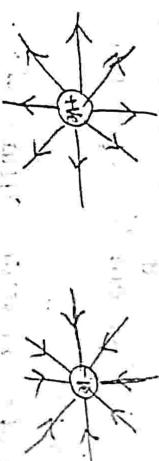
when  $q_1, q_2$  charges are in any medium

$$F = \frac{1}{4\pi\epsilon} \frac{q_1 q_2}{r^2} \quad \text{or} \quad F = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r^2}$$

Electric field: The space around the charge where influence of the charge can be felt is known as electric field.

The  $\vec{E}$ , when a test charge is placed in a electric field produced by positive charge, it moves away from it, when a test charge is placed in a electric field produced by

negative charge it moves towards it.



### Electric field intensity:

The intensity of the electric field at any point in the field is defined as "The force experienced by a unit +ve charge placed at that point." (or) The force experienced by a unit charge when placed at a point in the electric field is known as electric field intensity.

- \* It is denoted by  $E$ .
- \* Consider a point charge  $q_0$  placed in a uniform electric field. Let 'F' be the force experienced by the test charge.

$$F = E q_0 \quad \text{or} \quad E = \frac{F}{q_0}$$

S.I units : Newton or Volt

Coulomb or Meter

Electric field intensity due to a point charge



$E = \frac{F}{q_0}$

Consider a point charge  $+q$  at a point. Let  $q_0$  be the test charge placed at a point at a distance 'r' from the point charge as shown above fig.

A/c to coulomb's inverse square law let  $F$  be the force experienced by the test charge  $q_0$  at a distance 'r' from the point charge  $q$ .

$$F \propto q_0 \rightarrow 1$$

$$F \propto \frac{1}{r^2} \rightarrow 2$$

$$F = \frac{1}{4\pi\epsilon_0 r^2} q_0 \rightarrow 3$$

As per definition of intensity of electric field,

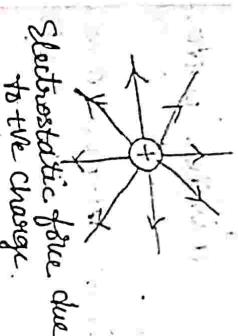
$$E = \frac{F}{q_0} \rightarrow 4$$

$$E = \frac{1}{4\pi\epsilon_0 r^2} q_0$$

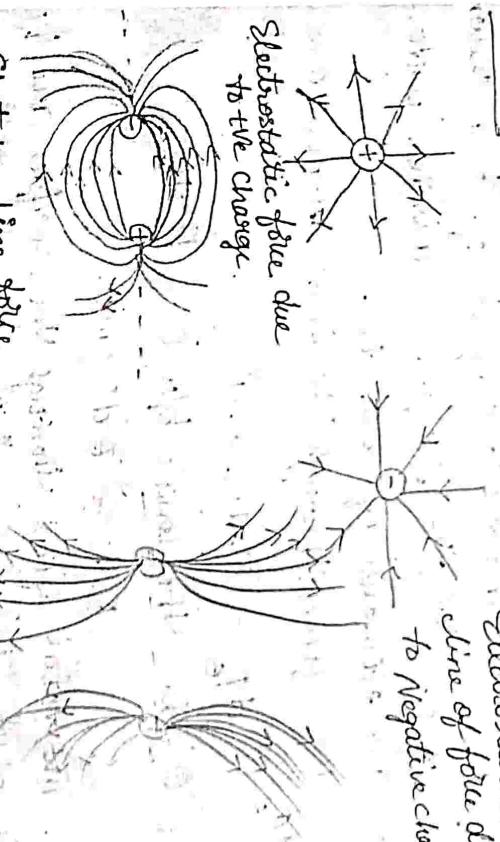
$$E = \frac{1}{4\pi\epsilon_0 r^2} q_0$$

The above eqn shows electric field intensity due to a point charge.

### Electric lines of force:



Electric lines of force due to the charge.



Electric lines of force due to two +ve charges.

Electric lines of force due to -ve +ve charge.

\* The path transversed by a small test +ve charge in the electric field is known as electric lines of force. Different types occurs due to the +ve, -ve, +ve & -ve, & same two +ve charges are shown in below fig:

### Electric flux:

The total electric lines of forces passing through a given surface is called electric flux. It is denoted by  $\phi_E$ .  $\phi_E = \text{flux} = \bar{S} \cdot E$ .

**Explanation:** Let us consider a closed surface in an electric field of  $\vec{E}$  as shown in fig. Let the surface is divided into small elements of area  $d\vec{s}$ .

The flux through the small element area  $d\vec{s}$

$$d\phi_E = \vec{E} \cdot d\vec{s} \rightarrow \textcircled{1}$$

If ' $\theta$ ' be the angle b/w  $\vec{E}$  &  $d\vec{s}$  then

$$d\vec{s} = \vec{E} d\vec{s} \cos\theta.$$

The total flux through the surface area  $\phi_E$

is given by  $\phi_E = \oint d\phi_E$

From eq \textcircled{2}

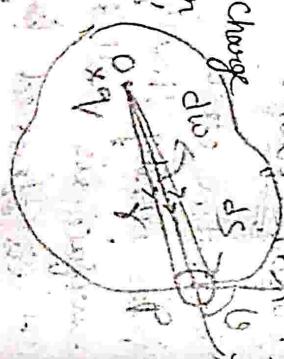
$$\phi_E = \oint \vec{E} \cdot d\vec{s} \cos\theta$$

Gauss law:

Statement: The total electric flux passed through a closed surface in an electric field is equal to  $\frac{1}{\epsilon_0}$  times the total charge enclosed by the surface.

# Let us consider a point charge  $q$  placed at point 'O' within the closed surface of area 'S'

as shown in fig.



\* Let 'P' be the point on the surface at a distance of 'r' from point 'O'. Now imagine a small area  $d\vec{s}$  around the point P. The normal to the surface  $d\vec{s}$  is represented by  $d\vec{s}$  which makes an angle  $\theta$  with the direction of electric field  $\vec{E}$ .

\* The electric flux through the area is given by  $d\phi_E = \vec{E} \cdot d\vec{s} \cos\theta \rightarrow \textcircled{1}$

We know that the eqn of electric field intensity at point is given by  $\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r} \rightarrow \textcircled{2}$

Substitute eq \textcircled{2} in eq \textcircled{1} we get

$$d\phi_E = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \vec{d}s \cos\theta \rightarrow d\phi_E = \frac{q}{4\pi\epsilon_0 r^2} \vec{d}s$$

$$\Rightarrow d\phi_E = \frac{q}{4\pi\epsilon_0} \times d\omega \rightarrow \textcircled{3} : \int_{\text{surface}} d\omega = \frac{d\phi_E}{2\pi r^2}$$

The total flux  $\phi_E$  through the surface

is given by  $\phi_E = \oint d\phi_E$

From eq \textcircled{3}

$$\phi_E = \oint \frac{q}{4\pi\epsilon_0} \times d\omega$$

$$\phi_E = \frac{q}{\epsilon_0} = \left( \frac{1}{\epsilon_0} \right) q$$

$$\phi_E = \frac{q}{4\pi\epsilon_0 S}$$

$$\therefore \phi_E = \oint \vec{E} \cdot d\vec{s} = \oint \vec{E} \cdot d\vec{s} \cos 0 = \left(\frac{q}{\epsilon_0}\right) \frac{1}{r}$$

Q10 Q12 Q13  
Derivation of Coulomb's law from Gauss' Law

Consider an isolated point charge 'q' at a spherical surface of radius 'r' as shown in figure. Construct

a Gaussian surface of radius 'r' at any point on the spherical surface. The electric field intensity will have

same magnitude & direction normal to the spherical surface. The total electric flux over the spherical surface is given by

$$\Phi_E = \oint \vec{E} \cdot d\vec{s}$$

$$\Phi_E = \oint \vec{E} \cdot d\vec{s} \cos 0$$

$$\Phi_E = \oint \vec{E} \cdot d\vec{s} \cos 0$$

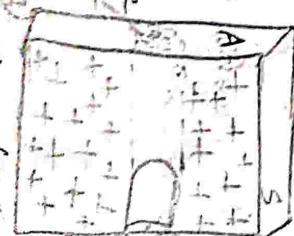
The above eqn represents Coulomb's law.  
Gauss law applications:

1) Electric field intensity due to infinite conducting sheet of charge:-

Consider a charge conductor as shown in fig. Let a point 'P'

just outside the surface of the conductor & surface charge density ( $\sigma$ ) on the surface

of the conductor near 'P' is given by



$$\epsilon_0 E \oint d\vec{s} = q \quad t = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \rightarrow (3)$$

$$E_b \vec{E} \times 4\pi r^2 = q \quad (\because \oint d\vec{s} = 4\pi r^2 \text{ area of sphere})$$

If at the spherical surface a second charge is placed it experiences a force is given by

$$F = E_a V_0 \rightarrow (4)$$

$$E = \frac{F}{q_0} \rightarrow (5) \quad (\because E = \frac{F}{q_0})$$

$$\text{Sub } (3) \text{ in eqi } (4)$$

$$F = \frac{1}{4\pi\epsilon_0} \frac{qV_0}{r^2}$$

$$F = \frac{1}{4\pi\epsilon_0} \frac{qV_0}{r^2}$$

$$\text{Surface charge density } \sigma = \frac{q}{A} \text{ or } q = \sigma A \rightarrow ①$$

Now calculate 'E' value at 'P'. Consider a small cylindrical surface having one flat surface passing through the point P. The other surface being perpendicular to the surface of the conductor as shown in fig.

The total electric flux passing through the gaussian surface is given by

$$\phi = \oint \bar{E} \cdot d\bar{s} + \oint \bar{E} \cdot d\bar{s} + \oint \bar{E} \cdot d\bar{s} \rightarrow ②$$

At the left end, there is no charge, hence  $\bar{E}$  will be zero.

$$\therefore \oint \bar{E} \cdot d\bar{s} = 0 \rightarrow ③$$

At curved surface,  $\bar{E}$  is perpendicular to  $d\bar{s}$  hence angle b/w them is  $90^\circ$ .

$$\therefore \oint \bar{E} \cdot d\bar{s} \cos 90^\circ$$

At the right end,  $\bar{E}$  is parallel to  $d\bar{s}$ ,

$$\text{hence } \theta = 0^\circ, \cos \theta = 1$$

$$\oint \bar{E} \cdot d\bar{s} \cos 1$$

$$= \rho \epsilon_0 d\bar{s} \rightarrow ④$$

$$\rho \epsilon_0 = \bar{E} \cdot d\bar{s} \rightarrow ⑤$$

But volume of the sphere

$$V = \frac{4}{3} \pi r^3$$

$$l = \frac{q}{V}$$

$$\therefore l = \frac{q}{4 \pi r^3} \rightarrow ⑥$$

Electric field intensity due to uniformly charged sphere:

consider a sphere of 'R' with centre at 'O'. Let a charge +q is distributed throughout the volume. Then the volume charge density  $\rho$  is given by



Gravitational  
surface

Case (i) Electric field at a point outside the charged sphere

Let 'P' be an external point at a distance 'x' from the centre of the sphere.

