

Privacy Preserving Image Registration

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Introduction

Image Registration (IR)

Image registration goal: spatially align imaging features between two or multiple images.

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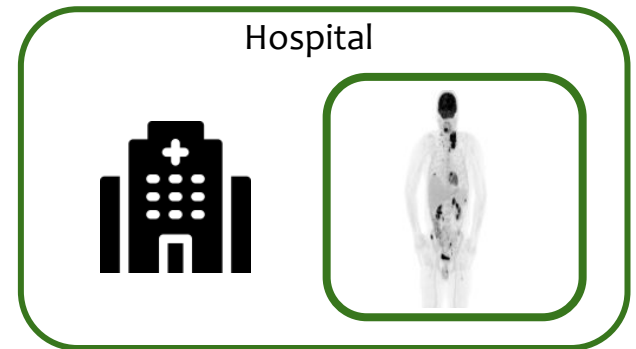


Image Registration (IR)

Image registration goal: spatially align imaging features between two or multiple images.

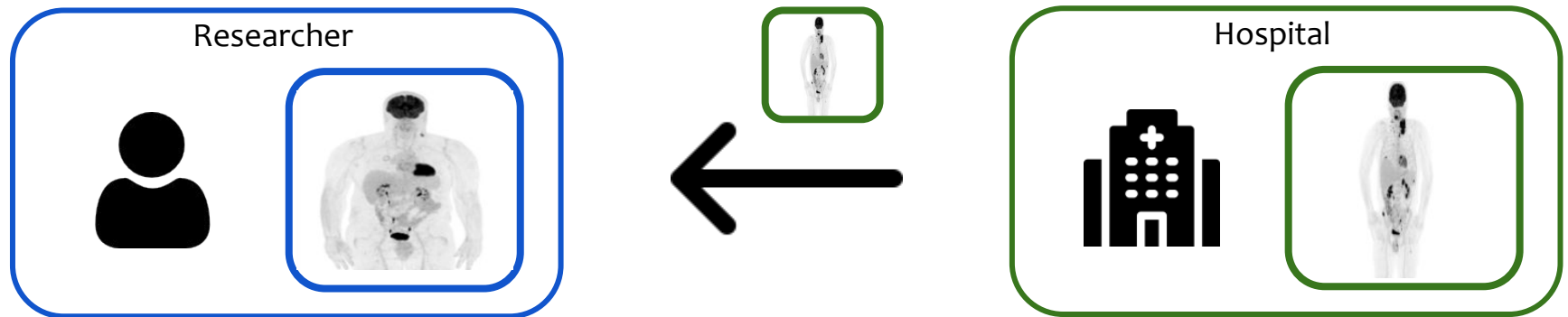


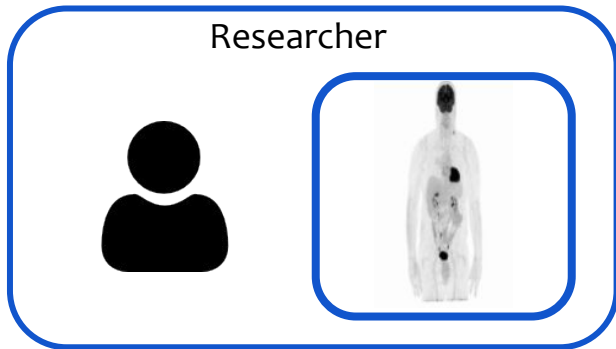
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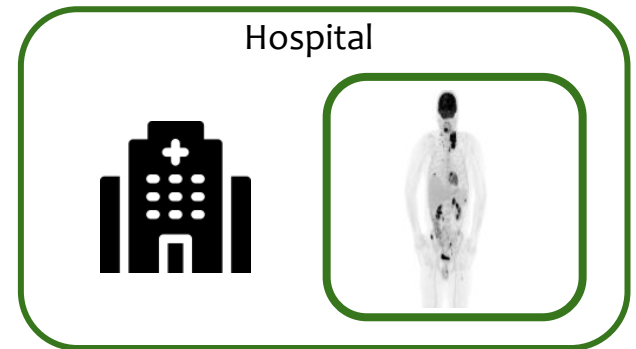


