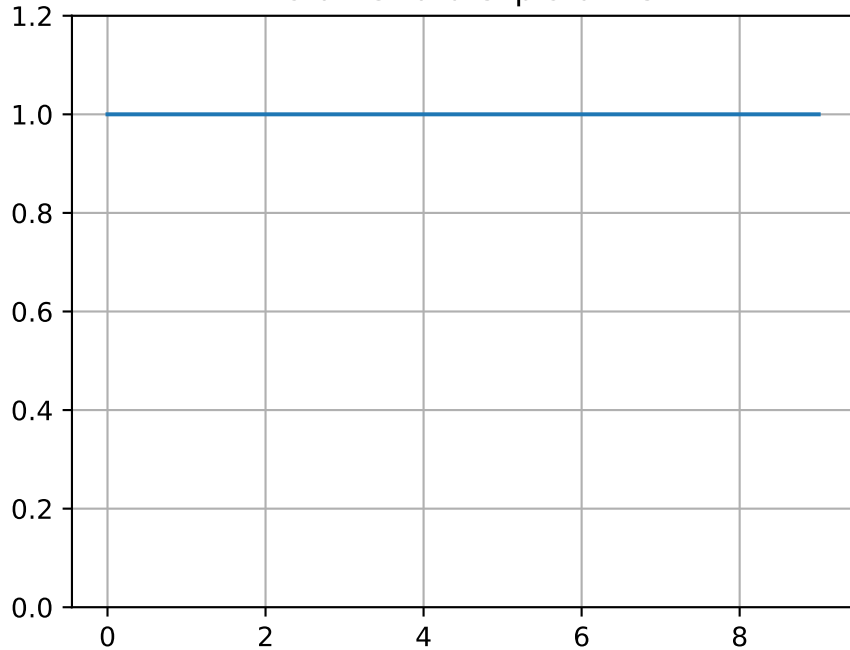
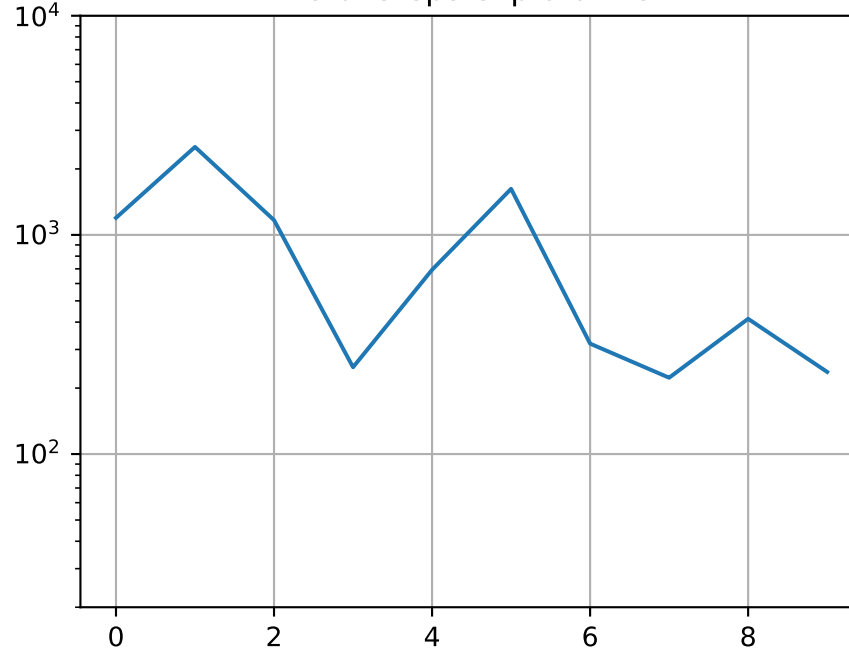