⇒ To calculate intensity of the electric field at a point P, Imagine a Gaussian surface (sphere) around the point P, as shown above fig.

→ The electric field 'E' at every point on the Gaussian surface by same magnitude and is directed along the outward drawn normal to the surface.

⇒ The electric flux through an elemental area ds around the point P on the Gaussian surface is given by  $d\phi_E = \bar{E} \cdot \bar{ds} = \bar{E} \cdot ds \cos 0^\circ$

$$\therefore (But \bar{E} \parallel \bar{ds}, 0^\circ = 0^\circ \cos 0^\circ)$$

∴  $d\phi_E = \bar{E} \cdot ds \rightarrow (2)$

∴ The total electric flux throughout the Gaussian surface is given by  $\phi_E = \oint \bar{E} \cdot d\bar{s}$

$$\text{From Eq (2)} \quad \phi_E = \oint \bar{E} \cdot d\bar{s}$$

$$= \bar{E} \oint ds$$

$$\phi_E = \bar{E} \times 4\pi r^2 \rightarrow (3)$$

$$\text{Acc to Gauss law, } \phi_E = \frac{q}{\epsilon_0} \rightarrow (4)$$

$$\bar{E} \times 4\pi r^2 = \frac{q}{\epsilon_0}$$

Case (ii) Electric field at a point on the surface of the charge sphere.

→ In this case the point P lies on the surface of the sphere. Hence  $x = R$

$$\therefore \text{From Eq (5)} \quad x = R$$

$$\bar{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{R^2}$$

Case (iii) Electric field E at a point inside the spherical charge sphere

Consider a point P is located inside the sphere S at a distance of 'x' from its centre O as shown in above fig.

→ To calculate intensity of the electric field E, at a point P.

Imagine Gaussian surface within the spherical charge sphere passing through P.

$\Rightarrow$  The electric flux through an element area  $d\vec{s}$  around the point P on the Gaussian surface is given by  $d\phi_E = \vec{E} \cdot d\vec{s} = \vec{E} \cdot d\vec{s} \cos \theta$

C. But  $\vec{E} \parallel d\vec{s}$   $\cos \theta = 1$

$$\therefore d\phi_E = \vec{E} \cdot d\vec{s} \rightarrow (7)$$

$$\phi_E = \oint_S d\phi_E$$

$$\phi_E = \oint_S \vec{E} \cdot d\vec{s}$$

$$\phi_E = \vec{E} \times 4\pi r^2 \rightarrow (8)$$

But in this case, the charge  $q'$  enclosed by the Gaussian surface is then  $q' = \frac{4}{3}\pi r^3 \rho \rightarrow (9)$

$$\text{From eq } (1) q' = \frac{4}{3}\pi r^3 \rho \rightarrow (10)$$

$$A/C \text{ Gaus law}$$

$$R^3$$

$$\text{charge density } q' = \frac{q'}{V} \rightarrow (11) \text{ (scalar)}$$

$$\frac{q'}{V} = \frac{q'}{\frac{4}{3}\pi r^3} \rightarrow (12)$$

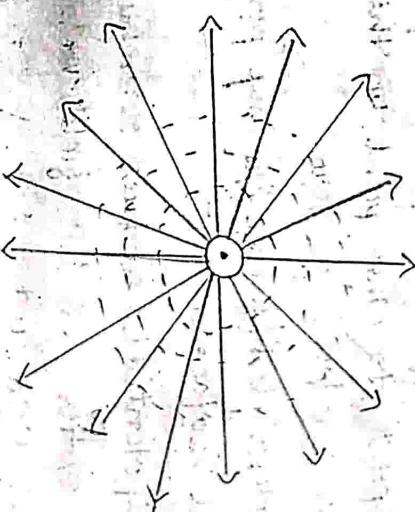
$$\frac{1}{E} = \frac{1}{4\pi\epsilon_0} \frac{q'}{r^2} \rightarrow (12)$$

$$\text{Sub eq (10) in eq (12), we have}$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q'r^3}{R^3 r^2}$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q'r^3}{R^3 r^2} \rightarrow (13)$$

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Consider the electric field around

the + $q'$ . Let us consider a plane that joins all the points having the same potential this plane is called equipotential surfaces.

Definition:

The locus of all points in the electric field which have same electrical potential is called equipotential surfaces.

Properties:

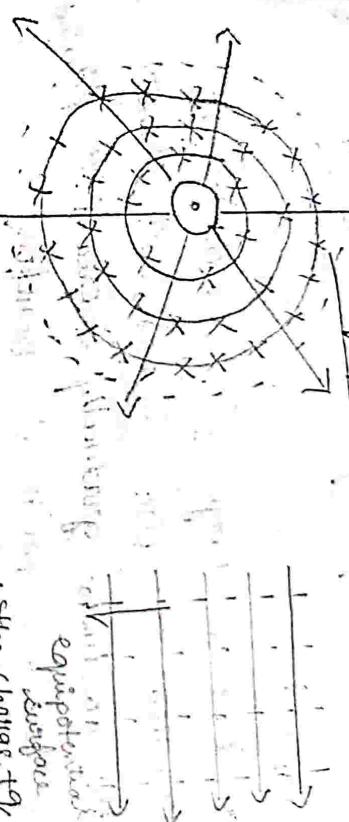
- \* If the charge is in point size, then the equipotential surfaces are concentric spheres.
- \* In uniform electric field, the equipotential surfaces are parallel.
- \* Equipotential surfaces are perpendicular to the electric field vector.
- \* The workdone for moving a unit point charge from one point to other point on the same equipotential surfaces is zero.
- \* The potential difference b/w any points on equipotential surfaces is zero.
- \* This equipotential surfaces resembles the wave fronts in optics, electric field vectors resembles the light waves.

### Electric dipole

- \* The arrangement of two equal & opposite charges at a fixed distance is called electric dipole.
- \* The product of magnitude of their charges & distance b/w the charges is called the electric dipole moment [P]

$$P = qd \times r \quad (P = 2dq)$$

### Equipotential Surfaces



Consider the electric field around the charge  $+q$ . Let us consider a plain that joining all the points having the same potential this plain is called equipotential surface.

Def: The locus of all points in the electric field which have same electric potential is called equipotential surface.

Properties:

- \* If the charge is in point size then the equipotential surfaces are concentric spheres.
- \* If uniform electric field the equipotential surfaces are parallel.
- \* Equipotential surfaces are perpendicular to the electric field vector.
- \* These equipotential surfaces resembles the wave fronts in optics, electric field vector resembles the light waves.

## IS/13 2. Capacity And Resistances

### Capacitance:

- \* If given charge ' $q$ ' a conductor with potential ( $v$ ) also increases. As change on the conductor gradually increases, the potential of the conductor is also therefore.

: If any instant charge given to the conductor, ' $q$ ' is given of the conductor

$$q \propto v$$

$\alpha = Cv$   
Here ' $C$ ' is proportionality constant, which is also known as capacity of the conductor.

$$C = \frac{q}{v}$$

$$\text{Units} = \frac{\text{coulomb}}{\text{volt}}$$

$$\text{Farad} = \frac{\text{coulomb}}{\text{volt}}$$

### Capacitor

- \* It is defined as the charge required to set the potential on the conductor by a unit amount less than capacity of the conductor.

$$C = \frac{q}{v}$$

$$\text{Units} = \frac{\text{coulomb}}{\text{volt}} = \text{Farad}$$

\* Symbol of capacitor, written as represented by either of their symbols.



Capacitor definition (QF):

- \* A device which can store

## Principle of a capacitor

To understand the principle of a capacitor consider an isolated conductor 'A' is charged to a positive potential 'v' as shown in fig.

$\Rightarrow$  known consider that another insulated metal plate 'B' is brought near plate 'A' due to induction, -ve charge will be induced on the inner surface of the plate 'B'. See equal positive charge on the outer surface as shown fig.

$\Rightarrow$  The negative charge lesser the potential of plate 'A' while the positive charge of the 'B' lens two increase the potential of 'A'.

$\Rightarrow$  The slide decreases in potential of 'A' because charge  $q$  remains constant. ( $C = \frac{q}{V}$ )

$\Rightarrow$  In many applications one of the plate is grounded. as shown fig. The positive charge of plate 'B' will immediately flow to the earth, the negative charge of 'B' will stay on it.

The potential of 'A' is considerably reduced due to negative charge on the

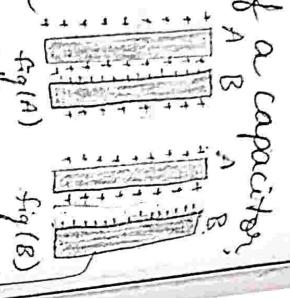


plate 'P'. As a result increases in capacity. So the capacitor is greatly. This is the principle of capacitor.

Conclusion: If a conductor is placed near charged conductor, the potential of charged conductor decreases  $\Rightarrow$  hence it can store more charge. The arrangement of two conductors that are placed close to each other  $\Rightarrow$  is called capacitor. The

amount of charge is called capacity of the capacitor plates.

Definition: A device which can store considerable amount of charge is called capacitor (or)

$\Rightarrow$  The capacity of the capacitor is depends upon the following factors such as (i) Area of the plates (ii) distance b/w plates (iii) permittivity of medium b/w the two plates.

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Capacity of parallel plate capacitor (without medium):

As shown in fig., a parallel plate capacitor consist of two parallel conducting plates area 'A' and separated by a distance 'd'.

When these two plates are connected to the battery, let a charge  $+q$  appear on the plate  $Q$ , on the other plate: If  $d$  denotes the distance between the plates, and  $E$  the electric field strength, then the electric force per unit area is  $E/d$ .

Two parallel equally spaced lines we take the mid

Here we take the medium as vaccine dry

are below the plates. In order to calculate capacitance, we find

calculate the value of electric field  $E$  below the two plates if uniformed i.e. the lines of force will all same.

$\Rightarrow$  Here we take the medium as Vacuum, i.e.

Wash the plates.

In order to calculate capacitance, we first calculate the value of electric field below the plates by using Gauss law. For this purpose we consider a Gaussian surface  $PQR$  in the form of closed cylinder of height  $h$  on the above plate as shown.