Image Registration

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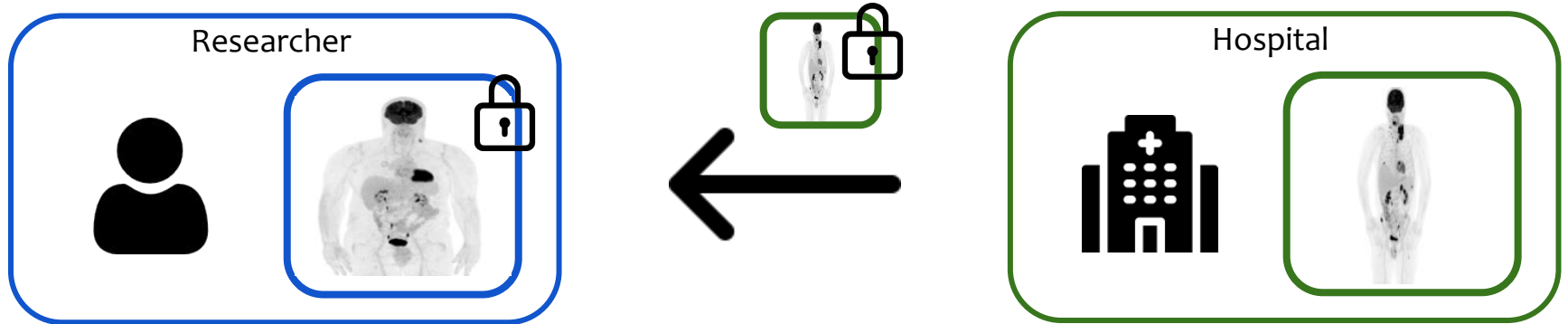


... completed!

