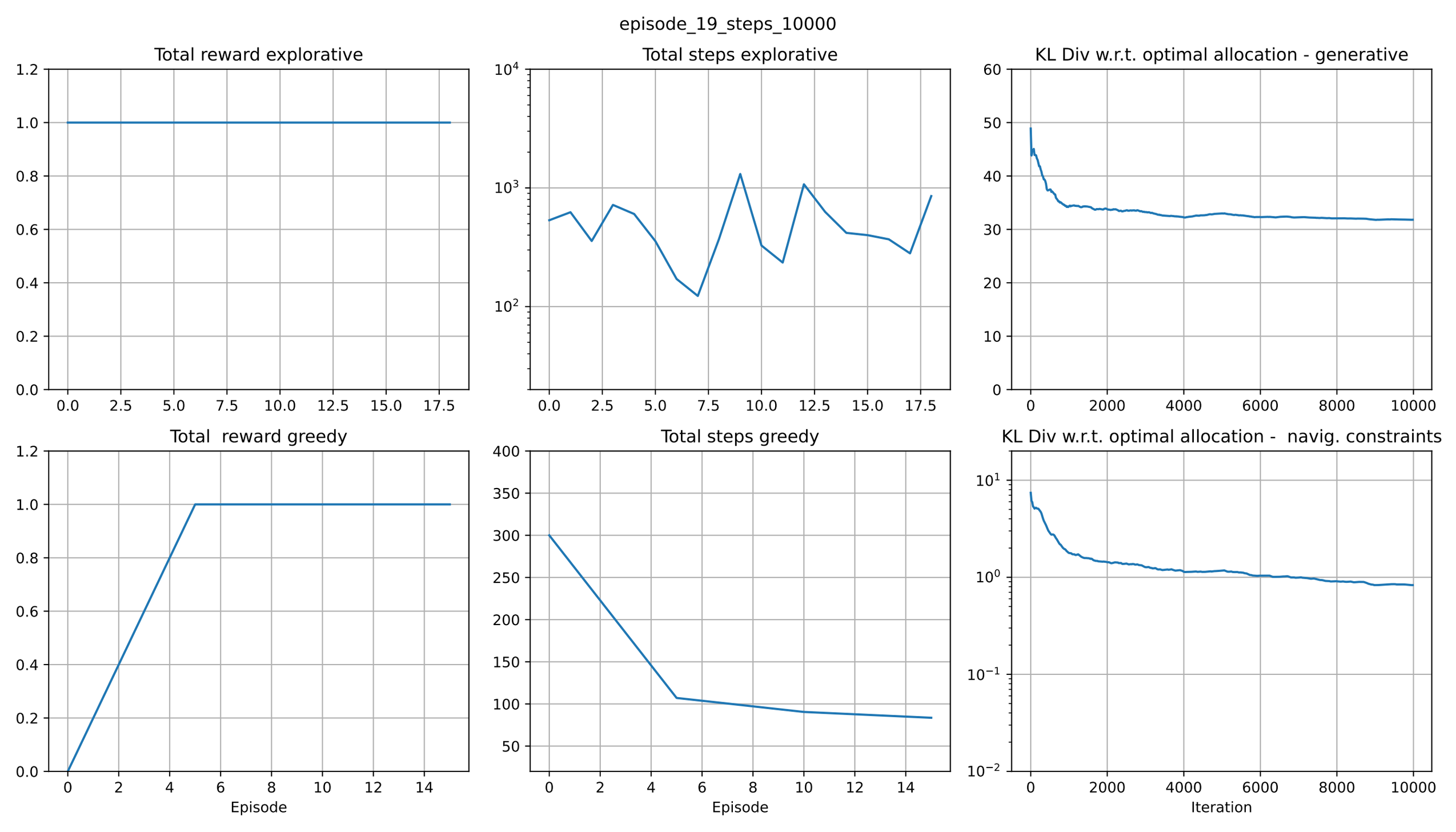
episode_19_steps_10000
Total reward explorative
Total steps explorative
KL Div w.r.t. optimal allocation - generative
Total reward greedy
Total steps greedy
KL Div w.r.t. optimal allocation - navig. constraints
Episode
Episode
Iteration