∴ The total hair shafting was shown by

Gaussian surface is given by  $\mu = \text{constant}$ . The entire

$$\phi = \frac{1}{\sqrt{2}}(E_x + iE_y)$$

$$\phi_E = \oint_S E \cdot dS \quad \text{and} \quad \phi_B = \oint_S B \cdot dS$$

$$\phi_E = \frac{\alpha}{\lambda} \rightarrow \textcircled{2}$$

$$E = \frac{V}{AE_0}$$

The potential difference b/w 2 plates can be written as

Sub (3) in eq (4) we get

$$V = \frac{qV_d}{A\bar{E}_D} \rightarrow \textcircled{5}$$

The capacities of parallel plate capacitors is given by

$$\textcircled{2} \rightarrow \sqrt{b} = C$$

Sub eq ③ in ④

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AE

$$C = \frac{A\epsilon_0}{d}$$

$\therefore$  The above  $\Rightarrow$  in source the capacitance of parallel plate capacitor without medium b/w the plates.

### Imp. points

- The capacity is directly proportional to the area of the plate i.e.  $C \propto A$ .
- The capacity is inversely proportional to the distance 'd' b/w the plates i.e.  $C \propto \frac{1}{d}$ .
- The capacity is independent of nature of metal thickness of plate.

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Capacitance of a parallel plate capacitor with Dielectric slab:-

From the fig a capacitor is filled with a dielectric material as shown in fig. 'A' & 'B' be the plates of the capacitor with area of 'A' & separation 'd'. The upper plate 'A' is given a charge 'q' while the lower plate 'B' is given a charge 'q' now the electric slab with thickness 't', dielectric constant 'k' is introduced b/w the plates.

The electric flux throughout the Gaussian surface:

$$dE = \int_S \vec{E}_0 \cdot d\vec{s} \quad (\because \int_S d\vec{s} = A)$$

$$\Phi_E = E_0 A \rightarrow \textcircled{1}$$

$$\Phi_E = \frac{k}{\epsilon_0} A \rightarrow \textcircled{2}$$

$$E_0 A = \frac{q}{\epsilon_0} \quad \text{From } \textcircled{1} \text{ & } \textcircled{2} \text{ we get}$$

$$\frac{1}{\epsilon_0} = \frac{q}{A\epsilon_0} \rightarrow \textcircled{3}$$

Similarly the electric flux Gaussian surface 'PQRS' is given by

$$\Phi_E = \int_S \vec{E} \cdot d\vec{s}$$

$$\Phi_E = k \int_S \vec{E}_0 \cdot d\vec{s}$$

$$A/C \rightarrow \text{Gauss law}$$

$$(0 \rightarrow) \Phi_E = \frac{q}{\epsilon_0} \rightarrow \textcircled{3}$$

In order to consider the electric field 'E' and 'B' is air & the electric

respectively we consider Gaussian surfaces PQR S 'P', 'Q', 'R', 'S' as shown in fig.

From Eqn ④ & ⑤ given by

$$kE_B = \frac{q}{E_0}$$

$$E = \frac{q}{kAE_0} \rightarrow ⑥$$

The potential difference b/w the two plates is the workdone in carrying a unit charge from one plate to another plate.

$$\text{Thus, } V = E_0 (d-t) + E_B t \rightarrow ⑦$$

Substitute ⑥ in ⑦, we have

$$V = \frac{q}{AE_0} (dt) + \frac{q}{kAE_0} + \frac{q}{AE_0} (dt + \frac{t}{k})$$

$$= \frac{q}{AE_0} (d+dt(1-\frac{1}{k}))$$

$$= \frac{q}{AE_0} [d+dt(\frac{k-1}{k})]$$

$$V = \frac{q}{AE_0} \left[ kd - t \left( \frac{k-1}{k} \right) \right] \rightarrow ⑧$$

: The capacitance of capacitor  $C = \frac{q}{V} \rightarrow ⑨$

Sub of ⑧ in ⑨, we get

$$C = \frac{q}{V}$$

$$A E_B k \left( kd - t \left( \frac{k-1}{k} \right) \right)$$

$$C = \frac{A E_B k}{kd - t(k-1)} \rightarrow ⑩$$

When dielectric is completely filled b/w the plates then  $t = d$ .

In this case capacitance given by

$$C = \frac{t}{A E_B k}$$

$$C = \frac{d}{kd - k(d-k)} = \frac{d}{kd - k^2} = \frac{d}{k(d-k)}$$

$$C = \frac{d}{A E_B k}$$

### Electrical energy stored in a capacitor

Consider a capacitor of capacitance  $C$  carrying a charge  $q$  at any instant.

Let the potential difference b/w

the plates be the ' $V$ '. Then

$$C = \frac{q}{V} \Rightarrow V = \frac{q}{C} \rightarrow ①$$



In an addition charge  $dQ$  is to be given to the capacitor then some work ( $dW$ ) must be done against the potential difference. So the workdone increasing the charge  $dQ$  is given by

$$dW = V dq \rightarrow ②$$

$$dW = \frac{q}{C} dq \rightarrow ③$$

The total work to charge a capacitor ( $CV$ ) is given by  $W = \int_0^V dW$ .

$$= \int_C \left(\frac{q}{C}\right) dq$$

$$= W = \frac{1}{C} \int_0^V q^2 dq$$

$$W = \frac{1}{C} \left(\frac{q^2}{2}\right)_0^V$$

$$W = \frac{q^2}{2C}$$

The energy of a charge capacitor is the amount of work done in changing it.

$\therefore$  The energy stored by a capacitor

$$V = \frac{q^2}{C}$$

(or)

$$V = \frac{1}{2} \frac{q^2}{C}$$

From eq(1)

$$C = \frac{q}{V} \rightarrow \boxed{q = CV}$$

### Electric dipole moment

The arrangement of two equal & opposite charges at a fixed distance cause by electric dipole.

$\Rightarrow$  The product of the magnitude of either charge & the distance b/w the charges is caused electric dipole moment.

$$\text{But } C = \frac{q}{V}$$

$$\text{From eq(4)} \quad V = \frac{1}{2} \frac{q^2}{C} \quad \therefore V = \frac{1}{2} \cdot \frac{q^2}{\left(\frac{q}{V}\right)} =$$

for parallel plate capacitor of area 'A' & plate separation 'd' then the capacitance is given by  $C = \frac{\epsilon_0 A}{d}$

$$V = Ed$$

From eq(5)

$$V = \frac{1}{2} \left(\frac{q^2}{C}\right) \quad (\text{eq})$$

$$V = \frac{1}{2} \left(\frac{q^2}{\frac{q}{V}}\right) = \frac{1}{2} V^2 \quad \therefore V^2 = \frac{q^2}{2} \cdot \frac{1}{\epsilon_0 E^2 d}$$

$$\Rightarrow V^2 = \frac{1}{2} \epsilon_0 E^2 d$$

$\therefore$  The energy for unit value, the energy stored in a capacitor

$$\boxed{U = \frac{1}{2} \epsilon_0 E^2 d}$$

From the fig., the charge of dipole  $P$  are  $-q$  &  $+q$ . Coulomb's law distance  $2L$  between them is  $(2L)$  meter. Then the electric dipole moment  $'P'$  is given by  $P = qL$ ,  $P = 2q(L)P$ .

$\rightarrow$  The unit of electric dipole moment is  $Cm$ . It is a vector quantity.

$\rightarrow$  The electric dipole moment is a vector quantity. Its direction is along the axis of dipole pointing from the negative charge to positive charge.

19/5/23  
Dielectrics

The substance which do not contain or have electrons are the number of such electrons to low constitute the electric current is caused dielectrics.

Ex: Mica, glass, plastics, papers etc.

Uses:

1. To increase the capacitance of the capacitor, the electric materials are placed in between the plates.
2. For insulation on electric conductors dielectrics are used in the form of layers around the conductors.
3. The electrons are mechanical support to H.T wires.

u. To increase the dielectric suit in the electric field, dielectric materials are used.

Types view of dielectrics or Atomic view of dielectrics

The atoms or molecules of positive charges as well as negative charges has an equal magnitude. The positive charges have one centre of gravity & negative charges of one centre of gravity.

$\Rightarrow$  Based on the atomic viewed of the electric dielectrics (i) Non-polar dielectrics (ii) Polar dielectrics.

i) Non Polar Dielectrics: If the centre of gravity of positive charges coincides with the centre of the gravity of negative charge molecules of non-polar dielectrics  $\Rightarrow$  The non polar molecules have symmetrical structure & '0' dipole moment.

Ex:  $H_2$ ,  $N_2$ ,  $CO_2$ ,  $O_2$  etc.

$CO_2$

$$\textcircled{C} = \textcircled{C} = \textcircled{C}$$

$$\overline{P} \rightarrow \leftarrow P_2$$

$$\boxed{P_2 \cdot \overline{P}_1 + \overline{P}_2 = 0}$$

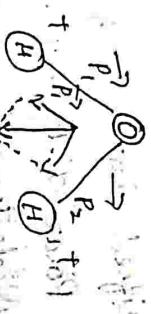
ii) non-polar molecules.

(iii) Polar dielectrics: If the centre of the gravity does not coincide with the centre of positive charges. Does not coincide with the centre of gravity of negative charges. Have molecular or polar dielectric.

molecular or polar dielectrics.  
→ The polar molecules have unsymmetrical structures.  
Ex has permanent dipole moment.

$\text{H}_2\text{O}$ ,  $\text{HCl}$ ,  $\text{CO}$ ,  $\text{NO}_2$  etc.

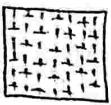
H<sub>2</sub>D



$$\bar{P} = \frac{P_1}{P_1 + P_2}$$

## Effect of electric field on directions

## Non-polar dielectrics



2

In general non-polar dielectric molecules randomly oriented such that the centre of gravity of positive & negative charge coincide with each other as shown in fig (a).  
 $\Rightarrow$  When this material is placed b/w the electrodes of an electric field  $E_0$ , the molecule

re-orientated such that the centre of gravity of positive charges are <sup>some</sup> found towards the  $-ve$  of  $\text{Si}$  vice versa when each molecule act as a charge electric dipole as shown in fig (b).  
 The separation of the centre of gravity of the  $\Rightarrow$  the charges by applying electric field is  
 $\Rightarrow$   $-ve$  polarization as shown fig (c).

From fig. c, the induced surface charge is such a way that the induced electric field  $E'$  is opposite to the original electric field  $E_0$ .

$\therefore$  The resultant electric field is given by  
 $E = E_0 - E_1$

So if the non-polar dielectrics as electric field, induced charge appears resultant electric field decreases

## Polar Dielectrics

Polar dielectrics have  
we know that the polar dielectrics have with  
permanent dipole moment ( $C_p$ ) below that with  
their random orientation as shown below fig

475

their random orientation.



fig 6a

If the material or placed on an electric field, the positive centres of dipole are pulled towards electric field & negative charges are pulled towards the positive.

The dipoles are oriented.

So the equipment changes with an increase of dipole moment. This increase dipole moment is called induced dipole moment ( $P_i$ ).

The resultant dipole moment becomes

$$P = P_0 + P_i$$

So if the polar dielectric is placed in an electric field induced dipole moment of arranged and resultant dipole momentum increases.

### Dielectric polarization

The process of producing

$$P = \frac{q_i}{4}$$

electric dipoles which are oriented along the fields called polarization in the dielectric.

