HW2

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Problem 1. Sakurai 1.21

Evaluate the x-p uncertainty product $\langle (\Delta x)^2 \rangle \langle (\Delta p)^2 \rangle$ for a one-dimensional particle confined between two rigid walls,

$$V = \begin{cases} 0 & \text{for } 0 < x < a, \\ \infty & \text{otherwise.} \end{cases}$$

Do this for both the ground and excited states.

The wavefunction for the particle can be found by solving the Schrodinger equation:

$$H\psi(x) = E_n \psi(x)$$
$$-\frac{\hbar^2}{2m} \frac{d^2}{dx^2} \psi(x) = E_n \psi(x)$$

Solving the differential equation and normalizing, we get the wavefunction for 0 < x < a:

$$\psi(x) = A\sin(kx) = \sqrt{\frac{2}{a}}\sin\left(\frac{n\pi}{a}x\right)$$

and for $\psi(x) = 0$ for x > a:

The expectation value of any operator \hat{A} is given by:

$$\left\langle \hat{A} \right\rangle = \int_0^\infty \psi(x)^* A \psi(x) dx$$
$$= \int_0^a \frac{2}{a} \sin\left(\frac{n\pi}{a}x\right) \hat{A} \sin\left(\frac{n\pi}{a}x\right) dx$$

^{*}LATEX source code: https://github.com/rstanuwijaya/hkust-advanced-qm/

Thus the expectation value of the following operators are:

$$\langle x \rangle = \frac{a}{2}$$

$$\langle x^2 \rangle = \frac{2a^2}{6}$$

$$\langle p \rangle = 0$$

$$\langle p^2 \rangle = \frac{-\hbar^2 n^2 \pi^2}{a^2}$$

Substituting these values into the uncertainty product, we get:

$$\langle (\Delta x)^2 \rangle \langle (\Delta p)^2 \rangle = (\langle x^2 \rangle - \langle x^2 \rangle) (\langle p^2 \rangle - \langle p \rangle^2)$$
$$= \frac{\hbar}{12} (-6 + n^2 \pi^2)$$

For ground state n = 1,

$$\langle (\Delta x)^2 \rangle \langle (\Delta p)^2 \rangle = \frac{\hbar}{12} (-6 + \pi^2) \approx 0.322 \hbar^2$$

which implies that the uncertainty principle holds, i.e. larger than $\hbar^2/4$. For excited states n > 1, the uncertainty principle also holds.

Problem 2. Sakurai 1.22

(a) Prove that $1/\sqrt{2}(1+\sigma_x)$ acting on a two-component spinor can be regarded as the matrix representation of the rotation operator about the x-axis by the angle of $\pi/2$. (The minus sign signifies that the rotation is clockwise)

The form of the rotation operator about the x-axis is:

$$D(\hat{x}, \phi) = \exp\left(-i\phi \frac{\hat{x} \cdot S}{\hbar}\right)$$

$$= \exp\left(-i\phi \frac{S_x}{\hbar}\right)$$

$$= \exp\left(-i\phi \frac{\sigma_x}{2}\right)$$

$$= \begin{pmatrix} \cos \frac{\phi}{2} & -i\sin \frac{\phi}{2} \\ -i\sin \frac{\phi}{2} & \cos \frac{\phi}{2} \end{pmatrix}$$

Which is the same as the matrix representation of $1/\sqrt{2}(1+\sigma_x)$ for $\phi=-\pi/2$, i.e.

$$\frac{1}{\sqrt{2}}(1+\sigma_x) = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -i \\ -i & 1 \end{pmatrix} = D(\hat{\boldsymbol{x}}, -\pi/2)$$

(b) Construct the matrix representation of S_z when the eigekets of S_y are used as base vector

The eigenkets of S_y are:

$$|\psi_{y+}\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1\\i \end{pmatrix}$$
$$|\psi_{y-}\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1\\-i \end{pmatrix}$$

Therefore to find the matrix representation of S_z , we need to find the projection of S_z onto the eigenkets:

$$\langle \psi_{y+} | \sigma_z | \psi_{y+} \rangle = 0$$
$$\langle \psi_{y+} | \sigma_z | \psi_{y-} \rangle = 1$$
$$\langle \psi_{y-} | \sigma_z | \psi_{y+} \rangle = 1$$
$$\langle \psi_{y-} | \sigma_z | \psi_{y-} \rangle = 0$$

Therefore, the matrix representation of S_z in the basis of $|\psi_{y+}\rangle$ and $|\psi_{y-}\rangle$ is:

$$\langle \psi_y | S_z | \psi_y \rangle = \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

Which is the same as S_x . This is because we rotate the basis clockwise by $\pi/2$ about the x-axis. This implies under this basis rotation, the old z axis is now the new x axis.

Problem 3. Sakurai 1.27

(a) Suppose that f(A) is a function of a Hermitian operator A with the property $A|a'\rangle=a'|a'\rangle$. Evaluate $\langle b''|f(A)|b'\rangle$ when the transformation from the a' basis to the b' basis is known.

$$\langle b''|f(A)|b'\rangle = \sum_{a''} \sum_{a'} \langle b''|a''\rangle \langle a''|f(A)|a'\rangle \langle a'|b'\rangle$$

$$= \sum_{a''} \sum_{a'} \langle b''|a''\rangle f(a')\delta_{a,a''} \langle a'|b'\rangle$$

$$= \sum_{a'} f(a') \langle b''|a'\rangle \langle a'|b'\rangle$$

(b) Using the continuum analogue of the result obtained in (a), evaluate

$$\langle \boldsymbol{p''} | F(r) | \boldsymbol{p'} \rangle$$

Simplify your expression as far as you can. Note that r is $\sqrt{x^2 + y^2 + z^2}$, where x, y, and z are operators.

We can start by applying continuum condition:

$$\langle \mathbf{p''} | F(r') | \mathbf{p'} \rangle = \int F(r') \langle \mathbf{p''} | \mathbf{x'} \rangle \langle \mathbf{x'} | \mathbf{p'} \rangle d^3 r'$$
$$= \frac{1}{(2\pi\hbar)^3} \int F(r') e^{i(\mathbf{p'} - \mathbf{p''}) \cdot \mathbf{x'} / \hbar} d^3 r'$$

Then, we can use symmetry argument to simplify the integral. Consider $q \equiv p' - p''$, and $q' \cdot x' = q'r' \cos \theta$, where θ is the angle between q and x'. Then the integral becomes:

$$\int F(r')e^{i\mathbf{q}\cdot\mathbf{x'}/\hbar}d^3r' = 2\pi \int_0^\infty dr' F(r') \int_0^\pi e^{iq'r'\cos\theta/\hbar}\sin\theta d\theta$$
$$= 2\pi \int_0^\infty dr' F(r') \int_0^\pi e^{iq'r'\cos\theta/\hbar}d\theta$$
$$= 2\pi \int_0^\infty dr' F(r') \frac{2\hbar}{q'r'}\sin(q'r'/\hbar)$$

Thus the final result is:

$$\langle \boldsymbol{p''}|F(r')|\boldsymbol{p'}\rangle = \frac{1}{2\pi^2\hbar^2}\int dr' F(r') \frac{\sin(q'r'/\hbar)}{q'r'}$$