

Reminders

9/9/2025

- ↳ Quiz
- ↳ Pset + Self Grade!
- ↳ Office Hours
- ↳ Discord
- ↳ Events
 - Conference Oct 3-5
 - Redistricting Sep 16 Lunch @ Ath
 - Trees Sep 16 7pm @ Mudd

Review

$$\underline{x}^{(i)} \in \mathbb{R}^d$$

$$y^{(i)} \in \mathbb{R}$$

$$\underline{X} \in \mathbb{R}^{n \times d}$$

$$\begin{bmatrix} -x^{(i)T} \end{bmatrix}$$

$$\underline{y} \in \mathbb{R}^n$$

$$\begin{bmatrix} y^{(i)} \end{bmatrix}$$

Goal: $f(\underline{x}^{(i)}) \approx y^{(i)}$

① Model Linear! $f(\underline{x}) = \underline{\omega}^T \underline{x}$

② Loss MSE! $\mathcal{L}(\underline{\omega}) = \sum_{i=1}^n [f(\underline{x}^{(i)}) - y^{(i)}]^2 / n$

③ Optimizer Exact! $\underline{\omega}^* = (\underline{X}^T \underline{X})^+ \underline{X}^T \underline{y}$

Why pseudo inverse?

"Invert" non-invertible matrices
e.g. $\underline{X} \in \mathbb{R}^{n \times d}$

$$\underline{X} = \sum_{i=1}^d \sigma_i \underline{u}_i \underline{v}_i^T$$

$$\begin{aligned} \underline{X}^+ \underline{X} &= \sum_{j=1}^d \frac{1}{\sigma_j} \underline{v}_j \underline{u}_j^T \sum_{i=1}^d \sigma_i \underline{u}_i \underline{v}_i^T \\ &= \sum_{i=1}^d \underline{v}_i \underline{v}_i^T = I_d \end{aligned}$$

Greatest advice: "Go sit on your rock"

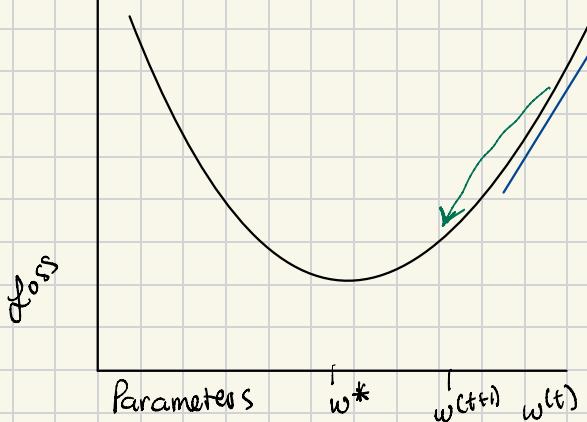
Two issues:

↳ Time to compute $\underline{\omega}^*$

↳ What if data is not linear?

Gradient Descent

$$\omega^{(t+1)} \in \omega^{(t)} - \alpha \nabla \mathcal{L}(\omega^{(t)})$$



Intuition: Move away from steepest ascent

α = "step size" or "learning rate"

The Math (as promised)

$$[\omega \in \mathbb{R}]$$

$$\frac{\partial \mathcal{L}(\omega)}{\partial \omega} = \lim_{\Delta \rightarrow 0} \frac{\mathcal{L}(\omega + \Delta) - \mathcal{L}(\omega)}{\Delta}$$

$$\Rightarrow \mathcal{L}(\omega + \Delta) - \mathcal{L}(\omega) \approx \frac{\partial \mathcal{L}(\omega)}{\partial \omega} \Delta$$

Choose Δ so $\mathcal{L}(\omega + \Delta) - \mathcal{L}(\omega)$ is negative ...

$$\Delta = -\frac{\partial \mathcal{L}(\omega)}{\partial \omega}$$

$$w \in \mathbb{R}^d$$

$$\frac{\partial \mathcal{L}(w)}{\partial w_i} = \lim_{\Delta \rightarrow 0} \frac{\mathcal{L}(w + \Delta e_i) - \mathcal{L}(w)}{\Delta}$$

$$\Rightarrow \mathcal{L}(w + \Delta e_i) - \mathcal{L}(w) \approx \Delta \langle \nabla_w \mathcal{L}(w), e_i \rangle$$

$$\mathcal{L}(w + v) - \mathcal{L}(w) \approx \Delta \langle \nabla_w \mathcal{L}(w), v \rangle$$

$$\text{choose } \Delta v = -\alpha \nabla_w \mathcal{L}(w)$$

$$\begin{aligned} \mathcal{L}(w + v) - \mathcal{L}(w) &\approx -\alpha \|\nabla_w \mathcal{L}(w)\|_2^2 \\ &= -\alpha \|\nabla_w \mathcal{L}(w)\|_2 \|\nabla_w \mathcal{L}(w)\|_2 \end{aligned}$$

$$\text{Recall } \langle a, b \rangle = \|a\|_2 \|b\|_2 \cos(\theta)$$

$$\max_{\theta} \cos \theta = 1 \Rightarrow \text{achieve "best" update!}$$

For linear regression,

$$\nabla_w \mathcal{L}(w) = \frac{2}{n} X^T(Xw - y)$$

Time to compute:

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↳ Notes!

