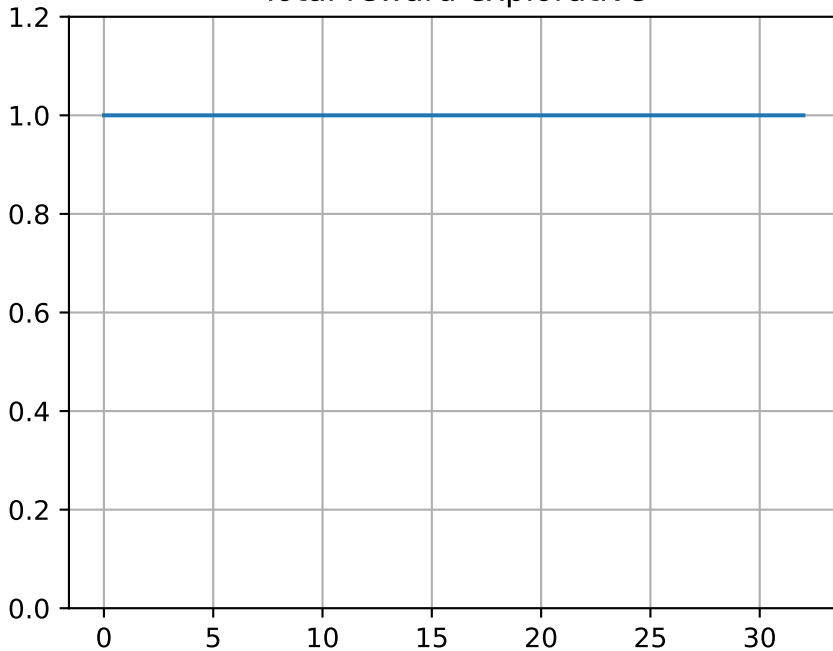
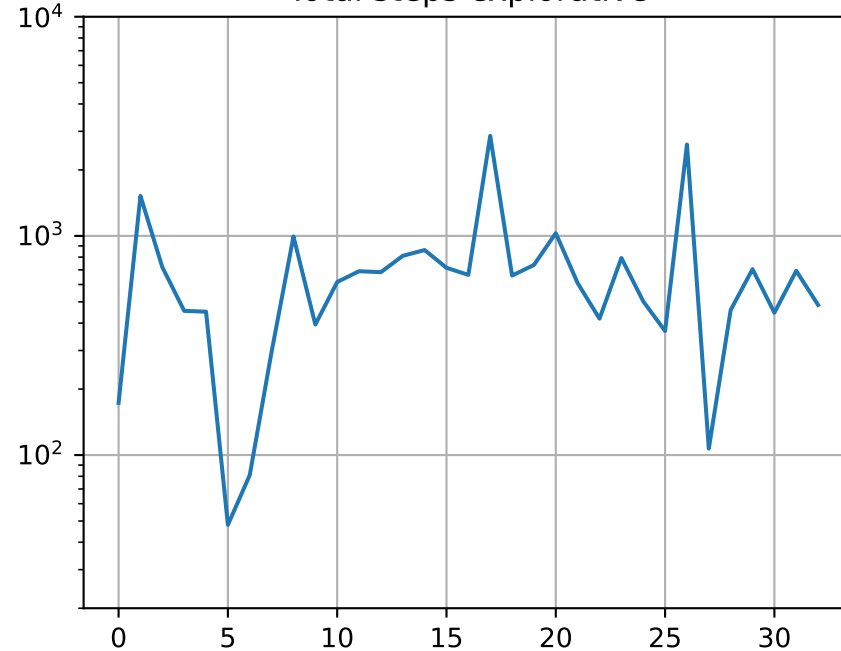


