

# Ordinary Differential Equations - 104131

## Homework Page No. 5

Solve the following differential systems and initial value problems:

$$1. \vec{x}'(t) = \begin{pmatrix} 1 & 1 & 1 \\ 2 & 1 & -1 \\ -8 & -5 & -3 \end{pmatrix} \vec{x}$$

$$2. \vec{x}'(t) = \begin{pmatrix} 3 & 1 & 1 \\ 1 & 0 & 2 \\ 1 & 2 & 0 \end{pmatrix} \vec{x}$$

$$3. \vec{x}'(t) = \begin{pmatrix} 3 & -4 \\ 1 & -1 \end{pmatrix} \vec{x}, \quad \vec{x}(0) = \begin{pmatrix} 3 \\ 5 \end{pmatrix}.$$

$$4. \vec{x}'(t) = \begin{pmatrix} 1789 & 1848 \\ 1914 & 1939 \end{pmatrix} \vec{x}, \quad \vec{x}(0) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.$$

$$5. \vec{x}'(t) = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix} \vec{x}$$

$$6. \vec{x}'(t) = \begin{pmatrix} 3 & 2 \\ -5 & 1 \end{pmatrix} \vec{x}$$

$$7. \vec{x}'(t) = \begin{pmatrix} 0 & 8 & 0 \\ 0 & 0 & -2 \\ 2 & 8 & -2 \end{pmatrix} \vec{x}$$

$$8. \vec{x}'(t) = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 4 & -4 & 1 \end{pmatrix} \vec{x}, \quad \vec{x}(0) = \begin{pmatrix} 2 \\ -2 \\ -8 \end{pmatrix}$$

9. It is given that  $\vec{x}^{(1)}(t) = \vec{w}e^t$  and  $\vec{x}^{(2)}(t) = \vec{u}e^t + \vec{v}te^t$  are solutions of a  $2 \times 2$  differential system  $\vec{x}' = A\vec{x}$ , (where  $\vec{u}, \vec{v}, \vec{w}$  are constant vectors and  $A$  is a constant matrix).

- (a) What are the eigenvalues of  $A$ ?
- (b) What are the eigenvectors of  $A$ ?
- (c) What are  $\det(A)$  and  $\text{trace}(A)$  ?

10. Find a differential system  $\vec{x}' = A\vec{x}$ , where  $A$  is a  $2 \times 2$  matrix, such that

$$\vec{x}^{(1)} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-2t}, \quad \vec{x}^{(2)} = \begin{pmatrix} t \\ t-1 \end{pmatrix} e^{-2t}$$

are it solutions. What are the eigenvalues and the eigenvectors of  $A$ ?

Solutions: 2.

$$p(r) = \det \begin{pmatrix} 3-r & 1 & 1 \\ 1 & -r & 2 \\ 1 & 2 & -r \end{pmatrix} = (r+2)(r-1)(r-4).$$

For  $r = -2$

$$\begin{pmatrix} 5 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 2 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0 \rightarrow c \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix}.$$

For  $r = 1$

$$\begin{pmatrix} 2 & 1 & 1 \\ 1 & -1 & 2 \\ 1 & 2 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0 \rightarrow c \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}$$

For  $r = 4$

$$\begin{pmatrix} -1 & 1 & 1 \\ 1 & -4 & 2 \\ 1 & 2 & -4 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0 \rightarrow c \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$$

and the general solution is

$$\vec{x}(t) = c_1 e^{-2t} \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} + c_2 e^t \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} + c_3 e^{4t} \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$$

4.  $\vec{x}(t) \equiv 0$  solves the equation and satisfies the initial condition and so by existence and uniqueness it is the solution.

6.

$$p(r) = \det \begin{pmatrix} 3-r & 2 \\ -5 & 1-r \end{pmatrix} = r^2 - 4r + 13.$$

For  $r = 2 + 3i$

$$\begin{pmatrix} 1-3i & 2 \\ -5 & -1-3i \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = 0 \rightarrow a \begin{pmatrix} 2 \\ -1+3i \end{pmatrix}$$

$$e^{(2+3i)t} \begin{pmatrix} 2 \\ -1+3i \end{pmatrix} = e^{2t}(\cos(3t) + i\sin(3t)) \begin{pmatrix} 2 \\ -1+3i \end{pmatrix} = \\ \begin{pmatrix} 2e^{2t}\cos(3t) \\ -e^{2t}\cos(3t) - 3e^{2t}\sin(3t) \end{pmatrix} + i \begin{pmatrix} 2e^{2t}\sin(3t) \\ -e^{2t}\sin(3t) + 3e^{2t}\cos(3t) \end{pmatrix}$$

and so the general solution is

$$\vec{x}(t) = c_1 \begin{pmatrix} 2e^{2t}\cos(3t) \\ -e^{2t}\cos(3t) - 3e^{2t}\sin(3t) \end{pmatrix} + c_2 \begin{pmatrix} 2e^{2t}\sin(3t) \\ -e^{2t}\sin(3t) + 3e^{2t}\cos(3t) \end{pmatrix}$$