The electric dipole moment per unit volume is called as dielectric polarization.

i) The electric polarization

$$\boxed{P = \frac{q_i}{A}}$$

20/5/23

### Dielectric Constant ( $\kappa$ )

\* Def 1: The ratio of capacitance of a condenser with dielectric to the capacitance of same capacitor without dielectric is known as dielectric constant.

$$\text{Def 2: } \kappa = \frac{C}{C_0} \rightarrow \text{①}$$

\* Def 3: The ratio of electrostatic force b/w the two charges in free space to the electrostatic force between two charges in dielectric medium.

$$\therefore \kappa = \frac{F}{F_0} \rightarrow \text{②}$$

\* Def 4: The ratio of potential difference b/w the two points in free space to the potential difference b/w same two points in dielectric media.

$$\therefore \kappa = \frac{V_0}{V} \rightarrow \text{③}$$

Def: The ratio of electric field at a point in free space to the electric field intensity at the same point in dielectric medium.

$$\therefore k = \frac{E_0}{E} \rightarrow \textcircled{1}$$

$$\boxed{\text{Dielectric constant } (k) = \frac{C}{C_0} = \frac{E}{E_0} = \frac{P_0}{P} = \frac{E_0}{E} = \frac{\epsilon}{\epsilon_0}}$$

### Electric Susceptibility

- \* When a dielectric is placed in an electric field it is polarized. The polarization ( $P$ ) is proportional to the electric field ( $E$ ).

$$P = \kappa E \quad \text{where } \kappa = \text{electric susceptibility}$$

$$\boxed{\kappa = \frac{P}{E}}$$

Def: The ratio of polarization to the electric intensity in dielectric is known as electric susceptibility.

### Electric displacement ( $D$ )

- \* The electric displacement at a point is defined as the product of electric field strength at a point & permittivity of the medium is known as electric displacement. It is also w/ displacement.
- \* In magnitude ' $D$ ' is equal to the surface charge density of free charges.

$$\boxed{D = \frac{q}{n} = \sigma}$$

where  $\sigma$  = surface charge density.

- \*  $D$ : Relation b/w  $D$ ,  $E$  and  $P$ :

$$\text{The electric displacement}$$

- \* ( $E$ ) electric field intensity:
- \* It is defined as the no. of lines of forces normal to the surface of unit area called electric field intensity.

$$\boxed{E = \frac{Q}{AE}}$$

$$\text{Relation b/w } D, E \text{ and } P:$$

- \* When a dielectric material of a dielectric constant  $(k)$  is kept b/w the 2 plates of charge capacitor an induced charge ( $q_i$ ) appears on the surface of the dielectric material ( $-q_i$ ) is on the plate  $\Sigma_1 (+q_i)$  charge on negative of the capacitor due to this the resultant charge reduces to  $(Q - q_i)$  which reduce the electric field as,  $E = E_0$

- \* Due to this the resultant charge reduces to  $(Q - q_i)$  which reduce the electric field as,  $E = E_0$

$$\text{Relation b/w } E_0 \text{ and } E: \boxed{E_0 = \frac{Q}{AE}} \rightarrow \textcircled{2}$$

$$E = \frac{Q}{AE}$$

$$\text{Relation b/w } E \text{ and } E_0: \boxed{E = \frac{Q}{AE} = \frac{Q}{A} \times \frac{1}{E_0} \rightarrow \textcircled{3} (E = E_0 \times \frac{1}{k})}$$

$$E_i = \frac{q_i}{AE_0}$$

$$\text{Sub. Eq. \textcircled{2}, \textcircled{3}, \textcircled{4} in Eq. \textcircled{1} we have } \frac{Q}{n} = E_0 \left[ \frac{Q}{kAE_0} + \frac{q_i}{AE_0} \right]$$

$$\therefore E = \frac{Q}{n} = \frac{Q}{AE_0} - \frac{q_i}{AE_0} \quad \because \text{From the above definition it can be written as}$$

$$\frac{Q}{AE_0} = \frac{Q}{kAE_0} + \frac{q_i}{AE_0}$$

$$\therefore \boxed{D = E_0 \vec{E} + P}$$

20/05/23

## II. Current Electricity

Electric current: "flow of charge through any cross

⇒ The rate of flow of charge is called "current".  
section of conductor is called "current".

⇒ If 'q' is amount of charge flows through  
any cross section of conductor in time  $t$ , then the current 'I' (A) is given by

$$I = \frac{q}{t}$$

In S.I. units: Coulomb = Ampere

Sec

→ By using ammeter we can measure the electric current.

Electric current density (J)

→ The electric current for unit area of cross section, called electric current density. Denoted by 'J'.

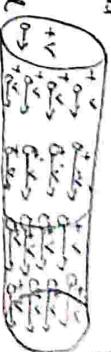
→ The current density is a vector whose magnitude is the

$$J = \frac{I}{A} \quad (or) \quad J = nevd \quad where, n = no. of e^-$$

e = charge of e^-  
 $v_d$  = Drift velocity  
The electric current density is measured in ampere per square meter.

Kinetic velocity ( $v_k$ ):

The drift velocity ( $v_d$ ) is defined as the avg. velocity attains in material due to an electric field.



As shown in fig, the cross section area of the conductor is 'A'. As shown in fig, the cross section area of the conductor is 'A'. Let there are  $n^2 e^-$  per unit volume. Then drift velocity  $v_d$  is given by

$$v_d = \frac{I}{ne} ; \text{ where } I \text{ is electric current density, } n = no. \text{ of } e^-$$

$$e = \text{charge of } e^-$$

→ The above eqn shows the relation between drift velocity and current density.

30/5/23

Electrical resistance ( $R$ ): Resistance is a measure of the opposition to current flow in an electrical circuit, it is denoted by ' $R$ '.

Resistance is measured in 'Ohms'.

- \* Resistance is symbolically by the Greek letter ' $\Omega$ '.
- \* It is [Ohm].

### Resistivity

Let us consider a specimen of a resistance having length ' $l$ ' & area of the cross section ' $A$ '. Then

1. The resistance of resistor is directly proportional to the length of the specimen i.e.  $R \propto l \rightarrow ①$
2. The resistance of resistor is inversely proportional to the area of the cross section of the specimen

$$\therefore R \propto \frac{1}{A} \rightarrow ②$$

$$\text{From eqn } ① \& ② \text{ we get}$$

$$R \propto \frac{l}{A} \Rightarrow \boxed{R = \frac{\rho l}{A}}$$

where  $\rho$  = proportionality constant which

is also known as resistivity. It depends on the material of the conductor but not on its dimensions.

$$\therefore \boxed{\rho = \frac{RA}{l}}$$

Units: Ohm-meter ( $\Omega \cdot m$ )

### Electrical conductivity (σ)

The electrical conductivity of a conductor is defined as the reciprocal of the resistivity material. It is denoted by ' $\sigma$ '

$$\sigma = \frac{1}{\rho}$$

S.I units of the conductivity is mho/meter

$$(\Omega^{-1} m^{-1})$$

### Ohm's law

Ohm's law states that the relationship b/w current & potential difference i.e. The electric current that flows through conductor is directly proportional to the voltage applied to it.

$$\therefore I \propto V \rightarrow ①$$

30/5/23

Electrical resistance ( $R$ ):- Resistance is a measure of the opposition to current flow in an electrical circuit, it is denoted by ' $R$ '.

- \* Resistance is measured in "Ohms".
- \* It is symbolically by the Greek letter ' $\Omega$ ' [ohm].

Unit: Ohm.meter  
( $\Omega \cdot m$ )

### Electrical conductivity ( $\sigma$ )

Resistivity: Let us consider a specimen of a resistance having length ' $l$ ' & area of the cross section ' $A$ '. Then

1. The resistance of resistor is directly proportional to the length of the specimen.

i.e.  $R \propto l \rightarrow ①$   
S.I units of the conductivity is mho/meter or  $(\Omega^{-1} m^{-1})$ .

$$\sigma = \frac{1}{Rl}$$

2. The resistance of resistor is inversely proportional to the area of the cross section of the specimen

$$i.e. R \propto \frac{1}{A} \rightarrow ②$$

From eqn ① & ②

$$R \propto \frac{l}{A} \Rightarrow R = \frac{\rho l}{A}$$

where  $\rho$  = proportionality constant. Which

is also known as resistivity.

It depends on the material of the conductor but not on its dimensions.

$$\rho = \frac{RA}{l}$$

Ohm's law states that the relationship b/w current & potential difference i.e. The electric current that flows through conductor is directly proportional to the voltage

Mathematically:

where 'R' resistance  
V = Voltage, I = current

$$V = RI$$

$$(low)$$

$$V = IR$$

$$I = \frac{V}{R}$$

$$(or)$$

$$R = \frac{V}{I}$$

$$I = \frac{V}{R}$$

$$R = \frac{V}{I}$$

### Limitations

\* Ohm's law cannot be applied to unilateral networks. Because unilateral networks allow currents in one direction.

The current ~~exists~~ in diodes, the current which flow only in one direction.

\* Ohm's law is not applicable in the case of unilateral networks.

\* Ohm's law is not proportional to voltage

current is not proportional to voltage

applied to non-metals

non-metallic conductors.

\* Ohm's law will not work in the case of

calculation using Ohm's law can be different in the case of complicated circuits.

3/15/23 ~~first~~ Kirchhoff's law  
Kirchhoff's law / Junction law: The algebraic sum of all the electric currents meeting at a point is equal to zero.  $\sum i = 0$ . The sum of the electric currents entering at the junction is equal to the currents leaving at the junction.

$$\sum i_{\text{entering}} = \sum i_{\text{leaving}}$$

### Explanation:

For our convenience, the current which enters the junction is taken as positive and the current which leaves the junction is taken as negative.

From the fig,

$$i_1 + i_2 + i_3 + i_4 + i_5 = 0$$

$$i_1 + i_2 + i_4 = i_3 + i_5$$

### Kirchhoff's second law or loop law:

The algebraic sum of potentials in a closed loop is equal to zero.

$$\sum V = 0$$

(or)

In a closed loop, the algebraic sum of EMFs is equal to the algebraic sum of potentials i.e.  $\sum \text{EMF} = \sum V$

If the loop travels from +ve to -ve terminal of the cell then EMF taken as -ve and vice versa.

### Sign conventions:

If the current passes along the loop then the potential difference across the resistor is +ve and vice versa.

From the fig, loop ABCDA

$$-E_1 + i_1 R_1 + i_1 R_2 + i_2 R_3 - E_2 i R_4 = 0$$

$$E_1 + E_2 = i_1 R_1 + i_1 R_2 + i_2 R_3 + i R_4$$

### Applications:

KCL is used to find the values of unknown voltage and unknown resistance in DC currents.

By applying this law, we can also find the unknown resistance in the circuits.