# episode\_33\_steps\_24000

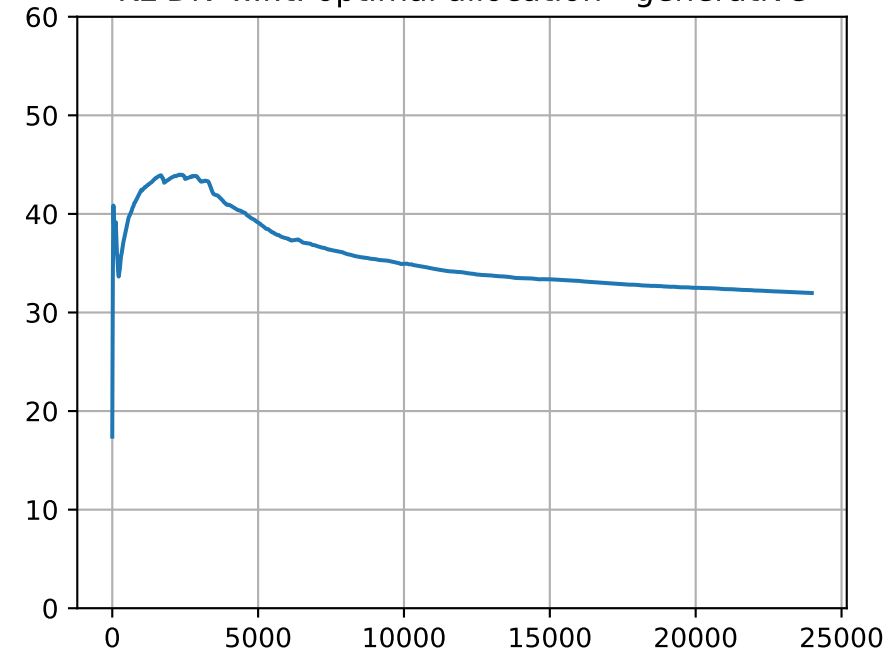
## Total reward explorative



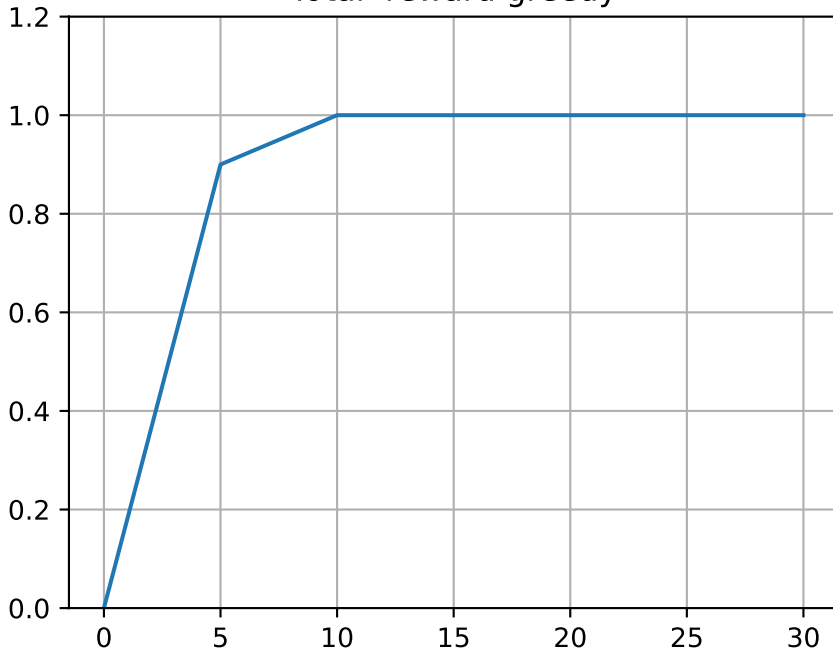
## Total steps explorative



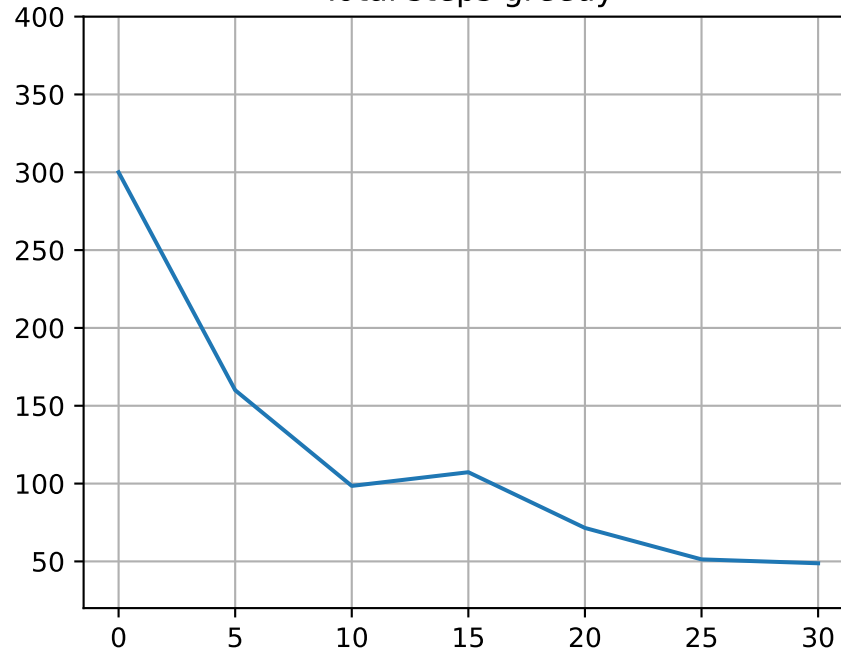
## KL Div w.r.t. optimal allocation - generative



## Total reward greedy



## Total steps greedy



## KL Div w.r.t. optimal allocation - navig. constraints