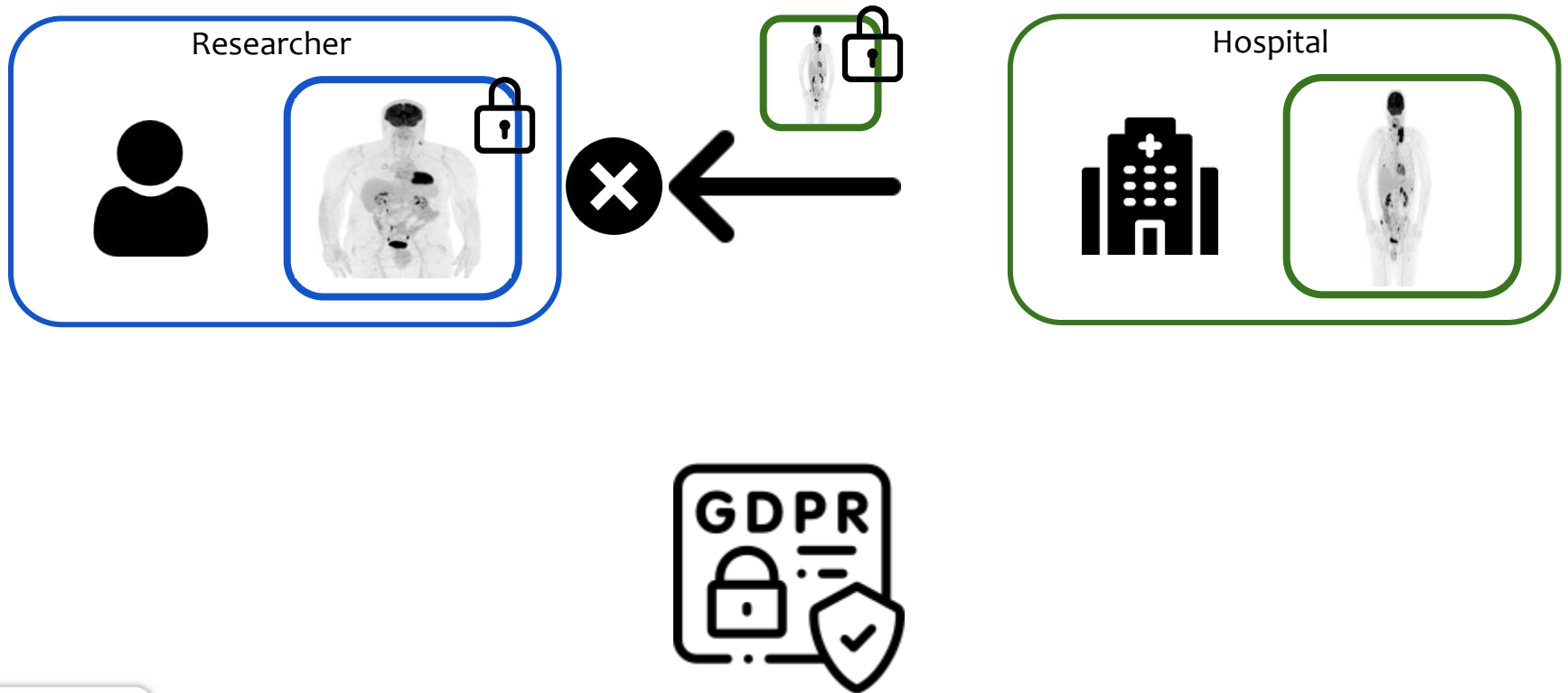


Problem

Privacy Concerns



Privacy Concerns



Background

Optimization problem - IR [Baker et al.]

$$\text{SSD}(I, J, \mathbf{p}) = \arg \min_{\mathbf{p}} \sum_{i,j} \left[(I(W_{\mathbf{p}}(i, j))) - J(i, j) \right]^2$$

$$\Delta \mathbf{p} = H^{-1} \cdot \sum_{i,j} S(i, j) \cdot (I(\mathbf{W}_{\mathbf{p}}(i, j)) - J(i, j))$$

$$S(i, j) = \nabla I(i, j) \frac{\partial \mathbf{W}_{\mathbf{p}}(i, j)}{\partial \mathbf{p}}$$

$$H = \sum_{i,j} \left(\nabla I(i, j) \frac{\partial \mathbf{W}_{\mathbf{p}}(i, j)}{\partial \mathbf{p}} \right)^T \left(\nabla I(i, j) \frac{\partial \mathbf{W}_{\mathbf{p}}(i, j)}{\partial \mathbf{p}} \right)$$

Method

Privacy Preserving Image Registration (PPIR)[Taiello et al.]

$$\Delta \mathbf{p} = H^{-1} \cdot \sum_{i,j} \overset{\text{Researcher (party}_1\text{)}}{\boxed{S(i,j)}} \cdot (I(\mathbf{W}_p(i,j)) - \overset{\text{Hospital (party}_2\text{)}}{\boxed{J(i,j)}})$$

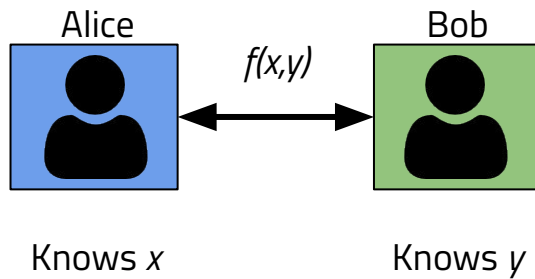
$$R = \sum_{i,j} \overset{\text{Researcher (party}_1\text{)}}{\boxed{S(i,j)}} \cdot \overset{\text{Hospital (party}_2\text{)}}{\boxed{J(i,j)}}$$

In a vectorized form:

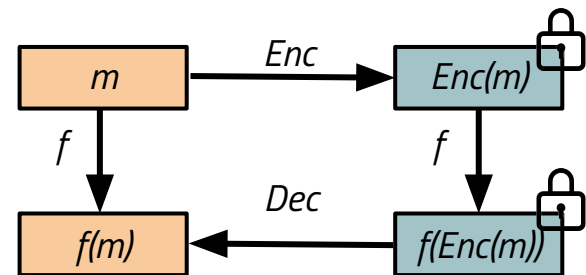
$$R = \overset{\text{Researcher (party}_1\text{)}}{\boxed{S^T}} \cdot \overset{\text{Hospital (party}_2\text{)}}{\boxed{J}}$$

Privacy Preserving Techniques

Multi Party Computation (MPC)