3. What stone bridge is an important application of KCL.

016123

### Wheat Stone Bridge Condition

Let us consider 4 resistors,

$P, Q, R, S$  are connected in

cyclic way and a

battery is connected

b/w the terminals A and C. Further a



galvanometer is connected b/w B and C terminals is called wheat stone bridge.

### A/C to KCL at junction B

$$i_1 = i_3 + i_4 \rightarrow \textcircled{1}$$

$$i_2 + i_3 = i_4 \rightarrow \textcircled{2}$$

### A/C to KCL

$$\text{Loop ABDA, } i_3 g = i_2 R \rightarrow \textcircled{3}$$

$$\text{for loop BCDB, } i_3 g = i_4 g + i_4 s \rightarrow \textcircled{4}$$

When points B and D are at same potentials then there is no current passing through the galvanometer! Hence the bridge is said to be balanced.

A/C to balancing condition, ( $i_g = 0$ )

$$\text{From eq } \textcircled{1}, i_1 = i_3 \rightarrow \textcircled{5}$$

$$\text{From eq } \textcircled{2}, i_2 = i_4 \rightarrow \textcircled{6}$$

$$\text{If from eq } \textcircled{3}, i_1 P = i_2 R \rightarrow \textcircled{7}$$

$$\text{or } " \textcircled{4}, i_3 Q = i_4 S \rightarrow \textcircled{8}$$

Eq \textcircled{7} is dividing by eq \textcircled{8}, we have

$$\frac{i_1 P}{i_3 Q} = \frac{i_2 R}{i_4 S}$$

From eq (4)

$$\frac{I_1 P}{I_2 Q} = \frac{\mu_0 R}{\mu_0 S}$$

$$\therefore \frac{P}{Q} = \frac{R}{S}$$

∴ This is the balancing condition of the Wheatstone Bridge.

Sensitivity of Wheatstone Bridge

1. Sensitivity is defined as deflection for unit

current.

2. When the bridge is unbalanced causing a deflection through the galvanometer pointers.

3. The amount of deflection is a function of the sensitivity of the galvanometer.

i. The more sensitive the galvanometer will deflect more with the same amount of current.

$$S = \frac{\text{Deflection (P)}}{\text{Current (I)}}$$

## 016/23 4. Electromagnetism

Magnetic flux: The total no. of magnetic lines passing through a surface is called magnetic flux. It is denoted  $\phi_B$ . It is measured in Weber (Wb).

$$\therefore \phi_B = B \times A = \text{Magnetic flux}$$

where  $B =$  magnetic field induction  
 $A =$  Area of the surface.

Magnetic field induction: The magnetic flux per unit area is known as magnetic field induction.

The no. of magnetic field lines passing through unit area is known as magnetic field induction.

It is denoted by 'B'.

It is measured in Tesla.

$$\therefore \text{Magnetic field induction } B = \frac{\phi_B}{A}$$

$$\text{Units: Weber} = \text{Tesla} / \text{m}^2$$

Ques

→ This law gives the magnetic field induction of the angle  $\theta$  below length of the strip of the line joining the element to the point i.e.  $dB \propto \sin\theta$

Consider an irregular conductor carrying current as shown above fig.

→ Now in order to calculate magnetic conductor field induction, conductor AB is divided into small current elements of length  $dl$ .

→ Let 'B' be a point at which magnetic field is to be calculated, at a distance of 'r' from the current element and  $\theta$  be the angle between  $dl$  and 'r'.

Let 'dB' be the magnetic field induction at a point 'B' due to current element  $dl$ ; then

- ①  $dB \propto i$  The  $dB$  is directly proportional to the current 'i' flowing through the conductor i.e.
- ② The  $dB$  is directly proportional to the length 'dl' of the current i.e.  $dB \propto dl$



The  $dB$  is directly proportional to the angle  $\theta$  below length of the strip of the line joining the element to the point i.e.  $dB \propto \sin\theta$

$$dB \propto \frac{1}{r^2}$$

$$\text{From the above eqn we get} \\ dB \propto \frac{1}{r^2} \sin\theta$$

$$dB = \frac{\mu_0}{4\pi} i dl \sin\theta$$

where  $\frac{\mu_0}{4\pi}$  is proportionality constant and

$\mu_0$  is permittivity of free space

In vector form above eqn is written as

$$dB = \frac{\mu_0}{4\pi} i dl \sin\theta$$

No new values proportionality constant  $\propto \mu_0$   
 Where  $\mu_0$  is permeability of free space  
 $\mu_0 = 4\pi \times 10^{-7}$  Weber Amp. Metre

In vector form above eqn is written as

d.

Application of Biot Savart law:

Magnetic induction due to a circular coil

Deep carrying current

consider a circular coil of

radius small a carrying current

Let 'P' be a point where

magnetic induction be measured

It is on the axis of circular coil

at a distance 'x' from the

center of coil. Consider a small element

a, b od length del in the coil & it is at a

distance 'r' from the point 'P'. The angle b/w

it is and 'P' is  $\phi$ . The angle b/w 'r' &

axis of the coil is ' $\theta$ '

then magnetic induction DB due to the

element 'dl' at a point 'P' is given by

Biot Savart law.

Special Cases:

(a) At

P is at the centre of the coil i.e.  $x = 0$

$$\text{So from Eq (1)} \quad B = \frac{\mu_0 N a^2}{2(\alpha)^{3/2}}$$

$$dB = \frac{\mu_0}{4\pi} \frac{id \sin \theta}{x^2} \quad (\text{but } \theta = 90^\circ)$$

$$dB = \frac{\mu_0}{4\pi} \frac{id \sin \theta}{x^2} \quad (\text{but } \theta = 90^\circ)$$

$$B = \int dB \sin \theta$$

$$B = \int \frac{\mu_0}{4\pi} \frac{id \sin \theta}{x^2} \sin \theta$$

$$\text{But } \sin \theta = \frac{a}{x}$$

$$B = \int \frac{\mu_0}{4\pi} \frac{id \sin \theta}{x^2} \left( \frac{a}{x} \right)$$

$$B = \frac{\mu_0 i a}{4\pi x^2} \int da \rightarrow \text{Eq (2)}$$

$$\text{Sub Eq (3) in (2)} \quad B = \frac{\mu_0 i a}{4\pi x^2} \times 2\pi a$$

$$B = \frac{\mu_0 i a^2}{2(x^2 + a^2)}$$

$$\text{For a no. of circles } B = \frac{\mu_0 N a^2}{2(x^2 + a^2)}$$

$$B = \frac{\mu_0 Ni}{2a}$$

Case 2 :  $\frac{q^2}{n^2}$  is greater than very greater than  $\frac{B^2}{2a^2}$   
 Case 2 :  $\frac{q^2}{n^2}$  is very low compared to  $\frac{B^2}{2a^2}$  value  
 $q^2$  value is zero  
 $\therefore \alpha^2 = 0$

$$B = \frac{\mu_0 Ni a^2}{2(x^2)^{3/2}}$$

$$B = \frac{\mu_0 Ni a^2}{2x^2}$$

Force on a current carrying conductor

Consider a conductor of angle  $\theta$ , it is placed  $\perp$  to the magnetic field induction 'B'.

Let 'i' be the current flowing through the conductor in time 't', it is placed  $\perp$  to the magnetic field induction 'B'. W.K.T the force  $F$  acting on a charge 'q' in motion with velocity 'v' is given by

$$F = q(v \times B)$$

$$F = qil(t) \sin\theta \quad (\because v = l/t)$$

$$F = \frac{q}{t} il^2 \sin\theta \quad (i = a/l)$$

$$F = ilB \sin\theta \Rightarrow F = Bils \infty$$

The above eqn shows force on a current carrying conductor

09/06/23 11:00 AM  
Hall Effect

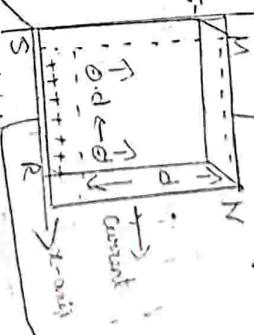
When a magnetic field is applied perpendicular to a current carrying conductor a voltage is developed across the specimen in a direction perpendicular to both current & magnetic field.

This phenomenon is known as Hall Effect. This voltage is so developed is called Hall voltage.

Consider a uniform thick metal strip placed with its length parallel to X-axis.

Let a current 'i' is passed through a conductor along X-axis & magnetic field 'B' is established along Y-axis. Due to a magnetic field a charge carriers experience a magnetic field a charge carriers experience a force (fm) perpendicular to X, Y plane ed by a force (fm) i.e along Z-axis.

If the charge carriers are electrons then they will experience a force ( $F_e$ ) in -ve direction of Z-axis due to this fact the back surface will be charged negatively and the front surface is



Hence they will accumulate on the back surface of the metallic strip (PQRS). Due to this fact the back surface will be charged negatively and the front surface is charged positively.

charged positively. Thus, a transverse potential difference is created. This EMF is known as Hall EMF.

Magnetic deflection force ( $F_m$ ) =  $q(Vd \times B) \rightarrow ①$   
Hall electric deflecting force is given by

$$F_e = E_H V \rightarrow ②$$

when an equilibrium state is reached, the magnetic deflection force of the charge carriers are balanced by the electric force due to electric field i.e.,

$$F_m = F_e \rightarrow ③$$

From ① & ③ we get

$$q(Vd \times B) = E_H V$$

$[E_H = V_d B] \rightarrow ④$  Velocity of the electron

$$\therefore V_d = \frac{J}{nq} \rightarrow ⑤$$

From ④ & ⑤ we get

$$E_H = \frac{J}{nq} B \rightarrow ⑥$$

$$\left[ \frac{E_H}{JB} = \frac{1}{nq} = R_H \right] \rightarrow ⑦ \text{ where } R_H =$$

$$R_H = \frac{E_H}{JB} = \frac{1}{nq}$$

### Applications:

- \* The sign of the charge carriers is determined.
- \* The charge carrier concentration can be determined.
- \* The mobility of the charge carrier can be measured directly.

$$B = \frac{E_H}{JR_H}$$

- \* It can be used to determine whether the given material, insulator or semi-conductor
- \* Electrical conductivity of material can be determined.

$$\therefore V_d = \frac{J}{nq} \rightarrow ⑤$$

### 13th Unit 11S. Electromagnetic induction

→ In 1831, Faraday discovered that "if

" whenever magnetic field lines are passed through a closed circuit, an induced current flows in the circuit i.e. change in magnetic flux, changing with time giving rise to current. The induced EMF giving rise to such current is called the induced electromotive force. This phenomenon is called electromagnetic induction.

### Faraday's Law of Electromagnetic Induction

Faraday first law: When the magnetic flux linked with a circuit is changed, an EMF is induced in the circuit.

Faraday's law: The magnitude of induced EMF is directly proportional to the negative rate of variation of magnetic flux linked with the circuit.

