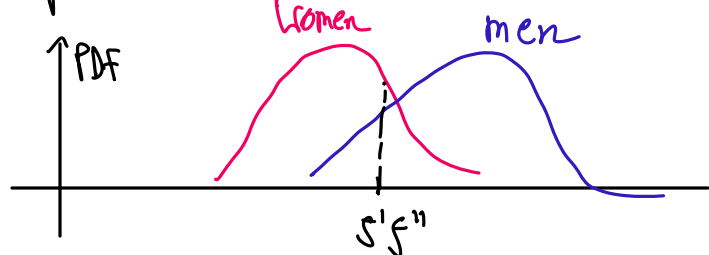


# Decision Theory (Risk minimization)

adult height  $\rightarrow$  man/Woman

1st issue: multiple pts w/ different classes could lie at same pt

Want: probabilistic classifier



Suppose 10% of population has cancer, 90% doesn't

Prob distributions for calorie intake,  $P(X|Y)$ :  $X = \# \text{ calories}$   $Y = \text{Cancer}$

Calories ( $X$ )	2,1200	1200-1600	> 1600
Cancer ( $Y=1$ )	20%	50%	30%
$\overline{\text{Cancer}}$ ( $Y=-1$ )	1%	10%	89%

Recall:  $P(X) = P(X|Y)P(Y) + P(X|\bar{Y})P(\bar{Y})$

$$P(1200 \leq X \leq 1600) = 0.5 \cdot 0.1 + 0.9 \cdot 0.10 = 0.14$$

guy eats  $X=1400$  calories.  $\text{prob}(\text{guy has cancer})$

Bayes' rule =  $\frac{\text{prob}(12-1600 | \text{cancer}) \overbrace{P(\text{cancer})}^{\text{Prior probability}}}{P(1200 \leq X \leq 1600)} = \frac{0.2 \cdot 0.1}{0.14} = \frac{0.02}{0.14}$

(posterior probability)

\*assumes equal loss for misclassifications  
 $\hookrightarrow$  need to punish false negatives more

$$\rightarrow P(\text{cancer} | 1200 \leq X \leq 1600) = \frac{2}{14} \approx 14\%$$

loss function  $L(z, y)$  specific badness if classifier predicts  $z$  but classifies  $y$

e.g.  $L(z, y) = \begin{cases} 1 & z=1, y=-1 \\ 5 & z=-1, y=1 \\ 0 & z=y \end{cases}$

asymmetrical

false positive is bad  
false negative really bad  
correct classification good

36% probability of loss 5, worse than 64% chance of loss 1

Definitions:

get next test/biggy

Symmetric loss fn: penalties are equal

0-1 loss fn: 0 if True, 1 if false/incorrect

let  $r: \mathbb{R}^d \rightarrow \pm 1$  (decision rule/classifier)

↳ maps feature vector to prediction

Risk for a decision rule  $R$  = expected loss over all possible values of  $x$  &  $y$

Risk = expected loss

$$\rightarrow R(r) = E[L(r(x), y)]$$

functional

set of all possible values of RV  $x$

$$= \sum_x \left[ \underbrace{L(r(x), 1)}_{\text{outcome}} \cdot \underbrace{P(y=1|x)}_{\text{prob of outcome}} + L(r(x), -1) P(y=-1|x=x) \right] P(x=x)$$

posterior

points not in class

$$(Bayes Rule) = P(y=1) \sum_x L(r(x), 1) P(x=x|y=1) + P(y=-1) \sum_x L(r(x), -1) P(x=x|y=-1)$$

Bayes decision rule: function  $r^*$  that minimizes functional  $R(r)$   
(Bayes classified) (takes in a function)

Assuming  $L(z, y) = 0$  for  $z=y$ :

discrete case

$$r^*(x) = \begin{cases} 1 & \text{if } L(-1, 1) P(y=1|x=x) > L(1, -1) P(y=-1|x=x) \\ -1 & \text{o/w} \end{cases}$$

which of 2 terms is bigger

When  $L$  is symmetric,  $L(-1, 1) = L(1, -1) \Rightarrow$  only compare  $P(y=1|x=x) > P(y=-1|x=x)$

↳ In other words: Pick class w/ biggest posterior probability

If not symmetric: weigh posteriors by respective loss functions

for cancer example:  $r^*(x) = 1$  for  $x \leq 1600$ ,  $r^*(x) = -1$  for  $x > 1600$

he chose these

Bayes/optimal risk: risk of best possible classifier (Bayes classifier)

Cancer example:  $R(r^*) = 0.1(5 \cdot 0.3) + 0.9(1 \times 0.01 + 1 \cdot 0.1) = 0.249$

\* using prior prob. formula

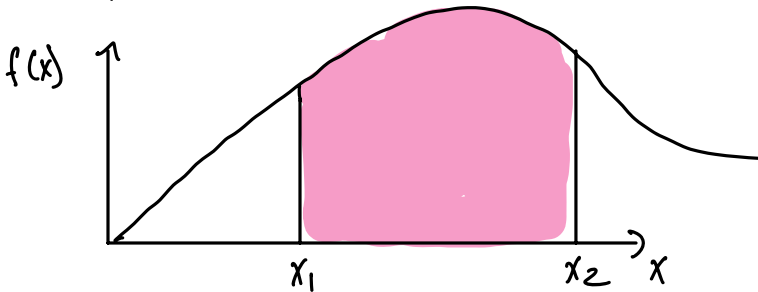
no decision rule gives lower risk

Deriving/using  $r^*$  is called risk minimization

## CONTINUOUS DISTRIBUTIONS

$X$  is continuous w/ a PDF

Review:



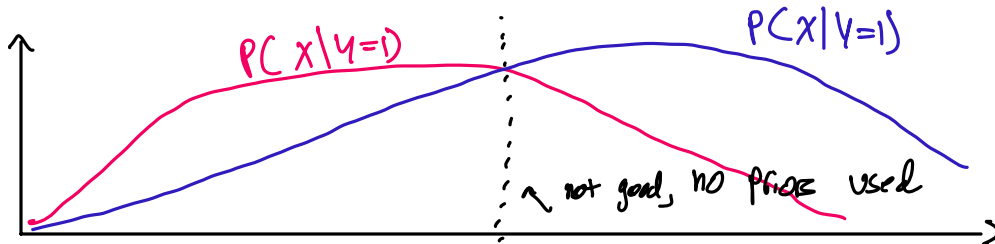
prob that  $X \in [x_1, x_2] = \int_{x_1}^{x_2} f(x) dx$

$X \in [-\infty, \infty] = 1$  (def of pdf)  $= \int_{-\infty}^{\infty} f(x) dx = 1$

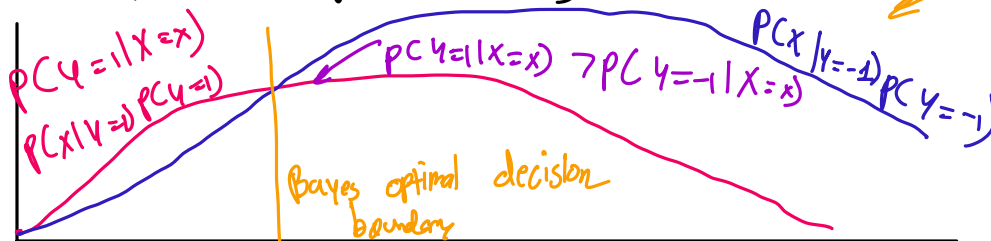
Expected value of  $g(x) = \int_{-\infty}^{\infty} g(x) f(x) dx$

mean  $\mu = E[X] = \int_{-\infty}^{\infty} x f(x) dx$

Variance:  $\sigma^2 = E[(X - \mu)^2] = E[X^2] - E[X]^2$



Suppose  $P(Y=1) = 1/3$ ,  $P(Y=-1) = 2/3$ , 0-1 loss



Posterior probabilities, don't need to divide by  $P(X)$

Define risk as before, Integral instead of Summation

$$\begin{aligned} R(r) &= E[L(r(x), y)] \\ &= P(Y=1) \int L(r(x), 1) f(x=x|Y=1) dx \\ &\quad + P(Y=-1) \int L(r(x), -1) f(x=x|Y=-1) dx \end{aligned}$$

Bayes risk = area under minimum of 2 functions

Assuming  $L(z, y) = 0$  for  $z = y$ :

$$R(r^*) = \int_{y=\pm 1}^{\min} L(-y, y) f(x=x|Y=y) P(Y=y) dx$$

0-1 loss  $\implies$  Risk =  $P(r(x) \text{ is wrong})$

$\hookrightarrow$  Bayes optimal decision boundary =  $\{x: \underbrace{P(Y=1|x=x)}_{\text{posterior probability}} = 0.5\}$   
 $\underbrace{\hspace{10em}}_{\text{decision function}} \quad \underbrace{\hspace{10em}}_{\text{isovalue}}$

### 3 WAYS TO BUILD Classifiers

#### ① generative models (e.g. LDA)

- Assume sample pts come from probability distributions, different for each class
- guess form of distributions
- For each class  $C_i$ , fit distribution parameters to the class, giving  $f(x|Y=C_i)$
- estimate prior probability for each class  $P(Y=c)$
- get posterior probability w/ Bayes thm
- If 0-1, pick  $C$  that maximizes  $P(Y=c|x=x)$   
equivalent to maximizing  $f(x=x|Y=C) P(Y=c)$

#### ② Discriminative Models (e.g. logistic regression)

- model posterior probability w/o class conditional probabilities

#### ③ Find decision boundary (e.g. SVM)

- model  $r(x)$  directly, (no posterior)

Advantages of 1 & 2:  $-P(Y|x)$  tells probability you're wrong

advantage of ①: easy to diagnose outliers:  $f(x)$  very small

disadvantage of ①: hard to estimate distributions, e.g. real distributions