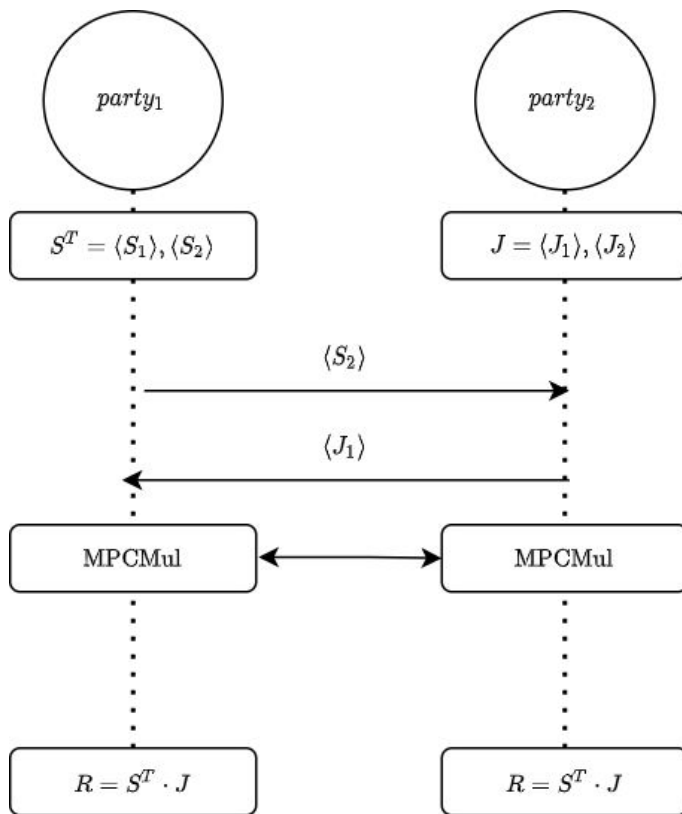


Fully Homomorphic Encryption (FHE)

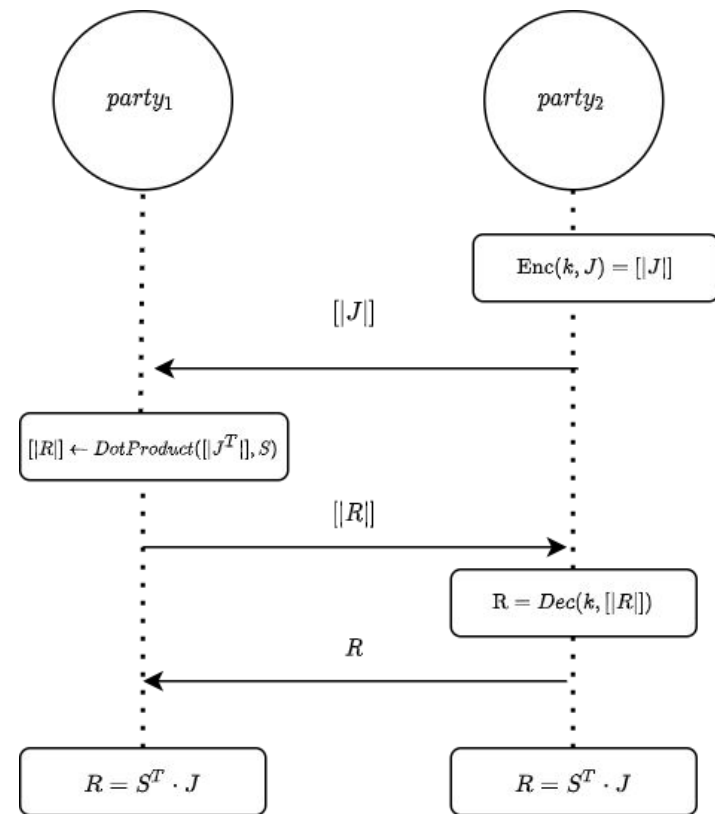


PPIR protocols [Taiello et al.]

Multi Party Computation (MPC)



Fully Homomorphic Encryption (FHE)



Optimization

For MPC & FHE:

Large images, solutions:

- Uniformly Random Selection (URS)[Mattes et al.]
- Gradient Magnitude Sampling (GMS)[Viola et al.]