If  $\Phi_B$  be the magnetic flux linked with the circuit at any instant &  $E$  be the induced EMF, then

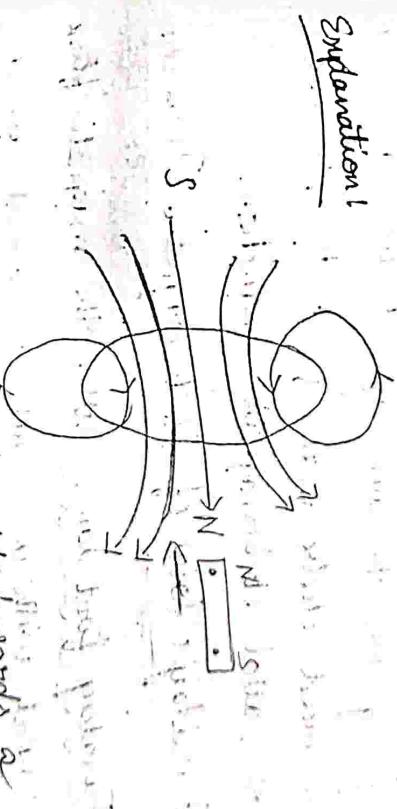
$$E = - \left( \frac{d\Phi_B}{dt} \right) \text{ (volts)}$$

If there are 'n' turns in the coil then,

$$\Sigma = -N \left( \frac{d\Phi_B}{dt} \right) \text{ (volts)}$$

Lenz's law: The direction of the induced current in the closed circuit is that it opposes the original cause that produced it, it is known as Lenz's law.

### Explanations:



Consider a magnet is brought towards a circular loop as shown in fig. Suppose the North pole of the magnet is moved towards a closed conducting loop - then the current is induced in the loop in anticlockwise direction and produces its own magnetic field. And, this acts as a north pole. → Thus, so, there will be a force of repulsion b/w them. Due to this force of repulsion

The most of the magnetic field is opposed i.e. it oppose the original cause.

Self Induction: The phenomenon of production of induced EMF in a circuit is itself due to variation of magnetic flux through same circuit is called self induction. It was discovered by J. Henry.

Coefficient of self induction ( $L$ )

The total magnetic flux ( $\phi_B$ ) linked with coil is directly proportional to current ( $i$ ) flowing through it.

$$\phi_B \propto i \quad \text{or} \quad \phi_B = L_i \quad \text{--- (1)}$$

$$L = \frac{\phi_B}{i}$$

Units:  $\frac{\text{Volts}}{\text{Ampsec}} = \frac{\text{Volt-sec}}{\text{Amp}} = \text{Henry}$

Definition: The coefficient of self induction is numerically equal to the induced EMF when the rate of current is unit.

The units of self induction is "Henry".

$$i = 1 \text{ amp} \quad \boxed{L = \phi_B}$$

Definition: Coefficient of self induction is numerically equal to magnetic flux linked with the circuit when unit current is flowing through it. A/c to Faraday Law,

The induced EMF is given by

$$E = - \int \frac{d\phi_B}{dt}$$

$$E = - \frac{d(\phi_B)}{dt}$$

$$\boxed{E = -L \left( \frac{di}{dt} \right) \text{ (or)}}$$



fig: Solenoid

→ Consider a long solenoid of length 'l'.  
 With uniform cross sectional area 'A'. When current  $i$  is given through it, a magnetic field is established.  
 It flows in it; a magnetic field is established.  
 This field is uniform inside and negligible  
 outside. So the volume associated with the  
 magnetic field is  $\pi A l$ .

∴ The magnetic field inside the solenoid  
 is given by

→ Let 'n' be the no. of turns per unit  
 length as shown in fig.

→ The magnetic field inside the solenoid  
 is given by

$$B = \mu_0 n i \text{ Weber/m}^2 \quad \text{①}$$

→ The magnetic flux through each turn  
 is given by  $\phi_B = B \cdot A \rightarrow \text{②}$   
 From eq ① & ②, we have

$$\phi_B = \text{constant}$$

→ Hence the magnetic flux linked with  
 all turns of solenoid is given by

$$\phi_B = \mu_0 n i A \rightarrow \text{③}$$

The self induction of the solenoid is  
 given by  $L = \frac{\phi_B}{i} \quad (\because \phi_B = L i) \rightarrow \text{④}$

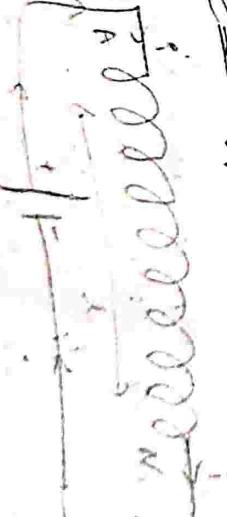
$$L = \frac{\mu_0 n^2 A l}{l}$$

$$L = \mu_0 \left( \frac{N}{l} \right)^2 A l \quad \text{or} \quad L = \frac{\mu_0 N^2 A}{l}$$

∴ From the above eq, self induction of a  
 solenoid depends on the

1. The length of the solenoid ( $l$ )
2. The area of the coil ( $A$ )
3. No. of turns in a coil ( $N$ )

(Part) Energy stored in a magnetic field



→ Consider a long solenoid of length 'l' with cross sectional area 'A'. When current flows in it, a magnetic field is established. This field is uniform inside and negligible outside. So the volume associated with the magnetic field is  $A \times l$ .

→ The amount of workdone in establishing a current in the solenoid is

$$W = \frac{1}{2} L I_0^2 \rightarrow (1)$$

where 'L' is the inductance of the solenoid.

This workdone is stored as energy in the magnetic field.

$$W = U = \text{energy stored} = \frac{1}{2} L I_0^2$$

i.e.  $U = \frac{1}{2} L I_0^2$

→ The inductance of the solenoid

$$L = \mu_0 n^2 A L \rightarrow (2)$$

$$\text{Substitute Eq (2) in (1)}$$

$$U = \frac{1}{2} \mu_0 n^2 A L \cdot \left( \frac{\mu_0 n^2 A L}{\mu_0 n^2 A L} \right)^2 = \frac{1}{2} \mu_0 n^2 A L \cdot \left( \frac{\mu_0 n^2 A L}{\mu_0 n^2 A L} \right)^2$$

No

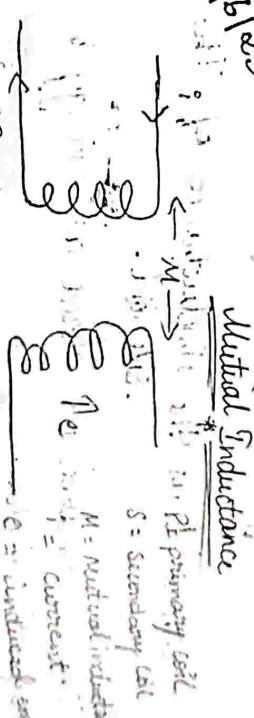
→ The energy per unit volume in magnetic field is known as energy density.

$$\text{Energy density } u = \frac{U}{V}$$

$$u = \frac{1}{2} B^2 (AL)$$

$$u = \frac{1}{2} \frac{\mu_0 I^2}{L}$$

### Ques 23



### Mutual Induction

P = primary coil

S = secondary coil

$\mu_0$  = mutual inductance

I = current

$\Delta \Phi$  = induced emf

Suppose two coils placed near to each other as shown fig.

When a current passes in the primary coil 'P', there is a change of magnetic flux linked with it & an induced EMF set in the secondary coil 'S'. This phenomenon is known as mutual inductance.

Let a current 'i' in primary coil 'P' produces a magnetic flux in the secondary 'S'. It is observed that the flux is proportional to the primary coil is directly proportional to the primary coil.

$$\text{Let } \Phi_B = \mu i \quad \text{where } \mu = \text{coefficient of mutual inductance}$$

where  $\mu = \text{coefficient of mutual inductance}$

$$\text{Now } \frac{d\Phi_B}{dt} = \mu \frac{di}{dt}$$

Coefficient of mutual inductance

According to Faraday's second law

$$\mathcal{E} = -\frac{d\Phi_B}{dt} \rightarrow \text{Eqn 2}$$

From Eqn 1

$$\mathcal{E} = -\frac{d(Mi)}{dt}$$

$$\mathcal{E} = -M \frac{di}{dt}$$

$$M = \frac{\mathcal{E}}{(di/dt)} \rightarrow \text{Eqn 3}$$

$$\therefore M \left( \frac{di}{dt} \right) = 1 \quad \therefore M = \frac{1}{i}$$

The coefficient of mutual inductance is equal to induced EMF when the negative rate of change of current in the circuit is unity.

Transformer

Transformer is an AC device, the transfer

electrical energy from one circuit to another. This uses not used in DC circuits.

It is used to either to increase the voltage with decreasing current (step up transformer) or to decrease the voltage with increasing current (step down transformer).

Construction:

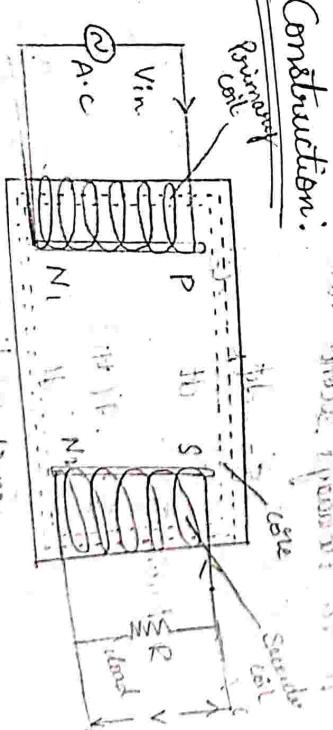


Fig: Transformer

\* Transformer consists of 2 coils they are  
i) primary coil ii) secondary coil.

\* The 2 separate coils are wound on same ferromagnetic core. Due to this the mutual induction b/w 2 coils will be minimum. The 2 coils are insulated but they are connected magnetically so that the energy from one coil is transformed to other coil by magnetic coupling.

\* Here  $N_1$  &  $N_2$  are no. of turns in primary & secondary coil.

### Working principle:

\* The transformer works on the principle of mutual inductance when an alternative voltage is applied to the primary coil, which produces alternative flux in the core. This alternative flux links with the turns of secondary coil so that an induced emf is generated in the secondary coil. Due to this secondary coil is capable of supplying the load.

\* Acc to Faraday's Second Law

$$E_1 = -N_1 \left( \frac{d\Phi_B}{dt} \right)$$

$$E_2 = -N_2 \left( \frac{d\Phi_B}{dt} \right)$$

The above eqn us known as transformer ratio.

$$\frac{\sum_1}{\sum_2} = \frac{N_1}{N_2}$$

When  $N_2 > N_1$ , the transformer is known as step up transformer.  
When  $N_2 < N_1$ , the transformer is known as step down transformer.