↳ Self-grade due Friday

↳ Sit on your rock

↳ Pset 3 due Monday

⌚ most important thing I can offer

↳ Quiz Tuesday

↳ exercises + notes = fair game

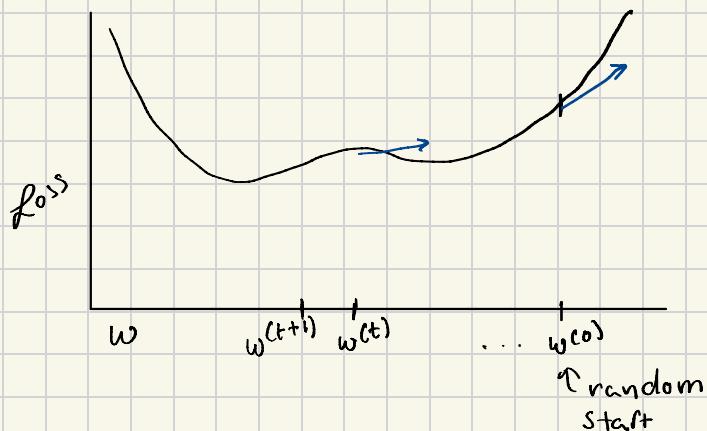
↳ Events!

↳ Please ask specific questions, e.g.,

"Explain concept A"

"Why is B true"

Review: Gradient Descent



$$w^{(t+1)} \leftarrow w^{(t)} - \alpha \nabla \mathcal{L}(w^{(t)})$$

Linear regression:

$$\nabla \mathcal{L}(w) = \underset{d \times n}{X^T} \underset{n \times d}{(Xw - y)}$$

Time:

Even Faster

n and d can be prohibitively large

Enter: STOCHASTIC gradient descent
 ↑
 "stochas"

$$S \subseteq \{1, \dots, n\} \quad \text{s.t. } |S| = m$$

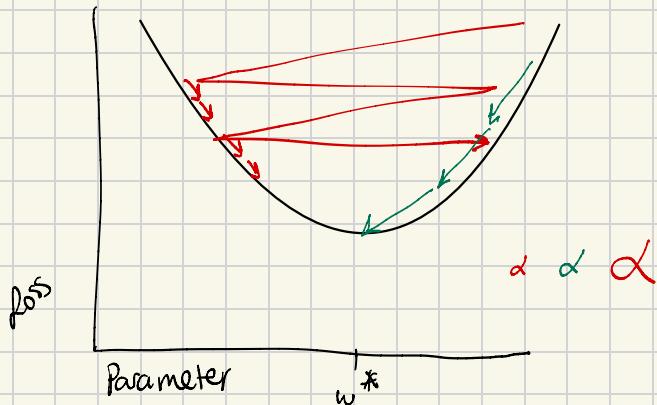
$$\mathcal{L}_s(w) = \frac{1}{m} \sum_{i \in S} [f(x^{(i)}) - y^{(i)}]^2$$

For linear regression,

$$\nabla_w \mathcal{L}_s(w) = \frac{2}{|S|} X_s^T (X_s w - y_s)$$

Time:

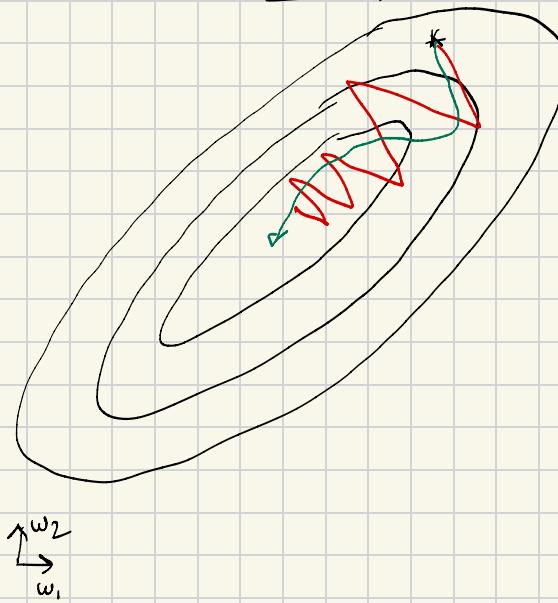
Learning Rate



heuristic strategies:

- ↳ If loss unstable, decrease ($\alpha/2$)
- If loss slowly decreasing, increase (2α)
- ↳ "scheduler" start big \rightarrow small, cycle
- ↳ Adaptive $\alpha^{(t+1)} \leftarrow \frac{\alpha^{(t)}}{(\nabla_w \mathcal{L}(w^{(t)}))^2}$

Momentum



$$m^{(t+1)} \leftarrow \beta m^{(t)} + (1-\beta) \nabla_w \mathcal{L}_s(w^{(t)})$$

$$w^{(t+1)} \leftarrow w^{(t)} - \alpha m^{(t+1)}$$

Polynomial Regression

Q: We covered how to speed up optimization, how do we address model mis-specification?