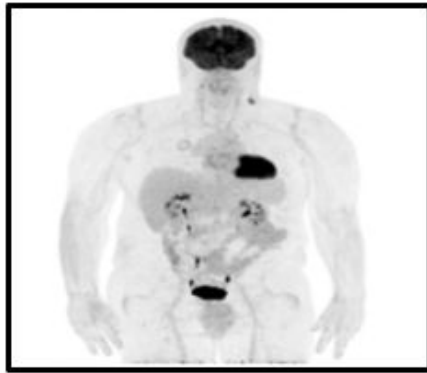
For FHE:

We propose to partition the image I into K sub-arrays, and the matrix S into K submatrices.

Results

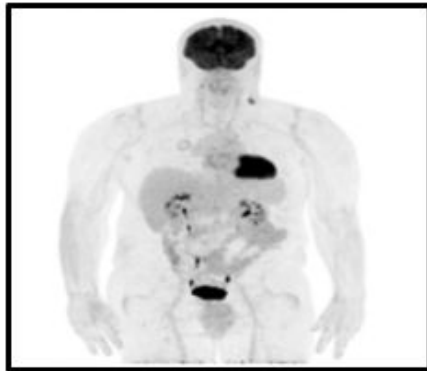
Results

Moving Image *I*

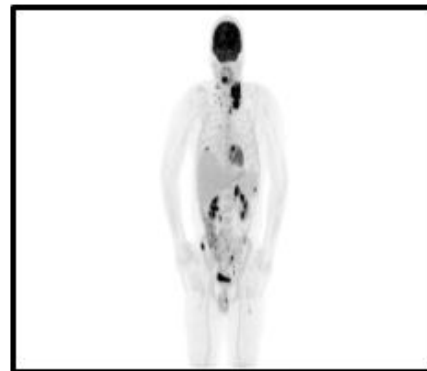


Results

Moving Image I

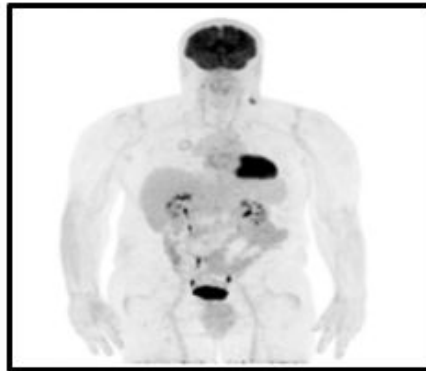


Template Image J

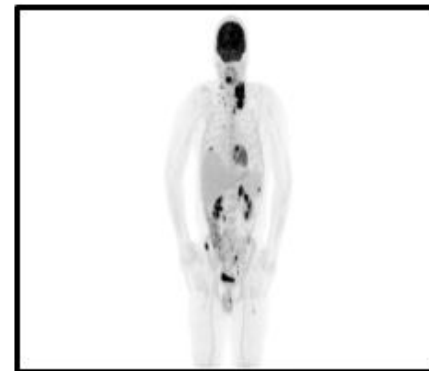


Results

Moving Image I



Template Image J

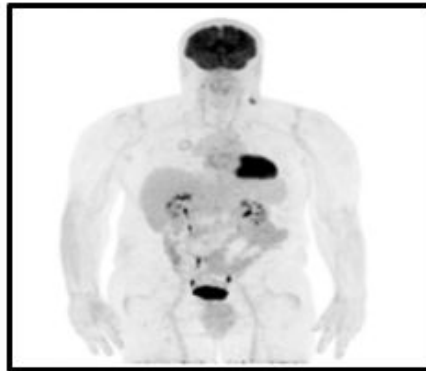


Transformed with Clear + URS

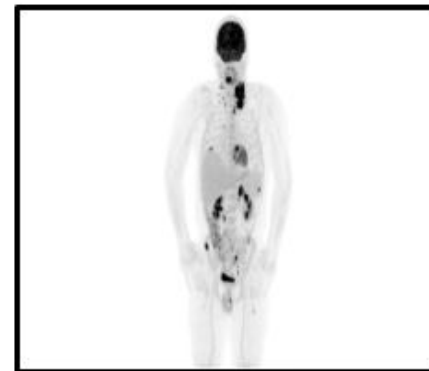


Results

Moving Image I



Template Image J



Transformed with Clear + URS

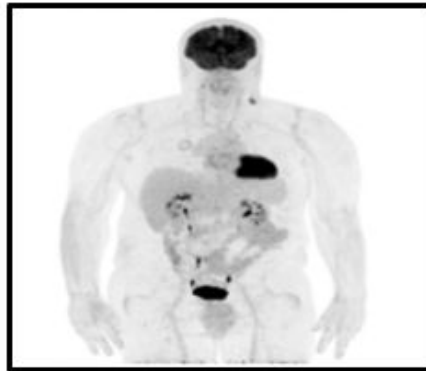


Transformed with SPDZ + URS

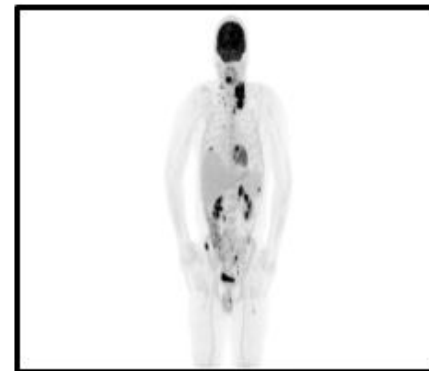


Results

Moving Image I



Template Image J



Transformed with Clear + URS



Transformed with SPDZ + URS



Transformed with CKKS + URS



Conclusions

PPIR a novel framework to allow image registration when images are confidential and **cannot be disclosed in clear**.

Future extensions:

- 3D medical image data;
- multimodal image registration problem.

References

Taiello, R., Önen, M., Humbert, O., Lorenzi, M.: Privacy Preserving Image Registration [**ACCEPTED MICCAI 2022**] <https://arxiv.org/abs/2205.10120>

Thanks!

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Inria

 **Antoine Lacassagne**
CENTRE DE LUTTE CONTRE LE CANCER
 **unicancer** **NICE**


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Inria