The efficiency of the transformer is the ratio of output power to the input power.

$$\text{Efficiency } \eta = \frac{\text{output power}}{\text{input power}} = \frac{V_o I_o}{V_i I_i}$$

15/6/23

## Digital Electronics

Introduction: The digital electronics is a branch of electronics which deals with digital circuits i.e. the generation, processing & storage of digital signals. It helps the analysis, design & construction of digital systems.

Digital Circuits: An electronic circuit that is designed for two state operation is called a digital circuit. (or) An electronic circuit that handles only a digital signal is called a digital circuit.  
 ⇒ The output voltage of digital circuit is either low or high & no other values. Here digital operation is a two state operation off or on, no or yes, false or true, open or closed, 0 or 1.

Number Systems: There are 4 types of number systems

- 1) Decimal number system
- 2) Binary " " system
- 3) Octal " " system
- 4) Hexadecimal " " system

Ex: The number 265 in decimal system should be written as  $(265)_{10}$

→ In this system each digit in the number has place values from right to left i.e. the values of a number  $(265)_{10}$  in this system is the sum of the product of the digits with its respective powers of 10.

∴  $(265)_{10} = (2 \times 10^2) + (6 \times 10^1) + (5 \times 10^0) \Rightarrow 2 \times 10^2 + (6 \times 10^1) + (5 \times 10^0)$

So, the left digit are called MSB (Maximum Significant Bit) and right digit are called LSB (Least Significant Bit).

Ex: The fractional decimal number should be written as

$$\Rightarrow 5 \times 10^{-1} + 6 \times 10^{-2} + 3 \times 10^{-3}$$

$$\Rightarrow (0.563)_{10} = (5 \times 10^1) + (6 \times 10^{-2}) + (3 \times 10^{-3})$$

## Decimal System

### Binary System:

In this system only two digits are used to represent a number, the digits are 0 & 1. The base of this system is 2.

→ This system is useful to utilize in computers & electronic circuits. Because they can recognize only two states i.e. On & Off states.

On → 1  
Off → 0

Ex: 1.  $(1101)_2$ .

The place value of  $(1101)_2$  is

$$\Rightarrow (1101)_2 = (1 \times 2^3) + (1 \times 2^2) + (0 \times 2^1) + (1 \times 2^0)$$

$$= (1 \times 8) + (1 \times 4) + 0 + (1 \times 1)$$

$$= 8 + 4 + 1$$

Ex: 2.  $(0.1101)_2 = (0.8125)_{10}$ .

$$= (1 \times 2^{-1}) + (1 \times 2^{-2}) + (0 \times 2^{-3}) + (1 \times 2^{-4})$$

$$= (1 \times \frac{1}{2}) + (1 \times \frac{1}{4}) + 0 + (1 \times \frac{1}{16})$$

$$= \frac{1}{2} + \frac{1}{4} + \frac{1}{16}$$

$$= 0.5 + 0.25 + 0.0625$$

$$(0.1101) - 10.8125$$

### Decimal System

### Binary System

0	1
2	10
3	11
4	100
5	101
6	110
7	111
8	1000
9	1001
10	1010
11	1011
12	1100
13	1101
14	1110
15	1111
16	10000
17	10001
18	10010
19	10011
20	10100

## Logic Gates

The digital circuits with one or more input signals but only with one output

circuits.

Since the logic gates are switching circuits their output can have only of the two possible states i.e either 'on' a high voltage (1) or, 'off' a low voltage (0)

Truth table: A Table shows that all the inputs and outputs of a logic circuit is known as truth table.

Basic logic gates: There are 8 types of basic logic gates

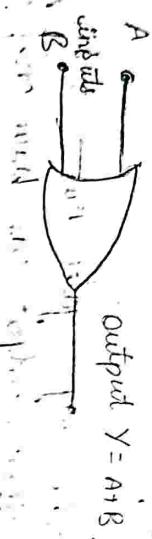
- 1) OR gate  $\rightarrow +$
- 2) AND gate  $\rightarrow \times$
- 3) NOT gate  $\rightarrow -$

1. OR Gate: ① The OR gate is a logic gate that has two or more inputs but only one output.

② (+) plus sign is used to show OR operation.

(5) The output of an OR gate is high if any 1 or more inputs are high.

Symbol: It is plus sign (+).



Truth table:

Input		Output
A	B	$Y = A + B$
0	0	0
0	1	1
1	0	1
1	1	1

From the above 'truth table' OR Gate's output is high, if anyone or more output are high. The only way to get is by two all inputs low.

Cases i)  $A = 0, B = 0, Y = A + B = 0 + 0 = 0$

ii)  $A = 0, B = 1, Y = A + B = 0 + 1 = 1$

iii)  $A = 1, B = 0, Y = A + B = 1 + 0 = 1$

iv)  $A = 1, B = 1, Y = A + B = 1 + 1 = 1$

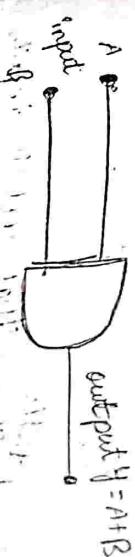
AND Gate

AND gate is a logic gate which has 2 or more inputs and have only 1 output.

\* (dot) sign used to show the AND gate.

\* The circuit has high output if all the inputs are high.

Symbol:



Truth table: A table shows that all the input and output possibilities of a logic tables is known as truth table.

Input		Output
A	B	$Y = A \cdot B$
0	0	0
0	1	0
1	0	0
1	1	1

Case(i):  $A = 0, B = 0, Y = A \cdot B = 0 \cdot 0 = 0$

ii)  $A = 0, B = 1, Y = A \cdot B = 0 \cdot 1 = 0$

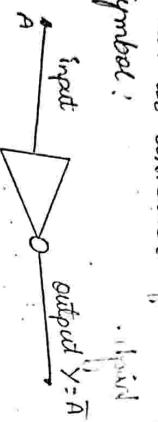
iii)  $A = 1, B = 0, Y = A \cdot B = 1 \cdot 0 = 0$

iv)  $A = 1, B = 1, Y = A \cdot B = 1 \cdot 1 = 1$

### NOT Gate:

The NOT Gate is a circuit which has one input and has only one output. The main purpose of this gate is to complement or invert the input. Hence the gate is also called as 'inverter'.

Symbol:



Truth table: A table shows that all the inputs and outputs possibilities of a logic gate is known as truth table.

Input	Output
0	1
1	0

Case(i)

$$A = 0, Y = \bar{A} = \bar{0} = 1$$

$$A = 1, Y = \bar{A} = \bar{1} = 0$$

NAND Gate:

$$\text{AND} + \text{NOT} = \text{NAND}$$

$$A \cdot B + \text{NOT } A \cdot \text{NOT } B = \text{NAND}$$

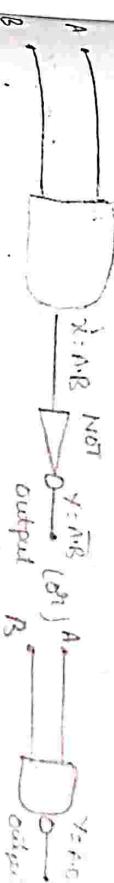
$$AB \rightarrow \text{NAND}$$

$$\begin{aligned} & A = 0, B = 0, A \cdot B = 0 \cdot 0 = 0, \bar{A} \cdot \bar{B} = \bar{0} \cdot \bar{0} = 1 \\ & A = 0, B = 1, A \cdot B = 0 \cdot 1 = 0, \bar{A} \cdot \bar{B} = \bar{0} \cdot 1 = 1 \\ & A = 1, B = 0, A \cdot B = 1 \cdot 0 = 0, \bar{A} \cdot \bar{B} = \bar{1} \cdot 0 = 1 \\ & A = 1, B = 1, A \cdot B = 1 \cdot 1 = 1, \bar{A} \cdot \bar{B} = \bar{1} \cdot \bar{1} = 0 \end{aligned}$$

The boolean expression for NAND gate is

- 1)  $A = 0, B = 0, A \cdot B = 0 \cdot 0 = 0, \bar{A} \cdot \bar{B} = \bar{0} \cdot \bar{0} = 1$
- 2)  $A = 0, B = 1, A \cdot B = 0 \cdot 1 = 0, \bar{A} \cdot \bar{B} = \bar{0} \cdot 1 = 1$

NAND gate is a combination of AND & NOT gate. The output of the AND gate is connected to the input of the NOT gate as shown below fig.



The output of a NAND gate is opposite to the output of the AND gate.

The output of NAND is always 1 except when all of the inputs are 0.

Truth table: A table shows that all the input and output possibilities of a logic circuit is known as 'Truth table'. The below table represents the truth table of NAND gate.

Input	AND Output	Output
0 0	0	1
0 1	0	1
1 0	0	1
1 1	1	0

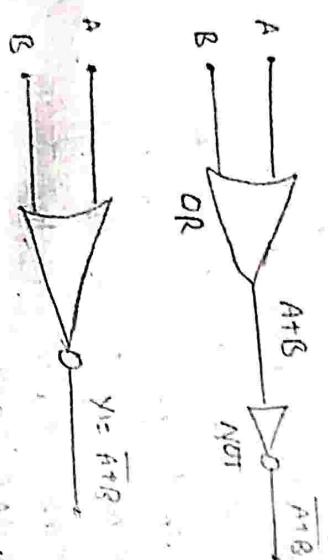
Input      AND      Output  
A      B      A · B      Y = \bar{A} \cdot \bar{B}

ii)  $A=1, B=0, A \cdot B = 1 \cdot 0 = 0, A + B = 0 + 1 = 1$   
 iv)  $A=1, B=1, A \cdot B = 1 \cdot 1 = 1, A + B = 1 + 1 = 0$

iii)  $A=0, B=0, A \cdot B = 0 \cdot 0 = 0, A + B = 0 + 0 = 0$   
 v)  $A=0, B=1, A \cdot B = 0 \cdot 1 = 0, A + B = 0 + 1 = 1$

NOR gate:  $OR + NOT$

- The combination OR & NOT gate.
- The output of OR is connected to the input of the NOT gate.
- The output of the NOR gate is applied to the OR gate.



- The output of the NOR gate is high if all the inputs are low.
- The output of the NOR gate is low when either of the inputs are high.

Truth table:

Input (OR)      Output  
 $A - B$        $x = A + B$        $y = \overline{A + B}$

0 - 0	0	1
0 - 1	1	0
1 - 0	1	0
1 - 1	0	1

Q. 11

The boolean expression for NOR gate:

i)  $A=0, B=0, A+B=0, \overline{A+B}=\overline{0}=1$   
 ii)  $A=1, B=0, A+B=1, \overline{A+B}=\overline{1}=0$

iii)  $A=1, B=1, A+B=1, \overline{A+B}=\overline{1}=0$   
 iv)  $A=0, B=1, A+B=0, \overline{A+B}=\overline{0}=1$

NOR gate as a universal gate. Why?

→ NOR gate is a universal gate. Because it can be used to perform the basic logic functions of OR and AND and NOT gate.

i)  $AB$  NOT gate:

→ If the inputs of NOR gate is tied together the output becomes  $\bar{1}$ .

$$\text{i.e. } y = \overline{A+A} = \overline{A}$$



∴  $y = \overline{\overline{A}}$ , then it works as NOT gate.

ii) AB OR gate

→ If the two NOR gates connected in series as below the output becomes  $A+B$ .

$$\text{i.e. } y = \overline{\overline{A+B}} = A+B$$

$$Y = A+B$$

$$\text{Hence } Y = A+B$$

$$\therefore Y = A+B$$

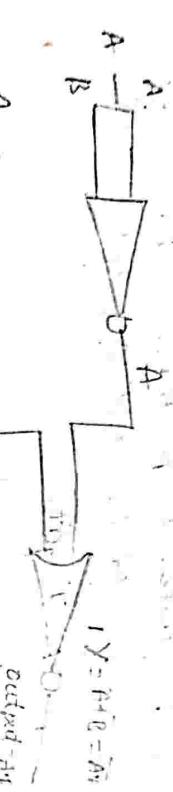
### NAND gate's theorem

#### Theorem - I.

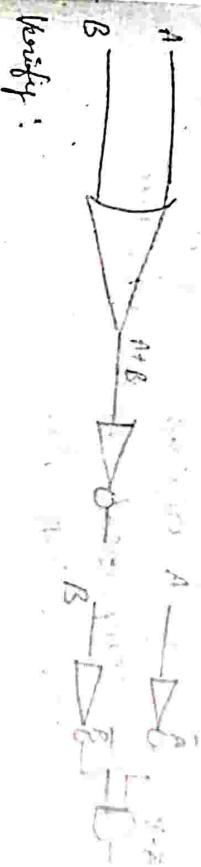
iii) As AND gate :  
 → If 3 NOR gates are connected as shown  
 fig below. The output becomes  $A \cdot B$  as per  
 demorgan's theorem.

$$\text{i.e., } Y = \overline{\overline{A} + \overline{B}} = \overline{A} \overline{B} = A \cdot B$$

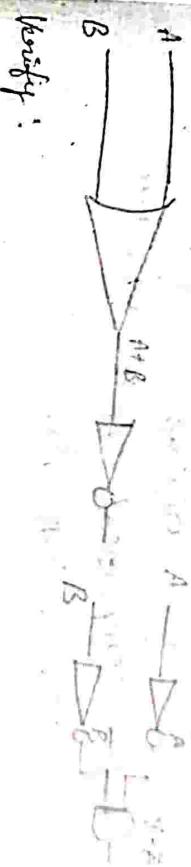
∴  $Y = A \cdot B$ , then it works as an AND gate.



NAND gate is a universal gate why?



Proof :



Verify :

Case i)  $A = 0, B = 0$

$$\begin{aligned} L.H.S &= \overline{\overline{A} + \overline{B}} = \overline{0+0} = \overline{0} = 1 \\ R.H.S &= \overline{A \cdot B} \\ &= \overline{0 \cdot 0} = 1 \cdot 1 = 1 \end{aligned}$$

Case ii)  $A = 0, B = 1$

$$L.H.S = \overline{\overline{A} + \overline{B}} = \overline{0+1} = \overline{1} = 0$$

$$R.H.S = \overline{A \cdot B} = \overline{0 \cdot 1} = 1 \cdot 0 = 0$$

Case iii)  $A = 1, B = 0$

$$L.H.S = \overline{\overline{A} + \overline{B}} = \overline{1+0} = \overline{1} = 0$$

$$R.H.S = \overline{A \cdot B} = \overline{1 \cdot 0} = 1 \cdot 1 = 0 \cdot 0 = 0$$

$$L.H.S = R.H.S$$

Case iv)  $A=1, B=1$

$$L.H.S = \bar{A} + B = \bar{1} + 1 = \bar{1} = 0$$

$$R.H.S = A\bar{B} = 1 \cdot \bar{1} = 0 \cdot 1 = 0$$

$$L.H.S = R.H.S$$

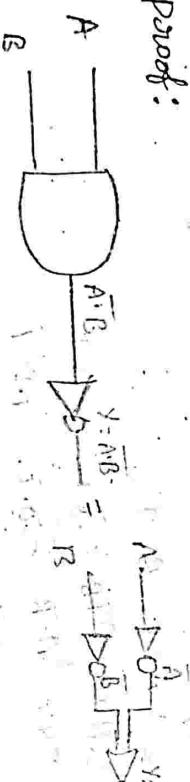
Demorgan's theorem is verified.

Theorem-2

Statement : The complement of the product of two (or) more variables is equal to the sum of the complement of the variables.

$$\overline{A \cdot B} = A + \overline{B}$$

Proof:



Verify :

Case i)  $A=0, B=0$ ,

$$L.H.S = \overline{A \cdot B} = \overline{0 \cdot 0} = 1$$

$$R.H.S = \bar{A} + \bar{B} = \bar{0} + \bar{0} = 1 + 1 = 0$$

L.H.S = R.H.S

Case ii)  $A=0, B=1$

$$L.H.S = A \cdot B = 0 \cdot 1 = 0$$

$$R.H.S = \bar{A} + \bar{B} = \bar{0} + 1 = \bar{1} + 1 = 1$$

L.H.S = R.H.S

Case iii)  $A=1, B=0$

$$L.H.S = A \cdot B = 1 \cdot 0 = 0$$

$$R.H.S = \bar{A} + \bar{B} = \bar{1} + \bar{0} = 0 + 1 = 1$$

$$L.H.S = R.H.S$$

Q3) 123

### Half adder

\* The half adder adds two binary digits at a time & to produce a two bit output data i.e., 1) carry (C) or (Q.) 2) sum(s)

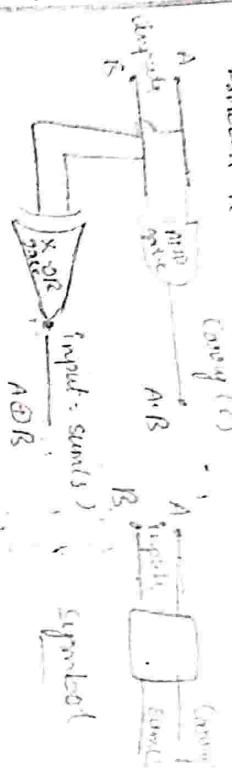
\* Half adder is capable of combining two binary numbers & produces an output which contains sum and carry.

\* This adder is called half adder cause it can't accept carry from the previous addition

\* The half adder is made with a AND gate and a EX-OR [XOR] gate such that the

output of AND gate is carry ( $A \cdot B$ ) & the output of X-OR gate is sum ( $A \oplus B$ ).

\* The circuit symbol of half adder is as follows:



Diagram

Truth table: The truth table below shows the operation of half adder.

Inputs		Output	Sum(S)	Carry(C)
A	B			
0	0	0	0	0
1	0	1	1	0
0	1	1	1	0
1	1	0	0	1

The boolean expression for half adder is

$$\text{Carry}(C) = A \cdot B$$

$$\text{Sum}(S) = A \oplus B$$

Verification:

$$\text{Case (i)} A=0, B=0$$

$$\text{Carry}(C) = 0 \cdot 0 = 0$$

$$\text{Sum}(S) = 0 \oplus 0 = 0$$

$$\begin{aligned} \text{Carry}(C) &= A \cdot B = 0 \cdot 1 = 0 \\ \text{Sum}(S) &= A \oplus B = 0 \oplus 1 = 1 \\ \text{Case (ii)} \quad A=1, \quad B=0 & \\ \text{Carry}(C) &= 1 \cdot 0 = 0 \\ \text{Sum}(S) &= 1 \oplus 0 = 1 \end{aligned}$$

$$\begin{aligned} \text{Case (iv)} \quad A=1, \quad B=1 & \\ \text{Carry}(C) &= 1 \cdot 1 = 1 \\ \text{Sum}(S) &= 1 \oplus 1 = 0 \end{aligned}$$

### Full adder (Essay)

\* The full adder adds 3 binary digits at a time & produces a 2 bit output data i.e.) Sum(S)

$$2) \text{Carry}(C)$$

\* This adder can accept a carry from the previous addition.

\* The full adder can be made by connecting 2 half adders and an OR gate as shown in below fig.



Circuit diagram of full adder

## Principle of full adder

04/11/23

## Unit V: Basic Electronics



Truth table

Truth table				
Inputs	Outputs			
A	B	C	Carry (Co)	Sum (S)
0	0	0	0	0
0	0	1	0	1
0	1	0	1	0
1	0	0	0	1
0	1	1	1	0
1	0	1	0	1
1	1	0	1	0
1	1	1	1	1

Completed

Intro:  
Based on the properties of electric conductivity  
substances are classified into 3 types. such as

### 1) conductor

### 2) Insulators

### 3) Semiconductors

1) conductors: The substances which allow the electric current to pass through them, known as conductor. The conductors are having plenty of free electrons.

Ex: Metals like [Cu], Iron (Fe), Nickel [Ni]

cobalt [Co] etc.

\* In case of conductors, there is no forbidden gap [energy gap] in valency bond & conduction band overlapping each other as shown in below fig



\* The total current in the conductor arises due to electrons only.

- Q) Insulators: The substances which do not allow the electric currents to pass through them are known as insulators.
- \* Insulator does not free of electrons.  
Ex: Wood, plastic, rubber etc.
  - \* In case of insulators the forbidden gap is very wide [ $E_g = 10eV$ ].

Ex: Germanium, Silicon [Pure Crystals]

- \* In this intrinsic S.C. the no. of free electrons is always equal to the no. of holes.

### Types of Semiconductors

- \* Semiconductors may be classified into 2 types
- 1) Intrinsic S.C
- 2) Extrinsic S.C

- 1) Intrinsic S.C: A semiconductor is an extrin

dy pure form, known as Intrinsic S.C

Ex: Germanium, Silicon [Pure Crystals]  
In this intrinsic S.C. the no. of free electrons is always equal to the no. of holes.

### Types of Extrinsic S.C:

- 2) Extrinsic S.C: At room temperature, in intrinsic S.C. the electrical conductivity of intrinsic S.C. can be increased by adding some impurities in the process of crystallization. Such S.C. called extrinsic S.C.
- \* The process of adding impurities to a S.C. known as doping.
- \* Usually the doped material is either pentavalent atoms [Bismuth (Bi), antimony (Sb), Arsenic (As), phosphorous (P) etc], which have 5 electrons or trivalent atoms [gallium (Ga), Indium (Id), Aluminium (Al), Boron (B)], which have 3 valency electrons. The pentavalent atoms is known as donor atoms, cause it donates 1 electron to the conduction band of semi conductor. The trivalent doping atoms is known as acceptor atoms cause it accept 1 electron from pure S.C.