7.

$$p(r) = \det \begin{pmatrix} -r & 8 & 0 \\ 0 & -r & -2 \\ 2 & 8 & -2-r \end{pmatrix} = (r+2)(-r^2-16).$$

For  $r = -2$

$$\begin{pmatrix} 2 & 8 & 0 \\ 0 & 2 & -2 \\ 2 & 8 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0 \rightarrow c \begin{pmatrix} -4 \\ 1 \\ 1 \end{pmatrix}.$$

For  $r = 4i$

$$\begin{pmatrix} -4i & 8 & 0 \\ 0 & -4i & -2 \\ 2 & 8 & -2-4i \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0 \rightarrow b \begin{pmatrix} -2i \\ 1 \\ -2i \end{pmatrix}.$$

$$e^{4it} \begin{pmatrix} -2i \\ 1 \\ -2i \end{pmatrix} = (\cos(4t) + i \sin(4t)) \begin{pmatrix} -2i \\ 1 \\ -2i \end{pmatrix} =$$

$$\begin{pmatrix} 2 \sin(4t) \\ \cos(4t) \\ 2 \sin(4t) \end{pmatrix} + i \begin{pmatrix} -2 \cos(4t) \\ \sin(4t) \\ -2 \cos(4t) \end{pmatrix}$$

and so the general solution is

$$\vec{x}(t) = c_1 e^{-2t} \begin{pmatrix} -4 \\ 1 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} 2 \sin(4t) \\ \cos(4t) \\ 2 \sin(4t) \end{pmatrix} + c_3 \begin{pmatrix} -2 \cos(4t) \\ \sin(4t) \\ -2 \cos(4t) \end{pmatrix}$$

8.

$$p(r) = \det \begin{pmatrix} -r & 1 & 0 \\ 0 & -r & 1 \\ 4 & -4 & 1-r \end{pmatrix} = (r-1)(-r^2-4).$$

For  $r = 1$

$$\begin{pmatrix} -1 & 1 & 0 \\ 0 & -1 & 1 \\ 4 & -4 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0 \rightarrow a \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}.$$

For  $r = 2i$

$$\begin{pmatrix} -2i & 1 & 0 \\ 0 & -2i & 1 \\ 4 & -4 & 1-2i \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0 \rightarrow b \begin{pmatrix} 1 \\ 2i \\ -4 \end{pmatrix}.$$

$$e^{2it} \begin{pmatrix} 1 \\ 2i \\ -4 \end{pmatrix} = (\cos(2t) + i \sin(2t)) \begin{pmatrix} 1 \\ 2i \\ -4 \end{pmatrix} =$$

$$\begin{pmatrix} \cos(2t) \\ -2 \sin(2t) \\ -4 \cos(2t) \end{pmatrix} + i \begin{pmatrix} \sin(2t) \\ 2 \cos(2t) \\ -4 \sin(2t) \end{pmatrix}$$

and so the general solution is

$$\vec{x}(t) = c_1 e^t \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} \cos(2t) \\ -2 \sin(2t) \\ -4 \cos(2t) \end{pmatrix} + c_3 \begin{pmatrix} \sin(2t) \\ 2 \cos(2t) \\ -4 \sin(2t) \end{pmatrix}$$

Now for the initial condition

$$\begin{pmatrix} 2 \\ -2 \\ -8 \end{pmatrix} = \vec{x}(0) = c_1 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 0 \\ -4 \end{pmatrix} + c_3 \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix} \rightarrow \begin{array}{l} c_1 = 0 \\ c_2 = 2 \\ c_3 = -1 \end{array}$$

$$\vec{x}(t) = 2 \begin{pmatrix} \cos(2t) \\ -2 \sin(2t) \\ -4 \cos(2t) \end{pmatrix} - \begin{pmatrix} \sin(2t) \\ 2 \cos(2t) \\ -4 \sin(2t) \end{pmatrix}$$