episode\_10\_steps\_9000

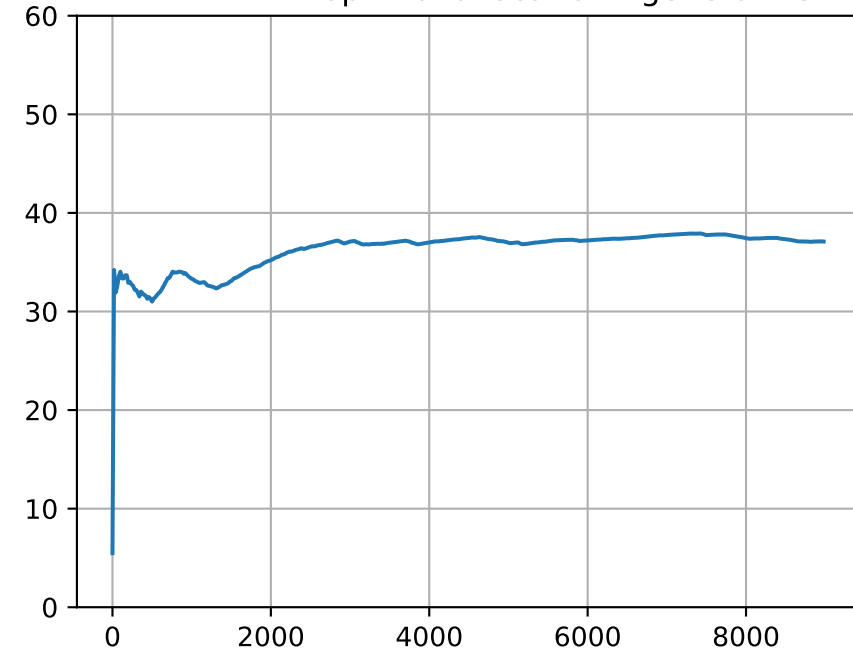
Total reward explorative



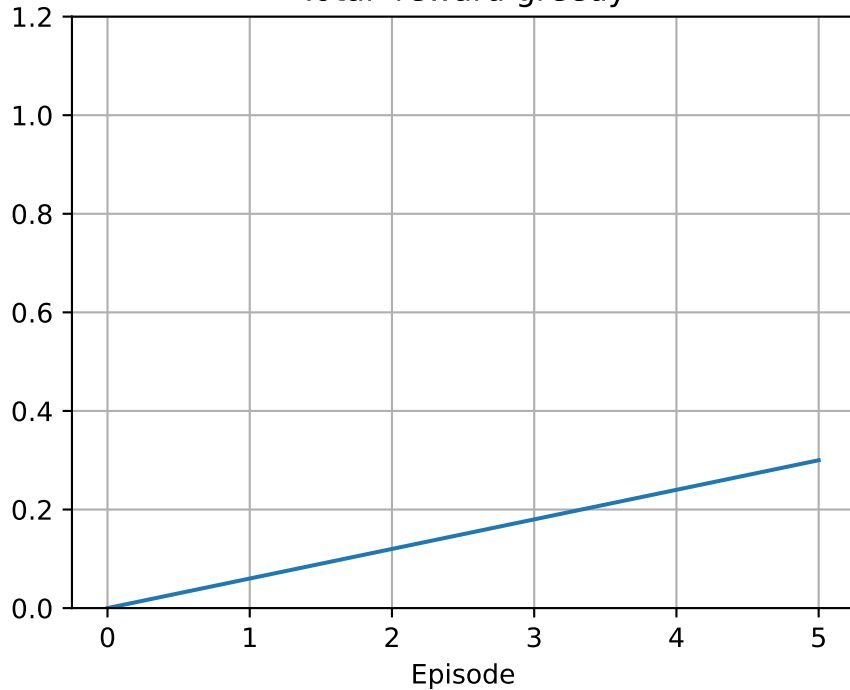
Total steps explorative



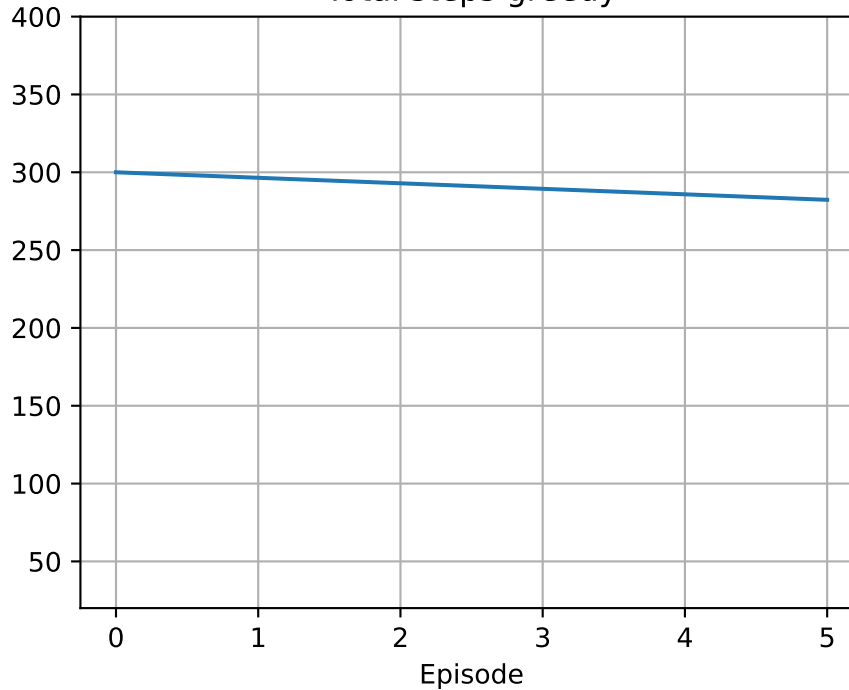
KL Div w.r.t. optimal allocation - generative



Total reward greedy



Total steps greedy



KL Div w.r.t. optimal allocation - navig. constraints