Result - Linear Transformation

Affine Registration metrics				
Solution	Intensity Error (SSD)	Num. Iteration	Displacement RMSE CLEAR vs PPIR (<i>mm</i>)	
CLEAR	4.31 ± 0.0	100 ± 0.0	-	
SPDZ	4.31 ± 0.0	91.8 ± 0.42	5.91 ± 0.14	
CKKS	X	X	X	
CLEAR + URS	4.32 ± 0.0	99.70 ± 4.25	-	
SPDZ + URS	4.31 ± 0.0	103.60 ± 4.67	12.17 ± 13.35	
CKKS ($D = 128$) + URS	4.48 ± 0.10	100.67 ± 3.32	19.54 ± 8.60	
CLEAR + GMS	4.31 ± 0.0	106 ± 0.0	-	
SPDZ + GMS	4.32 ± 0.0	101.10 ± 5.38	5.39 ± 2.29	
CKKS ($D = 128$) + GMS	4.36 ± 0.05	99 ± 4.27	13.64 ± 4.20	
Efficiency metrics				
Solution	Time <i>party</i> ₁ (s)	Time <i>party</i> ₂ (s)	Comm. <i>party</i> ₁ (MB)	Comm. <i>party</i> ₂ (MB)
CLEAR	0.0	0.0	-	-
SPDZ	0.73	0.73	14.15	14.15
CKKS	X	X	X	X
CLEAR + URS	0.0	0.0	-	-
SPDZ + URS	0.06	0.06	0.52	0.52
CKKS ($D = 128$) + URS	0.19	0.0	0.06	0.46f
CLEAR + GMS	0.0	0.0	-	-
SPDZ + GMS	0.07	0.07	0.54	0.54
CKKS ($D = 128$) + GMS	0.19	0.0	0.06	0.46

Result - Non Linear Transformation

Cubic splines Registration metrics				
Solution	Intensity Error (SSD)	Num. Iteration	Displacement RMSE CLEAR vs PPIR (mm)	
CLEAR	6.73 ± 0.0	413 ± 0.0	-	
SPDZ	6.73 ± 0.1	413.70 ± 0.48	1.34 ± 0.08	
CKKS	6.40 ± 0.07	183 ± 17.19	1.15 ± 0.27	
Cubic splines Efficiency metrics				
Solution	Time <i>party</i> ₁ (s)	Time <i>party</i> ₂ (s)	Comm. <i>party</i> ₁ (MB)	Comm. <i>party</i> ₂ (MB)
CLEAR	0.0	0.22 ± 0.02	-	-
SPDZ	0.53	0.53	16.32	20.12
CKKS	0.17	0.17	0.06	0.07