

## Application/data Classified data?

Yes: Categorical labels (classification) or quantitative (regression)  
No: Similarity (clustering) or partitioning (dimensionality reduction)

4 levels of abstraction

## Model/method

CS189

e.g.

- decision function: linear, polynomials, logistic, neural net...
- nearest neighbors, decision trees
- features: edge detectors, embeddings, raw pixels
- low vs. high capacity model: how Sinuous/complicated?  
↳ affects overfitting/underfitting, inference

## Optimization Problem

- variables/parameters, objective function, constraints  
e.g. unconstrained, convex programs, least squares linear regression, PCA

## Optimization Algorithms

e.g. gradient descent, SGD, Simplex, SVD (for PCA)

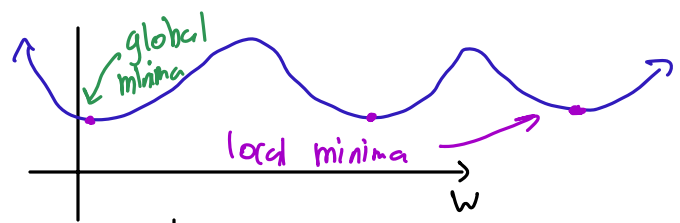
## Optimization Problems

**Unconstrained:** given continuous objective function  $f$ , find  $\vec{w}$  that minimizes/maximizes  $f$

-  $f$  is **smooth** if  $\frac{df}{dx}$  is also continuous

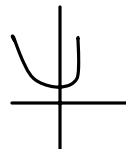
- **global minimum** of  $f$ : value  $w$  s.t.  $f(\vec{w}) \leq f(\vec{v}) \forall \vec{v}$

↳ Sometimes need to settle for **local minimum**:  $f(\vec{w}) \leq f(\vec{v})$ ,  
 $\vec{v}_i \in$  "tiny ball centered @  $\vec{w}$



Usually, finding local minima is easy, but  
finding global minima is hard or impossible

↳ exception: **convex functions**:  $\forall x, y \in \mathbb{R}^d$ , line connecting  $(x, f(x))$  &  $(y, f(y))$   
doesn't go below  $f(\cdot)$



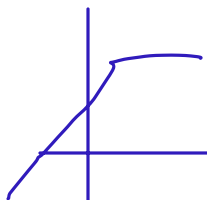
e.g. perceptron risk function is convex & nonsmooth

↳ convex since it's a sum of convex parts

Consider a continuous, convex function over a closed domain:

3 possibilities:

1) no minima (goes to  $-\infty$ )



2) just one local minimum

3) connected set of local minima

(that are all global minima w/ same objective values)

Walk downhill

Perceptron risk function

↳ risk = 0 in pie slice

Algos for smooth functions:

- gradient descent

$$W = W - \epsilon \nabla f(W)$$

- blind gradient descent: simply steps down, doesn't know how far to go down

- SGD (also blind)

- line search: looks ahead & tries to find minimum along the direction

- Newton's method (needs Hessian matrix of  $f$ )

↳ can be expensive, e.g. for NN's

- Nonlinear conjugate gradient method

- has line search as subroutine

these algos find local minimum, not global

Algos for nonsmooth  $f$ :

- can still do gradient descent

Wait! Work: Newton's method (needs 2nd order information)

- BFGS

line search: repeat { 1) pick direction  
2) find local minimum along that dimension/line by solving an optimization problem in 1D }

Some examples: 1) Secant method (smooth only)  
2) 2nd derivatives (must be smooth)  
3) direct line search  
    ↳ golden section search (nonsmooth functions)

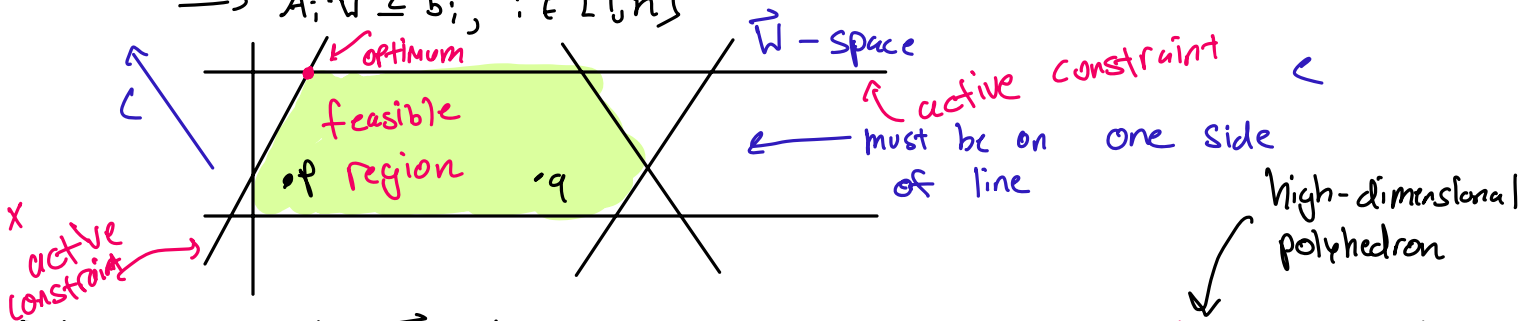
Constrained Optimization (smooth equality constraints) ↗ isosurface  
↳ find point on surface  
s.t.  
 $g(\vec{U}) = 0$   
goal: find  $\vec{U}$  that minimizes  $f(\vec{U})$  s.t.  $g(\vec{U}) = 0$ ,  $g$  is smooth  
algorithm: lagrange multipliers (constrained smooth optimization problem) → smooth unconstrained optimization problem

Linear Program: linear objective func. & linear inequality constraints

goal: find  $\vec{w}$  that maximizes  $C \cdot \vec{w}$  s.t.  $A\vec{w} \leq b$

$A \in \mathbb{R}^{n \times d}$ ,  $b \in \mathbb{R}^n \Rightarrow n$  linear constraints ↗ component-wise constraints

$$\Rightarrow A_i \cdot \vec{w} \leq b_i, i \in [1, n]$$



The set of points  $\vec{w}$  that satisfy all constraints is a **polytope** called the **feasible region F**

The **optimum** is point in  $F$  that maximizes  $C \cdot \vec{w}$  (furthest in direction of  $C$ )

A point set  $P$  is **convex** if for every  $p, q \in P$ , line connecting  $p$  &  $q$  is entirely in the point set

The optimum generally achieves equality for some constraints (but not most of them)  
    ↳ **active constraints** of the optimum

example: every feasible point  $(w, d)$  gives a linear classifier

↳ not necessarily the best in test time

↳ 100% training accuracy

→ find  $w, d$  that maximizes  $D$  s.t.  $y_i(x_i \cdot w + d) \geq 1 \quad \forall i \in [1 \dots n]$

IMPORTANT: linearly separable data iff feasible region  $\neq$  empty set

→ also true for maximum margin classifier (quadratic program)

Algos for solving linear programs:

- Simplex (George Dantzig, 1947)

- Walks from vertex to vertex in polytope

- Interior Point methods

Quadratic Program: quadratic, convex objective function

⇒ hessian is PSD

goal: find  $\vec{w}$  that minimizes  $f(w) = w^T Q w + c^T w$

s.t. same linear constraints as linear program

↳ only one local minimum (global minimum)

example: find maximum margin classifier

quadratic term

Symmetric  $Q$ , positive definite