A: Add more expressive features

Linear regression e.g.,

$$f(x) = w_1 x_1 + w_2 x_2$$

$$w^* = X^T y = (X^T X)^{-1} X^T y$$

Polynomial regression e.g.,

$$f(x) = w_1 x_1 + w_2 x_2 + w_3 x_1 x_2 + w_4 x_1^2 + w_5 x_2^2$$

$$x_{\text{aug}} = \begin{bmatrix} x & z \end{bmatrix}$$

$$\begin{bmatrix} & & \\ & & \\ \underbrace{\quad}_{d} \quad \underbrace{\quad}_{d'} & & \end{bmatrix}$$

$$w_{\text{aug}}^* = X_{\text{aug}}^T y$$

Q: What changes in 3 step recipe?

Expressivity

$$w^* = X^+ y$$

$$w_{\text{aug}}^* = X_{\text{aug}}^+ y$$

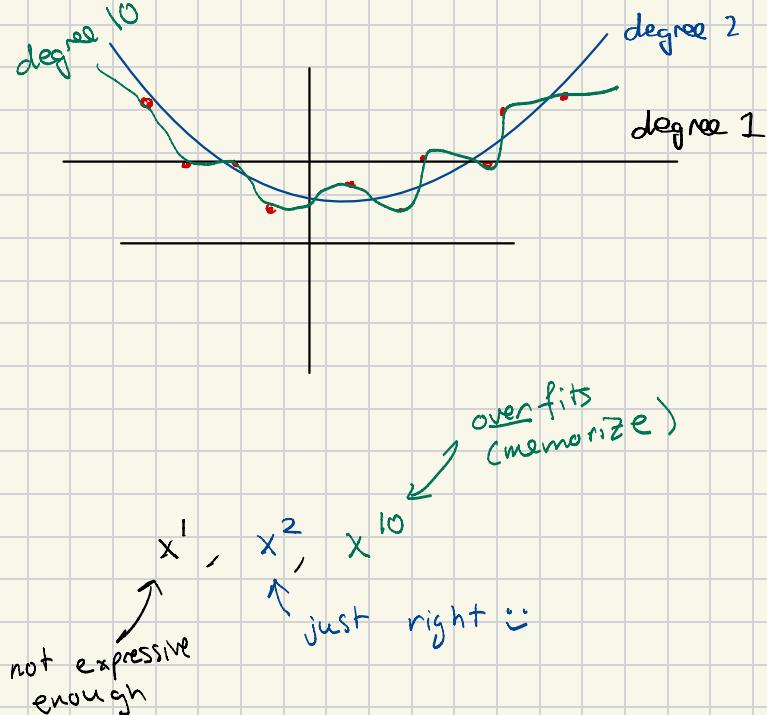
Claim: More expressive

$$\min_{w \in \mathbb{R}^{d+d'}} \|X_{\text{aug}} w - y\|_2^2 \leq \min_{w \in \mathbb{R}^d} \|X w - y\|_2^2$$

Proof: choose $\hat{w} = \begin{bmatrix} w^* \\ 0 \\ 0 \\ 0 \end{bmatrix}$. Then $\|X_{\text{aug}} \hat{w} - y\|_2^2 = \|X w^* - y\|_2^2$

Since \hat{w} is always a choice, w_{aug}^* must be at least as good

Which degree to choose?



Generalization Error

Training	Validation	Test
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Data

1. Train model
2. Check loss on validation set
3. Update hyperparameters
(learning rate, momentum, etc)
- repeat

Pernicious issue: model performs better on validation even though never "trained" on it

Solution: Use test loss once on final model

Regularization

Idea: Use simplest model

Weight magnitude \approx complexity

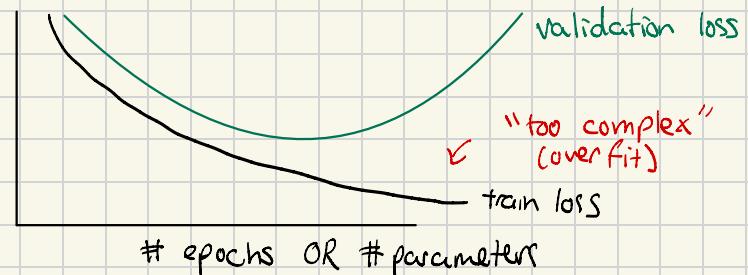
↳ More output variation per input change

New loss:

$$\mathcal{L} + \lambda \|\omega\|_2^2$$

Double Descent

Traditional View:



Modern View:

